

# MCT/IGBTs/Diodes





## HARRIS SEMICONDUCTOR

This MCT/IGBT/DIODES Databook represents the full line of these products made by Harris Semiconductor Discrete Power products for Commercial applications. For a complete listing of all Harris Semiconductor products, please refer to the Product Selection Guide (PSG-201.21; ordering information below).

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#### **U.S. HEADQUARTERS**

Harris Semiconductor P. O. Box 883, Mail Stop 53-210 Melbourne, FL 32902 TEL: 1-800-442-7747 (407) 729-4984 FAX: (407) 729-5321

#### SOUTH ASIA

Harris Semiconductor H.K. Ltd 13/F Fourseas Building 208-212 Nathan Road Tsimshatsui, Kowloon Hong Kong TEL: (852) 723-6339

#### EUROPEAN HEADQUARTERS

Harris Semiconductor Mercure Center 100, Rue de la Fusee 1130 Brussels, Belgium TEL: 32 2 724 21 11

#### NORTH ASIA

Harris K.K. Kojimachi-Nakata Bldg. 4F 5-3-5 Kojimachi Chiyoda-ku, Tokyo 102 Japan TEL: (81) 3-3265-7571 TEL: (81) 3-3265-7572 (Sales)



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## MCT/IGBT/DIODES PRODUCTS

Harris Semiconductor is a pioneer in developing and producing Discrete Power products for the most demanding Commercial applications in this world and beyond.

This databook fully describes Harris Semiconductor's line of MOS Controlled Thyistors, Insulated Gate Bipolar Transistors (IGBTs) and Power Diodes/Rectifiers. It includes a complete set of datasheets for product specifications, application notes with design details for specific applications of Harris products, and a description of the Harris Quality and Reliability program. A New AnswerFAX section has been added to allow Users to request the latest datasheets and have them delivered immediately to your FAX machine. A detailed listing of product Packaging dimensions provides a wide variety of information at your fingertips.

Harris offers an extensive line of MCT/IGBT/DIODES components including; • MOS Controlled Thyristors • Insulated Gate Bipolar Transistors (IGBTs) • IGBTs with Anti-Parallel Diodes • Current Sensing IGBTs • Voltage Clamping IGBTs • Ultrafast Diodes • Hyperfast Diodes found in Sections 2 through 7.

It is our intention to provide you with the most up-to-date information on MCT/IGBT/ DIODE Products. For complete, current and detailed technical specifications on any Harris devices please contact the nearest Harris sales, representative or distributor office, listed at the end of the databook; or direct literature requests to:

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Harris Semiconductor products are sold by description only. All specifications in this product guide are applicable only to packaged products; specifications for die are available upon request. Harris reserves the right to make changes in circuit design, specifications and other information at any time without prior notice. Accordingly, the reader is cautioned to verify that information in this publication is current before placing orders. Reference to products of other manufacturers are solely for convenience of comparison and do not imply total equivalency of design, performance, or otherwise.



# **MCT/IGBT/DIODES**

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\* Product Selection Guide located at the beginning of section.

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RHRD450S       4A, 400V - 600V Hyperfast Diodes       7-5         RHRD460       4A, 400V - 600V Hyperfast Diodes       7-5         RHRD460S       4A, 400V - 600V Hyperfast Diodes       7-5         RHRD4120       4A, 1200V Hyperfast Diodes       7-9         RHRD4120       30A, 1200V Hyperfast Diodes       7-9         RHRG30120       30A, 1200V Hyperfast Diodes       7-13         RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-40         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-22         RHR930120       30A, 1200V Hyperfast Diode       7-22         RHR930120       30A, 1200V Hyperfast Diodes       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfa	RHRD440S	4A, 400V - 600V Hyperfast Diodes	7-5
RHRD460       4A, 400V - 600V Hyperfast Diodes .       7-5         RHRD460S       4A, 400V - 600V Hyperfast Diodes .       7-5         RHRD4120       4A, 1200V Hyperfast Diodes .       7-9         RHRD4120S       4A, 1200V Hyperfast Diodes .       7-9         RHRG30120       30A, 1200V Hyperfast Diode .       7-13         RHRG30120CC       30A, 1200V Hyperfast Diode .       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes .       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes .       7-22         RHR930120       30A, 1200V Hyperfast Diode .       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes .       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes .       7-34         RHRU15040       150A, 400V - 600V Hyperfast Diodes .       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes .       7-34	RHRD450	4A, 400V - 600V Hyperfast Diodes	7-5
RHRD460S       4A, 400V - 600V Hyperfast Diodes       7-5         RHRD4120       4A, 1200V Hyperfast Diodes       7-9         RHRD4120S       4A, 1200V Hyperfast Diodes       7-9         RHRG30120       30A, 1200V Hyperfast Diode       7-13         RHRG30120CC       30A, 1200V Hyperfast Diode       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-22         RHR930120       30A, 1200V Hyperfast Diode       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-34         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060 </td <td>RHRD450S</td> <td>4A, 400V - 600V Hyperfast Diodes</td> <td>7-5</td>	RHRD450S	4A, 400V - 600V Hyperfast Diodes	7-5
RHRD4120       4A, 1200V Hyperfast Diodes       7-9         RHRD4120S       4A, 1200V Hyperfast Diodes       7-9         RHRG30120       30A, 1200V Hyperfast Diode       7-13         RHRG30120CC       30A, 1200V Hyperfast Dual Diode       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-34         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-34	RHRD460	4A, 400V - 600V Hyperfast Diodes	7-5
RHRD4120S       4A, 1200V Hyperfast Diodes.       7-9         RHRG30120       30A, 1200V Hyperfast Diode.       7-13         RHRG30120CC       30A, 1200V Hyperfast Diode.       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes.       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes.       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes.       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes.       7-22         RHRG50100       50A, 700V - 1000V Hyperfast Diodes.       7-22         RHR075120       75A, 1200V Hyperfast Diode.       7-22         RHRU10040       100A, 400V - 600V Hyperfast Diodes.       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes.       7-28         RHRU10060       100A, 1200V Hyperfast Diodes.       7-34         RHRU15040       150A, 400V - 600V Hyperfast Diodes.       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes.       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes.       7-34	RHRD460S	4A, 400V - 600V Hyperfast Diodes	7-5
RHRG30120       30A, 1200V Hyperfast Diode.       7-13         RHRG30120CC       30A, 1200V Hyperfast Dual Diode.       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-22         RHR930120       30A, 1200V Hyperfast Diode       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU100120       100A, 1200V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37 </td <td>RHRD4120</td> <td>4A, 1200V Hyperfast Diodes</td> <td>7-9</td>	RHRD4120	4A, 1200V Hyperfast Diodes	7-9
RHRG30120CC       30A, 1200V Hyperfast Dual Diode.       7-40         RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-22         RHRG75120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37	RHRD4120S	4A, 1200V Hyperfast Diodes	7-9
RHRG5070       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG75120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-16         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-31         RHRU100120       100A, 1200V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37	RHRG30120	30A, 1200V Hyperfast Diode	7-13
RHRG5080       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-22         RHRG75120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-28         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-31         RHRU100120       100A, 1200V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-34	RHRG30120CC	30A, 1200V Hyperfast Dual Diode	7-40
RHRG5090       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG75120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-16         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-31         RHRU100120       100A, 1200V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37	RHRG5070	50A, 700V - 1000V Hyperfast Diodes	7-19
RHRG50100       50A, 700V - 1000V Hyperfast Diodes       7-19         RHRG75120       75A, 1200V Hyperfast Diode       7-22         RHRP30120       30A, 1200V Hyperfast Diode       7-16         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37	RHRG5080	50A, 700V - 1000V Hyperfast Diodes	7-19
RHRG75120       75A, 1200V Hyperfast Diode.       7-22         RHRP30120       30A, 1200V Hyperfast Diode.       7-16         RHRU10040       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10050       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU10060       100A, 400V - 600V Hyperfast Diodes       7-28         RHRU100120       100A, 1200V Hyperfast Diodes       7-31         RHRU15040       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15050       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15060       150A, 400V - 600V Hyperfast Diodes       7-34         RHRU15090       150A, 900V - 1000V Hyperfast Diodes       7-37	RHRG5090	50A, 700V - 1000V Hyperfast Diodes	7-19
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# MCT/IGBT/DIODES 2

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	TO-247	MO-(	MO-093AA		5 LEAD TO-247	
	MCTG35P60F1	MCTA75P60E1	MCTA65P100E1	MCTV75P60E1	MCTV75P100E1	UNITS
BV <sub>DSS</sub>	600	600	1000	600	1000	v
I <sub>K90</sub>	35†	75	65	75	65	~ A
I <sub>KM</sub>	50	120	100	120	100	A
V <sub>TM</sub> at I <sub>K90</sub>	1.35†	1.3	1.4	1.3	1.4	· v
t <sub>Fi</sub>	1.4	1.4	1.9	1.4	1.9	μs

•

†  $I_{K115}$ ; Continuous Cathode Current rated at  $T_C = +115^{\circ}C$ .



## MCTG35P60F1

Packaging

Symbol

December 1993

## 35A, 600V P-Type MOS Controlled Thyristor (MCT)

JEDEC STYLE TO-247

TOP VIEW

#### Features

- 35A, -600V
- V<sub>тм</sub> = -1.3V(Maximum) at I = 35A and +150°С
- 800A Surge Current Capability
- 800A/us di/dt Capability
- MOS Insulated Gate Control
- 50A Gate Turn-Off Capability at +150°C

#### Description

The MCT is an MOS Controlled Thyristor designed for switching currents on and off by negative and positive pulsed control of an insulated MOS gate. It is designed for use in motor controls, inverters, line switches and other power switching applications.

The MCT is especially suited for resonant (zero voltage or zero current switching) applications. The SCR like forward drop greatly reduces conduction power loss.

MCTs allow the control of high power circuits with very small amounts of input energy. They feature the high peak current capability common to SCR type thyristors, and operate at junction temperatures up to +150°C with active switching.

The MCTG35P60F1 (formerly TA9789) is supplied in the JEDEC Style TO-247 package.

Due to space limitations, the brand on this part is abbreviated to G35P60F1. To order this part use the full part number.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	MCTG35P60F1	UNITS
Peak Off-State Voltage (See Figure 11) V <sub>DRM</sub>	-600	v
Peak Reverse Voltage	+5	v
Continuous Cathode Current (See Figure 2)		
T <sub>C</sub> = +25°C (Package Limited)	60	Α
T <sub>C</sub> = +115°C I <sub>K115</sub>	35	Α
Non-repetitive Peak Cathode Current (Note 1) IKSM	800	Α
Peak Controllable Current (See Figure 10)I <sub>KC</sub>	50	Α
Gate-Anode Voltage (Continuous)	±20	v
Gate-Anode Voltage (Peak)	±25	v
Rate of Change of Voltage dv/dt	See Figure 11	
Rate of Change of Current di/dt	800	A/µs
Maximum Power Dissipation	178	w
Linear Derating Factor	1.43	W/ºC
Operating and Storage Temperature Tراب T <sub>3</sub> , T <sub>3</sub> :	rg -55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.063" (1.6mm) from case for 10s)	260	°C
NOTE:		
1. Maximum Pulse Width of 250 $\mu$ s (Half Sine) Assume T <sub>J</sub> (Initial) = +90°C and T <sub>J</sub> (Final) = T <sub>J</sub>	(Max) = +150°C	

2

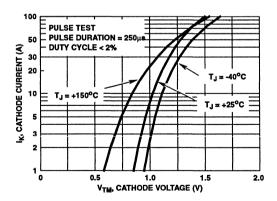


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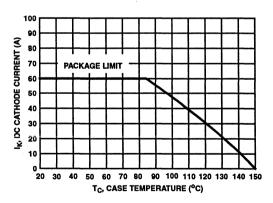
## Specifications MCTG35P60F1

				LIMITS			
PARAMETER	SYMBOL	TEST CONDI	rions	MIN	ТҮР	MAX	UNITS
Peak Off-State Blocking Current	IDRM	V <sub>KA</sub> = -600V,	T <sub>C</sub> = +150°C	-	-	1.5	mA
		V <sub>GA</sub> = +18V	T <sub>C</sub> = +25°C	-	-	50	μА
Peak Reverse Blocking	IRRM	V <sub>KA</sub> = +5V	T <sub>C</sub> = +150°C	•	-	2	mA
Current		V <sub>GA</sub> = +18V	T <sub>C</sub> = +25°C	-	-	50	μΑ
On-State Voltage	V <sub>TM</sub>	$I_{K} = I_{K115}$	T <sub>C</sub> = +150°C	-	-	1.35	v
		V <sub>GA</sub> = -10V	T <sub>C</sub> = +25°C	-	-	1.4	v
Gate-Anode Leakage Current	IGAS	V <sub>GA</sub> = ±20V		-	-	100	nA
Input Capacitance	C <sub>ISS</sub>	V <sub>KA</sub> = -20V, T <sub>J</sub> = +25°C V <sub>GA</sub> = +18V			5	-	nF
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	$L = 200\mu H, I_{K} = I_{K115}$	n./	-	140	-	ns
Current Rise Time	t <sub>RI</sub>	$R_{G} = 1\Omega, V_{GA} = +18V, -7$ $T_{J} = +125^{\circ}C$	v	-	180	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> i	V <sub>KA</sub> = -300V		-	640	-	ns
Current Fall Time	t <sub>FI</sub>	1			1.1	1.4	μs
Turn-off Energy	E <sub>OFF</sub>	]		-	5.6	-	mJ
Thermal Resistance	Rejc			-	0.6	0.7	°C/W

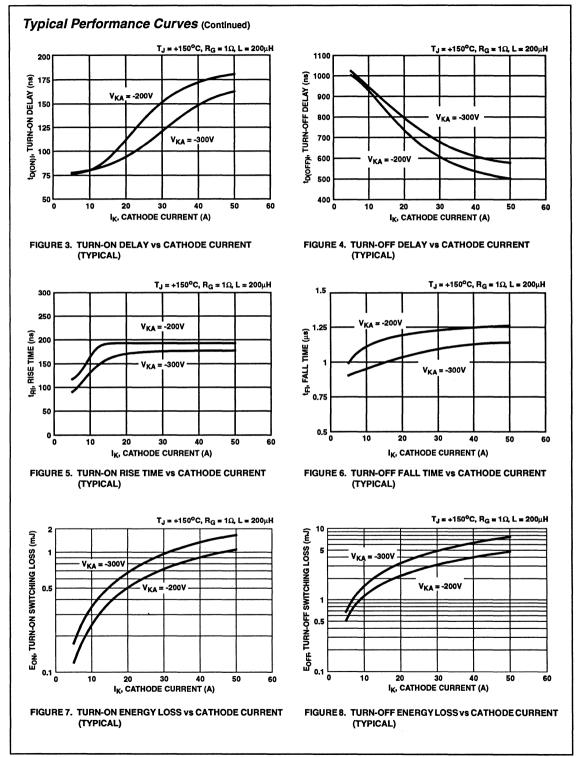
## **Typical Performance Curves**





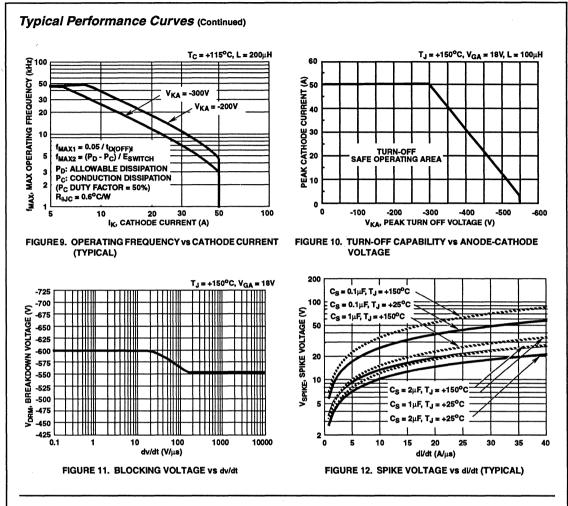






2

MCTs



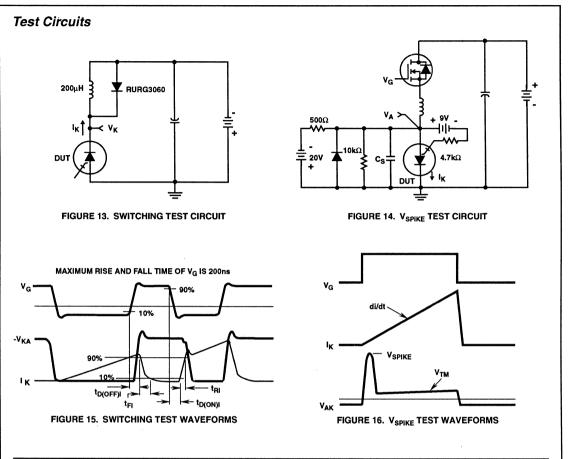
#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 9) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs cathode current ( $I_{AK}$ ) plots are possible using the information shown for a typical unit in Figure 3 to Figure 8. The operating frequency plot (Figure 9) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is lower at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05 / (t_{D(ON)1} + t_{D(OFF)1})$ .  $t_{D(ON)1} + t_{D(OFF)1}$  deadtime (the denominator) has been arbitrarily held to 10% of the on-state time for a 50% duty factor. Other definitions are possible.  $t_{D(ON)1}$  is defined as the 10% point of the leading edge of the input pulse and the point where the cathode current rises to 10% of its maximum value.  $t_{D(OFF)1}$  is defined as the 90% point of the trailing edge of the input pulse and the point where the cathode current falls to 90% of

its maximum value. Device delay can establish an additional frequency limiting condition for an application other than T<sub>JMAX</sub>.  $t_{D(OFF)}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2} = (P_D - P_C) / (E_{ON} + E_{OFF})$ . The allowable dissipation  $(P_D)$  is defined by  $P_D = (T_{JMAX} - T_C) / R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $PC = (V_{AK} \bullet I_{AK}) / (duty factor/100)$ .  $E_{ON}$  is defined as the sum of the instantaneous power loss starting at the leading edge of the input pulse and ending at the point where the anodecathode voltage equals saturation voltage ( $V_{AK} = V_{TM}$ ).  $E_{OFF}$  is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the cathode current equals zero ( $I_K = 0$ ).



## Handling Precautions for MCTs

Mos Controlled Thyristors are susceptible to gate-insulation damage by the electrostatic discharge of energy through the devices. When handling these devices, care should be exercised to assure that the static charge built in the handler's body capacitance is not discharged through the device. MCT's can be handled safely if the following basic precautions are taken:

- Prior to assembly into a circuit, all leads should be kept shorted together either by the use of metal shorting springs or by the insertion into conductive material such as ""ECCOSORB LD26" or equivalent.
- When devices are removed by hand from their carriers, the hand being used should be grounded by any suitable means - for example, with a metallic wristband.
- 3. Tips of soldering irons should be grounded.

4. Devices should never be inserted into or removed from circuits with power on.

2

MCTs

- 5. Gate Voltage Rating Never exceed the gate-voltage rating of V<sub>GA</sub>. Exceeding the rated V<sub>GA</sub> can result in permanent damage to the oxide layer in the gate region.
- 6. Gate Termination The gates of these devices are essentially capacitors. Circuits that leave the gate open-circuited or floating should be avoided. These conditions can result in turn-on of the device due to voltage buildup on the input capacitor due to leakage currents or pickup.
- 7. Gate Protection These devices do not have an internal monolithic zener diode from gate to emitter. If gate protection is required an external zener is recommended.
- \* Trademark Emerson and Cumming, Inc.

2-7



## *MCTV65P100F1 MCTA65P100F1*

P-Type MOS Controlled Thyristor (MCT)

65A. 1000V

December 1993

#### Features

- 65A, -1000V
- $V_{TM} \leq -1.4V$  at I = 65A and +150°C
- 2000A Surge Current Capability
- 2000A/µs di/dt Capability
- MOS Insulated Gate Control
- 100A Gate Turn-Off Capability at +150°C

#### Description

The MCT is an MOS Controlled Thyristor designed for switching currents on and off by negative and positive voltage control of an insulated MOS gate. It is designed for use in motor controls, inverters, line switches and other power switching applications.

The MCT is especially suited for resonant (zero voltage or zero current switching) applications. The SCR like forward drop greatly reduces conduction power loss.

MCTs allow the control of high power circuits with very small amounts of input energy. They feature the high peak current capability common to SCR type thyristors, and operate at junction temperatures up to +150°C with active switching.

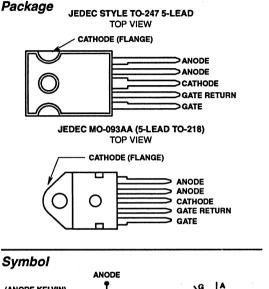
The MCTV65P100 is supplied in a 5-lead variation of the JEDEC Style TO-247 plastic package, and the MCTA65P100 in the JEDEC MO-093AA plastic package which is a 5-lead variation of the TO-218.

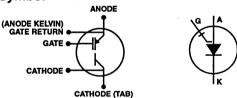
\* Formerly TA9900

#### Absolute Maximum Ratings (Tc = +25°C) Unless Otherwise Specified

	MCTV65P100F1 MCTA65P100F1	UNITS
Peak Off-State Voltage (See Figure 11)VDBM	-1000	v
Peak Reverse Voltage	+5	v
Continuous Cathode Current (See Figure 2)		
T <sub>C</sub> = +25°C (Package Limited)	85	Α
T <sub>C</sub> = +90°C I <sub>K90</sub>	65	Α
Non-repetitive Peak Cathode Current (Note 1)	2000	Α
Peak Controllable Current (See Figure 10) I <sub>TC</sub>	100	Α
Gate-Anode Voltage (Continuous) V <sub>GA</sub>	±20	v
Gate-Anode Voltage (Peak) V <sub>GA</sub>	±25	v
Rate of Change of Voltage dv/dt	See Figure 11	
Rate of Change of Current di/dt	2000	A∕µs
Maximum Power Dissipation	208	Ŵ
Linear Derating Factor	1.67	W/⁰C
Operating and Storage Temperature	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.063" (1.6mm) from case for 10s)	260	°C
NOTE:		
1 Novimum Bulas Midth of 2000 (Lloff Sine) Assume T (Initial)	(a) (15090	

1. Maximum Pulse Width of 200μs (Half Sine) Assume T<sub>J</sub> (Initial) = +90°C and T<sub>J</sub> (Final) = T<sub>J</sub> (Max) = +150°C

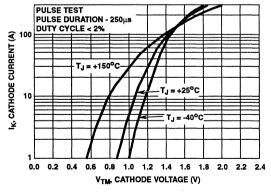


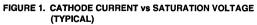


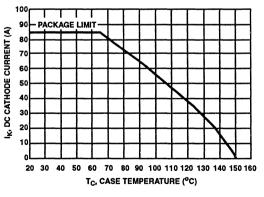
## Specifications MCTV65P100F1, MCTA65P100F1

PARAMETER					LIMITS	LIMITS	
	SYMBOL	TEST CONDITIONS		MIN	ТҮР	MAX	UNITS
Peak Off-State Blocking Current	IDRM	V <sub>KA</sub> = -1000V, V <sub>GA</sub> = +18V	T <sub>C</sub> = +150°C	-	-	3	mA
			T <sub>C</sub> = +25°C	-	-	100	μΑ
Peak Reverse Blocking Current	I <sub>RRM</sub>	V <sub>KA</sub> = +5V, V <sub>GA</sub> = +18V	T <sub>C</sub> = +150°C	-	-	4	mA
			T <sub>C</sub> = +25°C	-	-	100	μA
On-State Voltage	V <sub>TM</sub>	I <sub>K</sub> = I <sub>K90</sub> , V <sub>GA</sub> = -10V	T <sub>C</sub> = +150°C	-		1.4	v
			T <sub>C</sub> = +25°C	-	-	1.5	v
Gate-Anode Leakage Current	I <sub>GAS</sub>	$V_{GA} = \pm 20V$		-	-	200	nA
Input Capacitance	C <sub>ISS</sub>	V <sub>KA</sub> = -20V, T <sub>J</sub> = +25°C V <sub>GA</sub> = +18V		•	10	-	nF
Current Turn-On Delay Time	t <sub>D(ON)</sub> i			-	120	-	ns
Current Rise Time	t <sub>RI</sub>			-	160	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> i			-	750	-	ns
Current Fall Time	t <sub>FI</sub>	1		-	1.45	1.9	μs
Turn-off Energy	W <sub>OFF</sub>	]		-	18	-	mJ
Thermal Resistance	R <sub>eJC</sub>			-	0.5	0.6	°c/w

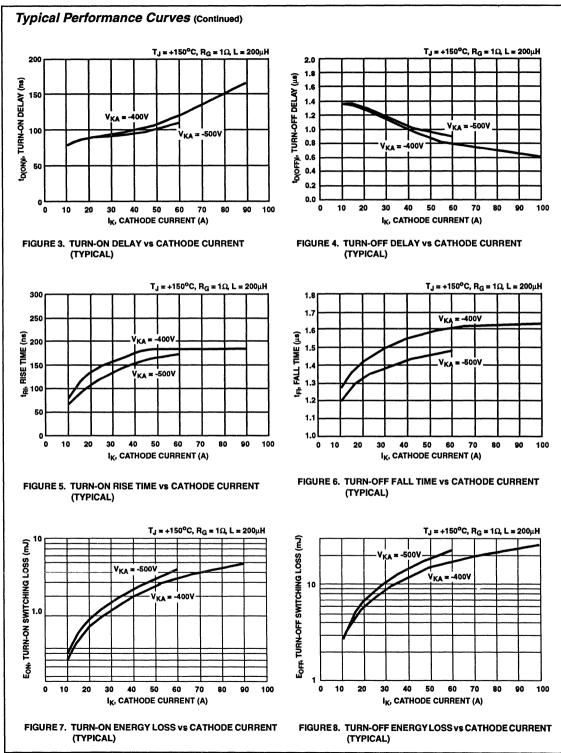
## **Typical Performance Curves**

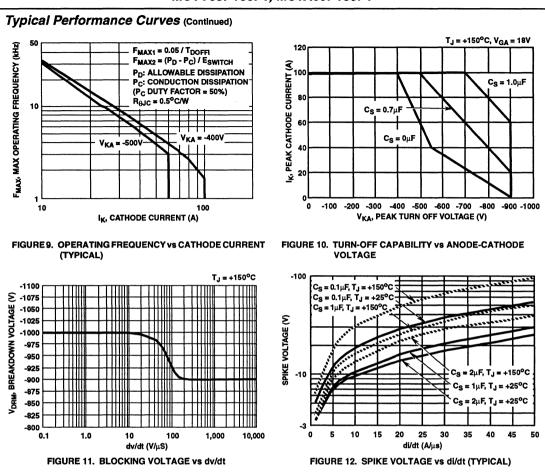












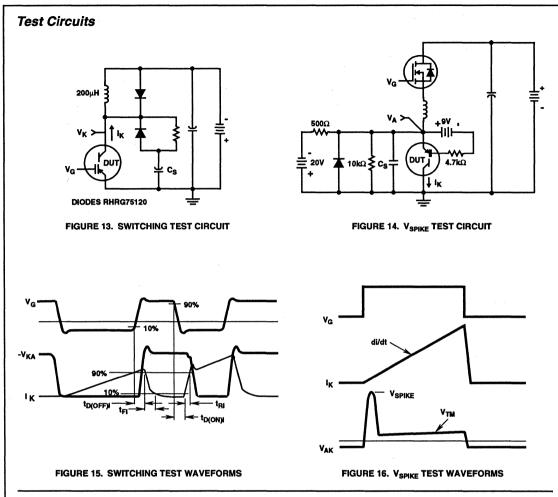
## **Operating Frequency Information**

Operating frequency information for a typical device (Figure 9) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs cathode current ( $I_{k}$ ) plots are possible using the information shown for a typical unit in Figures 3 to 8. The operating frequency plot (Figure 9) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05 / (t_{D(ON)I} + t_{D(OFF)I})$ .  $t_{D(ON)I} + t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the on-state time for a 50% duty factor. Other definitions are possible.  $t_{D(ON)I}$  is defined as the 10% point of the leading edge of the input pulse and the point where the cathode current rises to 10% of its maximum value.  $t_{D(OFF)I}$  is defined as the 90% point of the trailing edge of the input pulse and the point where the cathode current the cathode current falls to 90% of its maximum value.

Device delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly baded condition.  $f_{MAX2}$  is defined by  $f_{MAX2} = (P_D - P_C) / (E_{ON} + E_{OFF})$ . The allowable dissipation  $(P_D)$  is defined by  $P_D = (T_{JMAX} - T_C) / R_{eJC}$ . The sum of device switching and conduction losses must not exceed  $P_D$ . A 50% duty factor was used and the conduction losses ( $P_C$ ) are approximated by  $P_C = (V_{KA} \bullet I_K) / 2$ .  $E_{ON}$  is defined as the sum of the instantaneous power loss starting at the leading edge of the input pulse and ending at the point where  $V_{TM}$ ).  $E_{OFF}$  is defined as the sum of the instantaneous power loss starting at the point where the cathode current equals zero ( $I_K = 0$ ).

#### MCTV65P100F1, MCTA65P100F1



## Handling Precautions for MCT's

Mos Controlled Thyristors are susceptible to gate-insulation damage by the electrostatic discharge of energy through the devices. When handling these devices, care should be exercised to assure that the static charge built in the handler's body capacitance is not discharged through the device. MCT's can be handled safely if the following basic precautions are taken:

- Prior to assembly into a circuit, all leads should be kept shorted together either by the use of metal shorting springs or by the insertion into conductive material such as "ECCOSORB LD26" or equivalent.
- When devices are removed by hand from their carriers, the hand being used should be grounded by any suitable means - for example, with a metallic wristband.
- 3. Tips of soldering irons should be grounded.

- 4. Devices should never be inserted into or removed from circuits with power on.
- 5. Gate Voltage Rating Never exceed the gate-voltage rating of V<sub>GA</sub>. Exceeding the rated V<sub>GA</sub> can result in permanent damage to the oxide layer in the gate region.
- 6. Gate Termination The gates of these devices are essentially capacitors. Circuits that leave the gate open-circuited or floating should be avoided. These conditions can result in turn-on of the device due to voltage buildup on the input capacitor due to leakage currents or pickup.
- 7. Gate Protection These devices do not have an internal monolithic zener diode from gate to emitter. If gate protection is required an external zener is recommended.
- \* Trademark Emerson and Cumming, Inc.



## **MCTV75P60E1 MCTA75P60E1**

ANODE ANODE

GATE

ANODE ANODE

GATE

CATHODE GATE RETURN

CATHODE

**>GATE RETURN** 

75A. 600V

December 1993

P-Type MOS Controlled Thyristor (MCT)

JEDEC STYLE TO-247 5-LEAD TOP VIEW

JEDEC MO-093AA (5-LEAD TO-218) TOP VIEW

CATHODE (FLANGE)

ANODE

CATHODE (TAB)

CATHODE (FLANGE)

Package

Symbol

(ANODE KELVIN) GATE RETURN

GATE

CATHODE .

#### Features

- 75A, -600V
- V<sub>TM</sub> = -1.3V(Maximum) at I = 75A and +150°C
- 2000A Surge Current Capability
- 2000A/us di/dt Capability
- MOS insulated Gate Control
- 120A Gate Turn-Off Capability at +150°C

#### Description

The MCT is an MOS Controlled Thyristor designed for switching currents on and off by negative and positive pulsed control of an insulated MOS gate. It is designed for use in motor controls, inverters, line switches and other power switching applications.

The MCT is especially suited for resonant (zero voltage or zero current switching) applications. The SCR like forward drop greatly reduces conduction power loss.

MCTs allow the control of high power circuits with very small amounts of input energy. They feature the high peak current capability common to SCR type thyristors, and operate at junction temperatures up to +150°C with active switching.

The MCTV75P60 is supplied in a 5-lead variation of the JEDEC Style TO-247 plastic package, and the MCTA75P60 in the JEDEC MO-093AA plastic package which is a 5-lead variation of the TO-218.

\* Formerly TA9836

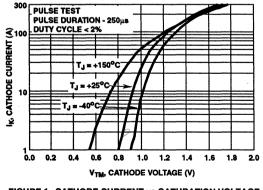
#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C) Unless Otherwise Specified

	MCTV75P60E1 MCTA75P60E1	UNITS
Peak Off-State Voltage (See Figure 11)V <sub>DRM</sub>	-600	v
Peak Reverse Voltage V <sub>RRM</sub>	+5	· <b>v</b>
Continuous Cathode Current (See Figure 2)		
T <sub>C</sub> = +25°C (Package Limited)	85	Α
$T_{\rm C} = +90^{\circ}{\rm C}$	75	Α
Non-repetitive Peak Cathode Current (Note 1)	2000	Α
Peak Controllable Current (See Figure 10)	120	Α
Gate-Anode Voltage (Continuous)	±20	v
Gate-Anode Voltage (Peak)	±25	v
Rate of Change of Voltage	See Figure 11	
Rate of Change of Current di/dt	2000	A/μs
Maximum Power Dissipation	208	w
Linear Derating Factor	1.67	W/ºC
Operating and Storage Temperature	-55 to +150	°C
Maximum Lead Temperature for Soldering	260	°C
NOTE:		
1. Maximum Pulse Width of 250 $\mu$ s (Half Sine) Assume T <sub>1</sub> (Initial) = +90°C and T <sub>1</sub> (Final) = T <sub>1</sub> (M	ax) = +150°C	

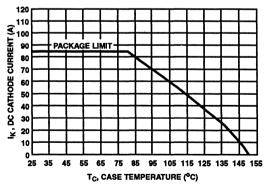
of 250 $\mu$ s (Half Sine) Assume T<sub>J</sub> (Initial) = +90°C and T<sub>J</sub> (Final) = T<sub>J</sub> (Max) = +150

PARAMETER				LIMITS			
	SYMBOL	TEST CONDITIONS		MIN	ТҮР	МАХ	UNITS
Peak Off-State	IDRM	V <sub>KA</sub> = -600V,	T <sub>C</sub> = +150°C	-	-	3	mA
Blocking Current		V <sub>GA</sub> = +18V	T <sub>C</sub> = +25°C		-	100	μА
Peak Reverse Blocking Current	I <sub>RRM</sub>	V <sub>KA</sub> = +5V	T <sub>C</sub> = +150°C		-	4	mA
		V <sub>GA</sub> = +18V	T <sub>C</sub> = +25°C		-	100	μА
On-State Voltage	V <sub>TM</sub>	I <sub>K</sub> = I <sub>K90</sub> ,	T <sub>C</sub> = +150°C	-	-	1.3	v
		V <sub>GA</sub> = -10V	T <sub>C</sub> = +25°C	-	-	1.4	v
Gate-Anode Leakage Current	I <sub>GAS</sub>	V <sub>GA</sub> = ±20V		-	-	200	nA
input capacitance	C <sub>ISS</sub>	V <sub>KA</sub> = -20V, T <sub>J</sub> = +25°C V <sub>GA</sub> = +18V			10		nF
Current Turn-on Delay Time	t <sub>D(ON)</sub> i			-	300	-	ns
Current Rise Time	t <sub>RI</sub>			•	200	-	ns
Current Turn-off Delay Time	<sup>t</sup> D(OFF)I			-	700	-	ns
Current Fall Time	t <sub>Fi</sub>				1.15	1.4	μs
Turn-off Energy	E <sub>OFF</sub>			-	10	-	mJ
Thermal Resistance	R <sub>eJC</sub>			<u> </u>	.5	.6	°C/M

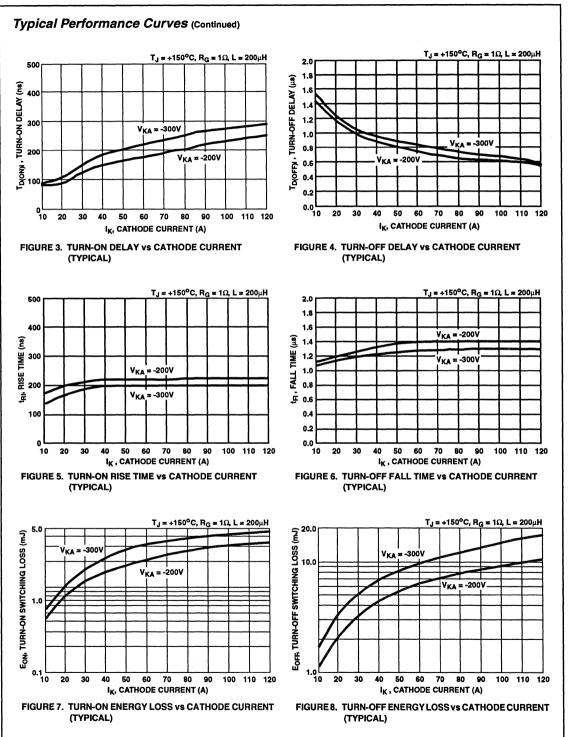
## Typical Performance Curves



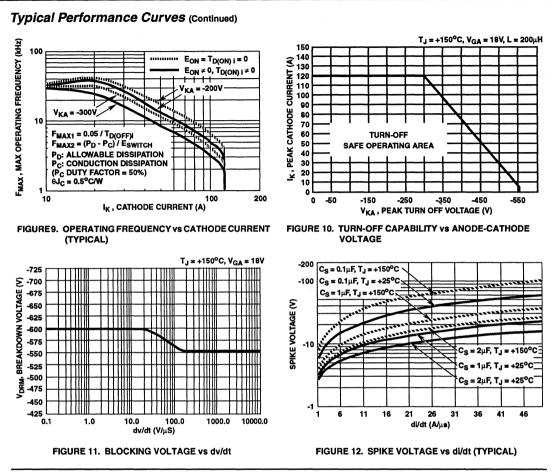








MCTs



## **Operating Frequency Information**

Operating frequency information for a typical device (Figure 9) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs cathode current ( $I_{AK}$ ) plots are possible using the information shown for a typical unit in Figures 3 to 8. The operating frequency plot (Figure 9) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

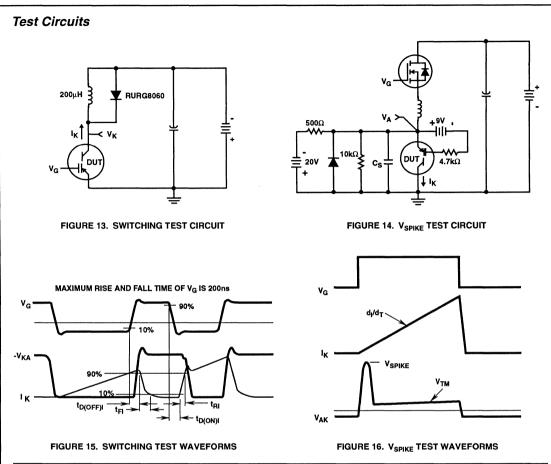
 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05$  /  $(t_{D(ON)I} + t_{D(OFF)I})$ .  $t_{D(ON)I} + t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the on-state time for a 50% duty factor. Other definitions are possible.  $t_{D(ON)I}$  is defined as the 10% point of the leading edge of the input pulse and the point where the cathode current rises to 10% of its maximum value.  $t_{D(OFF)I}$  is defined as the 90% point of the trailing edge of the input pulse and the point pulse and the point where the cathode current falls to 90% of its maximum value. Device delay can establish an additional frequency limiting condition for

an application other than  $T_{JMAX}.\ t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C) / (E_{ON} + E_{OFF})$ . The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C) / R_{\Theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$ . A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{AK} \bullet I_{AK}) / (duty factor/100)$ .  $E_{ON}$  is defined as the sum of the instantaneous power loss starting at the leading edge of the input pulse and ending at the point where the anodecathode voltage equals saturation voltage  $(V_{AK} = V_{TM})$ .  $E_{OFF}$  is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the cathode current equals zero  $(I_K = 0)$ .

The switching power loss (Figure 10) is defined as  $f_{MAX2} \cdot (E_{ON} + E_{OFF})$ . Because Turn-on switching losses can be greatly influenced by external circuit conditions and components,  $f_{MAX}$  curves are plotted both including and neglecting turn-on losses.

#### *MCTV75P60E1, MCTA75P60E1*



## Handling Precautions for MCT's

Mos Controlled Thyristors are susceptible to gate-insulation damage by the electrostatic discharge of energy through the devices. When handling these devices, care should be exercised to assure that the static charge built in the handler's body capacitance is not discharged through the device. MCT's can be handled safely if the following basic precautions are taken:

- Prior to assembly into a circuit, all leads should be kept shorted together either by the use of metal shorting springs or by the insertion into conductive material such as "ECCOSORB LD26" or equivalent.
- When devices are removed by hand from their carriers, the hand being used should be grounded by any suitable means - for example, with a metallic wristband.
- 3. Tips of soldering irons should be grounded.

4. Devices should never be inserted into or removed from circuits with power on. 2

MCTs

- 5. Gate Voltage Rating Never exceed the gate-voltage rating of V<sub>GA</sub>. Exceeding the rated V<sub>GA</sub> can result in permanent damage to the oxide layer in the gate region.
- 6. Gate Termination The gates of these devices are essentially capacitors. Circuits that leave the gate open-circuited or floating should be avoided. These conditions can result in turn-on of the device due to voltage buildup on the input capacitor due to leakage currents or pickup.
- 7. Gate Protection These devices do not have an internal monolithic zener diode from gate to emitter. If gate protection is required an external zener is recommended.
- \* Trademark Emerson and Cumming, Inc.

# MCT/IGBT/DIODES

# **INSULATED GATE BIPOLAR TRANSISTORS (IGBTs)**

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**IGBTs** 

3

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	MAXIMUN	I RATINGS	-							
			_						<b>o</b>	
BV <sub>CES</sub> (V)	I <sub>C90</sub> (A)	I <sub>СМ</sub> (А)	t <sub>F</sub> (μs)	TO-204AA	TO-220AB	TO-247	TO-218AC	TO-251AA	TO-252AA	MO-093AA
4002	5	10	1.0	2N6975						
			0.5	2N6977						
	6	7.5	1.0					HGTD6N40E1	HGTD6N40E1S	
	10	12	1.2					HGTD10N40F1	HGTD10N40F1S	
	10	17.5	1.0		HGTP10N40E1					
			0.5		HGTP10N40C1					
	12	17.5	1.0	HGTM12N40E1			HGTH12N40E1			
			0.5	HGTM12N40C1			HGTH12N40C1			
	15	35	1.0		HGTP15N40E1					
			0.5		HGTP15N40C1					
	20	35	1.0	HGTM20N40E1			HGTH20N40E1			
			0.5	HGTM20N40C1			HGTH20N40C1			
500	5	10	1.0	2N6976						
			0.5	2N6978						
	6	7.5	1.0					HGTD6N50E1	HGTD6N50E1S	
	10	12	1.2					HGTD10N50F1	HGTD10N50F1S	
	10	17.5	1.0		HGTP10N50E1					
			0.5		HGTP10N50C1					
	12	17.5	1.0	HGTM12N50E1			HGTH12N50E1			
			0.5	HGTM12N50C1			HGTH12N50C1			
	15	35	1.0		HGTP15N50E1					
			0.5		HGTP15N50C1					
	20	35	1.0	HGTM20N50E1			HGTH20N50E1			
			0.5	HGTM20N50C1			HGTH20N50C1			

# **Selection Guide**

ω

	MAXIMUN	RATINGS	; ,							
					O'H			0		
BV <sub>CES</sub> (V)	I <sub>C90</sub> (A)	I <sub>СМ</sub> (А)	t <sub>F</sub> (μs)	TO-204AA	TO-220AB	TO-247	TO-218AC	TO-251AA	TO-252AA	МО-093АА
600	12	48	0.6	HGTM12N60D1	HGTP12N60D1					· ·
	24	96	0.6	HGTM24N60D1		HGTG24N60D1				
	32	200	0.8			HGTG32N60E2				HGTA32N60E2
1000	20	100	0.68			HGTG20N100D2				
	34	200	0.87			HGTG34N100E2				
1200	20	100	1.00			HGTG20N120E2				
	30	200	0.75			HGTG30N120D2				

SHADING indicates DEVELOPMENTAL PRODUCTS NOTES:

1.  $I_{C90}$  = maximum continuous current rating at  $T_C$  = +90°C.

2.  $I_{CM}$  = maximum pulsed current rating.

3.  $t_F$  measured at  $T_C = +150^{\circ}C$ .

Selection Guide (continued)

## Selection Guide -

#### HARRIS IGBT'S WITH AN INTEGRAL REVERSE DIODE

	MAXIMUM	I RATINGS		Contraction of the second		
BV <sub>CES</sub> (V)	l <sub>C90</sub> (A)	I <sub>CM</sub> (A)	t <sub>∓</sub> (μs)	TO-220AB	TO-218AC	TO-247
400	6	7.5	1.0	HGTP6N40E1D		
	10	12	1.2	HGTP10N40F1D		
	10	17.5	1.0	HGTP10N40E1D		
			0.5	HGTP10N40C1D		
	12	17.5	1.0		HGTH12N40E1D	
			0.5		HGTH12N40C1D	
	20	35	1.0		HGTH20N40E1D	
			0.5		HGTH20N40C1D	
500	6	7.5	1.0	HGTP6N50E1D		
	10	12	1.2	HGTP10N50F1D		
	10	17.5	1.0	HGTP10N50E1D		
			0.5	HGTP10N50C1D		
	12	17.5	1.0		HGTH12N50E1D	
			0.5		HGTH12N50C1D	
	20	35	1.0	· · · · · · · · · · · · · · · · · · ·	HGTH20N50E1D	
			0.5		HGTH20N50C1D	HGTG20N50C1D
600	12	48	0.6			HGTG12N60D1D
	24	96	0.6			HGTG24N60D1D

#### HARRIS IGBT'S WITH INTEGRAL CURRENT SENSING

	MAXIMUM	RATINGS		
BV <sub>CES</sub> (V)	I <sub>С90</sub> (А)	I <sub>CM</sub> (A)	t <sub>F</sub> (μs)	TS-001AA (5 LEAD TO-220 )
600	12	40	1.0	HGTB12N60D1C

NOTES:

1.  $I_{C90}$  = maximum continuous current rating at  $T_C$  = +90°C.

2.  $I_{CM}$  = maximum pulsed current rating.

3.  $t_F$  measured at  $T_C = +150^{\circ}C$ .

3



# HGTD6N40E1, HGTD6N40E1S HGTD6N50E1, HGTD6N50E1S

6A, 400V and 500V N-Channel IGBTs

#### December 1993

#### Features

- · 6 Amp, 400 and 500 Volt
- V<sub>CE(ON)</sub> 2.5V Max.
- T<sub>FALL</sub> 1.0μs
- · Low On-State Voltage
- · Fast Switching Speeds
- High Input Impedance

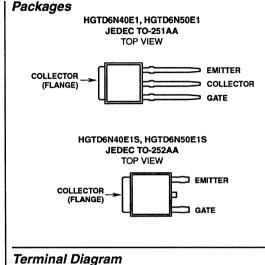
#### Applications

- Power Supplies
- Motor Drives
- Protective Circuits

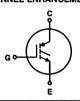
#### Description

The HGTD6N40E1, HGTD6N40E1S, HGTD6N50E1, and HGTD6N50E1S are n-channel enhancement-mode insulated gate bipolar transistors (IGBTs) designed for high voltage, low on-dissipation applications such as switching regulators and motor drivers. These types can be operated directly from low power integrated circuits.

The HGTD6N40E1 and the HGTD6N50E1 are supplied in the JEDEC TO-251AA plastic package. The HGTD6N40E1S and the HGTD6N50E1S are supplied in the JEDEC TO-252AA surface-mount plastic package.



## N-CHANNEL ENHANCEMENT MODE



Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

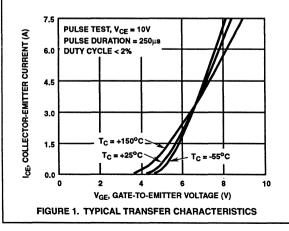
	HGTD6N40E1 HGTD6N40E1S	HGTD6N50E1 HGTD6N50E1S	UNITS
Collector-Emitter VoltageV <sub>CES</sub>	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $V_{CGR}$	400	500	v
Gate-Emitter VoltageV <sub>GE</sub>	±20	±20	v
Collector Current Continuous at T <sub>C</sub> = +25°CI <sub>C25</sub>	7.5	7.5	Α
at $T_{C} = +90^{\circ}C$	6.0	6.0	Α
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	60	60	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.48	0.48	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	-55 to +150	°C

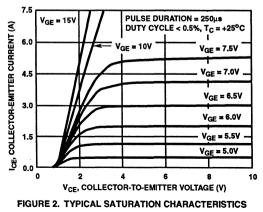
#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

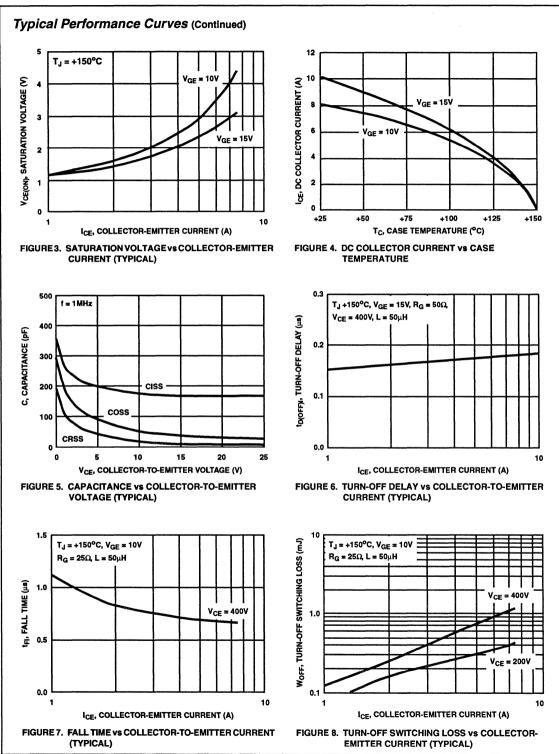
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641	
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762	
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690	
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606	
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951	
4,969,027								

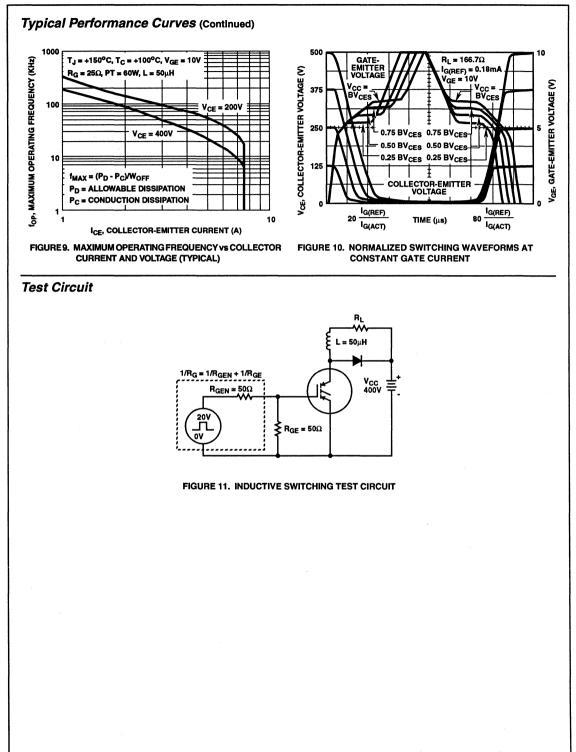
3

				LIM	IITS		
				6N40E1 N40E1S	HGTD6N50E1 HGTD6N50E1S		
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN MAX MIN		MIN	MAX	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> = 0V	400	-	500	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v
Zero Gate Voltage Collector	ICES	T <sub>J</sub> = +150°C, V <sub>CE</sub> = 400V	-	250	-	-	μΑ
Current		T <sub>J</sub> = +150°C, V <sub>CE</sub> = 500V	-	-	-	250	μΑ
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0V$	-	100	•	100	nA
Collector-Emitter On-Voltage	V <sub>CE(ON)</sub>	T <sub>J</sub> = +150°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 10V	-	2.9	-	2.9	v
		T <sub>J</sub> = +150°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 15V	-	2.5	-	2.5	V
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 15V	-	2.4	-	2.4	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 3A, V <sub>CE</sub> = 10V	6.5 (typ)				v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 3A, V <sub>CE</sub> = 10V	6.9 (typ)				nC
Turn-On Delay Time	t <sub>D(ON)</sub>	Resistive Load, I <sub>C</sub> = 3A,	90 (typ)				ns
Rise Time	t <sub>R</sub>	V <sub>CE</sub> = 400V, R <sub>L</sub> = 133Ω, T <sub>J</sub> = +150°C, V <sub>GE</sub> = 10V,		ns			
Turn-Off Delay Time	t <sub>D(OFF)</sub>	$R_{G} = 25\Omega$		24	(typ)		ns
Fall Time	t <sub>F</sub>			1100	) (typ)		ns
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>		0.29 (typ)				mJ
Turn-Off Delay Time	t <sub>D(OFF)</sub>	Inductive Load (See Figure 11),	-	190	-	190	ns
Fall Time	t <sub>FI</sub>	$I_{C} = 3A, V_{CE(CLP)} = 400V, R_{L} = 133\Omega,$ L = 50µH, T <sub>J</sub> = +150°C, V <sub>GE</sub> = 10V,	-	1	-	1	μs
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$R_{G} = 25\Omega$	-	0.43	•	0.43	mJ
Thermal Resistance Junction-to- Case (IGBT)	R <sub>ejc</sub>		-	2.08	-	2.08	°C/W











# HGTD10N40F1, HGTD10N40F1S HGTD10N50F1, HGTD10N50F1S

#### December 1993

#### Features

- 10 Amp, 400 and 500 Volt
- V<sub>CE(ON)</sub> 2.5V Max.
- T<sub>FALL</sub> 1.4µs
- · Low On-State Voltage
- Fast Switching Speeds
- High Input Impedance

#### Applications

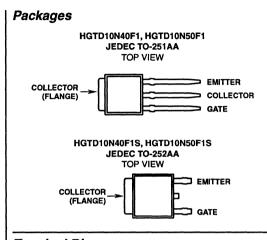
- Power Supplies
- Motor Drives
- Protective Circuits

#### Description

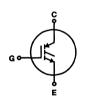
The HGTD10N40F1, HGTD10N40F1S, HGTD10N50F1, and HGTD10N50F1S are n-channel enhancement-mode insulated gate bipolar transistors (IGBTs) designed for high voltage, low on-dissipation applications such as switching regulators and motor drivers. These types can be operated directly from low power integrated circuits.

The HGTD10N40F1 and the HGTD10N50F1 are supplied in the JEDEC TO-251AA plastic package. The HGTD10N40F1S and the HGTD10N50F1S are supplied in the JEDEC TO-252AA surface-mount plastic package.

#### 10A, 400V and 500V N-Channel IGBTs



#### **Terminal Diagram**



N-CHANNEL ENHANCEMENT MODE

Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	HGTD10N40F1 HGTD10N40F1S	HGTD10N50F1 HGTD10N50F1S	UNITS
Collector-Emitter VoltageV <sub>CES</sub>	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $V_{CGR}$	400	500	V
Gate-Emitter VoltageV <sub>GE</sub>	±20	±20	v
Collector Current Continuous at T <sub>C</sub> = +25°CI <sub>C25</sub>	12	12	Α
at $T_{C} = +90^{\circ}C$	10	10	Α
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	75	75	W
Power Dissipation Derating T <sub>C</sub> > +25°C	0.6	0.6	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	-55 to +150	°C

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

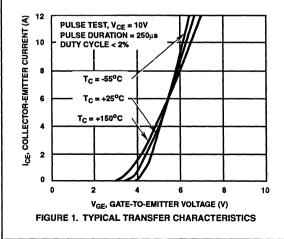
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

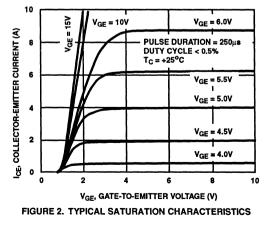
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

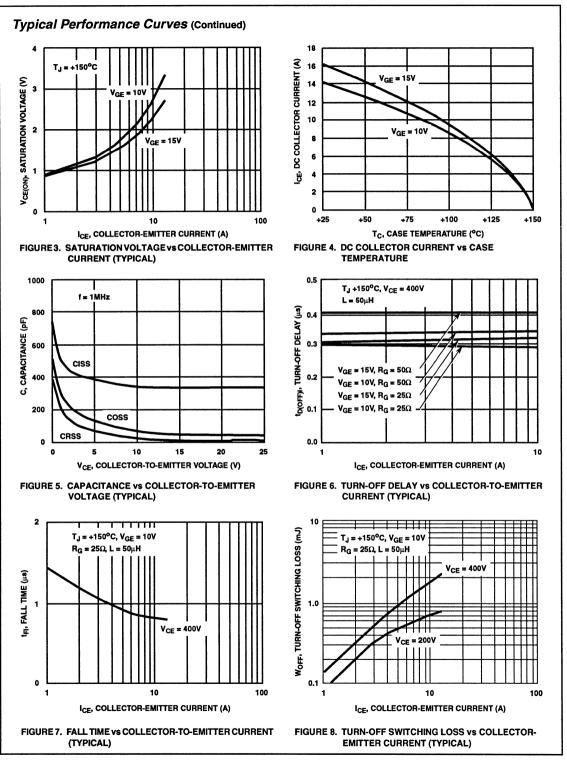
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GBTs

			LIMITS						
				0N40F1 0N40F1S		0N50F1 0N50F1S			
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN MAX		MIN MAX		UNITS		
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	l <sub>C</sub> = 250μA, V <sub>GE</sub> = 0V	400	-	500	-	v		
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v		
Zero Gate Voltage Collector	ICES	T <sub>J</sub> = +150°C, V <sub>CE</sub> = 400V	-	250	-	•	μΑ		
Current		T <sub>J</sub> = +150°C, V <sub>CE</sub> = 500V	-	-	-	250	μΑ		
Gate-Emitter Leakage Current	IGES	V <sub>GE</sub> = ±20V, V <sub>CE</sub> = 0V	-	100	-	100	nA		
Collector-Emitter On-Voltage	V <sub>CE(ON)</sub>	T <sub>J</sub> = +150°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 10V	-	2.5	•	2.5	v		
		T <sub>J</sub> = +150°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 15V	-	2.2	•	2.2	v		
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 10V	•	2.5	-	2.5	v		
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 15V	•	2.2	•	2.2	v		
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	5.3 (typ)				v		
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V			13.4 (typ)			
Turn-On Delay Time	t <sub>D(ON)</sub>	Resistive Load, I <sub>C</sub> = 5A,		45	(typ)		ns		
Rise Time	t <sub>RI</sub>	$V_{CE} = 400V, R_L = 80\Omega,$ $T_J = +150^{\circ}C, V_{GE} = 10V,$		35	(typ)		ns		
Turn-Off Delay Time	t <sub>D(OFF)</sub>	$R_{\rm G} = 25\Omega$		130	(typ)		ns		
Fall Time	t <sub>Fi</sub>			1400	(typ)		ns		
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>		0.64 (typ)				mJ		
Turn-Off Delay Time	t <sub>D(OFF)</sub>	Inductive Load (See Figure 11),	•	375	-	375	ns		
Fall Time	t <sub>FI</sub>	$I_{C} = 5A, V_{CE(CLP)} = 400V, R_{L} = 80\Omega,$ L = 50µH, T <sub>J</sub> = +150°C, V <sub>GE</sub> = 10V,	•	1200	-	1200	ns		
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$R_{\rm G} = 25\Omega$	-	1.2	-	1.2	mJ		
Thermal ResistanceJunction-to- Case (IGBT)	R <sub>eJC</sub>		•	1.67	-	1.67	°C/W		

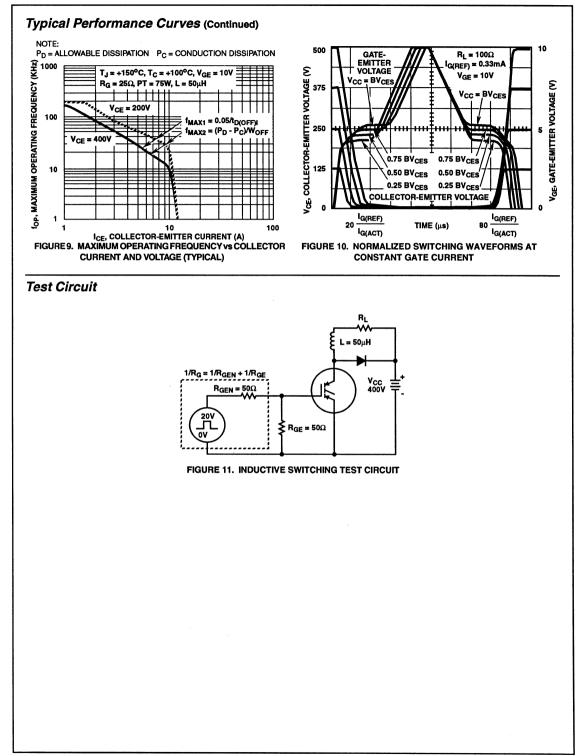






3

GBTs





## HGTH12N40C1, 40E1, 50C1, 50E1 HGTM12N40C1, 40E1, 50C1, 50E1 HGTP10N40C1, 40E1, 50C1, 50E1

10A. 12A. 400V and 500V N-Channel IGBTs

C

**HGTH-TYPES JEDEC TO-218AC** 

TOP VIEW

HGTP-TYPES JEDEC TO-220AB TOP VIEW

o

**HGTM-TYPES JEDEC TO-204AA** 

TOP VIEW

> EMITTER

> GATE

EMITTER
COLLECTOR

GATE

COLLECTOR (FLANGE)

> COLLECTOR

Packages

COLLECTOR (FLANGE)

COLLECTOR (FLANGE)

EMITTER

#### December 1993

#### Features

- 10A and 12A, 400V and 500V
- V<sub>CE(ON)</sub> 2.5V
- T<sub>FI</sub> 1μs, 0.5μs
- · Low On-State Voltage
- Fast Switching Speeds
- High Input Impedance
- No Anti-Parallel Diode

#### Applications

- Power Supplies
- Motor Drives
- Protection Circuits

#### Description

The HGTH12N40C1, HGTH12N40E1, HGTH12N50C1, HGTH12N50E1, HGTM12N40C1, HGTM12N40E1, HGTM12N50C1, HGTM12N50E1, HGTP10N40C1, HGTP10N40E1, HGTP10N50C1 and HGTP10N50E1 are n-channel enhancement-mode insulated gate bipolar transistors (IGBTs) designed for high-voltage, low on-dissipation applications such as switching regulators and motor drivers. These types can be operated directly from low-power integrated circuits.

The HGTH-types are supplied in the JEDEC TO-218AC plastic package and the HGTP-types in the JEDEC TO-220AB plastic package. The HGTM-types are supplied in the JEDEC TO-204AA steel package.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	HGTH12N40C1 HGTM12N40C1 HGTH12N40E1 HGTM12N40E1	HGTH12N50C1 HGTM12N50C1 HGTH12N50E1 HGTM12N50E1	HGTP10N40C1 HGTP10N40E1	HGTP10N50C1 HGTP10N50E1	UNITS
Collector-Emitter VoltageV <sub>CES</sub>	400	500	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $V_{CGR}$	400	500	400	500	v
Reverse Collector-Emitter Voltage V <sub>ECS</sub> (rev.)	15	15 -5	-5	-5	v
Gate-Emitter VoltageVGE	±20	±20	±20	±20	v
Collector Current Continuous Ic	12	12	10	10	A
Collector Current Pulsed I <sub>CM</sub>	17.5	17.5	17.5	17.5	Α
Power Dissipation at $T_c = +25^{\circ}C$ $P_D$	75	75	60	60	w
Power Dissipation Derating Above $T_C > +25^{\circ}C.$	0.6	0.6	0.48	0.48	W/⁰C
Operating and Storage Junction Temperature Range TJ, TSTG	-55 to +150	-55 to +150	-55 to +150	-55 to +150	°C

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951

3-15

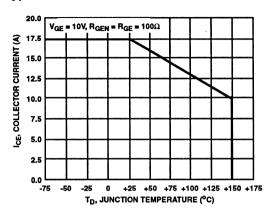
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright @ Harris Corporation 1993

Terminal Diagram

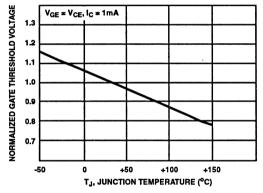
GATE



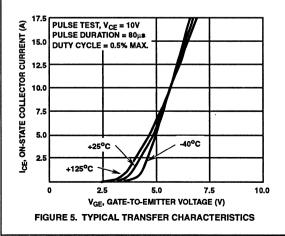
				LIMITS				
			HGTH12N HGTM12N HGTP10N	40C1, E1	HGTH12N50C1, E1, HGTM12N50C1, E1, HGTP10N50C1, E1			
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN MAX		MIN MAX		UNITS	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1mA, V <sub>GE</sub> = 0	400	-	500	-	v	
Gate Threshold Voltage	V <sub>GE(TH)</sub>	$V_{GE} = V_{CE}$ , $I_C = 1$ mA	2.0	4.5 3 (typ)	2.0	4.5 3 (typ)	v	
Zero Gate Voltage Collector	I <sub>CES</sub>	V <sub>CE</sub> = 400V, T <sub>C</sub> = +25°C	-	250	-	-	μA	
Current		$V_{CE} = 500V, T_{C} = +25^{\circ}C$	-	-	-	250	μΑ	
		V <sub>CE</sub> = 400V, T <sub>C</sub> = +125°C	-	1000	-	-	μA	
×		V <sub>CE</sub> = 500V, T <sub>C</sub> = +125°C	-	-	-	1000	μA	
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0$	-	100	-	100	nA	
Collector-Emitter on Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 10A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v	
		I <sub>C</sub> = 17.5A, V <sub>GE</sub> = 20V	-	3.2	-	3.2	v	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	6 (typ)	-	6 (typ)	v	
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	19 (typ)	-	19 (typ)	nC	
Turn-On Delay Time	t <sub>D(ON)</sub> i	$I_{C} = 10A, V_{CE(CLP)} = 300V,$	-	50	-	50	ns	
Rise Time	t <sub>RI</sub>	$L = 50\mu H$ , $T_J = +100^{\circ}C$ , $V_{GE} = 10V$ , $R_G = 50\Omega$	-	50	-	50	ns	
Turn-Off Delay Time	t <sub>D(OFF)</sub>		-	400	-	400	ns	
Fall Time	t <sub>F1</sub>	a de la companya de l						
40E1, 50E1			680 (typ)	1000	680 (typ)	1000	ns	
40C1, 50C1	1		400	500	400	500	ns	
Turn-Off Energy Loss per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$    I_{C} = 10A, V_{CE(CLP)} = 300V, \\     L = 50\mu H, T_{J} = +100^{\circ}C, \\     V_{GE} = 10V, R_{G} = 50\Omega $						
40E1, 50E1				680	(typ)		μ	
40C1, 50C1	1			400	(typ)		μJ	
Thermal Resistance	R <sub>NC</sub>	НСТН, НСТМ	-	1.67	-	1.67	°C/W	
Junction-to-Case		HGTP		2.083	-	2.083	°C/W	











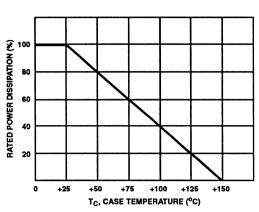


FIGURE 2. POWER DISSIPATION vs TEMPERATURE DERATING CURVE

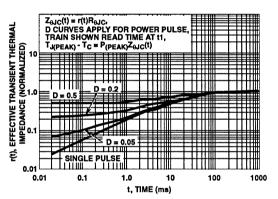
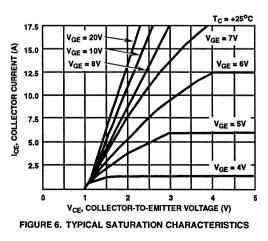
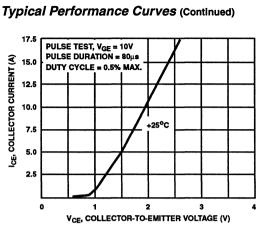
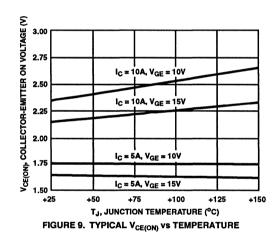


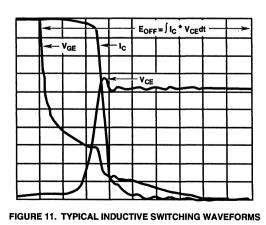
FIGURE 4. NORMALIZED THERMAL RESPONSE CHARAC-TERISTICS

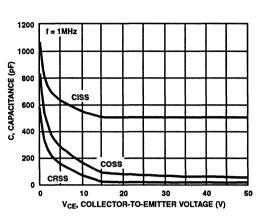


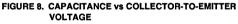


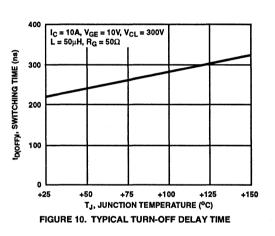


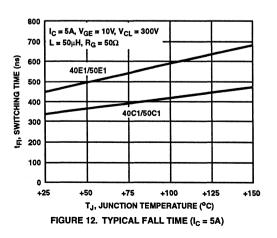


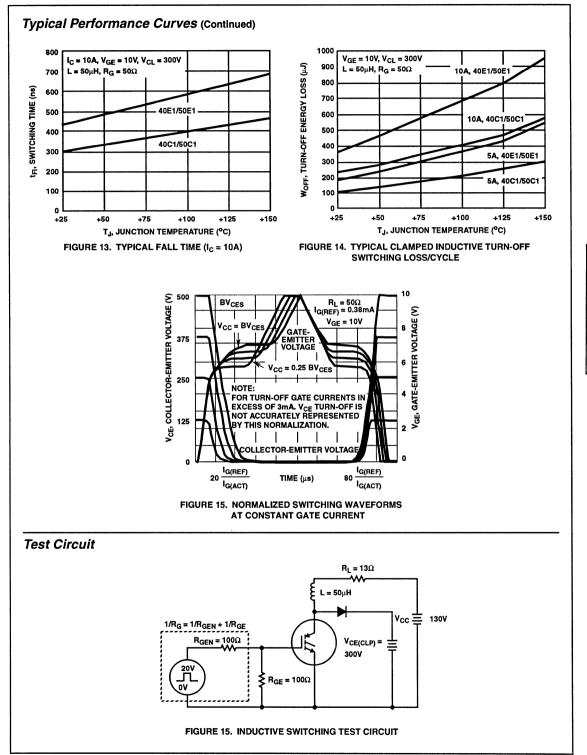












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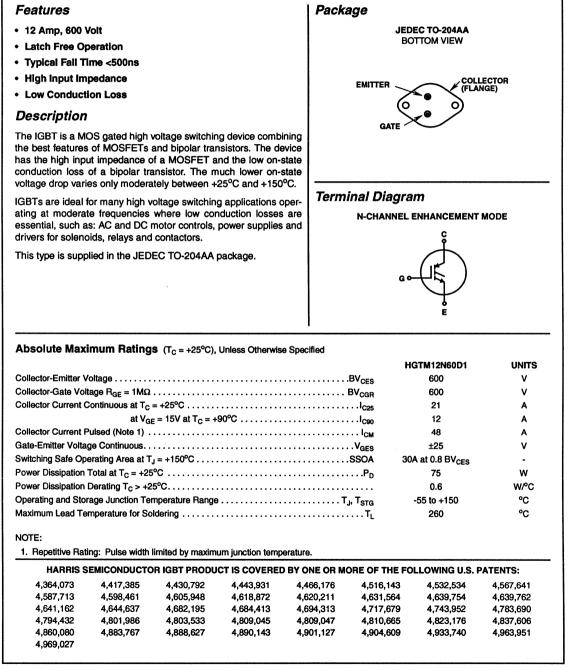
IGBTs



# HGTM12N60D1

December 1993

#### 12A, 600V N-Channel IGBT



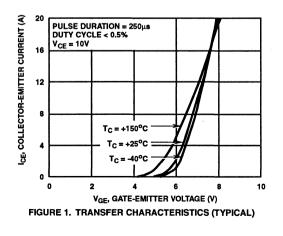
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

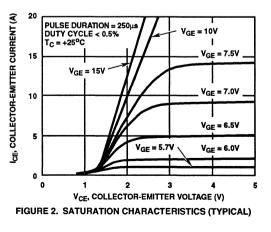
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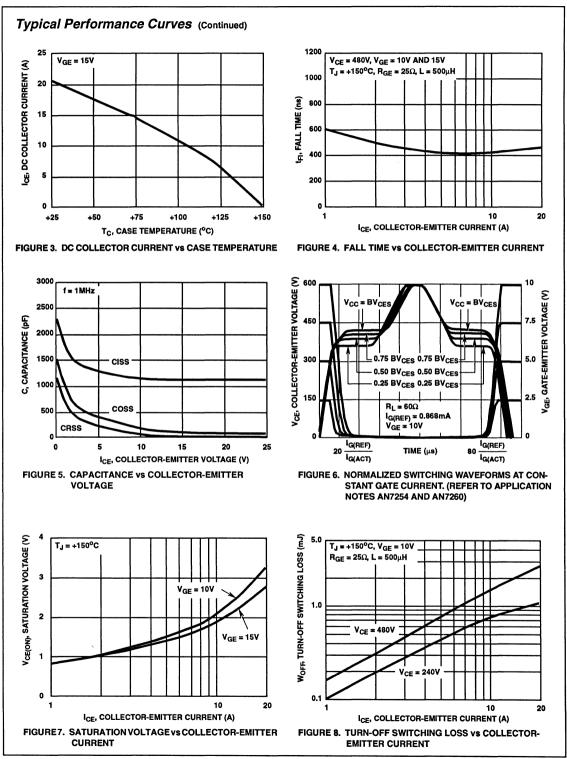
				LIMITS			
PARAMETERS	SYMBOL	TEST COND	ITIONS	MIN TYP MAX		МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> = 0V		600	-	-	v
Collector-Emitter Leakage Voltage	I <sub>CES</sub>	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	1.0	μΑ
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 15V	T <sub>C</sub> = +25°C	-	1.9	2.5	v
			T <sub>C</sub> = +125°C	-	2.1	2.7	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 250μA, V <sub>CE</sub> = V <sub>GE</sub>	3.0	4.5	6.0	v	
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V	-	-	±500	nA	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 BV	/ <sub>CES</sub>	-	7.2	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	V <sub>GE</sub> = 15V	-	45	60	nC
		V <sub>CE</sub> = 0.5 BV <sub>CES</sub>	V <sub>GE</sub> = 20V	-	70	90	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub> I	L = 500µH, I <sub>C</sub> = I <sub>C90</sub> , F		-	100	-	ns
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 15V, T_{J} = +150^{\circ}$ $V_{CE} = 0.8 BV_{CES}$	ЪС,	-	150	-	ns
Current Turn-Off	t <sub>D(OFF)</sub> i	1		-	430	600	ns
Current Fall Time	t <sub>FI</sub>		-	430	600	ns	
Turn-Off Energy (Note 1)	W <sub>OFF</sub>			-	1.8	-	mJ
Thermal Resistance	R <sub>NC</sub>				-	1.67	°C/W

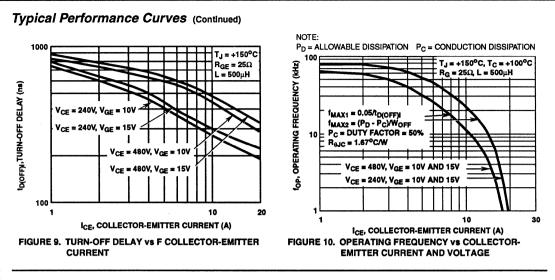
NOTE:

 Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A). The HGTM12N60D1 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss.









#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device turn-off delay can establish an additional

frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{eJC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) so that the conduction losses  $(P_C)$  can be approximated by  $P_C$  =  $(V_{CE} \times I_{CE})/2$ .  $W_{OFF}$  is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE} \cdot 0A$ ).

The switching power loss (Figure 10) is defined as  $f_{MAX1} \times W_{OFF}$  Turn on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# HGTP12N60D1

December 1993

#### Features

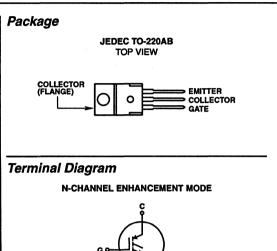
- 12 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time <500ns
- High Input Impedance
- Low Conduction Loss

#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

The IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC TO-220AB style package.



12A, 600V N-Channel IGBT

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	HGTP12N60D1	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	600	v
Collector-Gate Voltage R <sub>GE</sub> = 1MΩ BV <sub>CGR</sub>	600	v
Collector Current Continuous at T <sub>C</sub> = +25°CI <sub>C25</sub>	21	Α
at $V_{GE} = 15V$ at $T_{C} = +90^{\circ}CI_{C90}$	12	Α
Collector Current Pulsed (Note 1)I <sub>CM</sub>	48	Α
Gate-Emitter Voltage ContinuousVGES	±25	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	30A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.6	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL	260	°C

NOTE:

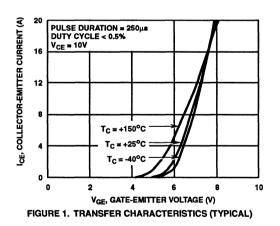
1. Repetitive Rating: Pulse width limited by maximum junction temperature.

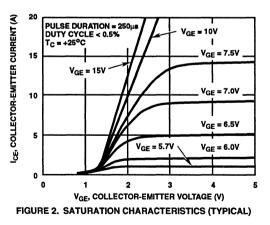
HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR MO	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

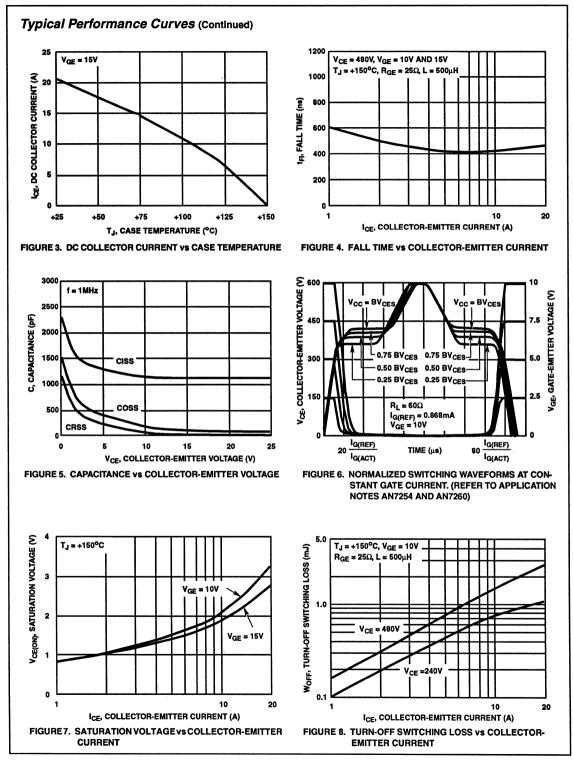
					LIMITS		
PARAMETERS	SYMBOL	TEST COND	$\frac{\text{TEST CONDITIONS}}{I_{C} = 250 \mu A, V_{GE} = 0 V}$			MAX	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	$I_{C} = 250 \mu A, V_{GE} = 0V$				-	v
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	•	1.0	μA
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 15V	T <sub>C</sub> = +25°C	•	1.9	2.5	v
			T <sub>C</sub> = +125°C	-	2.1	2.7	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	$I_{C} = 250 \mu A, V_{CE} = V_{GI}$	<sub>E</sub> , T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	IGES	V <sub>GE</sub> = ±20V	•	•	±500	nA	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 B	•	7.2	-	v	
On-State Gate Charge	Q <sub>G(ON)</sub>	$Q_{G(ON)}$ $I_C = I_{C90}$		•	45	60	nC
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	•	70	90	nC
Current Turn-On Delay Time	t <sub>d(ON)</sub> i	L = 500µH, I <sub>C</sub> = I <sub>C90</sub> , I			100	-	ns
Current Rise Time	t <sub>Ri</sub>	$V_{GE} = 15V, T_{J} = +150$ $V_{CE} = 0.8 BV_{CES}$	°C,	•	150	-	ns
Current Turn-Off	t <sub>D(OFF)</sub>			•	430	600	ns
Current Fall Time	t <sub>FI</sub>	1		•	430	600	ns
Turn-Off Energy (Note 1)	WOFF	1		-	1.8	•	mJ
Thermal Resistance IGBT	R <sub>NC</sub>			-	-	1.67	°C/W

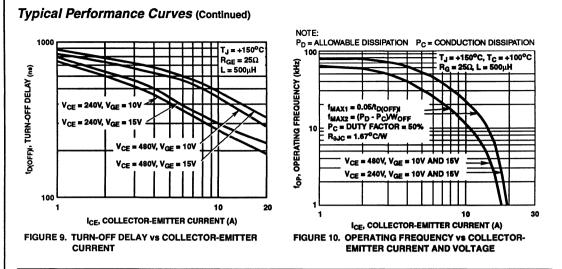
NOTE:

 Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A). The HGTP12N60D1 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss.









#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05 / t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta,JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ .  $W_{OFF}$  is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE}$  = 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \circ W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



## HGTH20N40C1, 40E1, 50C1, 50E1 HGTM20N40C1, 40E1, 50C1, 50E1 HGTP15N40C1, 40E1, 50C1, 50E1

#### December 1993

#### 15A, 20A, 400V and 500V N-Channel IGBTs



- 15A and 20A, 400V and 500V
- V<sub>CE(ON)</sub> 2.5V
- T<sub>FI</sub> 1μs, 0.5μs
- Low On-State Voltage
- Fast Switching Speeds
- High Input Impedance
- No Anti-Parallel Diode

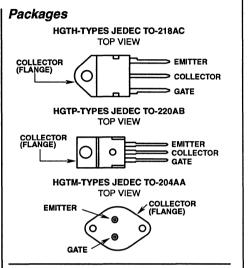
#### Applications

- Power Supplies
- Motor Drives
- Protection Circuits

#### Description

The HGTH20N40C1, HGTH20N40E1, HGTH20N50C1, HGTH20N50E1, HGTM20N40C1, HGTM20N40E1, HGTM20N50C1, HGTM20N50E1, HGTP15N40C1, HGTP15N40E1, HGTP15N50C1 and HGTP15N50E1 are n-channel enhancement-mode insulated gate bipolar transistors (IGBTs) designed for high-voltage, low on-dissipation applications such as switching regulators and motor drivers. These types can be operated directly from low-power integrated circuits.

The HGTH-types are supplied in the JEDEC TO-218AC plastic package and the HGTP-types in the JEDEC TO-220AB plastic package. The HGTM-types are supplied in the JEDEC TO-204AA steel package.



#### Terminal Diagram

N-CHANNEL ENHANCEMENT MODE



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

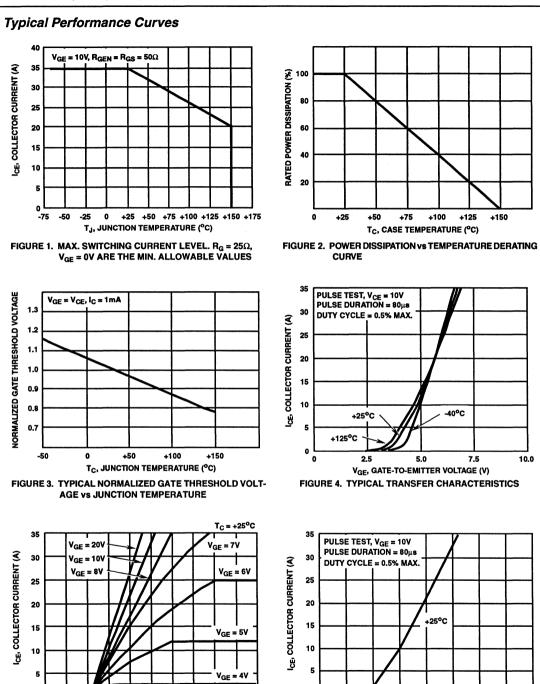
	HGTH20N40C1 HGTM20N40C1 HGTH20N40E1 HGTM20N40E1	HGTH20N50C1 HGTM20N50C1 HGTH20N50E1 HGTM20N50E1	HGTP15N40C1 HGTP15N40E1	HGTP15N50C1 HGTP15N50E1	UNITS
Collector-Emitter VoltageV <sub>CES</sub>	400	500	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $V_{CGR}$	400	500	400	500	v
Reverse Collector-Emitter Voltage V <sub>CES</sub> (rev.)	-5	-5	-5	-5	v
Gate-Emitter VoltageV <sub>GE</sub>	±20	±20	±20	±20	v
Collector Current Continuous Ic	20	20	15	15	Α
Collector Current Pulsed I <sub>CM</sub>	35	35	35	35	Α
Power Dissipation at $T_{C} = +25^{\circ}C$ $P_{D}$	100	100	75	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.8	0.8	0.6	0.6	W/ºC
Operating and Storage Junction Temperature Range T , TSTG		-55 to +150	-55 to +150	-55 to +150	°C

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
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4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1993

				LIM	ITS			
			HGTH20N HGTM20N HGTP15N	40C1, E1	HGTH20N50C1, E1, HGTM20N50C1, E1, HGTP15N50C1, E1			
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN MAX		MIN MAX		UNITS	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1mA, V <sub>GE</sub> = 0	400	-	500	-	v	
Gate Threshold Voltage	V <sub>GE(TH)</sub>	$V_{GE} = V_{CE}$ , $I_C = 1mA$	2.0	4.5	2.0	4.5	v	
Zero -Gate Voltage Collector	ICES	$V_{CE} = 400V, T_{C} = +25^{\circ}C$	-	250	-	-	μA	
Current		$V_{CE} = 500V, T_{C} = +25^{\circ}C$	-	-	-	250	μA	
		V <sub>CE</sub> = 400V, T <sub>C</sub> = +125°C	-	1000	-	-	μA	
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +125°C	-	-	-	1000	μA	
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V, V_{CE} = 0$	-	100	-	100	nA	
Reverse Collector-Emitter Leakage Current	I <sub>CE</sub>	$R_{GE} = 0\Omega, V_{EC} = 5V$	-	-5	-	-5	mA	
Collector-Emitter on Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 20A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v	
		I <sub>C</sub> = 35A, V <sub>GE</sub> = 20V	•	3.2	- 1	3.2	v	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V	-	•6 (Typ)	-	6 (Тур)	v	
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V		33 (Typ)	-	33 (Тур)	nC	
Turn-On Delay Time	t <sub>D(ON)</sub> I	I <sub>C</sub> = 20A, V <sub>CE(CLP)</sub> = 300V, L = 25μH, Τ <sub>J</sub> = +100°C,	-	50	-	50	ns	
Rise Time	t <sub>RI</sub>	$L = 25\mu$ H, $I_J = +100^{\circ}$ C, $V_{GE} = 10V$ , $R_G = 25\Omega$	-	50	-	50	ns	
Turn-Off Delay Time	t <sub>D(OFF)</sub> i		-	400	-	400	ns	
Fall Time 40E1, 50E1	t⊨i		680 (Typ)	1000	680 (Typ)	1000	ns	
40C1, 50C1			400	500	400	500	ns	
Turn-Off Energy Loss per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$\begin{split} & I_{C} = 10 \text{A},  V_{CE(CLP)} = 300 \text{V}, \\ & L = 25 \mu \text{H},  \text{T}_{\text{J}} = +100^{\circ} \text{C}, \\ & \text{V}_{\text{GE}} = 10 \text{V},  \text{R}_{\text{G}} = 25 \Omega \end{split}$		•		<b>.</b>		
40E1, 50E1				1810	(Тур)		μ	
40C1, 50C1				1070	(Тур)		μJ	
Thermal Resistance	R <sub>eJC</sub>	НСТН, НСТМ	1 -	1.25	-	1.25	°C/W	
Junction-to-Case		HGTP	-	1.67	- 1	1.67	°C/W	



V<sub>CE</sub>, COLLECTOR-TO-EMITTER VOLTAGE (V) FIGURE 5. TYPICAL SATURATION CHARACTERISTICS

3

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0

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3-30

5

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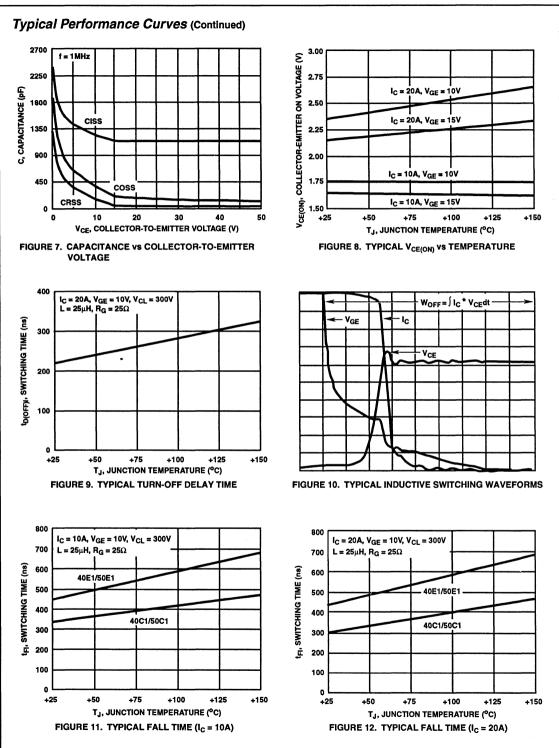
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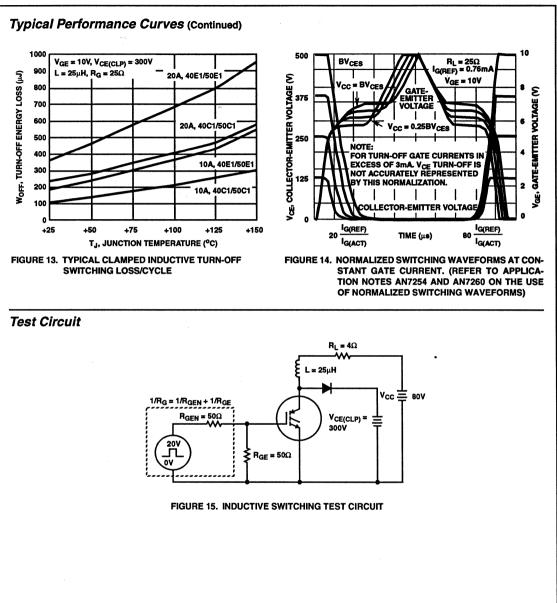
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V<sub>CE(ON)</sub>, COLLECTOR-TO-EMITTER VOLTAGE (V)

FIGURE6. TYPICAL COLLECTOR-TO-EMITTER ON-VOLTAGE vs COLLECTOR CURRENT







# HGTG20N100D2

JEDEC STYLE TO-247

TOP VIEW

N-CHANNEL ENHANCEMENT MODE

#### December 1993

### 20A, 1000V N-Channel IGBT

EMITTER

GATE

COLLECTOR



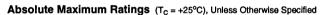
- 34 Amp, 1000 Volt
- Latch Free Operation
- Typical Fall Time 520ns
- High Input Impedance
- Low Conduction Loss

#### Description

The HGTG20N100D2 is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC style TO-247 package.



	HGTG20N100D2	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	1000	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	1000	v
Collector Current Continuous at T <sub>C</sub> = +25°Cl <sub>C25</sub>	34	Α
at $T_{C} = +90^{\circ}C$	20	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	100	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±20	v
Gate-Emitter Voltage Pulsed V <sub>GEM</sub>	±30	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	100A at 0.8 BV <sub>CES</sub>	· •
Power Dissipation Total at T <sub>c</sub> = +25°C P <sub>D</sub>	150	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.20	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.125 inch from case for 5 seconds)	260	°C
Short Circuit Withstand Time (Note 2) at V <sub>GE</sub> = 15V t <sub>SC</sub>	3	μs
at V <sub>GE</sub> = 10Vt <sub>SC</sub>	15	μs
NOTEO		

Package

COLLECTOR (BOTTOM SIDE

METAL)

Terminal Diagram

#### NOTES:

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

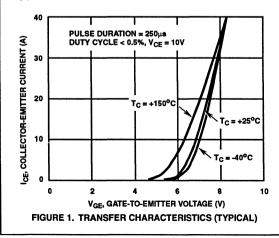
V<sub>CE(PEAK)</sub> = 600V, T<sub>C</sub> = +125°C, R<sub>GE</sub> = 25Ω.

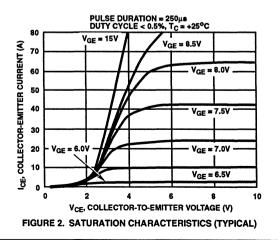
HARRIS S	EMICONDUCTO	OR IGBT PRODU	CT IS COVERED	BY ONE OR MO	ORE OF THE FO	LLOWING U.S. I	PATENTS:
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4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
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4,969,027							

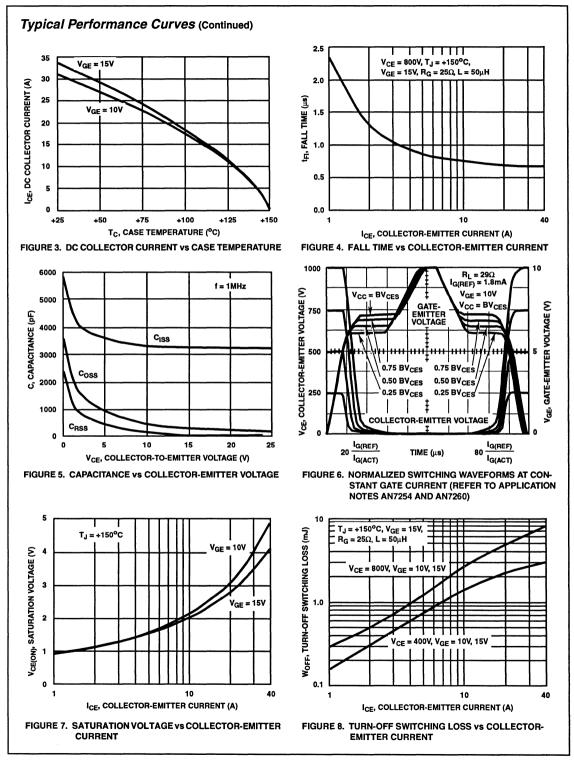
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PARAMETERS Collector-Emitter Breakdown Voltage	SYMBOL BV <sub>CES</sub>				LIMITS		
		TEST CONDITIONS		MIN	TYP	MAX	UNITS
		I <sub>C</sub> = 250mA, V <sub>GE</sub> = 0V		1000	-	-	V
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	250	μΑ
		$V_{CE} = 0.8 \text{ BV}_{CES}$	T <sub>C</sub> = +125°C	-	-	1.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 15V	T <sub>C</sub> = +25°C	-	3.1	3.8	v
			T <sub>C</sub> = +125°C	-	2.9	3.6	v
		I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 10V	T <sub>C</sub> = +25°C	-	3.3	4.1	v
			T <sub>C</sub> = +125°C	-	3.2	4.0	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	$i_{C} = 500\mu A,$ $V_{CE} = V_{GE}$	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±250	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 BV <sub>CES</sub>		-	7.1	-	V
On-State Gate Charge	Q <sub>G(ON)</sub>	$I_{C} = I_{C90},$ $V_{CE} = 0.5 \text{ BV}_{CES}$	V <sub>GE</sub> = 15V	-	120	160	nC
			V <sub>GE</sub> = 20V	-	163	212	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub>	L = $50\mu$ H, I <sub>C</sub> = I <sub>C20</sub> , R <sub>G</sub> = $25\Omega$ , V <sub>GE</sub> = $15V$ , T <sub>J</sub> = $+125^{\circ}$ C, V <sub>CE</sub> = $0.8 \text{ BV}_{CES}$		-	100	-	ns
Current Rise Time	t <sub>Ri</sub>			-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> I			•	500	650	ns
Current Fall Time	t <sub>FI</sub>			-	520	680	ns
Turn-Off Energy (Note 1)	WOFF			-	3.7	-	mJ
Current Turn-On Delay Time	t <sub>D(ON)I</sub>			-	100	-	ns
Current Rise Time	t <sub>RI</sub>			-	150	-	ns
Current Turn-Off	t <sub>D(OFF)</sub> i			-	410	530	ns
Current Fall Time	t <sub>FI</sub>	1	-	520	680	ns	
Turn-Off Energy (Note 1)	WOFF	1		-	3.7	-	mJ
Thermal Resistance	R <sub>eJC</sub>			-	0.7	0.83	°C/M

NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG20N100D2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss.

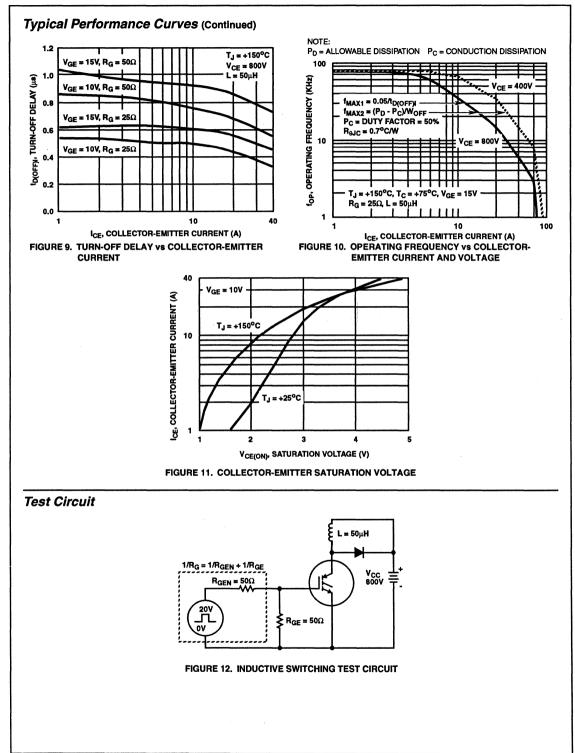






3

**IGBTs** 



Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}, t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ .  $W_{OFF}$  is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE}$  = 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \cdot W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.

GBTs

3-37



# ARRIS HGTG20N120E2

#### December 1993

# 34A, 1200V N-Channel IGBT

#### Features

- 34 Amp, 1200 Volt
- Latch Free Operation
- Typical Fall Time 780ns
- High Input Impedance
- Low Conduction Loss

#### Description

4,794,432

4,860,080

4,969,027

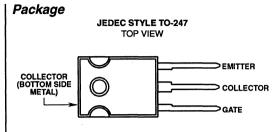
4,801,986

4,883,767

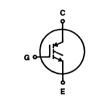
The HGTG20N120E2 is a MOS gated, high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors. The development type number for this device is TA49009.

This type is supplied in the JEDEC style TO-247 package.



## Terminal Diagram



Absolute Max	mum naung	$a(1C = +25^{\circ}C)$	, onless other	vise specilied	HGTG	20N120E2	UNITS
Collector-Emitter E	Breakdown Voltag	e		BV <sub>CE</sub>	s	1200	v
Collector-Gate Bre	akdown Voltage	R <sub>GE</sub> = 1MΩ		BV <sub>CG</sub>	R	1200	v
Collector Current (	Continuous						
						34	Α
				I <sub>Ct</sub>		20	A
Collector Current I	Pulsed (Note 1) .			I <sub>C</sub>	м	100	A
Gate-Emitter Volta	ge Continuous			V <sub>GE</sub>	S	±20	v
Gate-Emitter Volta					M .	±30	v
Switching SOA at	T <sub>C</sub> = +150°C			SSO	A 100A a	t 0.8 BV <sub>CES</sub>	-
Power Dissipation	Total at T <sub>C</sub> = +25	5°C		P	D	150	w
Power Dissipation						1.20	W/ºC
Operating and Sto	rage Junction Te	mperature		Т <sub>J</sub> , Т <sub>ST</sub>	-55 G	to +150	°C
•	se for 5 seconds)	-			Ĺ	260	°C
Short Circuit Withs						3	
				t <sub>s</sub>		15	μs
NOTES:	• • • • • • • • • • • • • • • • •		• • • • • • • • • • • • • • • •	lg	C	15	μs
1. Repetitive Rat	ting: Pulse width 20V, T <sub>C</sub> = +125°C	•	um junction temp	erature.			
HARRIS	SEMICONDUCTO	OR IGBT PRODU	ICT IS COVERED	BY ONE OR MO	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4.605.948	4,618,872	4,620,211	4,631,564	4,639,754	4 000 700
.,,	4,096,401	4,000,940	4,010,072	4,020,211	4,001,004	4,009,704	4,639,762

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1992

4,803,533

4,888,627

4,837,606

4,963,951

4,809,047

4,901,127

4,810,665

4,904,609

4,823,176

4,933,740

4,809,045

4,890,143

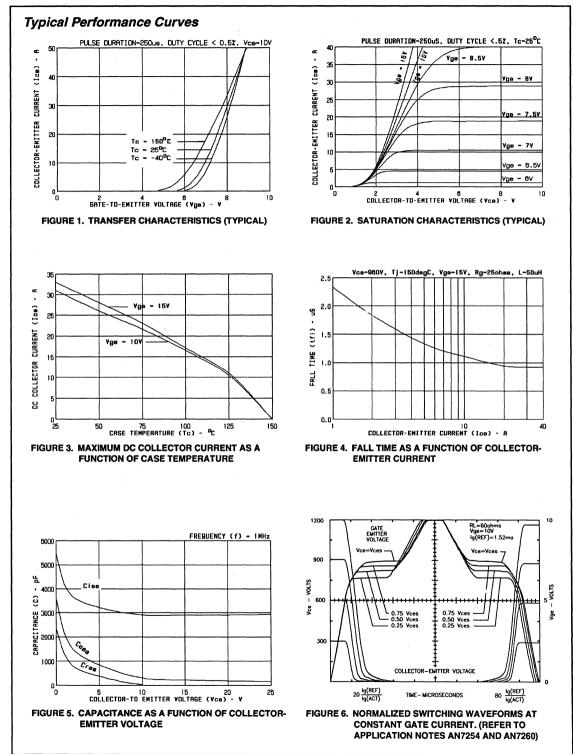
## Specifications HGTG20N120E2

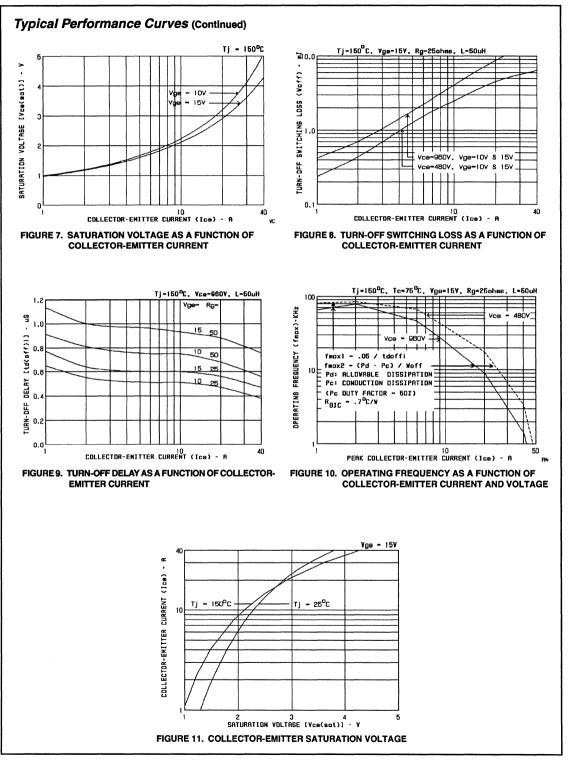
				LIMITS			
PARAMETERS	SYMBOL	TEST CO	TEST CONDITIONS		ТҮР	MAX	UNIT
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250µА, V <sub>GE</sub> = 0V		1200	-	-	v
Collector-Emitter Leakage Current	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	250	μΑ
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	1.0	mA
Collector-Emitter Saturation	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 15V	T <sub>C</sub> = +25°C	-	2.9	3.5	v
Voltage			T <sub>C</sub> = +125°C	-	3.0	3.6	v
		I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 10V	T <sub>C</sub> = +25°C	-	3.1	3.8	v
			T <sub>C</sub> = +125°C	-	3.3	4.0	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 500μA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25⁰C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V	V <sub>GE</sub> = ±20V		-	±250	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 B <sup>1</sup>	V <sub>CES</sub>	-	7.0	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	$I_{C} = I_{C90},$	V <sub>GE</sub> = 15V	-	110	150	nC
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V		150	200	nC
Current Turn-on Delay Time	t <sub>D(ON)</sub>	R <sub>L</sub> = 48Ω	$I_{C} = I_{C90}, V_{GE} = 15V,$	-	100		ns
Current Rise Time	t <sub>A</sub>		$V_{CE} = 0.8 \text{ BV}_{CES},$ $R_{G} = 25\Omega,$	-	150	-	ns
Current Turn-off Delay Time	t <sub>D(OFF)</sub> i	L = 50µH	T <sub>J</sub> = +125°C	-	520	620	ns
Current Fall Time	t <sub>FI</sub>			-	780	1000	ns
Turn-off Energy (Note 1)	WOFF			-	7.0	-	mJ
Current Turn-on Delay Time	t <sub>D(ON)</sub>	R <sub>L</sub> = 48Ω	$I_{\rm C} = I_{\rm C90}, V_{\rm GE} = 10V,$	-	100	-	ns
Current Rise Time	t <sub>R</sub>	1	$V_{CE} = 0.8 \text{ BV}_{CES},$ $R_G = 25\Omega,$	-	150	-	ns
Current Turn-off Delay Time	t <sub>D(OFF)</sub>	$T_{J} = +125^{\circ}C$		-	420	520	ns
Current Fall Time	t <sub>FI</sub>	1		•	780	1000	ns
Turn-off Energy (Note 1)	WOFF	1		-	7.0	•	mJ
Thermal Resistance	R <sub>eJC</sub>			-	0.70	0.83	°CM

NOTE:

 Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A). The HGTG20N120E2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss. IGBTs

#### HGTG20N120E2





### **Test Circuit**

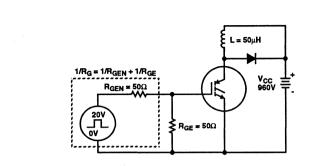


FIGURE 12. INDUCTIVE SWITCHING TEST CIRCUIT

#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

f<sub>MAX1</sub> is defined by f<sub>MAX1</sub> = 0.05/t<sub>D(OFF)</sub>. t<sub>D(OFF)</sub> deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible. t<sub>D(OFF)</sub> is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device turn-off delay can establish an additional frequency limiting condition for an application other than T<sub>JMAX</sub>. tD(OFF)I is important when controlling output ripple under a lightly loaded condition. fMAX2 is defined by fMAX2 = (Pd - Pc)/ WOFF The allowable dissipation (Pd) is defined by Pd = (T<sub>JMAX</sub> - T<sub>C</sub>)/R<sub>0JC</sub>. The sum of device switching and conduction losses must not exceed Pd. A 50% duty factor was used (Figure 10) and the conduction losses (Pc) are approximated by  $Pc = (V_{CE} \cdot I_{CE})/2$ . W<sub>OFF</sub> is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CF} = 0A$ ).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \bullet W_{OFF}$  Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.

#### Handling Precautions for IGBTs

Insulated Gate Bipolar Transistors are susceptible to gateinsulation damage by the electrostatic discharge of energy through the devices. When handling these devices, care should be exercised to assure that the static charge built in the handler's body capacitance is not discharged through the device. With proper handling and application procedures, however, IGBTs are currently being extensively used in production by numerous equipment manufacturers in military, industrial and consumer applications, with virtually no damage problems due to electrostatic discharge. IGBTs can be handled safely if the following basic precautions are taken:

- Prior to assembly into a circuit, all leads should be kept shorted together either by the use of metal shorting springs or by the insertion into conductive material such as "\*ECCOSORBD LD26" or equivalent.
- When devices are removed by hand from their carriers, the hand being used should be grounded by any suitable means - for example, with a metallic wristband.
- 3. Tips of soldering irons should be grounded.
- Devices should never be inserted into or removed from circuits with power on.
- Gate Voltage Rating Never exceed the gate-voltage rating of VGEM. Exceeding the rated VGE can result in permanent damage to the oxide layer in the gate region.
- 6. Gate Termination The gates of these devices are essentially capacitors. Circuits that leave the gate opencircuited or floating should be avoided. These conditions can result in turn-on of the device due to voltage buildup on the input capacitor due to leakage currents or pickup.
- Gate Protection These devices do not have an internal monolithic zener diode from gate to emitter. If gate protection is required an external zener is recommended.
- \* Trademark Emerson and Cumming, Inc.



# HGTG24N60D1

JEDEC STYLE TO-247 TOP VIEW

N-CHANNEL ENHANCEMENT MODE

# 24A, 600V N-Channel IGBT

>EMITTER

GATE

COLLECTOR

December 1993

#### Features

- 24 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time <500ns</li>
- High Input Impedance
- Low Conduction Loss

#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at moderate frequencies where low conduction losses are essential, such as: AC and DC motor controls. power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC style TO-247 package.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specific

	HGTG24N60D1	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	600	v
Collector Current Continuous at $T_c = +25^{\circ}C$	40	Α
at $V_{GE} = 15V$ at $T_C = +90^{\circ}CI_{C90}$	24	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	96	Α
Gate-Emitter Voltage Continuous.	±25	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	60A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	125	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.0	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.125 inch from case for 5 seconds)	260	°C

Package

COLLECTOR (BOTTOM SIDE METAL)

Terminal Diagram

NOTE:

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

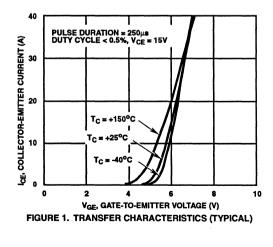
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

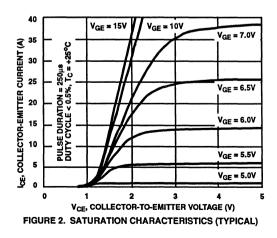
				LIMITS				
PARAMETERS	SYMBOL	TEST CON	TEST CONDITIONS			МАХ		
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> =	0V	600	-	-	v	
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	1.0	mA	
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA	
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>			-	1.7	2.3	v	
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	1.9	2.5	v	
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 250μA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	. <b>v</b>	
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±500	nA	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{\rm C} = I_{\rm C90}, V_{\rm CE} = 0.5$	BV <sub>CES</sub>	-	6.3	-	v	
On-State Gate Charge	Q <sub>G(ON)</sub>		V <sub>GE</sub> = 15V	-	120	155	nC	
		V <sub>CE</sub> = 0.5 BV <sub>CES</sub>	V <sub>GE</sub> = 20V	-	155	200	nC	
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	L = 500 $\mu$ H, I <sub>C</sub> = I <sub>C</sub>		-	100	-	ns	
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 15V, T_J = +1$ $V_{CE} = 0.8 BV_{CES}$	150°C,	•	150	-	ns	
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> i			-	700	900	ns	
Current Fall Time	t <sub>FI</sub>			-	450	600	ns	
Turn-Off Energy (Note 1)	WOFF			-	4.3	- 1	mJ	
Thermal Resistance	R <sub>eJC</sub>	1		-	-	1.00	°c∕w	

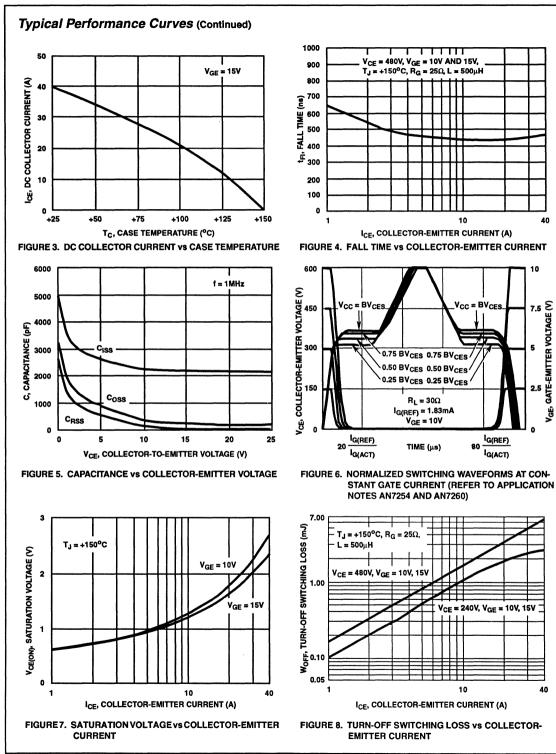
Electrical Specifications T<sub>c</sub> = +25°C, Unless Otherwise Specified

NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG24N60D1 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss.

## Typical Performance Curves

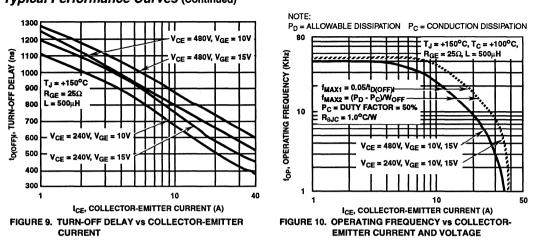






IGBTs

3



#### Typical Performance Curves (Continued)

#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)}$ .  $t_{D(OFF)}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D$  -  $P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$ . A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ .  $W_{OFF}$  is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE}$  = 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \bullet W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# HGTM24N60D1

December 1993

#### Features

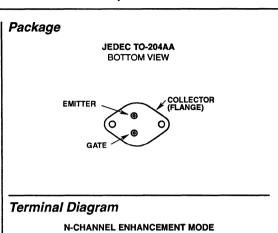
- 24 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time <500ns
- · High Input Impedance
- Low Conduction Loss

### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at moderate frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC TO-204AA package.



24A. 600V N-Channel IGBT



#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specific

	HGTG24N60D1	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	600	v
Collector Current Continuous at $T_c = +25^{\circ}CI_{c25}$	40	Α
at $V_{GE} = 15V$ at $T_{C} = +90^{\circ}CI_{C90}$	24	Α
Collector Current Pulsed (Note 1)	96	Α
Gate-Emitter Voltage Continuous.	±25	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	60A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	125	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.0	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.125 inches from case for 5 seconds)	260	°C

#### NOTE:

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

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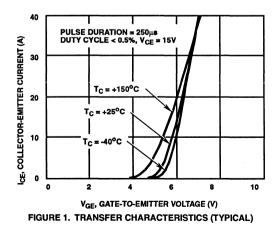
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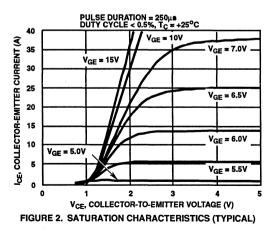
				LIMITS			
PARAMETERS	SYMBOL	TEST CON	DITIONS	MIN	ТҮР	MAX	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> =	0V	600	-	-	v
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	1.0	mA
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	$I_{\rm C} = I_{\rm C90},$	T <sub>C</sub> = +25°C	-	1.7	2.3	v
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	1.9	2.5	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 250μA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V	V <sub>GE</sub> = ±20V		-	±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5	BV <sub>CES</sub>	-	6.3	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	$l_{\rm C} = l_{\rm C90},$	V <sub>GE</sub> = 15V	-	120	155	nC
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	-	155	200	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	$L = 500 \mu H, I_{C} = I_{CS}$		-	100	-	ns
Current Rise Time	t <sub>RI</sub>	V <sub>GE</sub> = 15V, T <sub>J</sub> = +1 V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	50°C,	-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> I			-	700	900	ns
Current Fall Time	t⊨i			-	450	600	ns
Turn-Off Energy (Note 1)	W <sub>OFF</sub>			-	4.3	-	mJ
Thermal Resistance	R <sub>eJC</sub>			-	-	1.00	°c/w

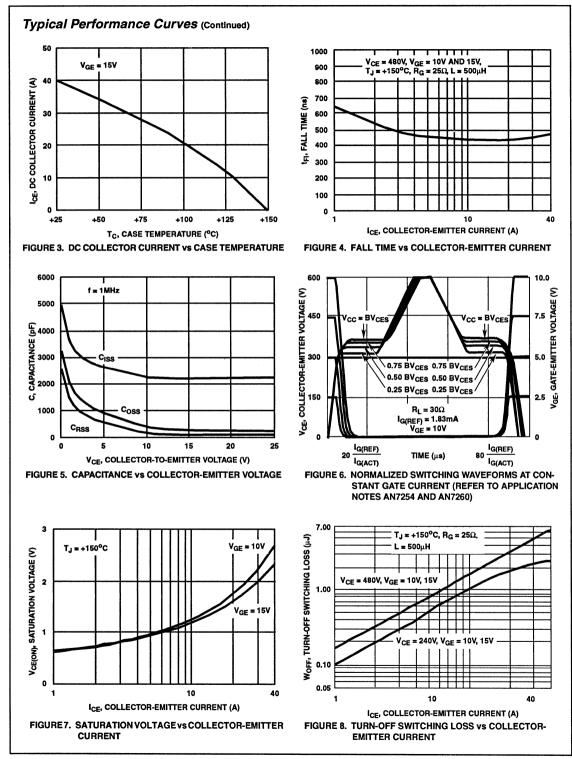
Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTM24N60D1 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss.

## Typical Performance Curves

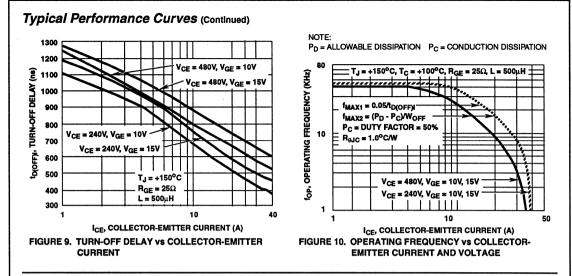






GBTs

3



Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows f<sub>MAX1</sub> or f<sub>MAX2</sub> whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1}$  = 0.05/ $t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2} = (P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D = (T_{JMAX} - T_C)/R_{eJC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C = (V_{CE} \bullet I_{CE})/2$ . W\_{OFF} is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE} = 0A$ ).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \circ W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# HARRIS HGTG30N120D2

#### December 1993

#### Features

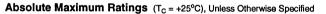
- 30 Amp 1200 Volt
- Latch Free Operation
- Typical Fall Time 580ns
- · High Input Impedance
- Low Conduction Loss

#### Description

The HGTG30N120D2\* is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

The IGBTs are ideal for many high voltage switching applications operating at moderate frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

\*Formerly Developmental Type TA49010



	HGTG30N120D2	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	1200	v
Collector-Gate Voltage, $R_{GE} = 1M\Omega$	1200	v
Collector Current Continuous at $T_c = +25^{\circ}Cl_{c25}$	50	Α
at V <sub>GE</sub> =15V at T <sub>C</sub> = +90°C	30	Α
Collector Current Pulsed (Note 1)	200	А
Gate-Emitter Voltage Continuous.	±20	v
Gate-Emitter Voltage Pulsed	±30	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	200A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at $T_c = +25^{\circ}C$ $P_D$	208	w
Power Dissipation Total Derating T <sub>C</sub> > +25°C	1.67	W/°C
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL	260	°C
Short Circuit Withstand Time (Note 2) at V <sub>GE</sub> = 15Vt <sub>SC</sub>	6	μS
at V <sub>GE</sub> = 10V	15	μS
NOTES:		

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

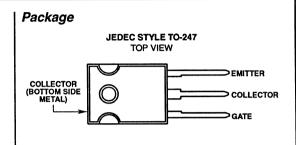
2. V<sub>CE(PEAK)</sub> = 720V, T<sub>C</sub> = +125°C, R<sub>GE</sub> = 25Ω.

HARRIS S	EMICONDUCTO	OR IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S.	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4.969.027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

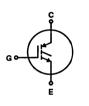
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# 30A, 1200V N-Channel IGBT









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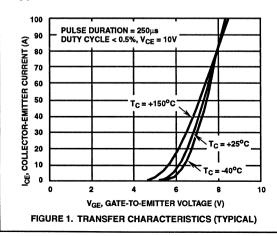
File Number 2834.1

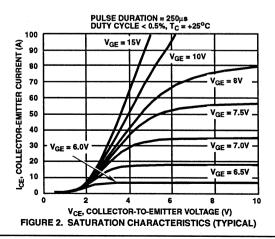
PARAMETERS	SYMBOL	TEST CON	DITIONS	MIN	MIN TYP		UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	$I_C = 250 \mu A$ , $V_{GE} =$	I <sub>C</sub> = 250μA, V <sub>GE</sub> = 0V			-	v
Zero Gate Voltage Collector Current	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	1.0	mA
		$V_{CE} = 0.8 \text{ BV}_{CES}$	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	T <sub>C</sub> = +25°C	-	3.0	3.5	v
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	3.2	3.5	v
		I <sub>C</sub> = I <sub>C90</sub> ,	T <sub>C</sub> = +25°C	-	3.2	3.8	v
		V <sub>GE</sub> = 10V	T <sub>C</sub> = +125°C	-	3.4	3.8	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	$V_{GE} = V_{CE},$ $I_C = 1mA$	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V	V <sub>GE</sub> = ±20V			±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{\rm C} = I_{\rm C90}, V_{\rm CE} = 0.5$	5 BV <sub>CES</sub>	-	7.3	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	V <sub>GE</sub> = 15V	-	185	240	nC
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	-	240	315	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub>	$L = 50 \mu H$ , $I_{C} = I_{C90}$	, R <sub>G</sub> = 25Ω,	-	100		ns
Current Rise Time	t <sub>RI</sub>	V <sub>GE</sub> = 15V, T <sub>J</sub> = + V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	125°C,	-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub>			-	760	990	ns
Current Fall Time	t <sub>FI</sub>	1		-	580	750	ns
Turn-Off Energy (Note 1)	WOFF	1		-	8.4	-	mJ
Current Turn-On Delay Time	t <sub>D(ON)</sub>	L = 50µH, I <sub>C</sub> = I <sub>C90</sub>		-	100	-	ns
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 10V, T_{J} = +125^{\circ}C,$ $V_{CE} = 0.8 BV_{CES}$		-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub>			-	610	790	ns
Current Fall Time	t <sub>FI</sub>	1		-	580	750	ns
Turn-Off Energy (Note 1)	WOFF	7		-	8.4	-	mJ
Thermal Resistance Junction-to-Case	R <sub>eJC</sub>	T		-	0.5	0.6	°C/W

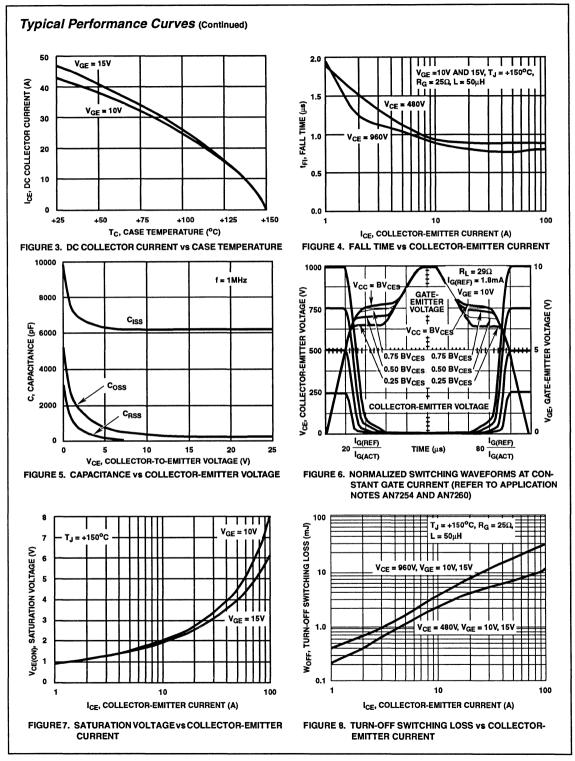
#### **Electrical Specifications** $T_{C} = +25^{\circ}C$ , Unless Otherwise Specified

NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG20N100D2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss.

#### **Typical Performance Curves**

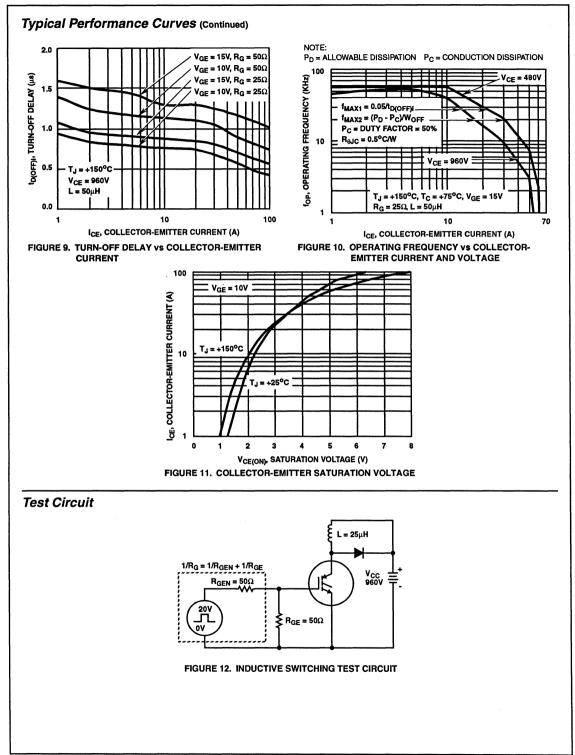






**IGBTs** 

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Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05 / t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$   $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ . W\_OFF is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero  $(I_{CE} = 0A)$ .

The switching power loss (Figure 10) is defined as  $f_{MAX2} \circ W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# HGTA32N60E2

December 1993

#### Features

- 32 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time 620ns
- High Input Impedance
- Low Conduction Loss

#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC MO-093AA (5 lead TO-218) package.



	HGTA32N60E2	UNITS
Collector-Emitter VoltageBV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$	600	v
Collector Current Continuous at T <sub>C</sub> = +25°Cl <sub>C25</sub>	50	Α
at $V_{GE} = 15V$ at $T_{C} = +90^{\circ}C$	32	Α
Collector Current Pulsed (Note 1)	200	Α
Gate-Emitter Voltage Continuous.	±20	v
Gate-Emitter Voltage Pulsed V <sub>GEM</sub>	±30	v
Switching Sage Operating Area T <sub>J</sub> = +150°CSSOA	200A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°CP <sub>D</sub>	208	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.67	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTI	260	°C
Short Circuit Withstand Time (Note 2) at V <sub>GE</sub> = 15V t <sub>SC</sub>	3	μs
at $V_{GE} = 10V$ $t_{SC}$	15	μs

#### NOTES:

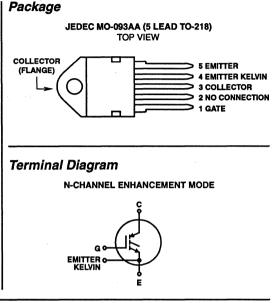
1. Repetitive Rating: Pulse width limited by maximum junctions temperature.

2.  $V_{CE(PEAK)} = 360V$ ,  $T_C = +125^{\circ}C$ ,  $R_{GE} = 25\Omega$ .

HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S.	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1993

# 32A, 600V N-Channel IGBT



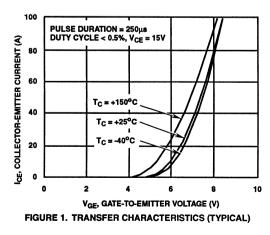
					LIMITS		
PARAMETERS	RAMETERS SYMBOL TEST CONDITIONS		NDITIONS	MIN	ТҮР	MAX	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> =	: 0V	600	•	-	v
Collector-Emitter Leakage Current	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	$V_{CE} = BV_{CES}$ $T_C = +25^{\circ}C$		-	250	μΑ
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage			T <sub>C</sub> = +25⁰C	•	2.4	2.9	v
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	2.4	3.0	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 1.0mA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 BV <sub>CE8</sub>		-	6.5	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	$l_{\rm C} = l_{\rm C90},$	V <sub>GE</sub> = 15V	-	200	260	nC
		V <sub>CE</sub> = 0.5 BV <sub>CES</sub>	V <sub>GE</sub> = 20V	-	265	345	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub>	$L = 500 \mu H, I_{C} = I_{C}$	$R_0, R_0 = 25\Omega,$	-	100	-	ns
Current Rise Time	t <sub>RI</sub>	V <sub>GE</sub> = 15V, T <sub>J</sub> = + V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	125°C,	-	150	-	ns
Current Turn-Off Delay Time	<sup>t</sup> D(OFF)I			•	630	820	ns
Current Fall Time	t <sub>FI</sub>			-	620	800	ns
Turn-Off Energy (Note 1)	WOFF			•	3.5	-	mJ
Thermal Resistance	Reuc			-	0.5	0.6	°c/w

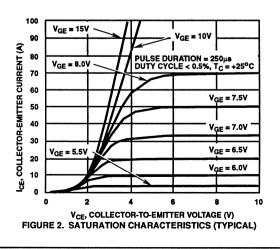
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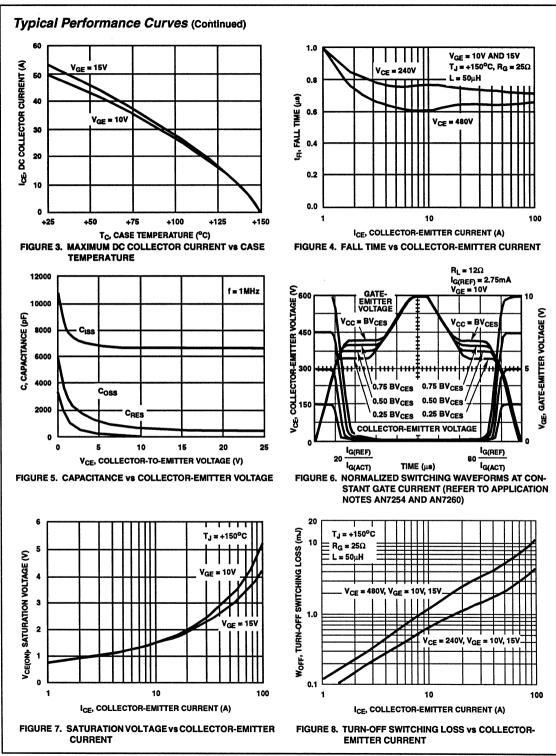
NOTE:

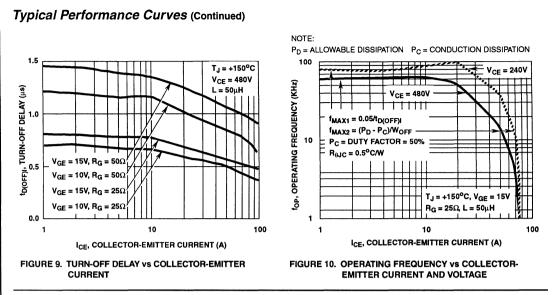
1. Turn-off Energy Loss (WOFF) is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and rending at the point where the collector current equals zero ( $l_{CE} = 0A$ ) The HGTA32N60E2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss.

## Typical Performance Curves









Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device turn-off delay can establish an additional

frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  = (P\_D - P\_C)/W\_{OFF} The allowable dissipation (P\_D) is defined by P\_D = (T\_{JMAX} - T\_C)/R\_{HJC}. The sum of device switching and conduction losses must not exceed P\_D A 50% duty factor was used (Figure 10) so that the conduction losses (P\_C) can be approximated by P\_C = (V\_{CE} \times I\_{CE})/2. W\_{OFF} is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero (I\_{CE} - 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX1}\ x$   $W_{OFF}$ . Turn on switching losses are not included because they can be greatly influenced by external circuit conditions and components.

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# HGTG32N60E2

December 1993

# 32A, 600V N-Channel IGBT

#### Features

- 32 Amp. 600 Volt
- Latch Free Operation
- Typical Fall Time 600ns
- High Input Impedance
- Low Conduction Loss

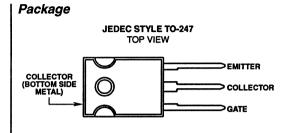
## Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors,

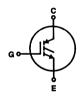
This device incorporates generation two design techniques which yield improved peak current capability and larger short circuit withstand capability than previous designs.

This type is supplied in the JEDEC style TO-247 package.



### Terminal Diagram

#### N-CHANNEL ENHANCEMENT MODE



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	HGTG32N60E2	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $V_{CGR}$	600	v
Collector Current Continuous at $T_c = +25^{\circ}C$	50	Α
at V <sub>GE</sub> = 15V, at T <sub>C</sub> = +90°CI <sub>C90</sub>	32	Α
Collector Current Pulsed (Note 1) ICM	200	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±20	v
Gate-Emitter Voltage Pulsed VGEM	±30	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	200A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	208	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.67	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTi	260	°C
Short Circuit Withstand Time (Note 2) at V <sub>GE</sub> = 15Vt <sub>SC</sub>	3	μs
at V <sub>GE</sub> = 10V	15	μs
NOTES:		•

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

2.  $V_{CE(PEAK)} = 360V$ ,  $T_{C} = +125^{\circ}C$ ,  $R_{GE} = 25\Omega$ .

HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR MO	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

### Specifications HGTG32N60E2

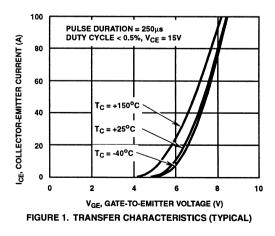
					LIMITS			
PARAMETERS	SYMBOL	TEST CON	DITIONS	MIN	ТҮР	МАХ	UNITS	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> =	0V	600	-	-	v	
Collector-Emitter Leakage Voltage	I <sub>CES</sub>	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	250	μΑ	
		$V_{CE} = 0.8 \text{ BV}_{CES}$	T <sub>C</sub> = +125⁰C	-	-	4.0	mA	
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	T <sub>C</sub> = +25°C	-	2.4	2.9	v	
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	2.4	3.0	v	
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 1mA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v	
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±500	nA	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{\rm C} = I_{\rm C90},  V_{\rm CE} = 0.5$	I <sub>C</sub> = I <sub>C90</sub> , V <sub>CE</sub> = 0.5 BV <sub>CES</sub>		6.5	-	v	
On-State Gate Charge	Q <sub>G(ON)</sub>	$I_{\rm C} = I_{\rm C90},$	V <sub>GE</sub> = 15V	-	200	260	nC	
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	-	265	345	nC	
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	$L = 500 \mu H, I_C = I_{CS}$		-	100	-	ns	
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 15V, T_J = +1$ $V_{CE} = 0.8 BV_{CES}$	125°C,	-	150	-	ns	
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> i	1		-	630	820	ns	
Current Fall Time	t <sub>FI</sub>	1			620	800	ns	
Turn-Off Energy (Note 1)	WOFF	1			3.5		mJ	
Thermal Resistance	R <sub>eJC</sub>				0.5	0.6	°C/W	

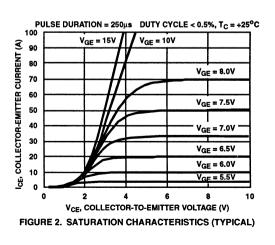
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

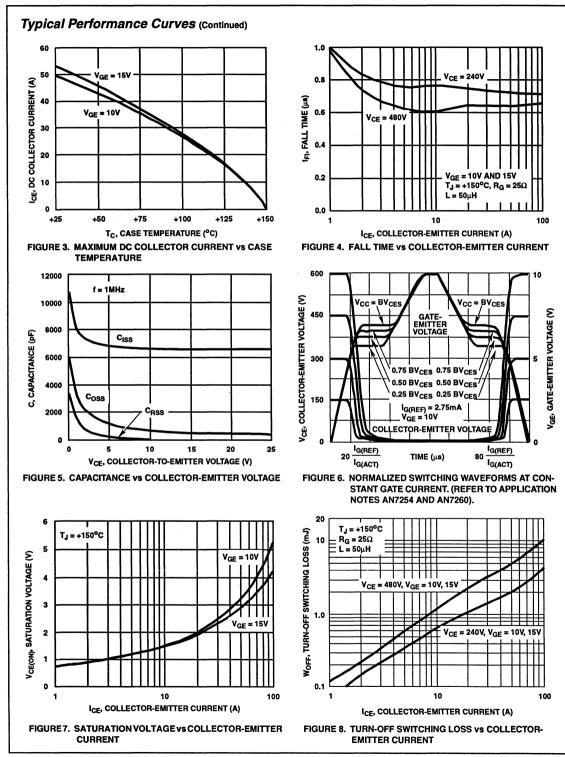
NOTE:

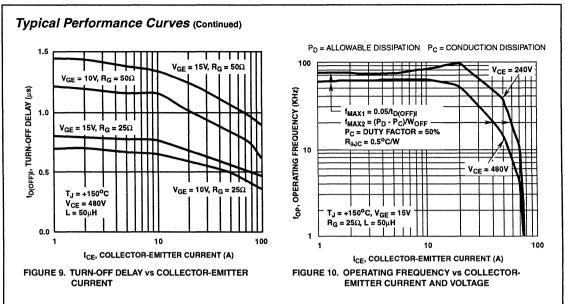
 Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG32N60E2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss.

# Typical Performance Curves









Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device turn-off delay can establish an additional

frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  = ( $P_D$  -  $P_C$ )/W\_{OFF}. The allowable dissipation ( $P_D$ ) is defined by  $P_D$  = ( $T_{JMAX}$  -  $T_C$ )/R\_{eJC}. The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) so that the conduction losses ( $P_C$ ) can be approximated by  $P_C$  = ( $V_C$  ×  $I_{CE}$ )/2. W\_{OFF} is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE}$  - 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX1} \ x \ W_{OFF}$ . Turn on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# HARRIS HGTG34N100E2

December 1993

#### Features

- 34 Amp 1000 Volt
- Latch Free Operation
- Typical Fall Time 710ns
- High Input Impedance
- Low Conduction Loss

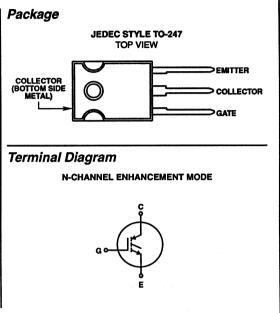
#### Description

The HGTG34N100E2\* is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C.

The IGBTs are ideal for many high voltage switching applications operating at moderate frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

\*Formerly Developmental Type TA9895

# 34A, 1000V N-Channel IGBT



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	HGTG34N100E2	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	1000	v
Collector-Gate Voltage, R <sub>GE</sub> =1MΩ V <sub>CGR</sub>	1000	v
Collector Current Continuous at T <sub>C</sub> = +25°CI <sub>C25</sub>	55	Α
at V <sub>GE</sub> =15V, at T <sub>C</sub> = +90°C	34	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	200	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±20	v
Gate-Emitter Voltage Pulsed V <sub>GEM</sub>	±30	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	200A at 0.8 BV <sub>CES</sub>	-
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	208	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.67	W/°C
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL	260	°C
Short Circuit Withstand Time (Note 2) at V <sub>GE</sub> =15V t <sub>SC</sub>	3	μs
at V <sub>GE</sub> =10Vt <sub>SC</sub>	10	μs

#### NOTE:

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

2.  $V_{CE(PEAK)} = 600V$ ,  $T_C = +125^{\circ}C$ ,  $R_{GE} = 25\Omega$ .

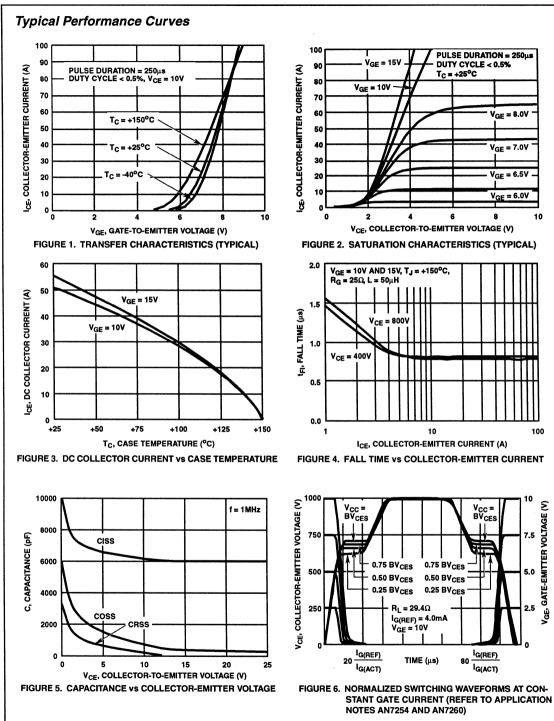
HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR MO	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

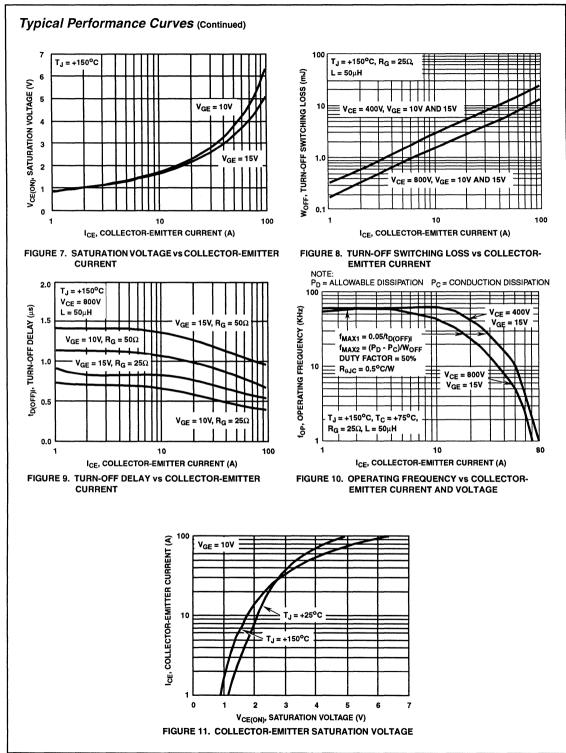
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

PARAMETERS	ARAMETERS SYMBOL TEST CONDITIONS		DITIONS	MIN	ТҮР	МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 250μA, V <sub>GE</sub> =	I <sub>C</sub> = 250μA, V <sub>GE</sub> = 0V			-	v
Collector-Emitter Leakage Voltage	I <sub>CES</sub>	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	1.0	mA
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125°C	-	-	4.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	$I_{\rm C} = I_{\rm C90},$	T <sub>C</sub> = +25°C	-	2.8	3.2	v
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	2.8	3.1	v
		$I_{C} = I_{C90},$ $V_{GE} = 10V$	T <sub>C</sub> = +25°C	-	2.9	3.3	v
		V <sub>GE</sub> = 10V	T <sub>C</sub> = +125°C	-	3.0	3.4	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 1mA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{C} = I_{C90}, V_{CE} = 0.5 \text{ BV}_{CES}$		-	7.3	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	$I_{C} = I_{C90},$ $V_{CE} = 0.5 \text{ BV}_{CES}$	V <sub>GE</sub> = 15V	-	185	240	nC
		VCE = 0.5 DVCES	V <sub>GE</sub> = 20V	-	240	315	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	$L = 50\mu H, I_{C} = I_{C90}$	$R_{G} = 25\Omega,$	-	100	-	ns
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 15V, T_J = +1$ $V_{CE} = 0.8 BV_{CES}$	125°C,	-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub> I	1		•	610	795	ns
Current Fall Time	t <sub>FI</sub>	1		-	710	925	ns
Turn-Off Energy (Note 1)	WOFF	1		-	7.1	-	mJ
Current Turn-On Delay Time	t <sub>D(ON)</sub> i	$L = 50\mu H, I_{C} = I_{C90}$	$R_{G} = 25\Omega,$	-	100	-	ns
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 10V, T_J = +$ $V_{CE} = 0.8 BV_{CES}$	125°C,	-	150	-	ns
Current Turn-Off	t <sub>D(OFF)</sub> I	1		•	460	600	ns
Current Fall Time	t <sub>FI</sub>	1		-	670	870	ns
Turn-Off Energy (Note 1)	WOFF	1		-	6.5	-	mJ
Thermal Resistance	R <sub>eJC</sub>			-	0.5	0.6	°C/W

#### **Electrical Specifications** $T_{C} = +25^{\circ}C$ , Unless Otherwise Specified

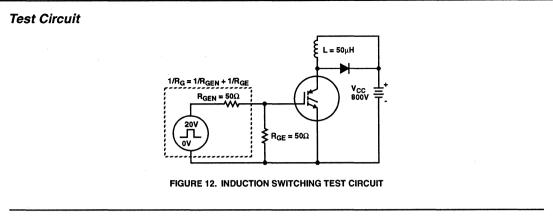
NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG34N100E2 was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss. IGBTs





3

**GBTs** 



Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1} = 0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX},\ t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

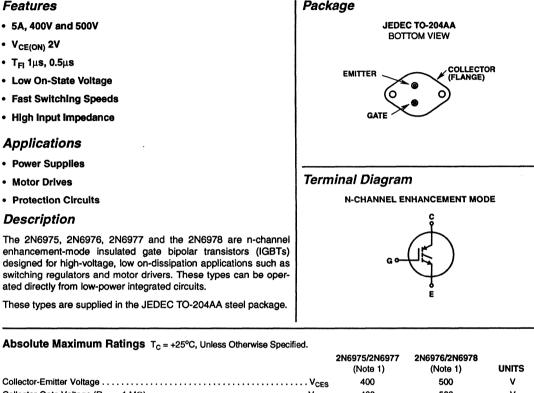
 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ .  $W_{OFF}$  is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CF}$  = 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \cdot W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.



# 2N6975, 2N6976 2N6977, 2N6978

# 5A, 400V and 500V N-Channel IGBTs



	(	(	••
Collector-Emitter VoltageV <sub>CES</sub>	400	500	v
Collector-Gate Voltage (R <sub>GE</sub> = 1 MΩ)V <sub>CGR</sub>	400	500	v
Reverse Collector-Emitter Voltage V <sub>CES(rev.)</sub>	5	5	v
Gate-Emitter VoltageV <sub>GE</sub>	±20	±20	v
Collector Current Continuous Ic	5	5	Α
Collector Current Pulsed I <sub>CM</sub>	10	10	Α
Power Dissipation Total at T <sub>C</sub> = +25°CP <sub>D</sub>	100	100	w
Power Dissipation Derating $T_{C} > +25^{\circ}C$	0.8	0.8	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	-55 to +150	°C
NOTE:			
1. JEDEC registered value.			

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

3-69

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

GBTs

- Low On-State Voltage
- Fast Switching Speeds
- · High Input Impedance

# Applications

December 1993

Features

- Power Supplies
- Motor Drives
- Protection Circuits

# Description

The 2N6975, 2N6976, 2N6977 and the 2N6978 are n-channel enhancement-mode insulated gate bipolar transistors (IGBTs) designed for high-voltage, low on-dissipation applications such as switching regulators and motor drivers. These types can be operated directly from low-power integrated circuits.

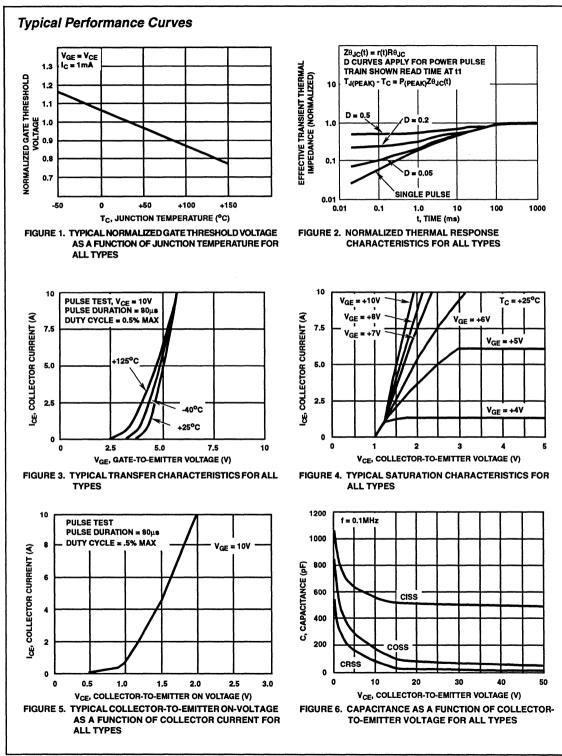
These types are supplied in the JEDEC TO-204AA steel package.

			2N6975	2N6977	2N6976	2N6978	
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	МАХ	MIN	МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	l <sub>C</sub> = 1 mA, V <sub>GE</sub> = 0	400 (Note 1)	-	500 (Note 1)	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2 (Note 1)	4.5 (Note 1)	2 (Note 1)	4.5 (Note 1)	v
Zero Gate Voltage Collector Current	I <sub>CES</sub>	V <sub>CE</sub> = 400V	-	250 (Note 1)	-	-	μΑ
		V <sub>CE</sub> = 500V	-	-	-	250 (Note 1)	μΑ
		T <sub>C</sub> = +125°C	-	-	-	-	μA
	e.	V <sub>CE</sub> = 400V	-	1000 (Note 1)	-	-	μΑ
		V <sub>CE</sub> = 500V	-	-	-	1000 (Note 1)	μA
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0V$	-	100 (Note 1)	-	100 (Note 1)	ns
Reverse Collector-Emitter Leakage Current	IECS	$R_{GE} = 0\Omega$ , $V_{EC} = 5V$	-	5 (Note 1)	-	5 (Note 1)	mA
Collector-Emitter On Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 5A, V <sub>GE</sub> = 10V	-	2 (Note 1)	-	2 (Note 1)	v
		I <sub>C</sub> = 10A, V <sub>GE</sub> = 20V	-	2.5	-	2.5	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	l <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	3.4 (Note 1)	6.8 (Note 1)	3.4 (Note 1)	6.8 (Note 1)	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	12 (Note 1)	25 (Note 1)	12 (Note 1)	25 (Note 1)	nC
Turn-On Delay Time	t <sub>D(ON)</sub>	$I_{\rm C} = 5A$		50	Max	-	ns
Rise Time	t <sub>R</sub>	$V_{CE(CLP)} = 300V$ L = 50 $\mu$ H		50	Max		ns
Turn-Off Delay Time	t <sub>D(ON)</sub>	T <sub>J</sub> = +125°C V <sub>GE</sub> = 10V R <sub>G</sub> = 50Ω			Max te 1)		ns
Fall Time	t <sub>FI</sub>		2N6975 2N6976		1000 Max (Note 1)		ns
			2N6977 2N6978		500 Max (Note 1)		ns
Turn-Off Energy Loss per Cycle	W <sub>OFF</sub>	$I_{C} = 5A$ $V_{CE(CLP)} = 300V$	2N6975 2N6976		1000 Max (Note 1)		μ
(Off Switching Dissipation= W <sub>OFF</sub> x Frequency)		L = 50μH T <sub>J</sub> = +125°C V <sub>GE</sub> = 10V R <sub>G</sub> = 50Ω	2N6977 2N6978		500 Max (Note 1)		μ
Thermal Resistance Junction-to-Case	R <sub>ejc</sub>				.25 ote 1)		°C/M

### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

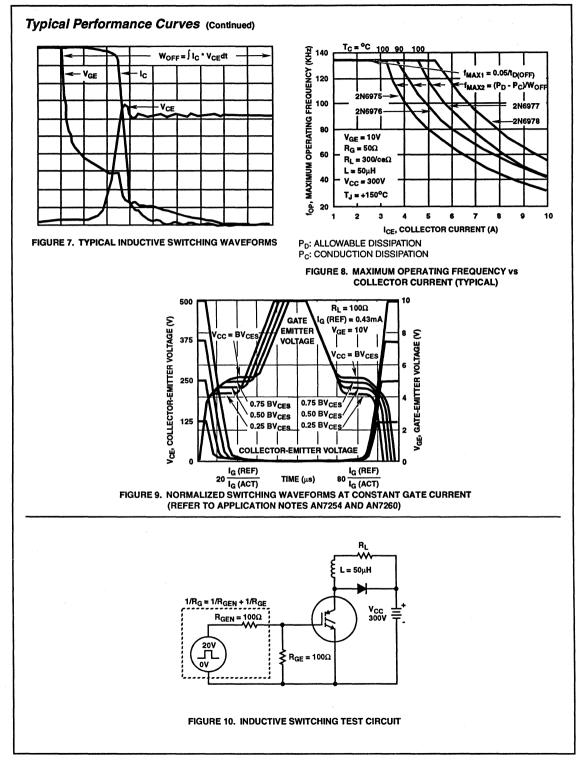
NOTE:

1. JEDEC registered value.



GBTs

3



# HARRIS HGTB12N60D1C

Package

COLLECTOR (FLANGE)

December 1993

#### 12A, 600V Current Sensing N-Channel IGBT

1 - Gate

2 - Sense 3 - Collector

5 - Emitter

Terminal Diagram

4 - (Kelvin) Emitter

N-CHANNEL ENHANCEMENT MODE

HOTP12NE0D1C

JEDEC TS-001AA (5 LEAD TO-220) TOP VIEW

#### Features

- 12A, 600V
- Low V<sub>CE(SAT)</sub> at 25A ......2.5V (Typ)
- Ultra-Fast Turn-On ...... 100ns (Typ)
- Polysilicon MOS Gate Voltage Controlled Turn On/Off
- High Current Handling at +100°C.....10A
- Current Sensing Pilot

#### Description

The HGTB12N60D1C Insulated-Gate Bipolar Transistor is a MOS-gate turn on/off power switching device combining the best advantages of power MOSFETs and bipolar transistors, and current sensing pilots. The result is a device that has the high input impedance of MOSFETs and the low on-state conduction losses similar to bipolar transistors. The device design and gate characteristics of the IGBT are also similar to power MOSFETs. An important difference is the equivalent  $r_{DS(ON)}$  drain resistance which is modulated to a low value (ten times lower) when the gate is turned on. The much lower on-state voltage drop also varies only moderately between +25°C and +150°C, offering extended power handling capability.

The IGBT is ideal for many high-voltage switching applications operating at low frequencies and where low conduction losses are essential, such as AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

The HGTB12N60D1C is supplied in a JEDEC TS-001AA (5 lead TO-220) package.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	INGI BIZNOUDIC	UNITS
Collector-Emitter Voltage (V <sub>GE</sub> = 0V)	600	v
Collector-Gate Voltage ( $R_{GE} = 1M\Omega$ ) $V_{CGR}$	600	v
Collector Current Continuous at T <sub>C</sub> = +100°C I <sub>C</sub>	12	А
at $T_c = +25^{\circ}C$ $I_c$	18	А
Collector Current Pulsed (Note 1)	40	А
Gate-Emitter VoltageV <sub>GE</sub>	±25	v
Power Dissipation Total at $T_c = +25^{\circ}C$ $P_p$	75	w
Power Dissipation Derating $T_{C} > +25^{\circ}C$	0.6	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Thermal Resistance, Junction to Case	1.67	°C/W
Maximum Lead Temperature for SolderingTL (1/8 inch from case for 5 seconds)	260	°C

NOTE: 1. Repetitive Rating: Pulse width limited by maximum junction temperature. Gate control turn-off not allowed above 50A.

HARRIS S	EMICONDUCTO	OR IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S. I	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

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LINITS

GBTS

					LIMITS		
PARAMETERS	SYMBOL	TEST COM	IDITIONS	MIN	ТҮР	MAX	UNITS
OFF CHARACTERISTICS							
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	$I_{\rm C} = 25 \mu {\rm A}, V_{\rm GE} = 0$	v	600	-	-	v
Collector Cut-Off Current	ICES	T <sub>C</sub> = +25°C, V <sub>GE</sub> = V <sub>CE</sub> = Maximum Ra		-	•	250	μA
		T <sub>C</sub> = +150°C, V <sub>GE</sub> = V <sub>CE</sub> = Maximum Ra		-	-	4	mA
Gate-Emitter Leakage Current	IGES	V <sub>GE</sub> = ±20V		-	-	±500	nA
ON CHARACTERISTICS (Note 2)		•					<b></b>
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>CE</sub> = V <sub>GE</sub> ,	T <sub>C</sub> = +25°C	2	4	5	v
		l <sub>C</sub> = 250μA	T <sub>C</sub> = +150°C	-	2.5	-	v
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	V <sub>GE</sub> = 15V, I <sub>C</sub> = 10A	A, T <sub>C</sub> = +25°C	-	2.5	2.7	v
		V <sub>GE</sub> = 15V, I <sub>C</sub> = 104	A, T <sub>C</sub> = +150°C	-	2.8	-	v
		$V_{GE} = 10V, I_{C} = 10A$	A, T <sub>C</sub> = +25°C	-	2.9	-	v
DYNAMIC CHARACTERISTICS							
Input Capacitance	CIES	V <sub>GE</sub> = 0V, V <sub>CE</sub> = 25	-	1050	-	pF	
Output Capacitance	C <sub>OES</sub>			-	340	-	pF
Reverse Transfer Capacitance	C <sub>RES</sub>	1		-	10	-	pF
SWITCHING CHARACTERISTICS (See	Figures 8 and 9	9) (Note 2)					
Turn-On Delay Time	t <sub>D(ON)</sub>	Resistive Load, T <sub>J</sub>	= +125°C,	-	100		ns
Rise Time	t <sub>R</sub>	$I_{C} = 10A, V_{CE} = 500$ $R_{G(ON)} = 50\Omega, R_{G(C)}$	0V, V <sub>GE</sub> = 15V, <sub>9FF)</sub> = 100Ω	-	100	-	ns
Turn-Off Delay Time	t <sub>D(OFF)</sub>			-	0.4	-	μs
Fall Time	ţ.	1		-	2.5	-	μs
Turn-Off Delay Time	t <sub>D(OFF)</sub> I	Inductive Load, T <sub>J</sub> :	= +125°C,	-	0.8	1.2	μs
Fall Time	t <sub>FI</sub>	L = $45\mu$ H, I <sub>C</sub> = $10$ A, V <sub>GE</sub> = $15$ V, R <sub>G(ON)</sub>		-	0.8	1.0	μs
Equivalent Fall Time	t <sub>F(EQ)</sub>	$R_{G(OFF)} = 100\Omega$		•	0.6	0.8	μs
Turn-Off Switching Losses	WOFF	1		-	1.6	2.0	mJ
PILOT CHARACTERISTICS (Notes 2, 3	and 4)	<b>.</b>				•	
Pilot-Emitter Kelvin Voltage	VPEK	V <sub>GE</sub> = 15V <sub>DC</sub> , R <sub>P</sub> =	2kΩ				
I <sub>C</sub> = 5A				-	1.25	-	v
I <sub>C</sub> = 10A	-			1.4	1.67	1.8	v
I <sub>C</sub> = 20A				-	2.06	<u> </u>	

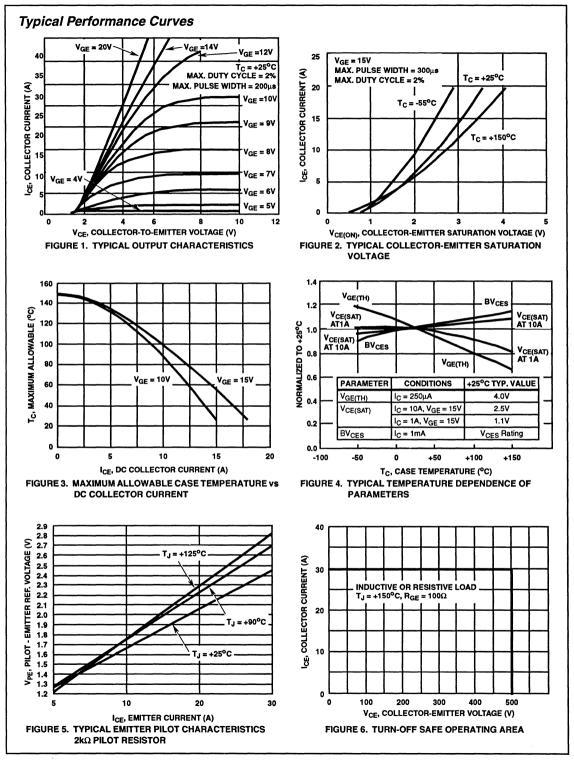
NOTES:

1. Applies for 3.3°C per watt maximum thermal resistance, case-to-ambient.

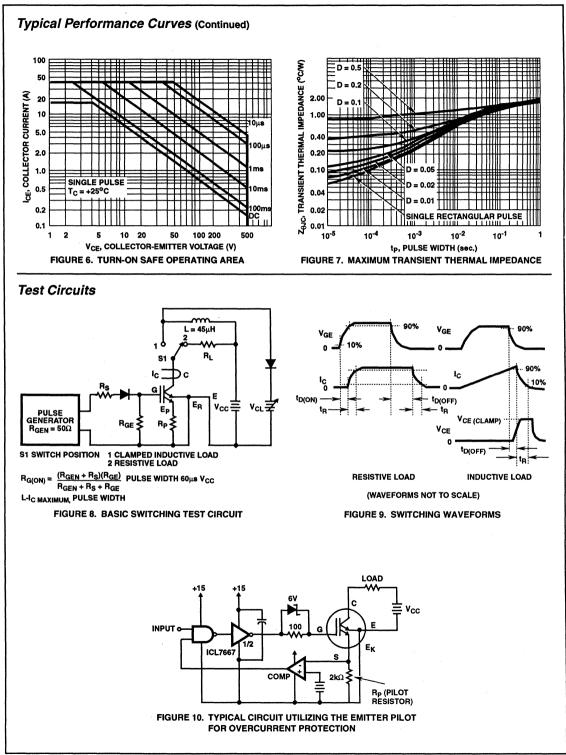
2. Pulse test: Pulse widths  $\leq$  300µs, duty cycle  $\leq$  2%.

3. Refer to Figure 10.

4. When Not in Use Connect S to Emitter.



GBTs



# HARRIS HGTP14N40F3VL

December 1993

### 14A, 400V N-Channel, Voltage Clamping IGBT

Package

COLLECTOR (FLANGE)

#### Features

- · Logic Level Gate Drive
- Internal Voltage Clamp
- ESD Gate Protection
- T<sub>1</sub> = +150°C
- Ignition Energy Capable

#### Applications

- Automotive lanition
- Small Engine Ignition
- Fuel Ignitor

#### Description

This N-Channel IGBT is a MOS gated, logic level device which is intended to be used as an ignition coil driver in automotive ignition circuits. Unique features include an active voltage clamp between the drain and the gate and ESD protection for the logic level gate. Some specifications are unique to this automotive application and are intended to assure device survival in this harsh environment. The development type number for this device is TA49023.

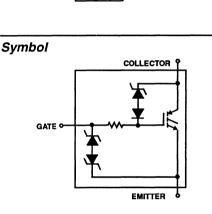
All Devices are supplied in the JEDEC TO-220AB plastic package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	HGTP14N40F3VL	UNITS
Collector-Emitter Breakdown Voltage at 10mABV <sub>CES</sub>	420	v
Collector-Gate Breakdown Voltage R <sub>GE</sub> = 10KΩ BV <sub>CGB</sub>	420	v
Collector Current Continuous		
V <sub>GE</sub> = 4.5V at T <sub>C</sub> = +25°CI <sub>C25</sub>	19	А
$V_{GE} = 4.5V$ at $T_{C} = +90^{\circ}CI_{C90}$	14	А
Gate-Emitter Voltage Continuous.	±10	v
Gate-Emitter Voltage Pulsed or	±12	v
Gate-Emitter Current Pulsed	±10	mA
Open Secondary Turn-Off Current		
L = 2.3mH at +25°C I <sub>CO</sub>	17	Α
L = 2.3mH at +150°C I <sub>co</sub>	12	Α
Drain to Source Avalanche Energy at L = 2.3mH, T <sub>C</sub> = +25°C EAS	330	mJ
Power Dissipation Total at $T_{C} = +25^{\circ}C$ $P_{T}$	83	w
Power Dissipation Derating $T_{C} > +25^{\circ}C$	0.67	W/ºC
Operating and Storage Junction Temperature Range	-40 to +150	°C
Maximum Lead Temperature for Soldering	260	°C
Electrostatic Voltage at 100pF, 1500ΩESD	6	кv

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993



JEDEC TO-220AB TOP VIEW

EMITTER

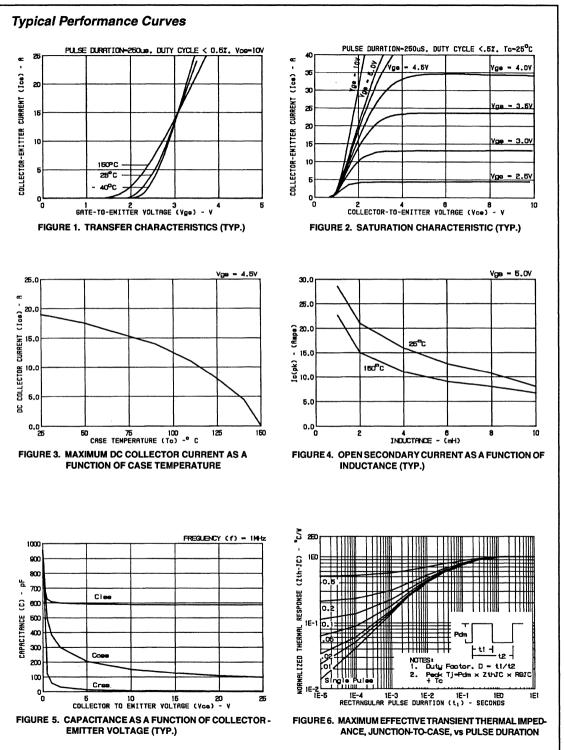
COLLECTOR GATE

GBTs

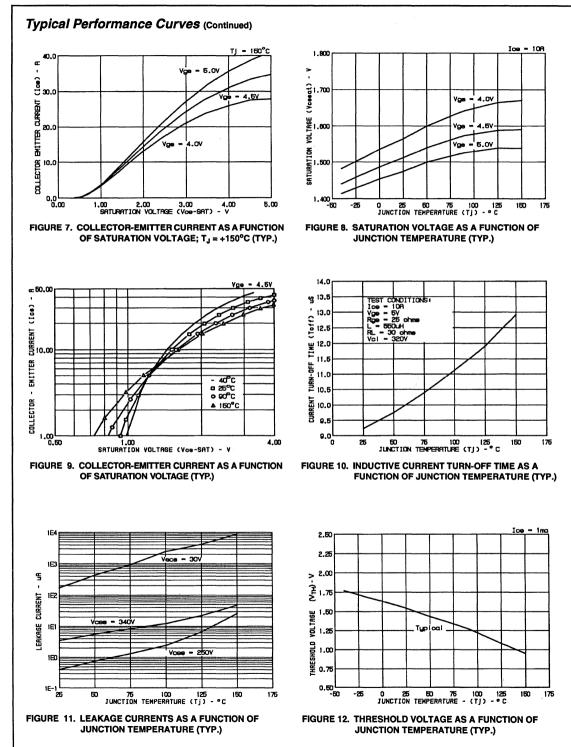
### Specifications HGTP14N40F3VL

PARAMETERS	SYMBOL	TEST CO	NDITIONS	MIN	ТҮР	МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 10mA,	T <sub>C</sub> = +150°C	345	370	415	v
		V <sub>GE</sub> = 0V	T <sub>C</sub> = +25°C	350	375	420	v
			T <sub>C</sub> = -40°C	355	380	425	v
Collector-Emitter Clamp Bkdn. Voltage	BV <sub>CE(CL)</sub>	I <sub>C</sub> = 10A	T <sub>C</sub> = +150°C	350	385	430	v
Emitter-Collector Breakdown Voltage	BVECS	I <sub>C</sub> = 1.0mA	T <sub>C</sub> = +25°C	24	-	-	v
Collector-Emitter Leakage Current	I <sub>CES</sub>	V <sub>CE</sub> = 250V	T <sub>C</sub> = +25°C	-	-	50	μΑ
		V <sub>CE</sub> = 250V	T <sub>C</sub> = +150°C	-	-	250	μΑ
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>		T <sub>C</sub> = +25°C	-	-	2.0	v
		V <sub>GE</sub> = 4.5V	T <sub>C</sub> = +150°C	-	-	2.3	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 1.0mA V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	1.0	1.5	2.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 10V$		-	-	±10	μΑ
Gate-Emitter Breakdown Voltage	BV <sub>GES</sub>	I <sub>GES</sub> = ±1.0mA		±12	-	-	v
Current Turn-off Time-Inductive Load	t <sub>D(OFF)</sub> i + t <sub>F(OFF)</sub> i	$R_L = 32\Omega, I_C = 10$ L = 550μH, V <sub>CL</sub> = T <sub>C</sub> = +125°C		-	12	16	μs
Inductive Use Test	UIS	L = 2.3mH,	T <sub>C</sub> = +150°C	12	-	-	A
		V <sub>G</sub> = 5V, Figure 13	T <sub>C</sub> = +25°C	17	-	-	A
Thermal Resistance	Rejc	1		-	1.5	-	°c∕n

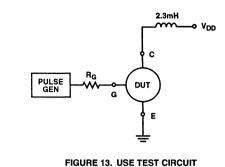
#### Electrical Specifications At Case Temperature (T<sub>c</sub>) = +25°C, Unless Otherwise Specified



3



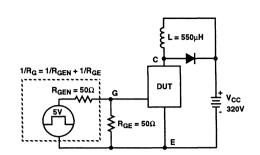
#### **Test Circuits**



### Handling Precautions for IGBT's

Insulated Gate Bipolar Transistors are susceptible to gateinsulation damage by the electrostatic discharge of energy through the devices. When handling these devices, care should be exercised to assure that the static charge built in the handler's body capacitance is not discharged through the device. With proper handling and application procedures, however, IGBT's are currently being extensively used in production by numerous equipment manufacturers in military, industrial and consumer applications, with virtually no damage problems due to electrostatic discharge. IGBT's can be handled safely if the following basic precautions are taken:

 Prior to assembly into a circuit, all leads should be kept shorted together either by the use of metal shorting springs or by the insertion into conductive material such as "\*ECCOSORBD LD26" or equivalent.



#### FIGURE 14. INDUCTIVE SWITCHING TEST CIRCUIT

- When devices are removed by hand from their carriers, the hand being used should be grounded by any suitable means - for example, with a metallic wristband.
- 3. Tips of soldering irons should be grounded.
- 4. Devices should never be inserted into or removed from circuits with power on.
- 5. Gate Voltage Rating Never exceed the gate-voltage rating of  $V_{GEM}$ . Exceeding the rated  $V_{GE}$  can result in permanent damage to the oxide layer in the gate region.
- 6. Gate Termination The gates of these devices are essentially capacitors. Circuits that leave the gate opencircuited or floating should be avoided. These conditions can result in turn-on of the device due to voltage buildup on the input capacitor due to leakage currents or pickup.
- \* Trademark Emerson and Cumming, Inc.



December 1993

# HGTP6N40E1D HGTP6N50E1D

#### 6A, 400V and 500V N-Channel IGBTs with Anti-Parallel Ultrafast Diodes

#### Features

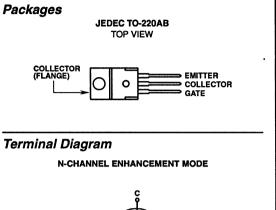
- 6 Amp, 400 and 500 Volt
- Latch Free Operation
- Typical T<sub>FALL</sub> < 1.0µs</li>
- High Input Impedance
- Low Conduction Loss
- With Anti-Parallel Diode
- t<sub>RR</sub> < 60ns

#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C. The diode used in parallel with the IGBT is an ultrafast ( $t_{RR} < 60$ ns) with soft recovery characteristic.

The IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

These devices are supplied in the JEDEC TO-220AB package.



Absolute Maximum Ratings (T <sub>C</sub> = +25°C), Unless Othe
--

	HGTP6N40E1D	HGTP6N50E1D	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	400	500	V
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	400	500	v
Collector Current Continuous at T <sub>C</sub> = +25°C	7.5	7.5	Α
at $T_{c} = +90^{\circ}C$	6	6	Α
Collector Current Pulsed (Note 1)ICM	7.5	7.5	Α
Gate-Emitter Voltage ContinuousVGES	±20	±20	v
Diode Forward Current at T <sub>C</sub> = +25°C I <sub>F25</sub>	10	10	Α
at T <sub>C</sub> = +90°C I <sub>F90</sub>	6	6	Α
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	75	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.6	0.6	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	-55 to +150	°C
Maximum Lead Temperature for SolderingTL	260	260	°C

#### NOTE:

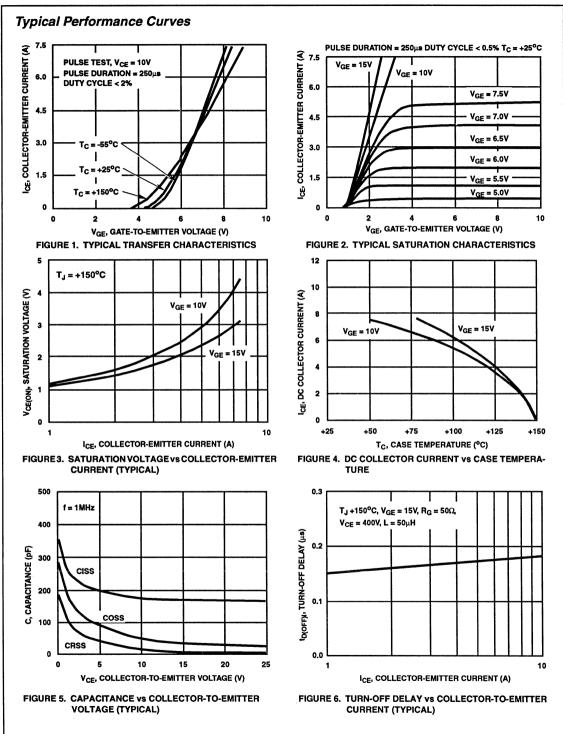
1.  $T_J = +150^{\circ}$ C, Min.  $R_{GE} = 25\Omega$  without latch.

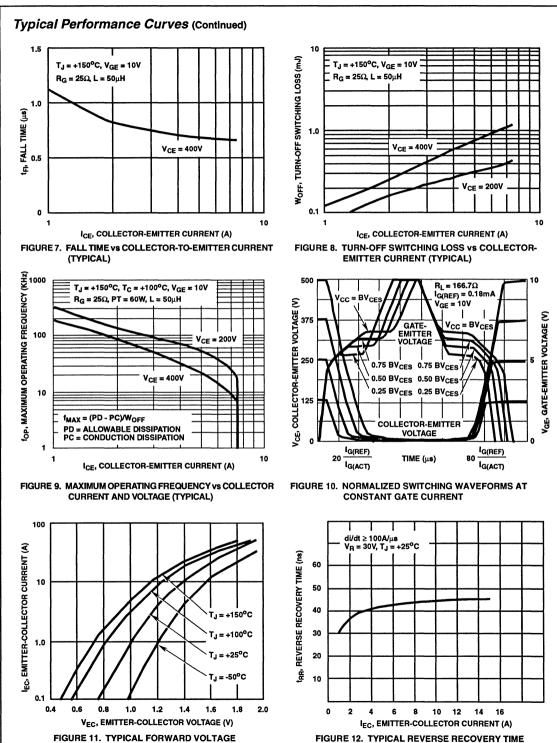
HARRIS S	EMICONDUCTO	OR IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S.	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
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4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1993

				LIM	ITS		
			HGTP6N40E1D HGTP6N5			N50E1D	
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	MAX	MIN MAX		UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1.25mA, V <sub>GE</sub> = 0V	400	-	500	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v
Zero Gate Voltage Collector	I <sub>CES</sub>	T <sub>J</sub> = +150°C, V <sub>CE</sub> = 400V	-	1.25	-	-	mA
Current		T <sub>J</sub> = +150°C, V <sub>CE</sub> = 500V	-	-		1.25	mA
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0V$	-	100		100	nA
Collector-Emitter On-Voltage	V <sub>CE(ON)</sub>	T <sub>J</sub> = +150°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 10V	-	2.9	-	2.9	v
		$T_J = +150^{\circ}C, I_C = 3A, V_{GE} = 15V$	-	2.5		2.5	v
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 3A, V <sub>GE</sub> = 15V	-	2.4	-	2.4	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 3A, V <sub>CE</sub> = 10V	6.5 (typ)				v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 3A, V <sub>CE</sub> = 10V	6.9 (typ)			nC	
Turn-On Delay Time	t <sub>D(ON)</sub>	Resistive Load, I <sub>C</sub> = 3A, 90 (typ)					ns
Rise Time	t <sub>R</sub>	$V_{CE} = 400V, R_L = 133\Omega,$ $T_J = +150^{\circ}C, V_{GE} = 10V,$		32 (typ)			
Turn-Off Delay Time	t <sub>D(OFF)</sub>	$R_{G} = 25\Omega$	24 (typ) 1100 (typ) 0.29 (typ)				ns
Fall Time	t <sub>F</sub>	1					ns
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>						mJ
Turn-Off Delay Time	t <sub>D(OFF)</sub> i	Inductive Load (See Figure 13),	-	190	-	190	ns
Fall Time	t <sub>FI</sub>	$I_{C} = 3A, V_{CE(CLP)} = 400V, R_{L} = 133\Omega,$ L = 50µH, T <sub>J</sub> = +150°C, V <sub>GE</sub> = 10V,	-	1	-	1	μs
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$R_{G} = 25\Omega$	-	0.43	-	0.43	mJ
Thermal Resistance Junction-to- Case (IGBT)	R <sub>ŧJC</sub>		-	2.08	-	2.08	°C/W
Thermal Resistance of Diode	R <sub>eJC</sub>		-	2.00	-	2.00	°C/W
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 6A	· 1	1.6	-	1.6	v
Diode Reverse Recovery Time	t <sub>BB</sub>	I <sub>EC</sub> = 6A, dI <sub>EC</sub> /dt = 100A/µs		60	-	60	ns

IGBTs





IGBTs

3

Test Circuit

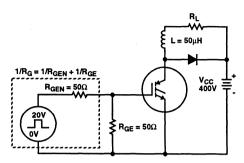


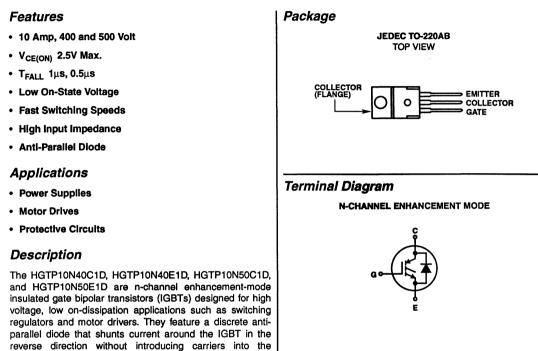
FIGURE 13. INDUCTIVE SWITCHING TEST CIRCUIT



December 1993

## HGTP10N40C1D, HGTP10N40E1D HGTP10N50C1D, HGTP10N50E1D

10A, 400V and 500V N-Channel IGBTs with Anti-Parallel Ultrafast Diodes



They are supplied in the JEDEC TO-220AB plastic package.

depletion region. These types can be operated directly from

low power integrated circuits.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

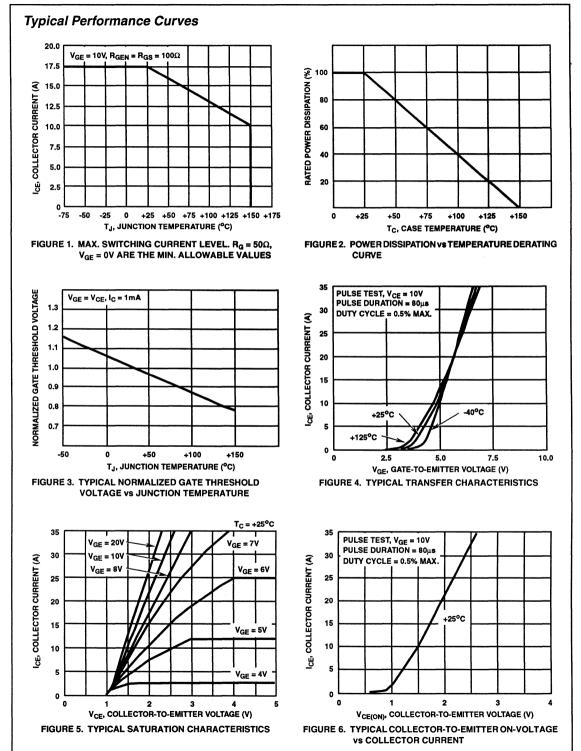
					HGTP10N40C1D HGTP10N40E1D	HGTP10N50C1 HGTP10N50E1	-
ollector-Emitter V	/oltage			V <sub>CES</sub>	400	500	v
ollector-Gate Vol	tage $R_{GE} = 1M\Omega$			V <sub>CGR</sub>	400	500	v
ate-Emitter Volta	ge			V <sub>GE</sub>	±20	±20	v
ollector Current C	Continuous at To	= +25°C		I <sub>C25</sub>	17.5	17.5	Α
	at T <sub>c</sub>	= +90°C		I <sub>C90</sub>	10	10	
ower Dissipation	Total at T <sub>C</sub> = +25	°C		Pp	75	75	w
	Derating T <sub>C</sub> > +2				0.6	0.6	W/ºC
perating and Sto	rage Junction Te	mperature Range	••••••	T <sub>J</sub> , T <sub>STG</sub>	-55 to +150	-55 to +150	°C
HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR	MORE OF THE FOL	LOWING U.S. PAT	ENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951

**GBTs** 

#### Specifications HGTP10N40C1D, HGTP10N40E1D, HGTP10N50C1D, HGTP10N50E1D

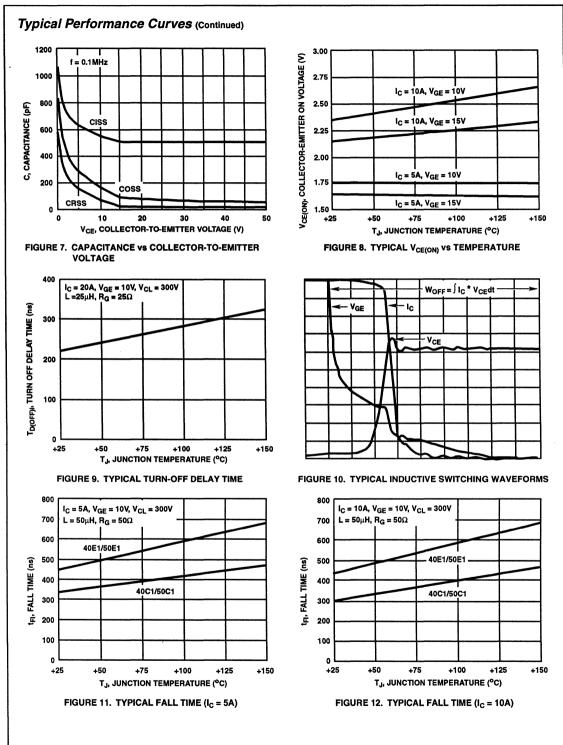
<i>i</i>				LIM	ITS			
			HGTP10N40C1D, HGTP10N40E1D		HGTP10N50C1D, HGTP10N50E1D			
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	МАХ	MIN	MAX	UNITS	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1mA, V <sub>GE</sub> = 0	400	-	500	-	v	
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v	
Zero Gate Voltage Collector Current	ICES	V <sub>CE</sub> = 400V, T <sub>C</sub> = +25°C	-	250	-	-	μA	
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +25°C	-	-		250	μΑ	
		V <sub>CE</sub> = 400V, T <sub>C</sub> = +125°C	-	1000	-	-	μΑ	
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +125°C	-	-	-	1000	μΑ	
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V, V <sub>CE</sub> = 0	-	100	-	100	nA	
Collector-Emitter On Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 10A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	V	
		l <sub>C</sub> = 17.5A, V <sub>GE</sub> = 20V	-	3.2	-	3.2	v	
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	6 (typ)		6 (typ)	v	
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	19 (typ)	-	19 (typ)	nC	
Turn-On Delay Time	t <sub>D(ON)</sub> i	l <sub>C</sub> = 10A, V <sub>CE(CLP)</sub> = 300V, L = 50μH, T <sub>J</sub> = +100°C,	-	50	-	50	ns	
Rise Time	t <sub>RI</sub>	$V_{GE} = 10V, R_G = 50\Omega$	-	50	-	50	ns	
Turn-Off Delay Time	t <sub>D(OFF)</sub> i		-	400	-	400	ns	
Fall Time	t <sub>FI</sub>							
40E1D, 50E1D			680 (typ)	1000	680 (typ)	1000	ns	
40C1D, 50C1D			400 (typ)	500	400 (typ)	500	ns	
Turn-Off Energy Loss per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$    I_{C} = 10A, V_{CE(CLP)} = 300V, \\    L = 50 \mu H, T_{J} = +100^{\circ}C, \\    V_{GE} = 10V, R_{G} = 50 \Omega $						
40E1D, 50E1D				1810	) (typ)		μ	
40C1D, 50C1D	1			1070	) (typ)		μ	
Thermal Resistance Junction-to-Case	R <sub>eJC</sub>		-	1.67	-	1.67	°C/W	
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 10A	-	2	-	2	v	
Diode Reverse Recovery Time	t <sub>RR</sub>	I <sub>EC</sub> = 10A, di/dt = 100A/µs		100	-	100	ns	

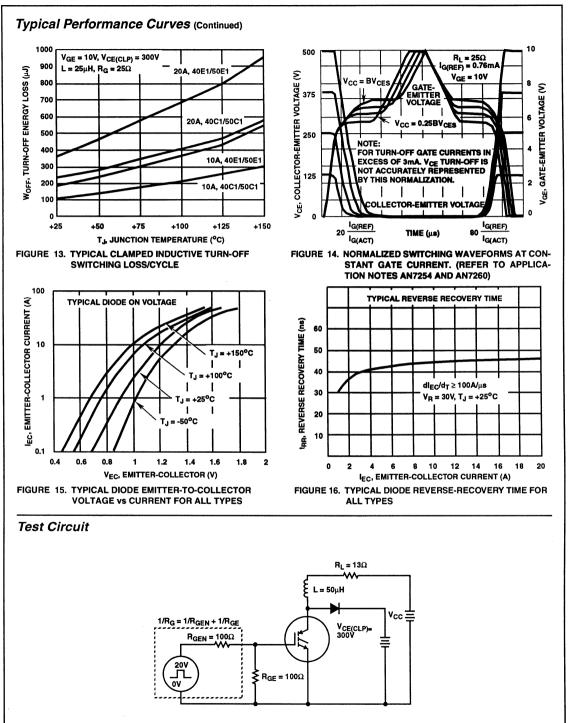
Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

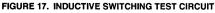


3

IGBTs







GBTs

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December 1993

#### Features

- 10 Amp, 400 and 500 Volt
- Latch Free Operation
- Typical Fall Time < 1.4μs
- High Input Impedance
- Low Conduction Loss
- With Anti-Parallel Diode
- t<sub>RR</sub> < 60ns

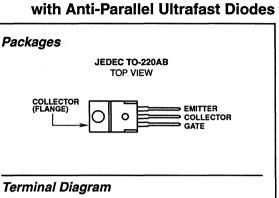
#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C. The diode used in parallel with the IGBT is an ultrafast ( $t_{RR} < 60$ ns) with soft recovery characteristic.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

These devices are supplied in the JEDEC TO-220AB package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified



HGTP10N40F1D

HGTP10N50F1D

10A, 400V and 500V N-Channel IGBTs

#### N-CHANNEL ENHANCEMENT MODE



			HGTP10N40F1D	HGTP10N50F1D	UNITS
Collector-Emitter Voltage		BV <sub>CES</sub>	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$			400	500	v
Collector Current Continuous at T <sub>C</sub> = +	25°C	I <sub>C25</sub>	12	12	Α
at $T_c = +$	90°C	I <sub>C90</sub>	10	10	Α
Collector Current Pulsed (Note 1)		I <sub>см</sub>	12	12	Α
Gate-Emitter Voltage Continuous			±20	±20	v
Diode Forward Current at T <sub>C</sub> = +25°C		I <sub>F25</sub>	16	16	Α
			10	10	Α
Power Dissipation Total at $T_{C} = +25^{\circ}C$			75	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C			0.6	0.6	W/ºC
Operating and Storage Junction Tempe	rature Range	T <sub>J</sub> , T <sub>STG</sub>	-55 to +150	-55 to +150	°C
Maximum Lead Temperature for Solder	ing	T <sub>L</sub>	260	260	°C
NOTE:					
1. $T_J = +150^{\circ}C$ , Min. $R_{GE} = 25\Omega$ with	ut latch.				
HARRIS SEMICONDUCTOR	GBT PRODUCT IS COVEREI	BY ONE OR	MORE OF THE FOL	LOWING Ú.S. PATEI	NTS:
4 364 073 4 417 385	4 430 792 4 443 931	4 466 176	4 516 143	4 532 534 4	67 641

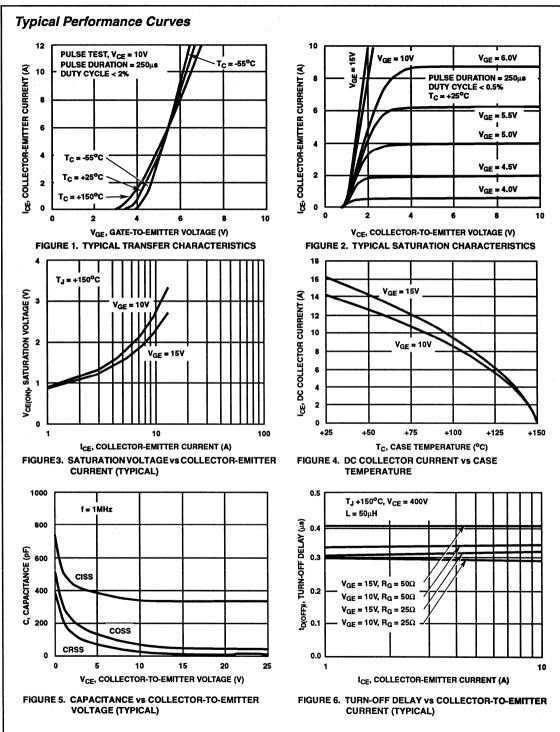
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

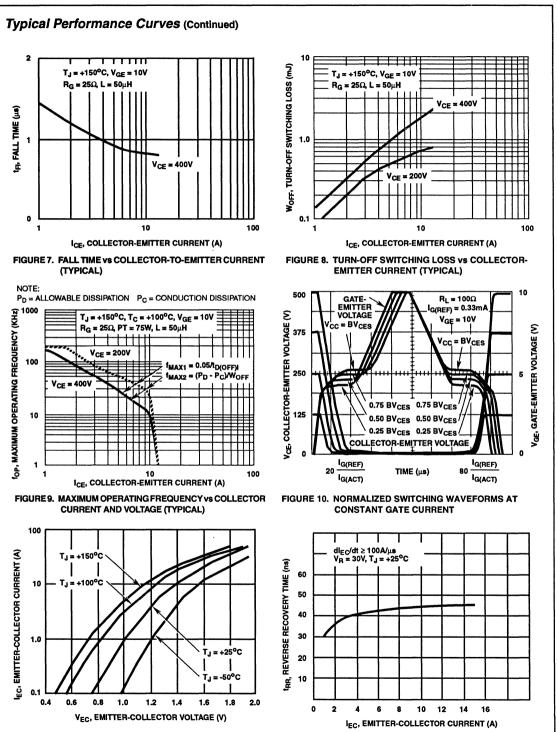
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1993

			HGTP10	0N40F1D	HGTP10N50F1D		Ì
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN MAX		MIN MAX		UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1.25mA, V <sub>GE</sub> = 0V	400	-	500	-	V ·
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v
Zero Gate Voltage Collector	I <sub>CES</sub>	T <sub>J</sub> = +150°C, V <sub>CE</sub> = 400V	-	1.25	-	-	mA
Current		T <sub>J</sub> = +150°C, V <sub>CE</sub> = 500V	-	-	-	1.25	mA
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0V$	-	100	-	100	nA
Collector-Emitter On-Voltage	V <sub>CE(ON)</sub>	T <sub>J</sub> = +150°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
		T <sub>J</sub> = +150°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 15V	-	2.2	-	2.2	v
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
		T <sub>J</sub> = +25°C, I <sub>C</sub> = 5A, V <sub>GE</sub> = 15V	-	2.2	-	2.2	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	5.3 (typ)		v		
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	/ <sub>CE</sub> = 10V 13.4 (typ)				nC
Turn-On Delay Time	t <sub>D(ON)</sub>	$D(ON)$ Resistive Load, $I_C = 5A$ , 45 (typ)					ns
Rise Time	t <sub>RI</sub>	$ \begin{array}{c} V_{CE} = 400V, \ R_L = 80\Omega, \\ T_J = +150^\circ C, \ V_{GE} = 10V, \end{array} \end{array} $					ns
Turn-Off Delay Time	t <sub>D(OFF)</sub>	$R_{G} = 25\Omega$		130	(typ)		ns
Fall Time	t <sub>FI</sub>			1400	) (typ)		ns
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>		0.64 (typ)				mJ
Turn-Off Delay Time	t <sub>D(OFF)</sub> I	Inductive Load (See Figure 13),	-	375	-	375	ns
Fall Time	t <sub>FI</sub>	$I_{C} = 5A, V_{CE(CLP)} = 400V, R_{L} = 80\Omega,$ L = 50µH, T <sub>J</sub> = +150°C, V <sub>GE</sub> = 10V,	-	1200	-	1200	ns
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$R_{G} = 25\Omega$	-	1.2	-	1.2	mJ
Thermal ResistanceJunction-to- Case (IGBT)	R <sub>tuc</sub>		-	1.67	-	1.67	°C/W
Thermal Resistance of Diode	R <sub>eJC</sub>		-	2.0	-	2.0	°C/W
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 10A	•	1.7	-	1.7	v
Diode Reverse Recovery Time	t <sub>RR</sub>	I <sub>EC</sub> = 10A, dI <sub>EC</sub> /dt = 100A/μs		60	<u> </u>	60	ns

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

IGBTs





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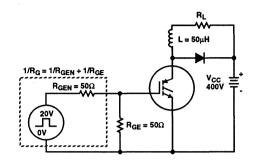
GBTs

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FIGURE 12. TYPICAL REVERSE RECOVERY TIME

FIGURE 11. TYPICAL FORWARD VOLTAGE

#### Test Circuit



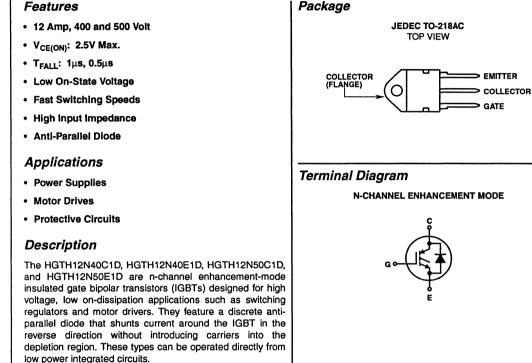
#### FIGURE 13. INDUCTIVE SWITCHING TEST CIRCUIT



December 1993

## HGTH12N40C1D, HGTH12N40E1D HGTH12N50C1D. HGTH12N50E1D

#### 12A, 400V and 500V N-Channel IGBTs with Anti-Parallel Ultrafast Diodes



They are supplied in the JEDEC TO-218AC plastic package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	HGTH12N40C1D HGTH12N40E1D	HGTH12N50C1D HGTH12N50E1D	UNITS
Collector-Emitter Voltage V <sub>CES</sub>	400	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$	400	500	v
Gate-Emitter Voltage	±20	±20	v
Collector Current ContinuousIc	12	12	Α
Collector Current Pulsed	17.5	17.5	Α
Power Dissipation Total at $T_{C} = +25^{\circ}C$ $P_{D}$	75	75	W
Power Dissipation Derating $T_{C} > +25^{\circ}C$	0.6	0.6	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	-55 to +150	°C

HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MO	DRE OF THE FOLLOWING U.S. PATENTS:
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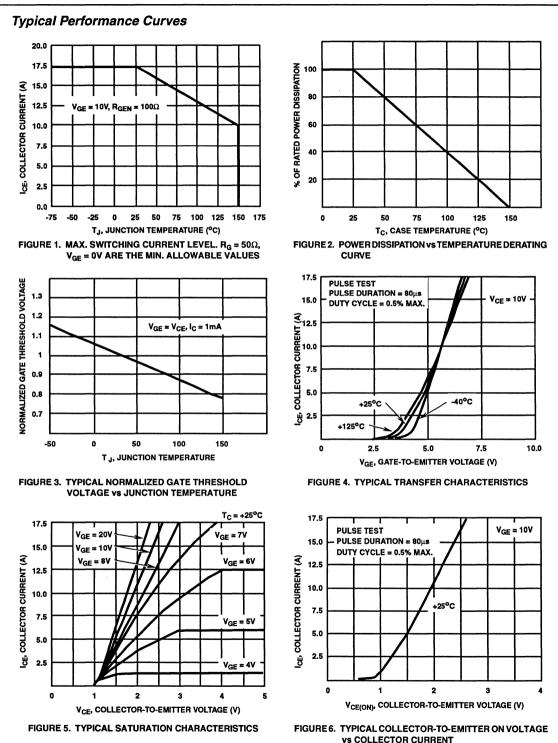
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

GBTs

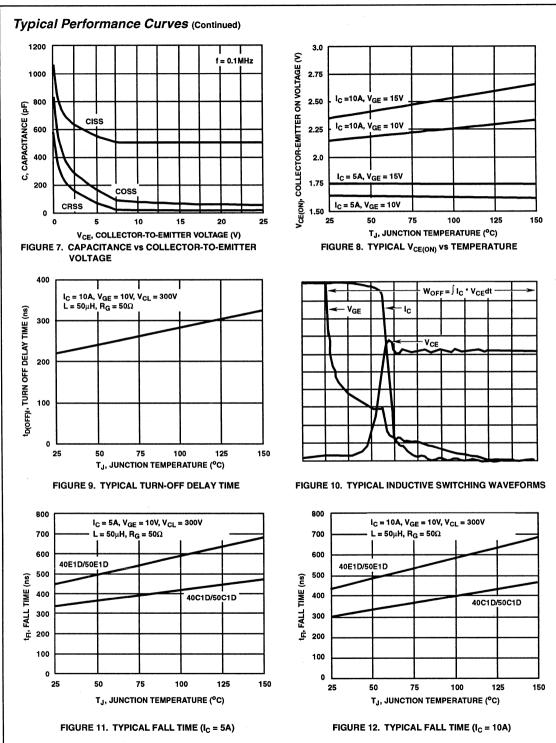
Electrical Specifications T <sub>c</sub> = +28	5°C, Unless Otherwise Specified
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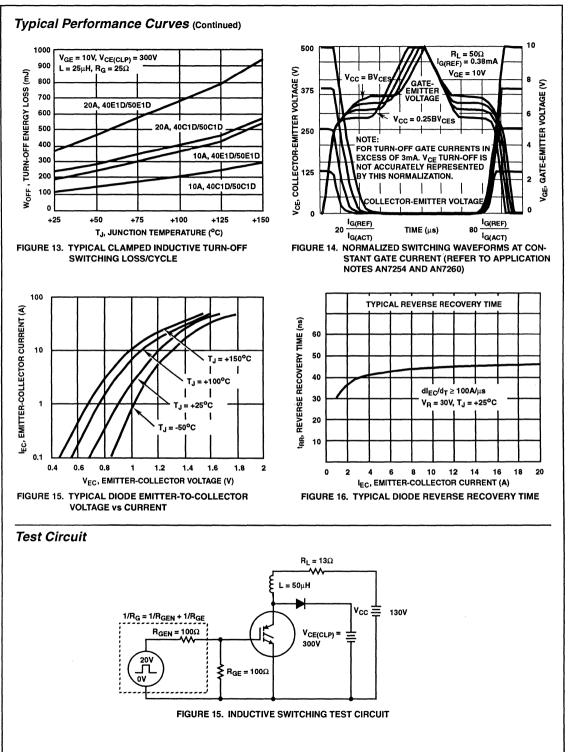
			LIMITS				
				N40C1D, 2N40E1D		N50C1D, 2N50E1D	
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	MAX	MIN	MAX	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1mA, V <sub>GE</sub> = 0	400	-	500	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v
Zero Gate Voltage Collector Current	I <sub>CES</sub>	V <sub>CE</sub> = 400V, T <sub>C</sub> = +25°C		250	-	-	μA
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	250	μA
		V <sub>CE</sub> = 400V, T <sub>C</sub> = +125°C	-	1000	-	-	μΑ
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +125°C	-	-	-	1000	μA
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0$	-	100	-	100	nA
Collector-Emitter On Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 10A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
		I <sub>C</sub> = 17.5A, V <sub>GE</sub> = 20V	-	3.2	-	3.2	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	6 (typ)	-	6 (typ)	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 5A, V <sub>CE</sub> = 10V	-	19 (typ)	-	19 (typ)	nC
Turn-On Delay Time	t <sub>D(ON)</sub> I	$I_{C} = 10A, V_{CE(CLP)} = 300V,$ L = 50µH, T <sub>J</sub> = +100°C,	-	50	-	50	ns
Rise Time	t <sub>RI</sub>	$V_{GE} = 10V, R_G = 50\Omega$ See Note 9	•	50	-	50	ns
Turn-Off Delay Time	t <sub>D(OFF)</sub> i	346 1016 9	-	400	•	400	ns
Fall Time	t <sub>FI</sub>						
40E1D, 50E1D			680 (typ)	1000	680 (typ)	1000	ns
40C1D, 50C1D			400 (typ)	500	400 (typ)	500	ns
Turn-Off Energy Loss per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$    I_{C} = 10A, V_{CE(CLP)} = 300V, \\     L = 50 \mu H, T_{J} = +100^{\circ}C, \\     V_{GE} = 10V, R_{G} = 50 \Omega $					
40E1D, 50E1D				1810	) (typ)		ω
40C1D, 50C1D			1070 (typ)			μ	
Thermal Resistance Junction-to-Case	R <sub>eJC</sub>		-	1.67	-	1.67	°c∕w
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 10A	-	2	-	2	v
Diode Reverse Recovery Time	t <sub>RR</sub>	l <sub>EC</sub> = 10A, dl <sub>EC</sub> /dt = 100A/μs	-	100	-	100	ns



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IGBTs





**IGBTs** 

# HARRIS HGTG12N60D1D

#### December 1993

#### Features

- 12 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time <500ns</li>
- Low Conduction Loss
- With Anti-Parallel Diode
- t<sub>RR</sub> < 60ns

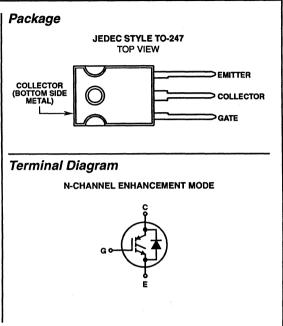
#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C. The diode used in parallel with the IGBT is an ultrafast (t<sub>BB</sub> < 60ns) with soft recovery characteristic.

The IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC style TO-247 package.

#### 12A, 600V N-Channel IGBT with Anti-Parallel Ultrafast Diode



#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	HGTG12N60D1D	UNITS
Collector-Emitter VoltageBV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	600	v
Collector Current Continuous at T <sub>C</sub> = +25°Cl <sub>C25</sub>	21	Α
at $T_{C} = +90^{\circ}C$	12	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	48	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±20	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	30A at 0.8 BV <sub>CES</sub>	-
Diode Forward Current at T <sub>C</sub> = +25°C I <sub>F25</sub>	21	Α
at $T_{C} = +90^{\circ}C$ I <sub>F90</sub>	12	Α
Power Dissipation Total at $T_C \approx +25^{\circ}C$ P <sub>D</sub>	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.6	W/°C
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.125 inches from case for 5 seconds)	260	°C

#### NOTE:

1. Repetitive Rating: Pulse width limited by maximum junction temperature.

HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR M	ORE OF THE FO	LLOWING U.S.	PATENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080 4,969,027	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

File Number 2800.3

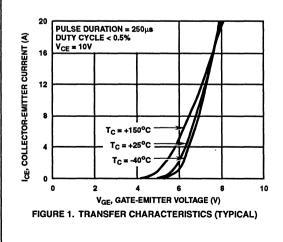
				LIMITS			
PARAMETERS	SYMBOL	TEST COND	ITIONS	MIN	ТҮР	MAX	
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 280μA, V <sub>GE</sub> = 0V		600	-	-	v
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	280	μΑ
		V <sub>CE</sub> = 0.8 BV <sub>CES</sub>	T <sub>C</sub> = +125⁰C	-	-	5.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> , V <sub>GE</sub> = 15V	T <sub>C</sub> = +25°C	-	1.9	2.5	v
			T <sub>C</sub> = +125°C	-	2.1	2.7	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 250μA, V <sub>CE</sub> = V <sub>G</sub>	$I_{C} = 250\mu A$ , $V_{CE} = V_{GE}$ , $T_{C} = +25^{\circ}C$		4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	V <sub>GE</sub> = ±20V		-	-	±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{C} = I_{C90}, V_{CE} = 0.5 \text{ BV}_{CES}$		-	7.2	-	v
On-State Gate Charge	$Q_{G(ON)}$ $I_{C} = I_{C90},$ $V_{CE} = 0.5 \text{ BV}_{CES}$	V <sub>GE</sub> = 15V	-	45	60	nC	
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	-	70	90	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub>	L = 500µH, I <sub>C</sub> = I <sub>C90</sub> , I		-	100	-	ns
Current Rise Time	t <sub>Ri</sub>	$V_{GE} = 15V, T_J = +150$ $V_{CE} = 0.8 BV_{CES}$	°C,	-	150	-	ns
Current Turn-Off	t <sub>D(OFF)</sub> i			-	430	600	ns
Current Fall Time	t <sub>FI</sub>			-	430	600	ns
Turn-Off Energy (Note 1)	WOFF			•	1.8	-	mJ
Thermal Resistance IGBT	R <sub>NC.</sub>			-	-	1.67	°C/W
Thermal Resistance Diode	R <sub>NC</sub>			-	-	1.5	°C/W
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 12A		-	-	1.50	v
Diode Reverse Recovery Time	t <sub>AR</sub>	I <sub>EC</sub> = 12A, dI <sub>EC</sub> /dt = 1	00A/μs	-	-	60	ns

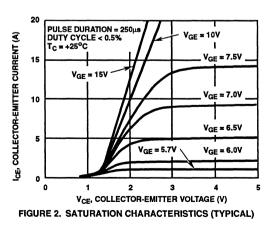
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

NOTE:

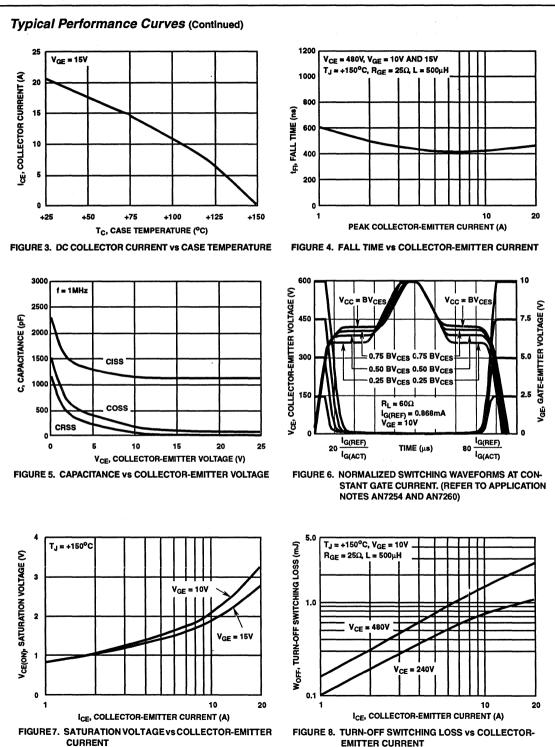
 Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A). The HGTG12N60D1D was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-off Switching Loss. This test method produces the true total Turn-off Energy Loss.

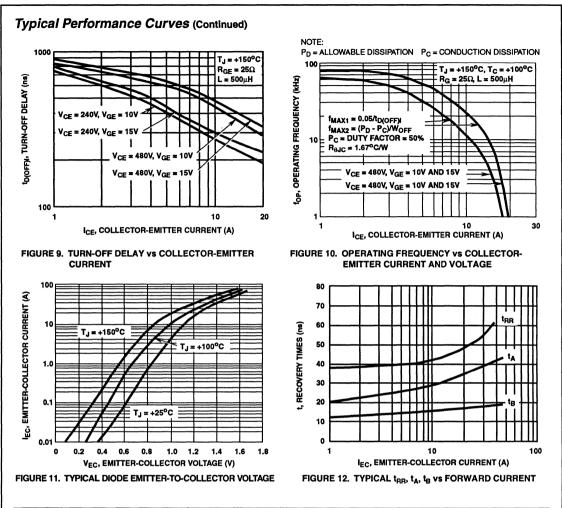
#### **Typical Performance Curves**





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#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temeprature.

 $f_{MAX1}$  is defined by  $f_{MAX1}=0.05/t_{D(OFF)I}$ .  $t_{D(OFF)I}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)I}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device turn-off delay can establish an additional

frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D - P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{eJC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) so that the conduction losses  $(P_C)$  can be approximated by  $P_C$  =  $(V_{CE} \times I_{CE})/2$ . W\_{OFF} is defined as the sum of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero  $(I_{CE} - 0A)$ .

The switching power loss (Figure 10) is defined as  $f_{MAX1} \ x \ W_{OFF}$  Turn on switching losses are not included because they can be greatly influenced by external circuit conditions and components.

3-105

# HARRIS HGTG20N50C1D

#### December 1993

#### Features

- 20 Amp, 500 Volt
- Latch Free Operation
- Typical Fall Time < 500ns
- High Input Impedance
- Low Conduction Loss
- With Anti-Parallel Diode
- t<sub>RR</sub> < 60ns

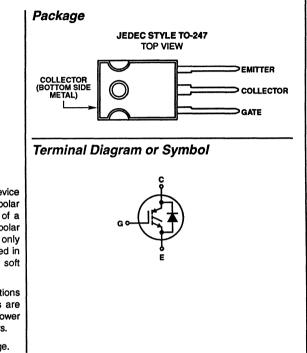
#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C. The diode used in parallel with the IGBT is an ultrafast ( $t_{\rm RR}$  < 60ns) with soft recovery characteristic.

IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contractors.

This type is supplied in the JEDEC style TO-247 package.

## 20A, 500V N-Channel IGBT with Anti-Parallel Ultrafast Diode



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	HGTG20N50C1D	UNITS
Collector-Emitter VoltageBV <sub>CES</sub>	500	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGR}$	500	V
Collector Current Continuous at T <sub>C</sub> = +25°Cl <sub>C25</sub>	26	Α
at $T_{C} \approx +90^{\circ}C$	20	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	35	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±20	v
Diode Forward Current at T <sub>C</sub> = +25°CI <sub>F25</sub>	26	Α
at $T_{C} = +90^{\circ}C$ I <sub>F90</sub>	20	Α
Power Dissipation Total at T <sub>C</sub> = +25°CP <sub>D</sub>	75	w
Power Dissipation Derating T <sub>C</sub> > +25°C	0.8	W/°C
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL	260	°C
NOTE: 1. $T_J = +150^{\circ}$ C, Minimum $R_{GE} = 25\Omega$ without latch		

#### HARRIS SEMICONDUCTOR IGBT PRODUCT IS COVERED BY ONE OR MORE OF THE FOLLOWING U.S. PATENTS:

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641	
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762	
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690	
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606	
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951	
4,969,027								

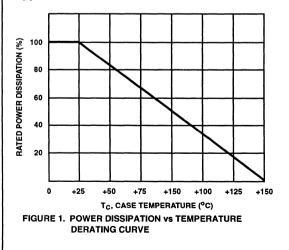
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures.

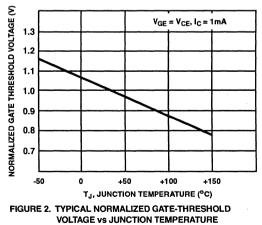
Copyright C Harris Corporation 1993

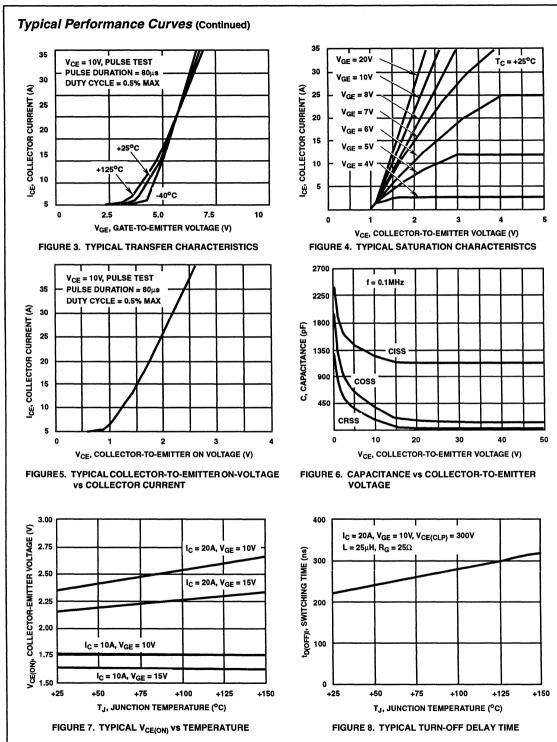
			LIMITS		
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	MAX	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	I <sub>C</sub> = 1mA, V <sub>GE</sub> = 0V	500	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2	4.5	v
Zero Gate Voltage Collector Current	I <sub>CES</sub>	V <sub>CE</sub> = 500V	-	250	μΑ
		T <sub>C</sub> = +125°C, V <sub>CE</sub> = 500V	-	1000	μΑ
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V, V_{CE} = 0V$		100	nA
Collector-Emitter On-Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = 20A, V <sub>GE</sub> = 10V	-	2.5	v
		I <sub>C</sub> = 35A, V <sub>GE</sub> = 20V	-	3.2	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V	-	6 (typ)	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V	-	33 (typ)	nC
Turn-On Delay Time	t <sub>D(ON)</sub> I	$I_{C} = 20A, V_{CE(CLP)} = 300V, L = 25\mu H,$	·	50	ns
Rise Time	t <sub>RI</sub>	$T_{J} = +100^{\circ}C, V_{GE} = 10V, R_{G} = 25\Omega$		50	ns
Turn-Off Delay Time	t <sub>D(OFF)</sub> i		•	400	ns
Fall Time	t <sub>FI</sub>	1	400 (typ)	500	ns
Turn-Off Energy Loss Per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	W <sub>OFF</sub>	$    I_{C} = 20 \text{A}, V_{CE(CLP)} = 300 \text{V}, L = 25 \mu \text{H}, \\ T_{J} = +100^{\circ}\text{C}, V_{GE} = 10 \text{V}, R_{G} = 25 \Omega $	1070 (typ)		μJ
Thermal ReisstanceJunction-to-Case (IGBT)	R <sub>ejc</sub>		-	1.25	°C/W
Thermal Resistance of Diode	R <sub>eJC</sub>		-	1.5	ns
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 20A	-	1.8	v
Diode Reverse Recovery Time	t <sub>RR</sub>	I <sub>EC</sub> = 20A, di <sub>EC</sub> /dt = 100A/μs	-	60	ns

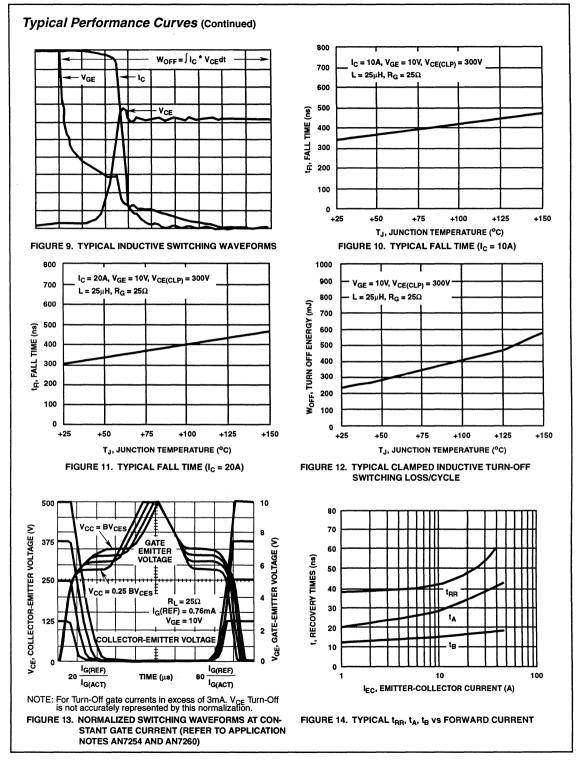
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

#### Typical Performance Curves



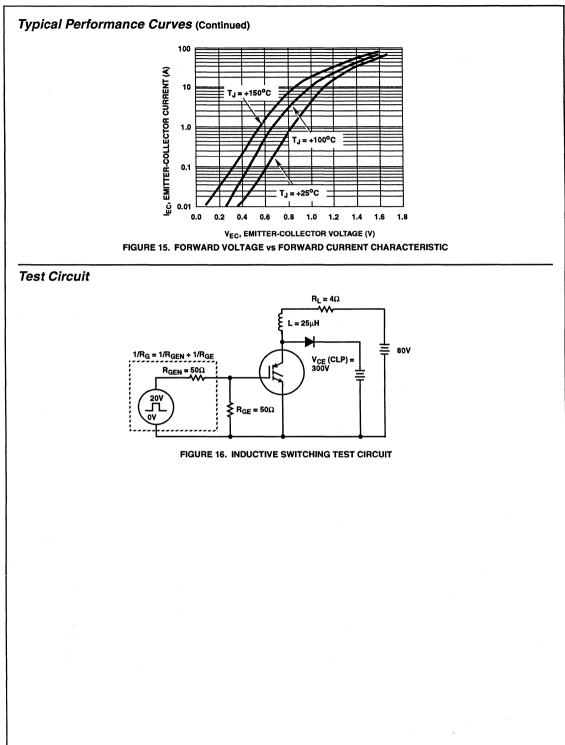






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GBTs





December 1993

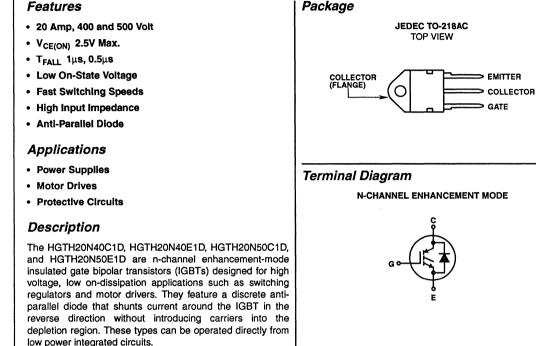
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4,969,027

4,883,767

## HGTH20N40C1D, HGTH20N40E1D HGTH20N50C1D, HGTH20N50E1D

20A, 400V and 500V N-Channel IGBTs with Anti-Parallel Ultrafast Diodes



They are supplied in the JEDEC TO-218AC plastic package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

					HGTH20N40C1D HGTH20N40E1D	HGTH20N50C1 HGTH20N50E1	-
Collector-Emitter \	/oltage			V <sub>CES</sub>	400	500	v
Collector-Gate Vol	tage $R_{GE} = 1M\Omega$			V <sub>CGR</sub>	400	500	v
Gate-Emitter Volta	ge			V <sub>GE</sub>	±20	±20	v
Collector Current (					20	20	A
Collector Current I	Pulsed			I <sub>CM</sub>	35	35	А
Diode Forward Cu	rrent Continuous	at T <sub>C</sub> = +25°C .		I <sub>F25</sub>	35	35	А
		at $T_{J} = +90^{\circ}C$		I <sub>F90</sub>	20	20	А
Power Dissipation	Total at T <sub>C</sub> = +25	°C		P <sub>D</sub>	100	100	w
Power Dissipation					0.8	0.8	W/ºC
Operating and Sto	rage Junction Te	mperature Range		T <sub>J</sub> , T <sub>STG</sub>	-55 to +150	-55 to +150	°C
HARRIS S	EMICONDUCTO	R IGBT PRODU	CT IS COVERED	BY ONE OR	MORE OF THE FOI	LOWING U.S. PAT	ENTS:
4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4.837.606

4,901,127

4,904,609

4,933,740

4,890,143

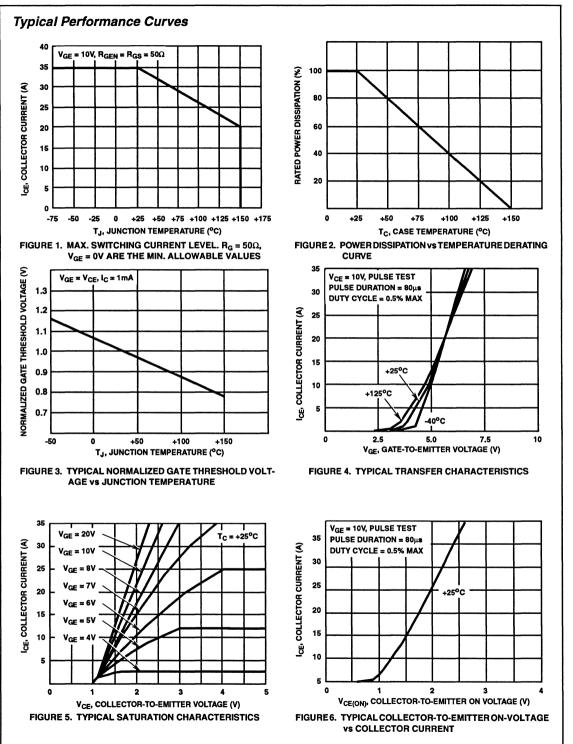
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright <sup>©</sup> Harris Corporation 1993 3-111

4,888,627

4,963,951

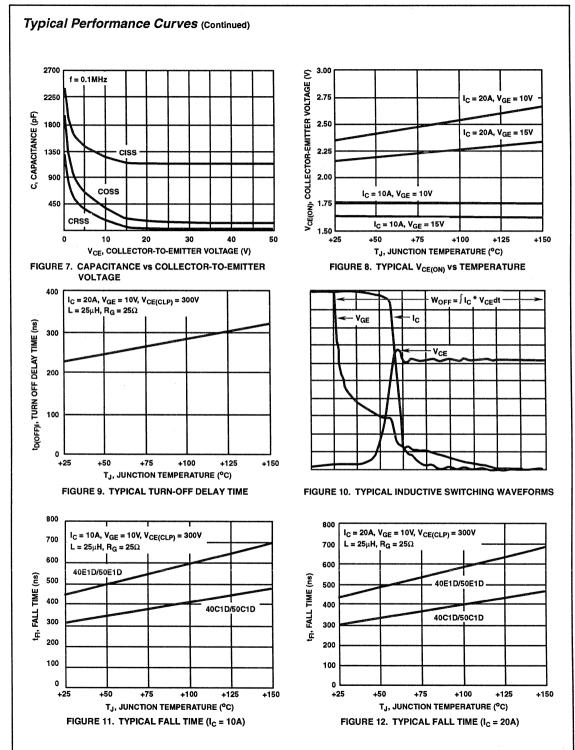
Electrical Specifications  $T_{C} = +25^{\circ}C$ , Unless Otherwise Specified

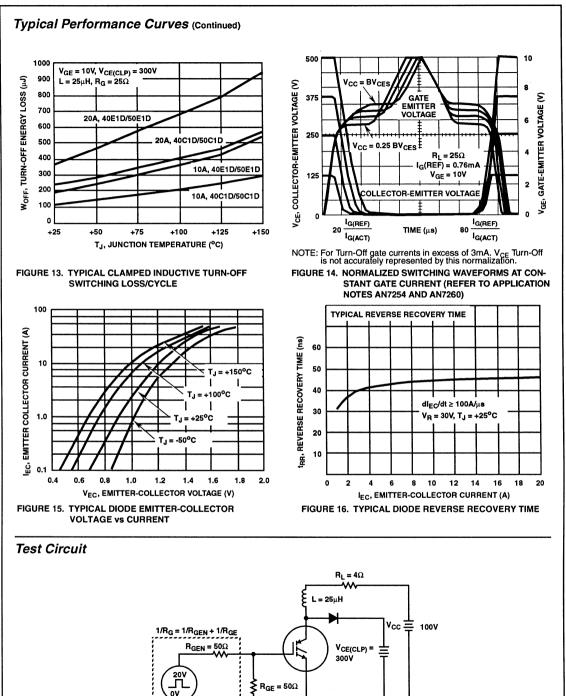
			HGTH20 HGTH20		HGTH20 HGTH20		
PARAMETERS	SYMBOL	TEST CONDITIONS	MIN	МАХ	MIN	МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	l <sub>C</sub> = 1mA, V <sub>GE</sub> = 0	400	-	500	-	v
Gate Threshold Voltage	V <sub>GE(TH)</sub>	V <sub>GE</sub> = V <sub>CE</sub> , I <sub>C</sub> = 1mA	2.0	4.5	2.0	4.5	v
Zero Gate Voltage Collector Current	I <sub>CES</sub>	V <sub>CE</sub> = 400V, T <sub>C</sub> = +25°C		250	•	-	μA
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	250	μA
		V <sub>CE</sub> = 400V, T <sub>C</sub> = +125°C	-	1000	-	-	μΑ
		V <sub>CE</sub> = 500V, T <sub>C</sub> = +125°C	-	-	-	1000	μA
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$ , $V_{CE} = 0$	-	100	-	100	nA
Collector-Emitter On Voltage	V <sub>CE(ON)</sub>	I <sub>C</sub> = 20A, V <sub>GE</sub> = 10V	-	2.5	-	2.5	v
· · · ·		I <sub>C</sub> = 35A, V <sub>GE</sub> = 20V	-	3.2	-	3.2	v
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V	-	6 (typ)	-	6 (typ)	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = 10A, V <sub>CE</sub> = 10V	-	33 (typ)	-	33 (typ)	nC
Turn-On Delay Time	t <sub>D(ON)</sub> i	I <sub>C</sub> = 20A, V <sub>CE(CLP)</sub> = 300V, L = 25µH, T <sub>J</sub> = +100°C,	-	50	-	50	ns
Rise Time	t <sub>RI</sub>	$V_{GE} = 10V, R_G = 25\Omega$	-	50	-	50	ns
Turn-Off Delay Time	t <sub>D(OFF)</sub> i		-	400	-	400	ns
Fall Time	t <sub>Fi</sub>						
40E1D, 50E1D			680 (typ)	1000	680 (typ)	1000	ns
40C1D, 50C1D			400 (typ)	500	400 (typ)	500	ns
Turn-Off Energy Loss per Cycle (Off Switching Dissipation = W <sub>OFF</sub> x Frequency)	WOFF	$ \begin{split} &I_{C} = 20\text{A}, \ V_{CE(CLP)} = 300\text{V}, \\ &L = 25\mu\text{H}, \ T_{J} = +100^{\circ}\text{C}, \\ &V_{GE} = 10\text{V}, \ R_{G} = 25\Omega \end{split} $					
40E1D, 50E1D				181(	) (typ)		μ
40C1D, 50C1D	1			1070	) (typ)		μ
Thermal Resistance Junction-to-Case	R <sub>eJC</sub>		-	1.25	-	1.25	°C/W
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 20A		2	-	2	v
Diode Reverse Recovery Time	t <sub>BB</sub>	I <sub>EC</sub> = 20A, dI <sub>EC</sub> /dt = 100A/μs	-	100	-	100	ns

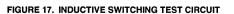


3

GBTs







3

IGBTs

# HARRIS HGTG24N60D1D

December 1993

### 24A, 600V N-Channel IGBT with Anti-Parallel Ultrafast Diode

#### Features

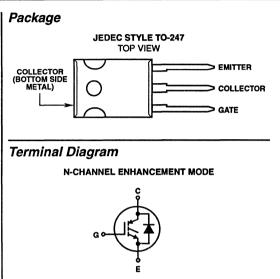
- 24 Amp, 600 Volt
- Latch Free Operation
- Typical Fall Time <500ns</li>
- Low Conduction Loss
- With Anti-Parallel Diode
- t<sub>RR</sub> < 60ns

#### Description

The IGBT is a MOS gated high voltage switching device combining the best features of MOSFETs and bipolar transistors. The device has the high input impedance of a MOSFET and the low on-state conduction loss of a bipolar transistor. The much lower on-state voltage drop varies only moderately between +25°C and +150°C. The diode used in parallel with the IGBT is an ultrafast (t<sub>BB</sub> < 60ns) with soft recovery characteristic.

The IGBTs are ideal for many high voltage switching applications operating at frequencies where low conduction losses are essential, such as: AC and DC motor controls, power supplies and drivers for solenoids, relays and contactors.

This type is supplied in the JEDEC style TO-247 package.



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specific

	HGTG24N60D1D	UNITS
Collector-Emitter Voltage BV <sub>CES</sub>	600	v
Collector-Gate Voltage $R_{GE} = 1M\Omega$ $BV_{CGB}$	600	v
Collector Current Continuous at $T_c = +25^{\circ}C$	40	А
at $T_{C} = +90^{\circ}C$	24	Α
Collector Current Pulsed (Note 1) I <sub>CM</sub>	96	Α
Gate-Emitter Voltage ContinuousV <sub>GES</sub>	±25	v
Switching Safe Operating Area at T <sub>J</sub> = +150°CSSOA	60A at 0.8 BV <sub>CES</sub>	-
Diode Forward Current at $T_c = +25^{\circ}CI_{F25}$	40	Α
at $T_{\rm C} = +90^{\circ}$ CI <sub>F90</sub>	24	Α
Power Dissipation Total at T <sub>C</sub> = +25°C P <sub>D</sub>	125	w
Power Dissipation Derating T <sub>C</sub> > +25°C	1.0	W/ºC
Operating and Storage Junction Temperature Range	-55 to +150	°C
Maximum Lead Temperature for SolderingTL (0.125 inch from case for 5 seconds)	260	°C
NOTE: 1. Repetitive Rating: Pulse width limited by maximum junction temperature.		

4,364,073	4,417,385	4,430,792	4,443,931	4,466,176	4,516,143	4,532,534	4,567,641
4,587,713	4,598,461	4,605,948	4,618,872	4,620,211	4,631,564	4,639,754	4,639,762
4,641,162	4,644,637	4,682,195	4,684,413	4,694,313	4,717,679	4,743,952	4,783,690
4,794,432	4,801,986	4,803,533	4,809,045	4,809,047	4,810,665	4,823,176	4,837,606
4,860,080	4,883,767	4,888,627	4,890,143	4,901,127	4,904,609	4,933,740	4,963,951
4,969,027							

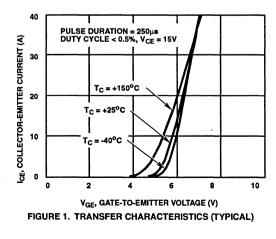
CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright C Harris Corporation 1993

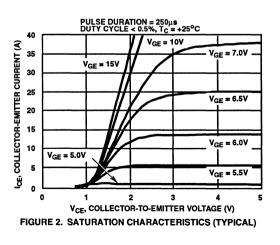
						J	
PARAMETERS	SYMBOL	TEST CON	DITIONS	MIN	ТҮР	МАХ	UNITS
Collector-Emitter Breakdown Voltage	BV <sub>CES</sub>	$I_C = 280 \mu A$ , $V_{GE} =$	I <sub>C</sub> = 280μA, V <sub>GE</sub> = 0V			-	v
Collector-Emitter Leakage Voltage	ICES	V <sub>CE</sub> = BV <sub>CES</sub>	T <sub>C</sub> = +25°C	-	-	280	μΑ
		$V_{CE} = 0.8 \text{ BV}_{CES}$	T <sub>C</sub> = +125°C	-	-	5.0	mA
Collector-Emitter Saturation Voltage	V <sub>CE(SAT)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	T <sub>C</sub> = +25°C	-	1.7	2.3	v
		V <sub>GE</sub> = 15V	T <sub>C</sub> = +125°C	-	1.9	2.5	v
Gate-Emitter Threshold Voltage	V <sub>GE(TH)</sub>	I <sub>C</sub> = 250μA, V <sub>CE</sub> = V <sub>GE</sub>	T <sub>C</sub> = +25°C	3.0	4.5	6.0	v
Gate-Emitter Leakage Current	I <sub>GES</sub>	$V_{GE} = \pm 20V$		-	-	±500	nA
Gate-Emitter Plateau Voltage	V <sub>GEP</sub>	$I_{C} = I_{C90}, V_{CE} = 0.5 \text{ BV}_{CES}$		-	6.3	-	v
On-State Gate Charge	Q <sub>G(ON)</sub>	I <sub>C</sub> = I <sub>C90</sub> ,	V <sub>GE</sub> = 15V	-	120	155	nC
		$V_{CE} = 0.5 BV_{CES}$	V <sub>GE</sub> = 20V	-	155	200	nC
Current Turn-On Delay Time	t <sub>D(ON)</sub> I	$L = 500 \mu H, I_{C} = I_{CS}$	<sub>90</sub> , R <sub>G</sub> = 25Ω,	-	100	-	ns
Current Rise Time	t <sub>RI</sub>	$V_{GE} = 15V, T_{J} = +$ $V_{CE} = 0.8 BV_{CES}$	150°C,	-	150	-	ns
Current Turn-Off Delay Time	t <sub>D(OFF)</sub>			-	700	900	ns
Current Fall Time	t <sub>F1</sub>	1		-	450	600	ns
Turn-Off Energy (Note 1)	WOFF	1		-	4.3	-	mJ
Thermal Resistance (IGBT)	R <sub>eJC</sub>			-	-	1.00	°C/W
Thermal Resistance Diode	R <sub>eJC</sub>			-	-	1.50	°C/W
Diode Forward Voltage	V <sub>EC</sub>	I <sub>EC</sub> = 24A		-	-	1.50	v
Diode Reverse Recovery Time	t <sub>RR</sub>	I <sub>EC</sub> = 24A, di/dt = 1	100A/µs	-	-	60	ns

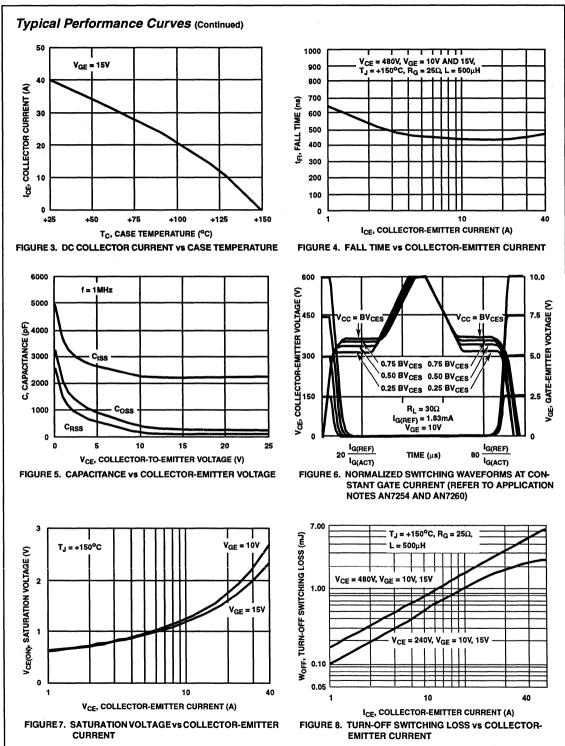
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

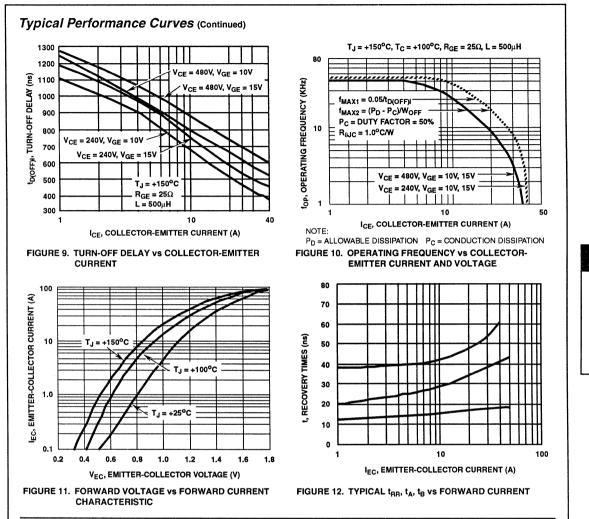
NOTE: 1. Turn-off Energy Loss (W<sub>OFF</sub>) is defined as the integral of the instantaneous power loss starting at the trailing idge of the input pulse and ending at the point where the collector current equals zero (I<sub>CE</sub> = 0A) The HGTG24N60D1D was tested per JEDEC standard No. 24-1 Method for Measurement of Power Device Turn-Off Switching Loss. This test method produces the true total Turn-Off Energy Loss.

#### **Typical Performance Curves**









#### **Operating Frequency Information**

Operating frequency information for a typical device (Figure 10) is presented as a guide for estimating device performance for a specific application. Other typical frequency vs collector current ( $I_{CE}$ ) plots are possible using the information shown for a typical unit in Figures 7, 8 and 9. The operating frequency plot (Figure 10) of a typical device shows  $f_{MAX1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.

 $f_{MAX1}$  is defined by  $f_{MAX1}=0.05/t_{D(OFF)l}$ .  $t_{D(OFF)l}$  deadtime (the denominator) has been arbitrarily held to 10% of the onstate time for a 50% duty factor. Other definitions are possible.  $t_{D(OFF)l}$  is defined as the time between the 90% point of the trailing edge of the input pulse and the point where the collector current falls to 90% of its maximum value. Device

turn-off delay can establish an additional frequency limiting condition for an application other than  $T_{JMAX}$ .  $t_{D(OFF)I}$  is important when controlling output ripple under a lightly loaded condition.

3

GBT

 $f_{MAX2}$  is defined by  $f_{MAX2}$  =  $(P_D$  -  $P_C)/W_{OFF}$  The allowable dissipation  $(P_D)$  is defined by  $P_D$  =  $(T_{JMAX} - T_C)/R_{\theta JC}$ . The sum of device switching and conduction losses must not exceed  $P_D$  A 50% duty factor was used (Figure 10) and the conduction losses  $(P_C)$  are approximated by  $P_C$  =  $(V_{CE} \bullet I_{CE})/2$ .  $W_{OFF}$  is defined as the integral of the instantaneous power loss starting at the trailing edge of the input pulse and ending at the point where the collector current equals zero ( $I_{CE}$  = 0A).

The switching power loss (Figure 10) is defined as  $f_{MAX2} \cdot W_{OFF}$ Turn-on switching losses are not included because they can be greatly influenced by external circuit conditions and components.

# **MCT/IGBT/DIODES**

## **GENERAL PURPOSE DIODES**

		PAGE
SELECTION GUIDE	E	4-2
GENERAL PURPOS	SE DIODE DATA SHEETS	
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1N5059, 1N5060, 1N5061, 1N5062	1A, 200V - 800V Diodes	4-6
1N5624, 1N5625, 1N5626, 1N5627	3A, 200V - 800V Diodes	4-9
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## 

HARRIS STANDARD AND FAST RECOVERY RECTIFIER PRODUCT LINE

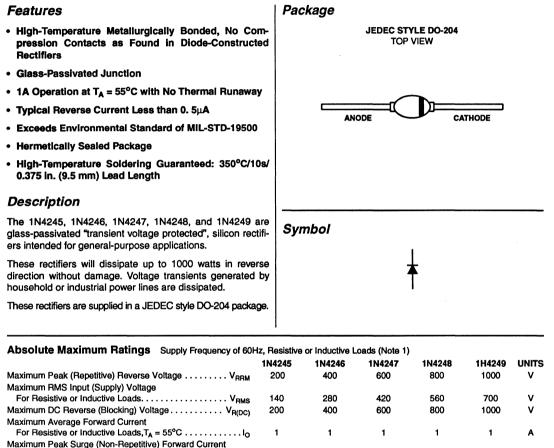
	DO-204				AI	3	BR-4
		I <sub>F(AVG)</sub> I <sub>F(,</sub>		I <sub>F(AVG)</sub> I <sub>F(AVG)</sub>			I <sub>F(AVG)</sub>
V <sub>RRM</sub>	1A	1A	1A	1A	3A	3A	1A
50V	A14F		GER4001	A114F	A15F	A115F	DB1F
100V	A14A		GER4002	A114A	A15A	A115A	DB1A
150V							
200V	1N5059	1N4245	GER4003	A114B	1N5624	A115B	DB1B
300V	A14C			A114C		A115C	
400V	1N5060	1N4246	GER4004	A114D	1N5625	A115D	DB1D
500V	A14E			A114E	I	A115E	
600V	1N5061	1N4247	GER4005	A114M	1N5626	A115M	DB1M
800V	1N5062	1N4248	GER4006		1N5627		DB1N
1000V	A14P	1N4249	GER4007				DB1P
t <sub>RR</sub> (µsec)	5/6	5		0.2	5	0.15/0.25	



## 1N4245, 1N4246, 1N4247 1N4248, 1N4249

#### December 1993

### 1A, 200V - 1000V Diodes



Maximum Peak Surge (Non-Repetitive) Forward Current						
For 8.3ms Half Sine Wave, Superimposed on Rated Load,						
T <sub>A</sub> = 55° C I <sub>FSM</sub>	50	50	50	50	50	Α
Operating Temperature Range	-65 to +160	°C				
Storage Temperature Range	-65 to +200	°C				
NOTE:						

1. In accordance with JEDEC registration format.

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1993

#### Specifications 1N4245, 1N4246, 1N4247, 1N4248, 1N4249

		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop (at 1A) (Note 1)	V <sub>F</sub>	-	-	1.2	v
Maximum Reverse Current: (Note 1)					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	1	μΑ
At Maximum DC Reverse (Blocking) Voltage, $T_A = +125^{\circ}C$	I <sub>R</sub>	-	-	25	μΑ
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm), $T_A = 55^{\circ}C$	1 <sub>R</sub>	-	-	50	μA
Junction Capacitance (at 1MHz and Applied Reverse Voltage = 4V)	Сј	-	15	-	pF

NOTE:

1. In accordance with JEDEC registration format.

#### **Typical Performance Curves**

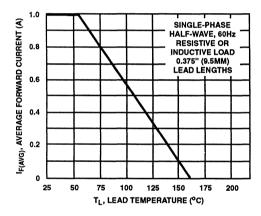


FIGURE 1. MAXIMUM AVERAGE FORWARD OUTPUT CURRENT CHARACTERISTIC

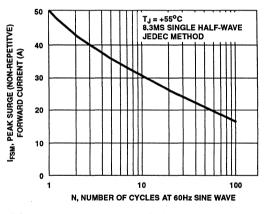
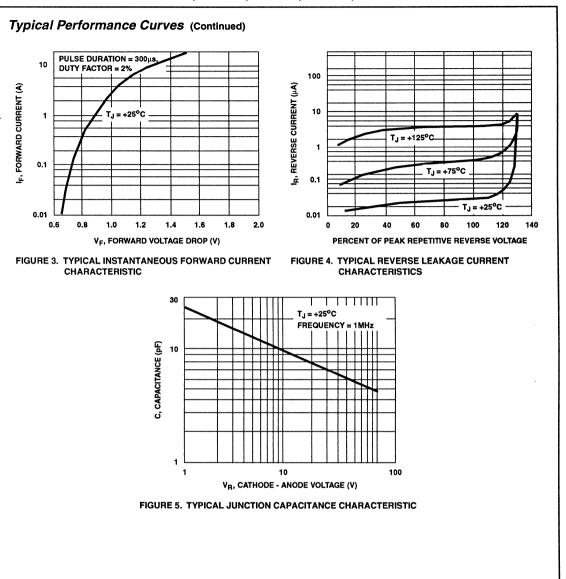


FIGURE 2. MAXIMUM PEAK SURGE (NON-REPETITIVE) FORWARD CURRENT CHARACTERISTIC



4

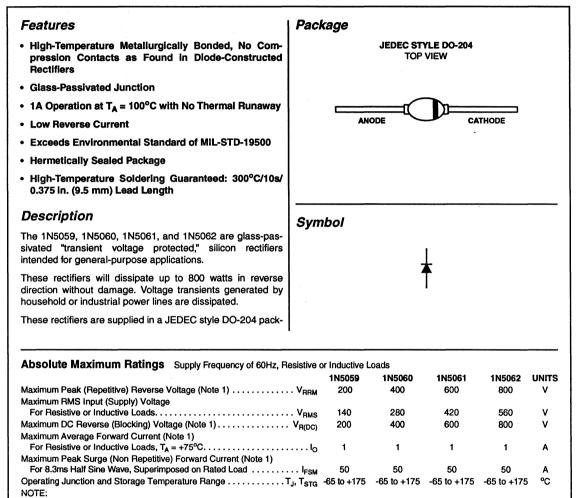
GENERAL PURPOSE DIODES



# 1N5059, 1N5060 1N5061, 1N5062

#### December 1993

#### 1A, 200V - 800V Diodes



1. In accordance with JEDEC registration format.

		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop (Note 1) At 1A, T <sub>A</sub> = +75°C	V <sub>F</sub>	-	-	1.2	v
Maximum Full-Load Reverse Current					
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) T <sub>A</sub> = +25°C	I <sub>R</sub>	-	-	5	μΑ
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +175^{\circ}C$	۱ <sub>R</sub>	-	-	150 (Note 2)	μA
Maximum Reverse Current: (Note 1)					
At Average DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	5	μΑ
At Maximum DC Reverse (Blocking) Voltage, $T_A = +175^{\circ}C$	1 <sub>R</sub>	-	-	300 (Note 3)	μА
Maximum Reverse Recovery Time					
At $I_F = 0.5A$ , $I_R = 1A$ , $I_{RR} = 0.25A$	I <sub>R</sub>	-	-	2	μs
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	CJ	-	15	-	pF

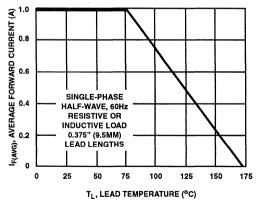
NOTES:

1. In accordance with JEDEC registration format.

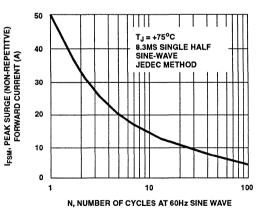
2.  $100\mu A$  for 1N5061 and 1N5062.

3. 200µA for 1N5061 and 1N5062.

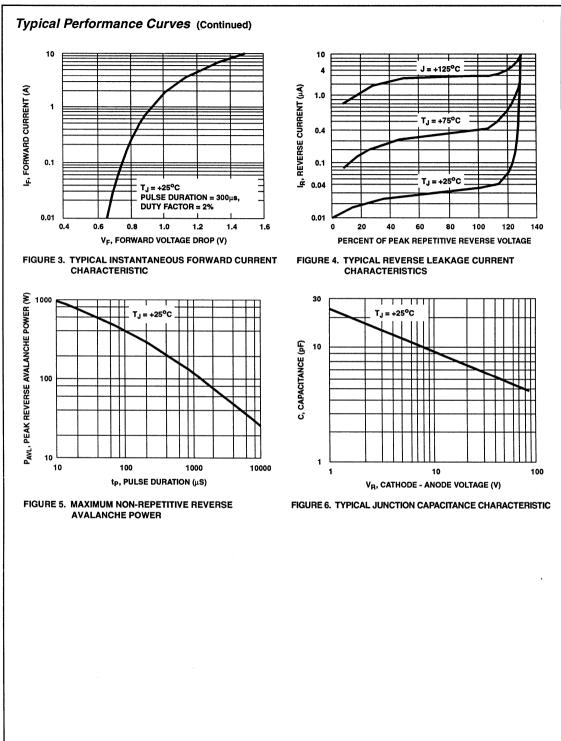
### Typical Performance Curves













# 1N5624, 1N5625 1N5626, 1N5627

3A, 200V - 800V Diodes

#### December 1993

#### Features

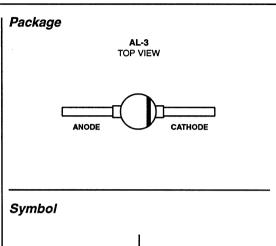
- High Temperature Metallurgically Bbonded, No Compression Contacts as Found in Diode-Constructed Rectifiers
- Glass Passivated Junction
- 3A Operation at T<sub>A</sub> +70°C with No Thermal Runaway
- Low Reverse Leakage Current
- Exceeds Environmental Standard of MIL-STD-19500
- Hermetically Sealed Package
- High Temperature Soldering: 350° C/10s/0.375 in. (9.5mm) Lead Length

### Description

The 1N5624, 1N5625, 1N5626, and 1N5627 are glass-passivated "transient voltage protected," silicon rectifiers intended for general-purpose applications.

These rectifiers will dissipate up to 800 watts in reverse direction without damage. Voltage transients generated by household or industrial power lines are dissipated.

These rectifiers are supplied in a AL-3 package.



Absolute Maximum Ratings For Single Phase, 60Hz, Half-Wave Resistive or Inductive Loads (Note 1) 1N5624 1N5625 1N5626 1N5627 UNITS Maximum Peak (Repetitive) Reverse Voltage (Note 2) .....V<sub>BBM</sub> 400 600 200 800 v Maximum RMS Input (Supply) Voltage For Resistive or Inductive Loads. 140 280 420 560 v Maximum DC Reverse (Blocking) Voltage (Note 2) . . . . . . . . . . . V<sub>B(DC)</sub> 200 400 600 800 v Maximum Average Forward Current (Note 2) For Resistive or Inductive Loads, T<sub>A</sub> = +75°C..... I<sub>O</sub> 3 3 3 3 Α Maximum Peak Surge Forward Current (Note 2) For 8.3ms Half Sine Wave, Superimposed on Rated Load .....IFSM 125 125 125 125 А -65 to +175 °C -65 to +200 -65 to +200 °C NOTES:

1. For capacitive load derate current by 20%.

2. In accordance with JEDEC registration format.

		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	MAX	UNITS
Maximum Instantaneous Forward-Voltage Drop (Note 1)					
At 3A, T <sub>A</sub> = +25°C	V <sub>F</sub>	•	-	1.0	v
At 3A, T <sub>A</sub> = +70°C	V <sub>F</sub>	-	-	0.95	v
Maximum Full-Load Reverse Current (Note 1)					
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +70^{\circ}C$	I <sub>R</sub>	-	-	150 (Note 2)	μΑ
Maximum Reverse Current (Note 1)					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	i <sub>R</sub>	-	-	5	μA
At Maximum DC Reverse (Blocking) Voltage, T <sub>A</sub> = +175°C	I <sub>R</sub>	-	-	300 (Note 3)	μΑ
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	C <sup>1</sup>	-	40	-	pF

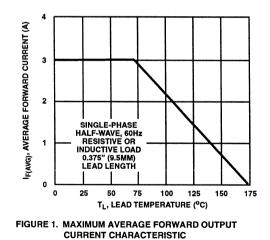
NOTES:

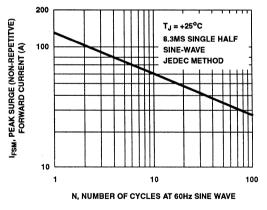
1. In accordance with JEDEC registration format.

2.  $100\mu A$  for 1N5626 and 1N5627.

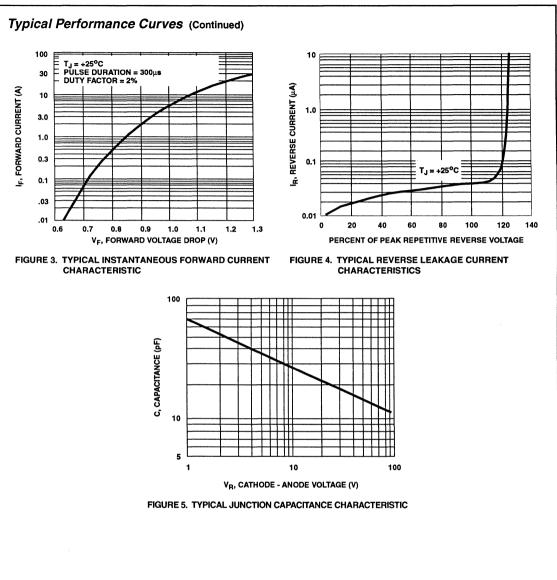
3. 200 $\mu A$  for 1N5624 and 1N5625.

#### **Typical Performance Curves**







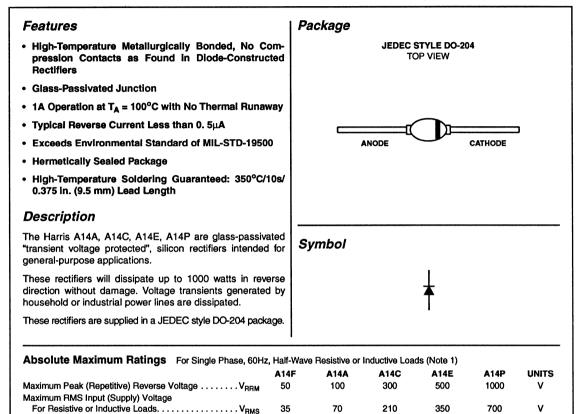




# A14A, A14C, A14E A14F, A14P

December 1993

#### 1A, 50V - 1000V Diodes



50

1

50

Operating Junction and Storage Temperature .....TJ TSTG -65 to +175 -65 to +175 -65 to +175 -65 to +175 -65 to +175

100

1

50

300

1

50

500

1

50

1000

1

50

ν

A

°C

Maximum DC Reverse (Blocking) Voltage ..... V<sub>R(DC)</sub>

Maximum Peak Surge (Non-Repetitive) Forward Current: For 8.3ms Half Sine Wave, Superimposed

For Resistive or Inductive Loads;  $T_A = 100^{\circ}C....l_{O}$ 

on Rated Load .....IFSM

Maximum Average Forward Output Current

1. For capactive load derate current by 20%.

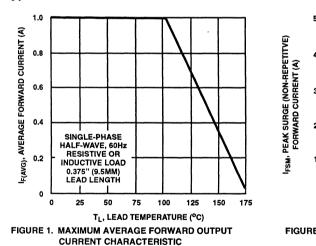
NOTE:

PARAMETERS		LIMITS FOR ALL TYPES			
	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop At 1A	V <sub>F</sub>	-	-	1.2 (Note 1)	v
Maximum Full-Load Reverse Current					
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = 100^{\circ}C$	۱ <sub>R</sub>	-	-	200	μА
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage	I <sub>R</sub>	-	-	2	μА
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>	-	-	2	μs
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	CJ	-	15	-	pF

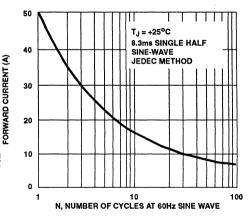
### Specifications A14A, A14C, A14E, A14F, A14P

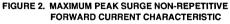
NOTE:

1. 1.1V for A14C, A14E, and A14P

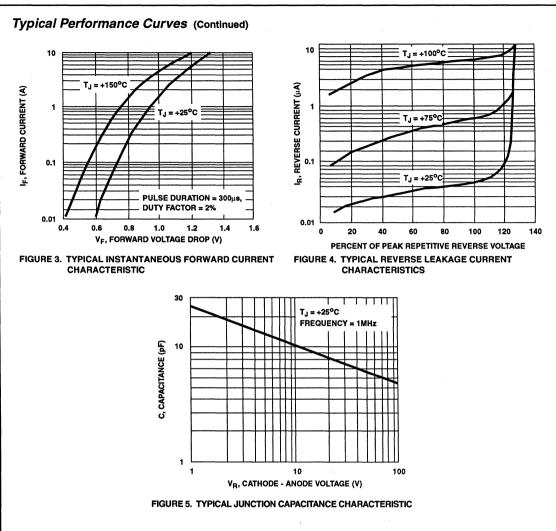








4 GENERAL PURPOSE DIODES





# A15A, A15F

#### December 1993

### 3A, 50V - 100V Diodes

#### Features Package · High-Temperature Metallurgically Bonded, No Com-AL-3 pression Contacts as Found in Diode-Constructed TOP VIEW **Rectifiers** Glass-Passivated Junction • 3A Operation at T<sub>A</sub> = 70°C with No Thermal Runaway Low Reverse Current ANODE CATHODE Exceeds Environmental Standard of MIL-STD-19500 Hermetically Sealed Package • High-Temperature Soldering: 350°C/10s/0.375 in. (9.5 mm) Lead Length Description Symbol The A15A and A15F are glass-passivated "transient voltage protected", silicon rectifiers intended for general-purpose applications. These rectifiers will dissipate up to 100 watts in reverse direction without damage. Voltage transients generated by household or industrial power lines are dissipated. These rectifiers are supplied in a AL-3 package. Absolute Maximum Ratings Supply Frequency of 60Hz, Resistive or Inductive Loads (Note 1) UNITS A15F A15A Maximum Peak (Repetitive) Reverse Voltage ..... VRRM 50 100 ν Maximum RMS Input (Supply) Voltage ...... V<sub>RMS</sub> 35 70 ν Maximum DC Reverse (Blocking) Voltage ..... V<sub>B(DC)</sub> 50 100 ν Maximum Average Forward Output Current А

Maximum Average Forward Output Current		
Lead Length = 0.375 in. (9.5mm); T <sub>A</sub> = 70°CI <sub>O</sub>	3	3
Maximum Peak Surge (Non-Repetitive) Forward Current		
For 8.3ms Half Sine Wave, Superimposed on Rated Load,	125	125
Operating Junction and Storage Temperature	-65 to +175	-65 to +17
NOTE:		

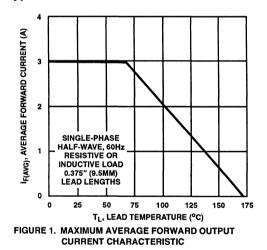
1. For capacitive load derate current by 20%.

5 A +175 °C

### Specifications A15A, A15F

		LIMITS FOR ALL TYPES			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop at 3A	V <sub>F</sub>	-	-	1.2	v
Maximum Full-Load Reverse Current					
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm), $T_A = 70^{\circ}C$	I <sub>R</sub>	-	-	200	μΑ
Maximum Reverse Current					
At Maximum DC Reverse (blocking) Voltage	I <sub>R</sub>		-	5	μА
Maximum Reverse Recovery Time					
At $I_F = 0.5A$ , $I_R = 1A$ , $I_{RR} = 0.25A$	t <sub>RR</sub>	-	-	3	μs
Typical Junction Capacitance					
At Frequency = 1MHz and Applied Reverse Voltage = 4V	С	-	40	-	pF

#### Typical Performance Curves



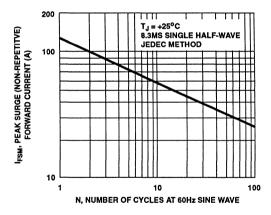
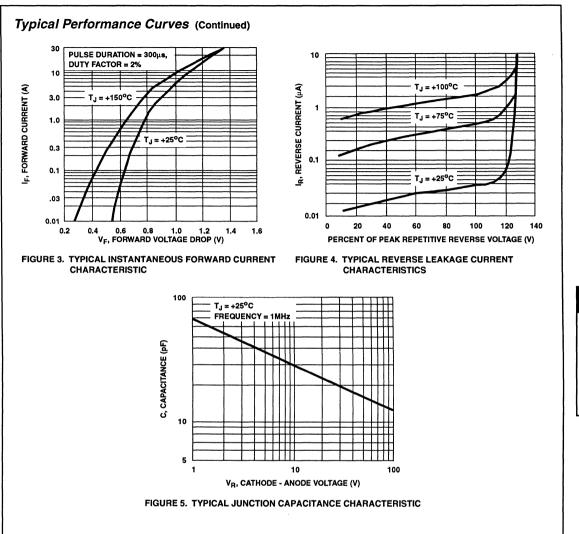


FIGURE 2. MAXIMUM PEAK SURGE (NON-REPETITIVE) FORWARD CURRENT CHARACTERISTIC



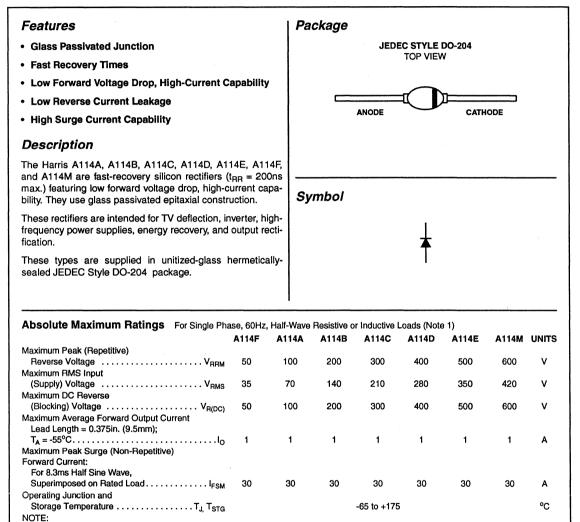
Δ



# A114 Series

#### December 1993

#### 1A, 50V - 600V Diodes



1. For capacitive load derate current by 20%.

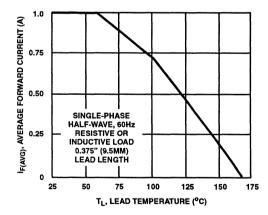
		LIMIT	S FOR ALL			
PARAMETERS	SYMBOL	MIN TYP MAX		МАХ	UNITS	
Maximum Instantaneous Forward-Voltage Drop						
At 1A	V <sub>F</sub>	-		1.3	v	
Maximum Full-Load Reverse Current						
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	1	μA	
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +150^{\circ}C$	I <sub>R</sub>	-	-	100	μA	
Maximum DC Reverse Current at Maximum DC Reverse (Blocking) Voltage	1 <sub>R</sub>	-	-	2	μA	
Maximum Reverse Recovery Time						
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>	-	-	150 (Note 1)	μs	
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	Cj	-	10	-	pF	

#### Electrical Specifications T<sub>A</sub> = +25°C, Unless Otherwise Specified

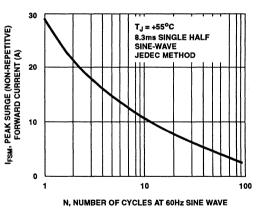
NOTE:

1. 200ns for A115M

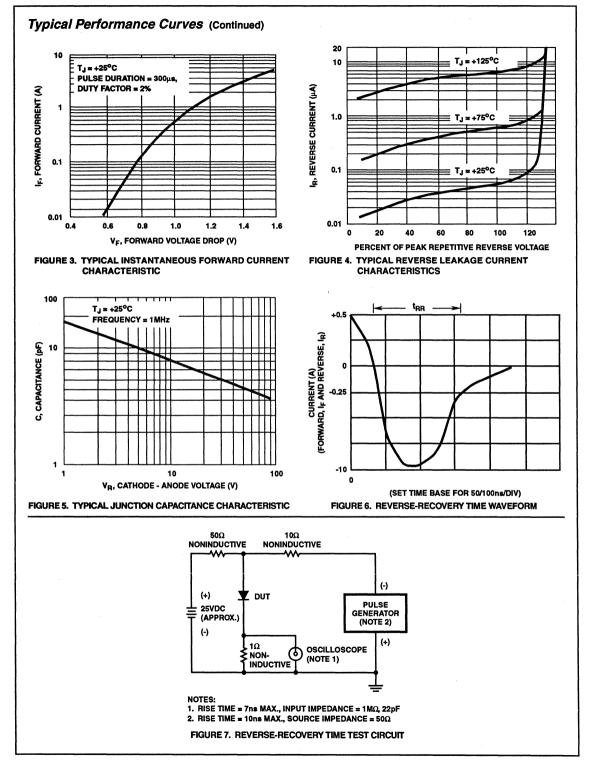
#### **Typical Performance Curves**













# A115 Series

3A, 50V - 600V Diodes

#### December 1993

#### Features

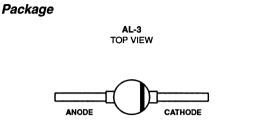
- Glass Passivated Junction
- Fast Recovery Times
- Low Forward Voltage Drop, High-Current Capability
- Low Reverse Current Leakage
- High Surge Current Capability

#### Description

The Harris A115A, A115B, A115C, A115D, A115E, A115F, and A115M are fast-recovery silicon rectifiers ( $t_{RR}$  = 250ns max.) featuring low forward voltage drop, high-current capability. They use glass passivated epitaxial construction.

These rectifiers are intended for TV deflection, inverter, highfrequency power supplies, energy recovery, and output rectification.

These types are supplied in unitized-glass hermetically-sealed AL-3 package.



Symbol



# GENERAL PURPOSE DIODES

	A115F	A115A	A115B	A115C	A115D	A115E	A115M	UNITS
/aximum Peak (Repetitive)								
Reverse Voltage	50	100	200	300	400	500	600	v
Aaximum RMS Input								
(Supply) Voltage V <sub>RMS</sub>	35	70	140	210	280	350	420	v
Aaximum DC Reverse								
Blocking) Voltage V <sub>R(DC)</sub>	50	100	200	300	400	500	600	v
Aximum Average Forward Output Current								
Lead Length = 0.375in. (9.5mm);								
$T_A = -55^{\circ}CI_O$	3	3	3	3	3	3	3	Α
faximum Peak Surge (Non-Repetitive)								
Forward Current:								
For 8.3ms Half Sine Wave,								
Superimposed on Rated Load IFSM	100	100	100	100	100	100	100	Α
Operating Junction and								
Storage Temperature				-65 to +175	i			°C
IOTE:								
1. For capacitive load derate current by 20%.								

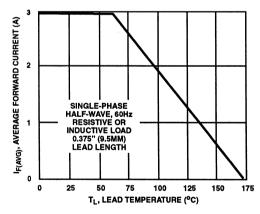
#### Specifications A115 Series

		LIMIT	LIMITS FOR ALL TYPES		
PARAMETERS	SYMBOL	MIN TYP N		МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop At 3A	V <sub>F</sub>	-	-	1.3	v
Maximum Full-Load Reverse Current					
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	2	μA
At Average Full-Cycle, Lead Length = 0.375 in. (9.5mm) $T_A = +150^{\circ}C$	I <sub>R</sub>	-	-	100	μA
Maximum DC Reverse Current at Maximum DC Blocking Voltage	I <sub>R</sub>	-	-	5	μА
Maximum Reverse Recovery Time					
At $I_F = 0.5A$ , $I_R = 1A$ , $I_{RR} = 0.25A$	t <sub>RR</sub>	-	-	150 (Note 1)	μs
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	CJ	-	40	-	pF

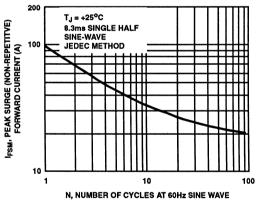
NOTE:

1. 250ns for A115M

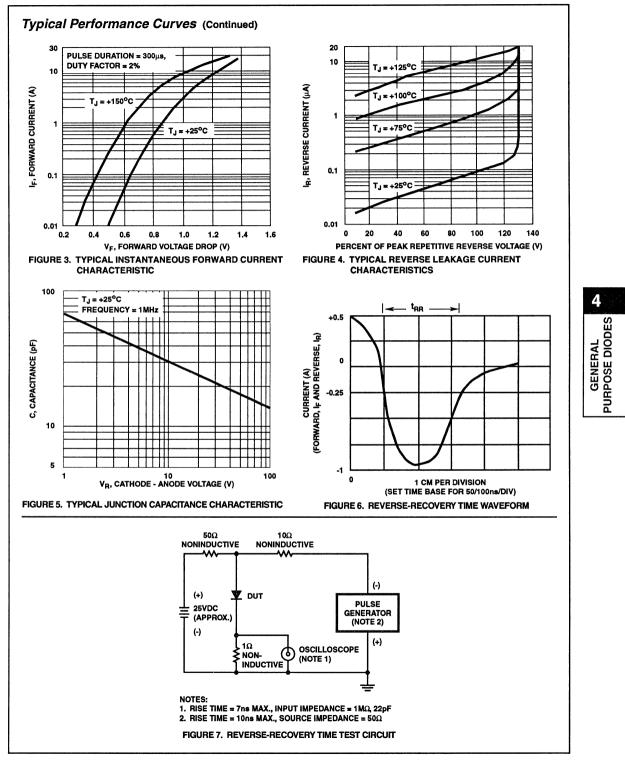
#### **Typical Performance Curves**













# **DB1** Series

## 1A, 50V - 1000V Single-Phase **Full-Wave Bridge Rectifiers**

 Glass-Passivated Construction BR-4 TOP VIEW Surge Ratings: 50A Designed for PC Board Mounting UL Recognized Package Material Description The DB1 Series are full-wave bridge silicon rectifiers Symbol intended for low power rectification. These bridge rectifiers are supplied in BR-4 compact plastic package.

Package

Absolute Maximum Ratings For Single Pha	ase, 60Hz	, Half-Wave	Resistive o	r Inductive	Loads (Note	ə 1)		
•	DB1F	DB1A	DB1B	DB1D	DB1M	DB1N	DB1P	UNITS
Maximum Peak (Repetitive)								
Reverse VoltageV <sub>RRM</sub>	50	100	200	400	600	800	1000	v
Maximum RMS Bridge Input								
(Supply) Voltage V <sub>RMS</sub>	35	70	140	280	420	560	700	v
Maximum DC Reverse								
(Blocking) Voltage V <sub>B(DC)</sub>	50	100	200	400	600	800	1000	v
Maximum Average Forward Current								
For Resistive or Inductive Loads,								
$T_A = 40^{\circ}C$	1	1	1	1	1	1	1	Α
Maximum Peak Surge Forward Current								
For 8.3ms Half Sine Wave,								
Superimposed on Rated Load IFSM	50	50	50	50	50	50	50	Α
Fusing Current (For Bridge Rectifier Protection)								
$T_{J} = -55^{\circ}C$ , t = 1 to 8.35msl <sup>2</sup> t	10	10	10	10	10	10	10	A <sup>2</sup> s
Operating Junction and								
Storage Temperature				-55 to +150	)			°C
NOTE:								

1. For capacitive load derate current by 20% or use conduction angle data (derating curve) Figure 5.

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Features

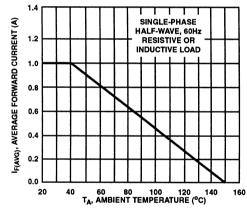
Exceeds Environmental Standard of MIL-STD-19500

## Specifications DB1 Series

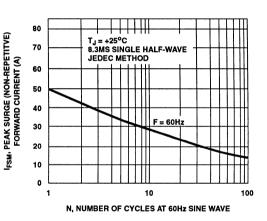
		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop (per Bridge Element) At 1A	V <sub>F</sub>	-	-	1.1	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage $T_J = +25^{\circ}C$		-	-	10	μΑ
At Maximum DC Reverse (Blocking) Voltage T <sub>J</sub> = +125°C	l <sub>R</sub>	-	-	0.5	mA
Typical Junction Capacitance (per Bridge Element)					
Measured at 2MHz, Applied Reverse Voltage = 4V	С	-	25	-	pF
Typical Thermal Resistance					
Junction-to-Ambient, PC Board Mounted	R <sub>eja</sub>	-	80		°c/w

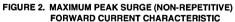
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## Typical Performance Curves

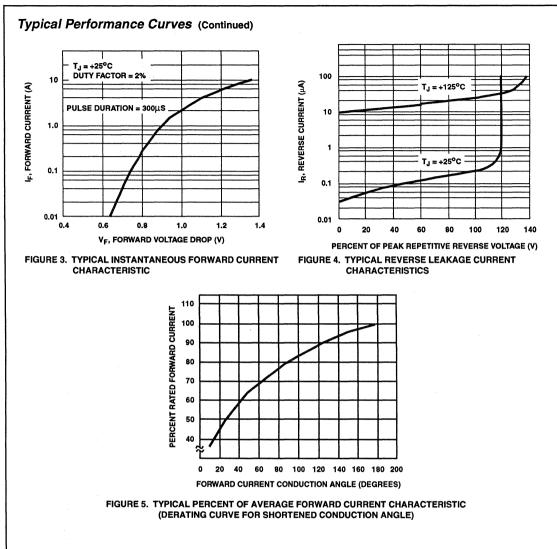








4 PURPOSE DIODES GENERAL





December 1993

# GER4001 thru GER4007

## 1A, 50V - 1000V Diodes

Features Package High-Temperature Metallurgically Bonded, No Com-JEDEC STYLE DO-204 TOP VIEW pression Contacts as Found in Diode-Constructed Rectifiers Glass-Passivated Junction 1A Operation at T<sub>A</sub> = 100°C with No Thermal Runaway Low Reverse Current ANODE CATHODE Exceeds Environmental Standard of MIL-STD-19500 Hermetically Sealed Package High-Temperature Soldering 350°C/10s/0.375 in. (9.5 mm) Lead Length Description Symbol The GER4001 - GER4007 are glass-passivated "transient voltage protected", silicon rectifiers intended for general-purpose applications. These rectifiers will dissipate up to 1000 watts in reverse direction without damage. Voltage transients generated by household or industrial power lines are dissipated. These rectifiers are supplied in a JEDEC style DO-204 package.

#### Absolute Maximum Ratings For Single Phase, 60Hz, Half-Wave Resistive or Inductive Loads

GER4001 GER4002 GER4003 GER4004 GER4005 GER4006 GER4007 UNITS Maximum Peak (Repetitive) Reverse Voltage .....V<sub>RRM</sub> 50 100 200 400 600 800 1000 v Maximum RMS Supply Voltage 35 70 140 280 420 560 700 v Maximum DC Reverse (Blocking) Voltage ..... V<sub>R(DC)</sub> 50 100 200 400 600 800 1000 v Maximum Average Forward Output Current For Resistive or Inductive Loads,  $T_{A} = 100^{\circ}C$  .....  $I_{O}$ 1 1 1 1 1 1 1 Α Maximum Peak Surge (Non-Repetitive) Forward Current For 8.3ms Half Sine Wave, Superimposed On Rated Load .....IFSM 50 50 50 50 50 50 50 Α Operating Junction and Storage Temperature ..... T<sub>J.</sub> T<sub>STG</sub> °C -65 to +175

#### Specifications GER4001 thru GER4007

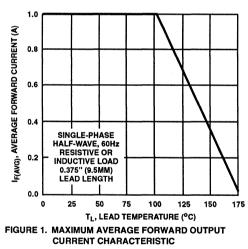
		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	MAX	UNITS
Maximum Instantaneous Forward-Voltage Drop At 1A	V <sub>F</sub>	-	-	1.2 (Note 1)	v
Maximum Full-Load Reverse Current					
At Average Full-Ccycle, Lead Length = 0.375 in. (9.5mm), $T_A = 100^{\circ}C$	I <sub>R</sub>	-	-	200	μA
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage	I <sub>R</sub>	-	-	2	μA
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>	-	-	2	μs
Typical Junction Capacitance					
At Frequency = 1MHz and Applied Reverse Voltage = 4V	Cj	-	15	-	pF

#### Electrical Specifications T<sub>A</sub> = +25°C, Unless Otherwise Specified

NOTE:

1. 1.1V for GER4003 - GER4007

#### **Typical Performance Curves**



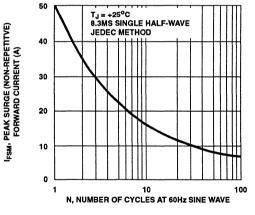
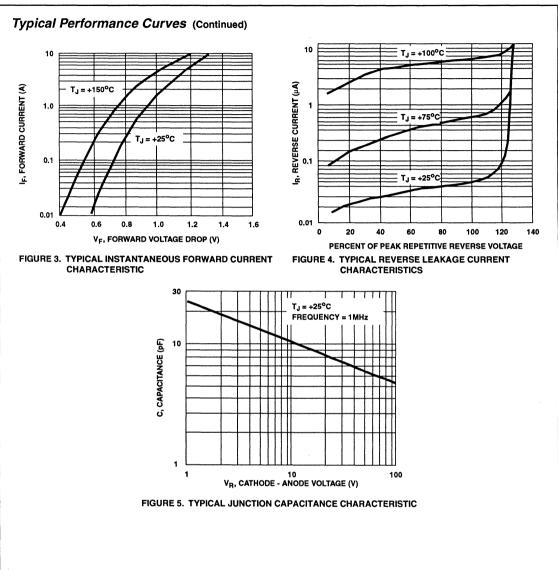


FIGURE 2. MAXIMUM PEAK SURGE (NON-REPETITIVE) FORWARD CURRENT CHARACTERISTIC



GENERAL PURPOSE DIODES

# MCT/IGBT/DIODES

## **ULTRAFAST SINGLE DIODES**

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ULTRAFAST GI SINGLE DIODES

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## Selection Guide -

		DO-204		AL	4	0 TO-251		TO	
		I <sub>F(AVG)</sub>			IVG)	I <sub>F(AVG)</sub>	I <sub>F(AVG)</sub>	I <sub>F(AVG)</sub>	I <sub>F(AVG)</sub>
V <sub>RRM</sub>	1A	2A	2.5A	3A	6A/5A	4A	6A	4A	6A
50V	GE1001	A214F	GE1101	A315F	GE1301				
100V	GE1002	A214A	GE1102	A315A	GE1302	RURD410	RURD610	RURD410S	RURD610S
150V	GE1003	A214G	GE1103	A315G	GE1303	RURD415	RURD615	RURD415S	RURD615S
200V	GE1004	A214B	GE1104	A315B	GE1304	RURD420	RURD620	RURD420S	RURD620S
400V						RURD440	RURD640	RURD440S	RURD640S
500V						RURD450	RURD650	RURD450S	RURD650S
600V						RURD460	RURD660	RURD460S	RURD660S
700V									
800V									
900V									
1000V									
1200V						RURD4120	RURD6120	RURD4120S	RURD61205

SHADING = Future Product Offerings

ULTRAFAST 61 SINGLE DIODES

			— S	electi	on Gi	uide (c	continued)			
IARR	IS ULTRA	FAST RE	COVERY	RECTIFIE	R PRODU	CT LINE				
		TO-220AC		2	LEAD TO-24	17		SINGLE L	EAD TO-218	
	I <sub>F(AVG)</sub>			IF(AVG)			I <sub>F(AVG)</sub>			
V <sub>RRM</sub>	8A	15A	30A	30A	50A	75A/80A	50A	75A/80A	100 <b>A</b>	150A
100V	MUR810 RURP810	MUR1510 RURP1510	RURP3010	RURG3010						
150V	MUR815 RURP815	MUR1515 RURP1515	RURP3015	RURG3015						
200V	MUR820 RURP820	MUR1520 RURP1520	RURP3020	RURG3020						
400V	MUR840 RURP840	MUR1540 RURP1540	RURP3040	RURG3040	RURG5040	RURG8040	RURU5040	RURU8040	RURU10040	RURU1504
500V	MUR850 RURP850	MUR1550 RURP1550	RURP3050	RURG3050	RURG5050	RURG8050	RURU5050	RURU8050	RURU10050	RURU1505
600V	MUR860 RURP860	MUR1560 RURP1560	RURP3060	RURG3060	RURG5060	RURG8060	RURU5060	RURU8060	RURU10060	RURU1506
700V	MUR870E RURP870	RURP1570	RURP3070	RURG3070	RURG5070	RURG8070	RURU5070	RURU8070	RURU10070	RURU1507
800V	MUR880E RURP880	RURP1580	RURP3080	RURG3080	RURG5080	RURG8080	RURU5080	RURU8080	RURU10080	RURU1508
900V	MUR890E RURP890	RURP1590	RURP3090	RURG3090	RURG5090	RURG8090	RURU5090	RURU8090	RURU10090	RURU1509
1000V	MUR8100E RURP8100	RURP15100	RURP30100	RURG30100	RURG50100	RURG80100	RURU50100	RURU80100	RURU100100	RURU15010
1200V	RURP8120	RURP15120	RURP30120	RURG30120	RURG50120	RURG75120	RURU50120	RURU75120	RURU100120	RURU15012

SHADING = Future Product Offerings



December 1993

# A214 Series

## 2A, 50V - 200V Ultrafast Diodes

Features Package Glass-Passivated Junction JEDEC STYLE DO-204 TOP VIEW Ultra-Fast Recovery Times Low Forward Voltage Drop, High-Current Capability Low Leakage Current ANODE CATHODE High Surge Current Capability Description The A214A, A214B, A214F, and A214G are ultra-fast recovery silicon rectifiers (t<sub>BB</sub> = 35ns max.) featuring low forward Symbol voltage drop, high-current capability. They use glass passivated epitaxial construction. These rectifiers are intended for TV deflection, inverter, highfrequency power supplies, energy recovery, and output rectification. These types are supplied in unitized-glass hermeticallysealed JEDEC style DO-204 package.

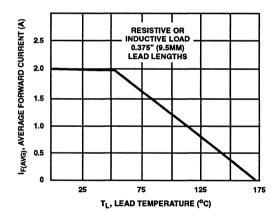
Absolute Maximum Ratings Supply Frequency of 60Hz, Resis	stive or Induct	ive Loads			
	A214F	A214A	A214G	A214B	UNITS
Maximum Peak Repetitive Reverse VoltageV <sub>RRM</sub>	50	100	150	200	V
Maximum RMS Input (Supply) VoltageVBMS	35	70	105	105	v
Maximum DC Reverse (Blocking) Voltage VB(DC)	50	100	150	200	v
Maximum Average Forward Current					
Lead Length = 0.375 in. (9.5mm); T <sub>A</sub> = 55°C I <sub>O</sub>	2	2	2	2	A
Maximum Peak Surge (Non-Repetitive) Forward Current					
For 8.3ms Half Sine Wave, Superimposed on Rated Load, IFSM	50	50	50	50	Α
Operating Junction and Storage TemperatureT <sub>J.</sub> T <sub>STG</sub>	-65 to +175	-65 to +175	-65 to +175	-65 to +175	°C

ULTRAFAST SINGLE DIODES

#### **Specifications A214 Series**

		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	MAX	UNITS
Maximum Instantaneous Forward-Voltage Drop at 2A	V <sub>F</sub>	-	-	0.95	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	2	μΑ
At Maximum DC Reverse (Blocking) Voltage, $T_A = +150^{\circ}C$	I <sub>R</sub>	-	-	50	μA
Maximum Reverse Recovery Time					
At $I_F = 0.5A$ , $I_R = 1A$ , $I_{RR} = 0.25A$	t <sub>RR</sub>	-	-	35	ns
Typical Junction Capacitance					
At 1MHz and Applied Reverse Voltage = 4V	CJ	-	45	-	pF
Thermal Resistance					
Junction-to-Ambient at 0.375 in. (9.5mm) Lead Length	R <sub>eja</sub>	-	60	-	°c/w

#### **Typical Performance Curves**





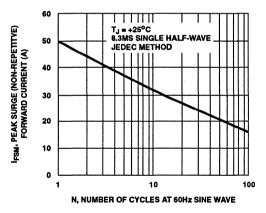
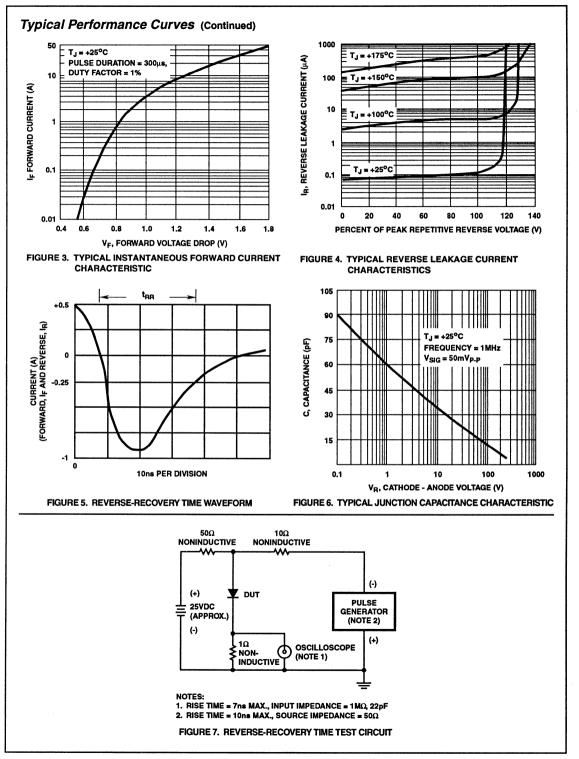


FIGURE 2. MAXIMUM PEAK SURGE (NON-REPETITIVE) FORWARD CURRENT CHARACTERISTIC



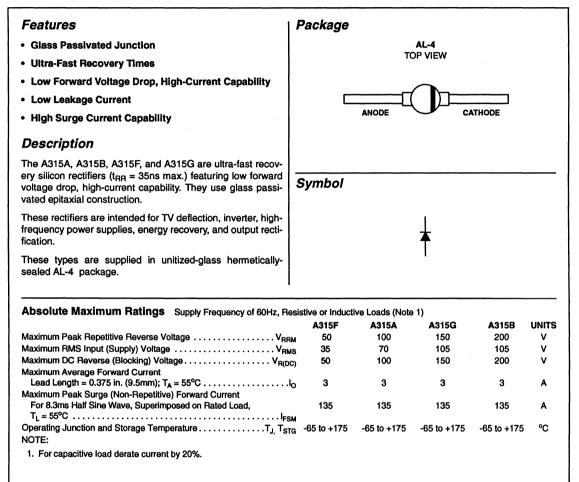
ULTRAFAST SINGLE DIODES



# A315 Series

#### December 1993

## 3A, 50V - 200V Ultrafast Diodes

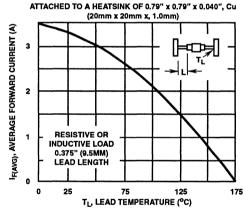


## Specifications A315 Series

		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop					
At 3A	V <sub>F</sub>		-	0.95	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	3	μА
At Maximum DC Reverse (Blocking) Voltage, $T_A = +150^{\circ}C$	I <sub>R</sub>	-	-	50	μΑ
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>	-	-	35	ns
Typical Junction Capacitance At Frequency = 1MHz and Applied Reverse Voltage = 4V	Cj	-	100	-	pF

#### atrical Creations -0500 11-1 . . . . .

#### **Typical Performance Curves**





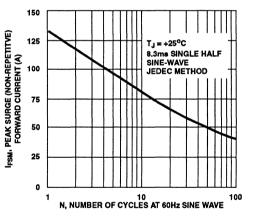
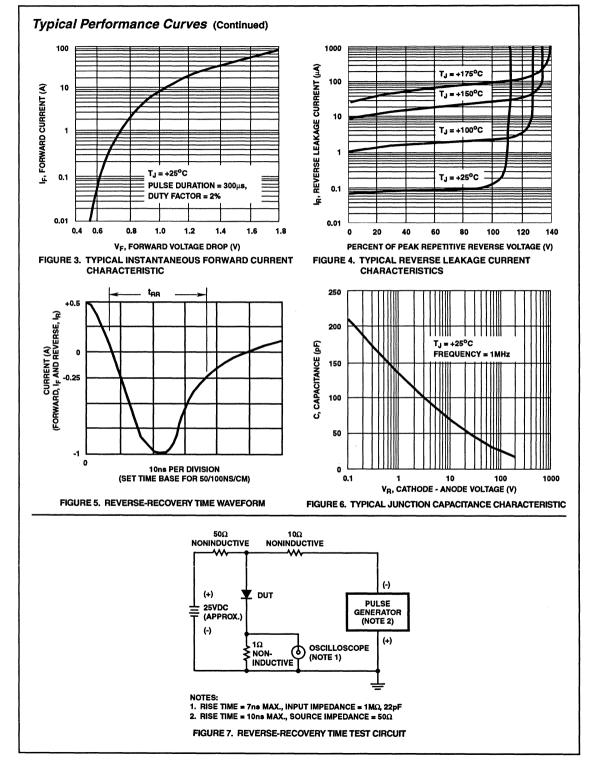


FIGURE 2. MAXIMUM PEAK SURGE (NON-REPETITIVE) FORWARD CURRENT CHARACTERISTIC

5 ULTRAFAST SINGLE DIODES





December 1993

# GE1001, GE1002 GE1003, GE1004

## 1A, 50V - 200V Ultrafast Diodes

Features: Package Glass Passivated Junction JEDEC STYLE DO-204 TOP VIEW Ultra-Fast Recovery Times Low Forward Voltage Drop, High-Current Capability Low Reverse Current Leakage ANODE CATHODE High Surge Current Capability Description The GE1001, GE1002, GE1003, and GEl004 are ultra-fastrecovery silicon rectifiers (t<sub>BB</sub> = 35ns max.) featuring low for-Symbol ward voltage drop, high-current capability. They use glass passivated epitaxial construction. These rectifiers are intended for TV deflection, inverter, highfrequency power supplies, energy recovery, and output rectification. These types are supplied in unitized-glass hermeticallysealed JEDEC style DO-204 package.

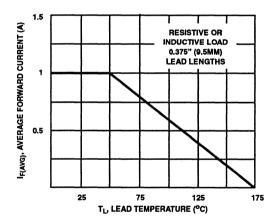
Absolute Maximum Ratings Supply Frequency of 60Hz, Resi	stive or Induct	ive Loads, Note	1		
	GE1001	GE1002	GE1003	GE1004	UNITS
Maximum Peak Repetitive Reverse VoltageV <sub>RRM</sub>	50	100	150	200	v
Maximum RMS Input (Supply) VoltageV <sub>RMS</sub>	35	70	105	140	v
Maximum DC Reverse (Blocking) Voltage V <sub>R(DC)</sub>	50	100	150	200	v
Maximum Average Forward Output Current Lead Length = 0.375 in. (9.5mm); T <sub>A</sub> = 55°C	1	1	1	1	A
Maximum Peak Surge (Non-Repetitive) Forward Current For 8.3ms Half Sine Wave, Superimposed on Rated Load,I <sub>FSM</sub>	30	30	30	30	A
Operating Junction and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	-65 to +175	°C

1. For capacitive load derate current by 20%.

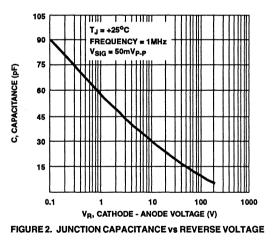
		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	МАХ	UNITS
Maximum Instantaneous Forward-Voltage Drop at 1A	V <sub>F</sub>	-	-	0.95	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	2	μΑ
At Maximum DC Reverse (Blocking) Voltage, $T_A = +150^{\circ}C$	I <sub>R</sub>	•	-	50	μА
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>	-	-	35	ns
Typical Junction Capacitance					
At Frequency 1MHz and Applied Reverse Voltage = 4V	СJ	-	45	-	pF
Thermal Resistance					
Junction-to-Ambient at 0.375 in. (9.5mm) Lead Length	R <sub>eja</sub>		-	65	°c/w

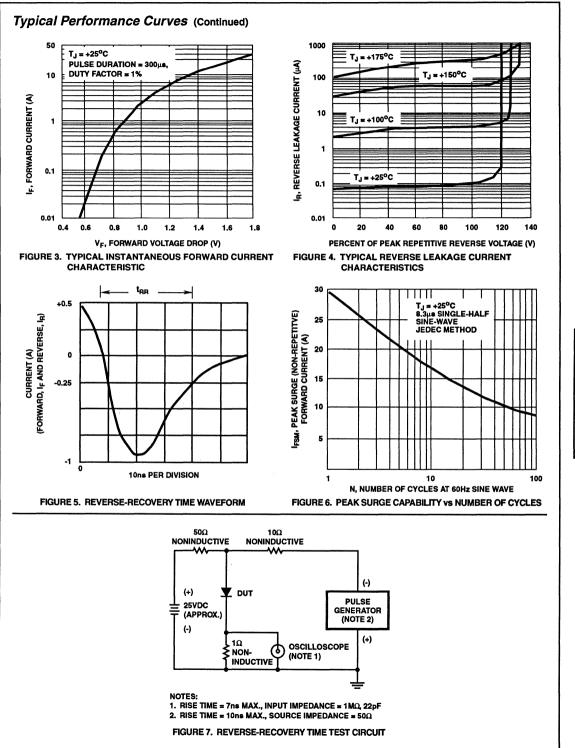
#### **Electrical Specifications** $T_A = +25^{\circ}C$ , Unless Otherwise Specified

### **Typical Performance Curves**







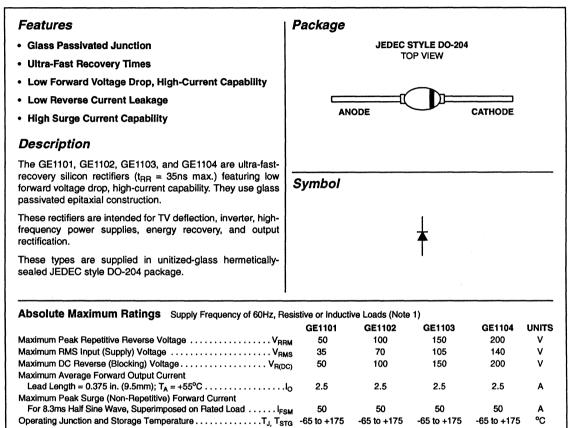




December 1993

# GE1101, GE1102 GE1103, GE1104

## 2.5A, 50V - 200V Ultrafast Diodes



-65 to +175

-65 to +175

-65 to +175

#### NOTE:

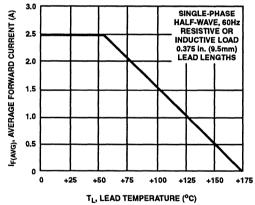
1. For capacitive load derate current by 20%.

Specifications	GE1101,	GE1102,	GE1103,	GE1104
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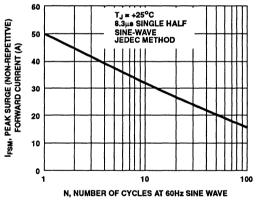
		LIMIT			
PARAMETERS	SYMBOL	MIN	ТҮР	MAX	UNITS
Maximum Instantaneous Forward-Voltage Drop at 2A	V <sub>F</sub>	-	-	0.95	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	2	μΑ
At Maximum DC Reverse (Blocking) Voltage, T <sub>A</sub> = +150°C	I <sub>R</sub>	-	-	50	μА
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>		-	35	ns
Typical Junction Capacitance					
At Frequency 1MHz and Applied Reverse Voltage = 4V	С	-	45	-	pF
Thermal Resistance					
Junction-to-Ambient at 0.375 in. (9.5mm) Lead Length	R <sub>eja</sub>	-	60	- 1	°c/w

#### Electrical Specifications T<sub>A</sub> = +25°C, Unless Otherwise Specified

#### **Typical Performance Curves**

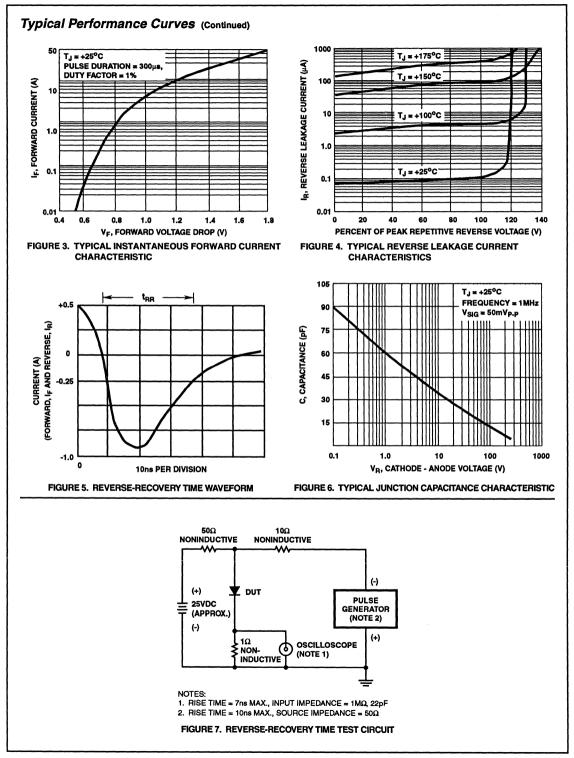








ULTRAFAST **31** SINGLE DIODES





December 1993

# GE1301, GE1302 GE1303, GE1304

## 6A, 50V - 200V Ultrafast Diodes

Features Package Glass-Passivated Junction AL-4 TOP VIEW Ultra-Fast Recovery Times Low Forward Voltage Drop, High-Current Capability Low Leakage Current ANODE CATHODE High Surge Current Capability Description The GE1301, GE1302, GE1303, and GE1304 are ultra-fast recovery silicon rectifiers (t<sub>BB</sub> = 35ns max.) featuring low Symbol forward voltage drop, high-current capability. They use glasspassivated epitaxial construction. These rectifiers are intended for TV deflection, inverter, highfrequency power supplies, energy recovery, and output rectification. These types are supplied in unitized-glass hermeticallysealed AL-4 package. Absolute Maximum Ratings Supply Frequency of 60Hz, Resistive or Inductive Loads (Note 1)

	GE1301	GE1302	GE1303	GE1304	UNITS	
Maximum Peak Repetitive Reverse VoltageV <sub>RRM</sub>	50	100	150	200	v	
Maximum RMS Input (Supply) VoltageV <sub>RMS</sub>	35	70	105	140	v	
Maximum DC Reverse (Blocking) Voltage V <sub>R(DC)</sub>	50	100	150	200	v	
Maximum Average Forward Output Current		_	-	-		
Lead Length = 0.375 in. (9.5mm); T <sub>A</sub> = +55°C	6	6	6	6	A	
Maximum Peak Surge (Non-Repetitive) Forward Current						
For 8.3ms Half Sine Wave, Superimposed on Rated Load IFSM	150	150	150	150	Α	
Operating Junction and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	-65 to +175	°C	

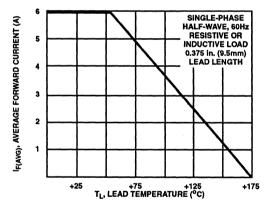
#### NOTE:

1. For capacitive load derate current by 20%.

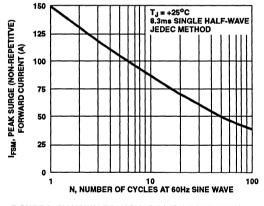
		LIMIT	S FOR ALL T	YPES	
PARAMETERS	SYMBOL	MIN	ТҮР	MAX	UNITS
Maximum Instantaneous Forward-Voltage Drop at 2A	V <sub>F</sub>	-	-	0.975	v
Maximum Reverse Current					
At Maximum DC Reverse (Blocking) Voltage, $T_A = +25^{\circ}C$	I <sub>R</sub>	-	-	5	μA
At Maximum DC Reverse (Blocking) Voltage, $T_A = +150^{\circ}C$	I <sub>R</sub>	-	-	50	μА
Maximum Reverse Recovery Time					
At I <sub>F</sub> = 0.5A, I <sub>R</sub> = 1A, I <sub>RR</sub> = 0.25A	t <sub>RR</sub>		-	35	ns
Typical Junction Capacitance					
At Frequency = 1MHz and Applied Reverse Voltage = 4V	CJ		100	-	pF
Thermal Resistance					
Junction-to-Lead at 0.375 in. (9.5mm)	R <sub>eja</sub>	-	16	-	°c/w

## Specifications GE1301, GE1302, GE1303, GE1304

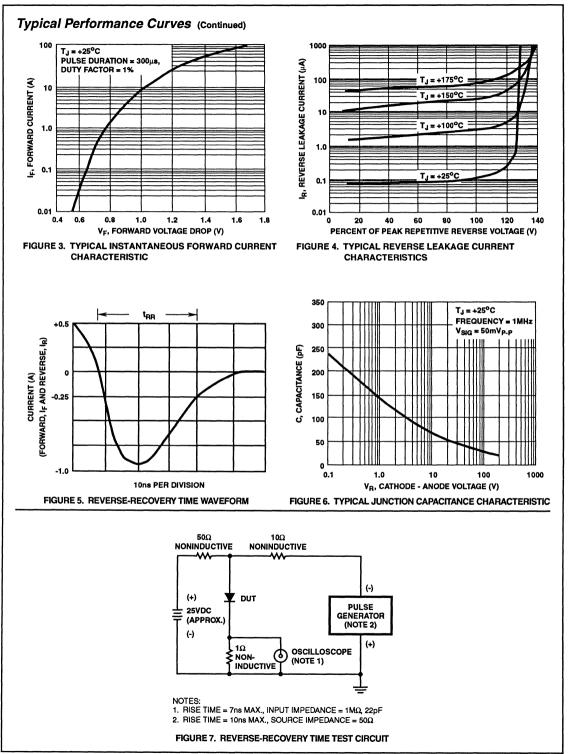
#### **Typical Performance Curves**









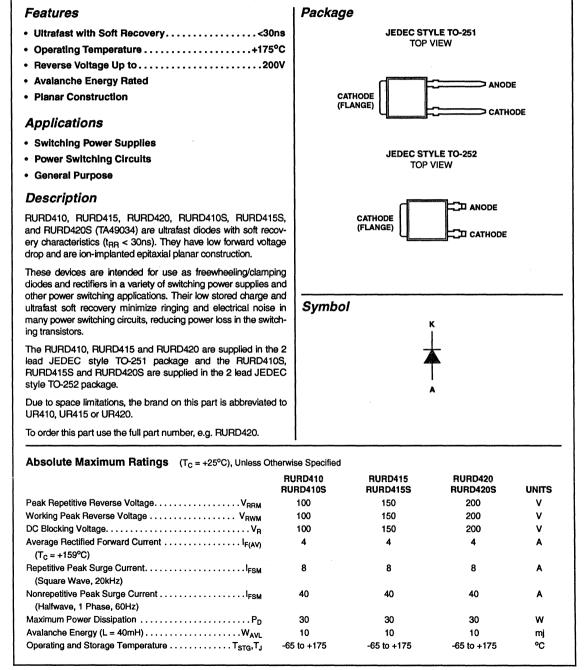


ULTRAFAST SINGLE DIODES

## HARRIS RURD410, RURD415, RURD420 SEMICONDUCTOR RURD410S, RURD415S, RURD420S

#### December 1993

### 4A, 100V - 200V Ultrafast Diodes



CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright @ Harris Corporation 1992

	LIMITS										
	TEST		RURD410 RURD410S			RURD415 RURD415S			RURD420 RURD420S		
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 4A, T <sub>C</sub> = +25°C	·	-	1.0	-	-	1.0	-	-	1.0	
V <sub>F</sub>	I <sub>F</sub> = 4A, T <sub>C</sub> = +150°C	-	-	0.83	-	-	0.83	-		0.83	<b>- -</b>
IR	$V_{R} = 100V, T_{C} = +25^{\circ}C$ $V_{R} = 150V, T_{C} = +25^{\circ}C$ $V_{R} = 200V, T_{C} = +25^{\circ}C$	-		5 - -	•	-	- 5 -	-	-	- - 5	μΑ
1 <sub>R</sub>	$V_{R} = 100V, T_{C} = +150^{\circ}C$ $V_{R} = 150V, T_{C} = +150^{\circ}C$ $V_{R} = 200V, T_{C} = +150^{\circ}C$	-	-	250 - -	•	-	- 250 -	•	- - -	- 250	μА
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	· ·	-	30	•	-	30	-	-	30	
	l <sub>F</sub> = 4A, dl <sub>F</sub> /dt = 100A/μs	-	-	35	-	-	35	-	-	35	1
t <sub>A</sub>	l <sub>F</sub> = 4A, dl <sub>F</sub> /dt = 100A/μs	- 1	11	-	-	11	-	-	11	-	
t <sub>B</sub>	l <sub>F</sub> = 4A, dl <sub>F</sub> /dt = 100A/μs	-	9	-	-	9	-	-	9	•	ns
Q <sub>RR</sub>	l <sub>F</sub> = 4A, dl <sub>F</sub> /dt = 100A/μs	•	12	-	-	12	-	-	12	-	nC
Cj	V <sub>R</sub> = 10V, I <sub>F</sub> = 0A	•	15		•	15	-	-	15	-	pf
R <sub>eJC</sub>		-	-	5	•	-	5	•		5	°C/W

#### **Electrical Specifications** $T_{C} = +25^{\circ}C$ , Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

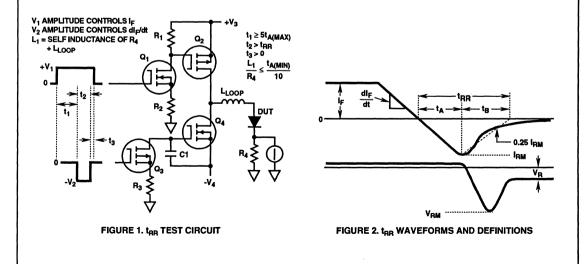
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

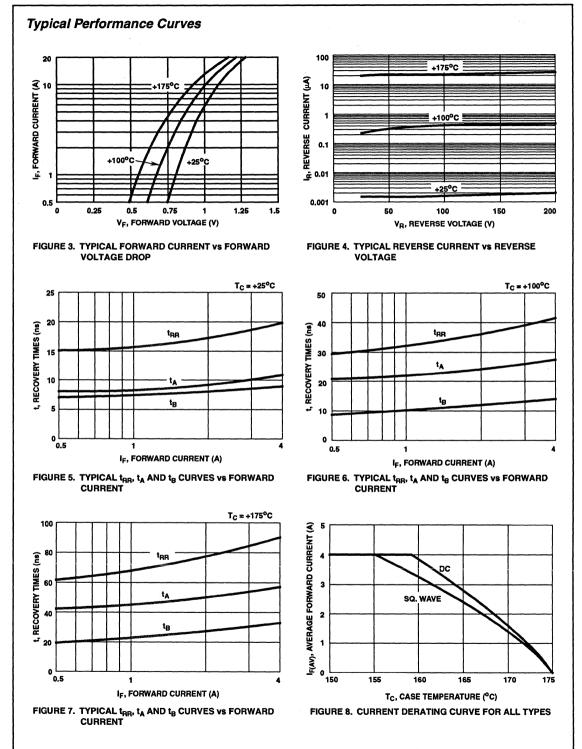
 $R_{\theta,JC}$  = Thermal resistance junction to case.

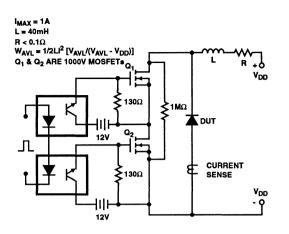
 $W_{AVL}$  = Controlled avalanche energy (See Figures 9 and 10).

pw = pulse width.

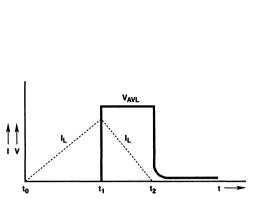
D = duty cycle.









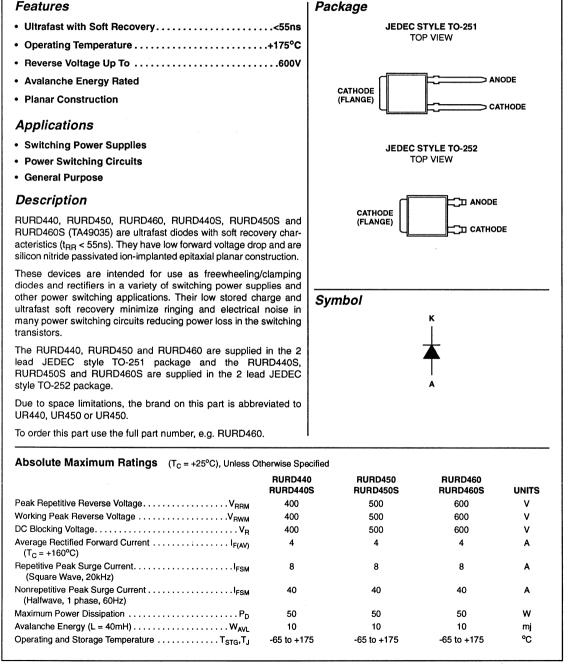




## HARRIS RURD440, RURD450, RURD460 SEMICONDUCTOR RURD440S, RURD450S, RURD460S

#### January 1994

### 4A, 400V - 600V Ultrafast Diodes



CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1994

			LIMITS								
SYMBOL	TEST	RURD	RURD440, RURD440S			RURD450, RURD450S			RURD460, RURD460S		
	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 4A, T <sub>C</sub> = +25°C	-	-	1.5	-	-	1.5	-	-	1.5	v
V <sub>F</sub>	I <sub>F</sub> = 4A, T <sub>C</sub> = +150°C	-	-	1.2	•	-	1.2	-	-	1.2	v
l <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	10	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	•	-	10	-	-	-	μA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	10	μΑ
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +150°C	-	-	500	-	-	-	-	•	-	μA
	$V_{R} = 500V, T_{C} = +150^{\circ}C$	-	-	-	-	-	500	-	-	-	μΑ
	V <sub>R</sub> = 600V, T <sub>C</sub> = +150°C	-	-	-	•	-	-	-	-	500	μΑ
t <sub>RR</sub>	l <sub>F</sub> = 1A, dl <sub>F</sub> /dt = 100A/μs	-	-	55	-	•	55	•	-	55	ns
	$I_F = 4A, dI_F/dt = 100A/\mu s$	-	-	60	-	-	60	-	-	60	ns
t <sub>A</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	32	-	-	32	-	-	32	-	ns
t <sub>B</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	15	-	-	15	-	-	15	-	ns
Q <sub>RR</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/µs	-	50	•	•	50	-	-	50	-	nC
CJ	V <sub>R</sub> = 10V, I <sub>F</sub> = 0A	-	15	-	•	15	-	•	15	•	pF
R <sub>NC</sub>		- 1	-	3	-	- 1	3	-	-	3	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

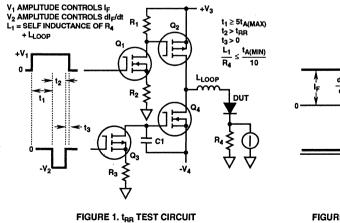
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

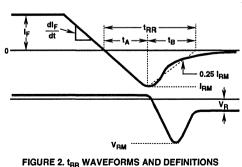
 $R_{\Theta JC}$  = Thermal resistance junction to case.

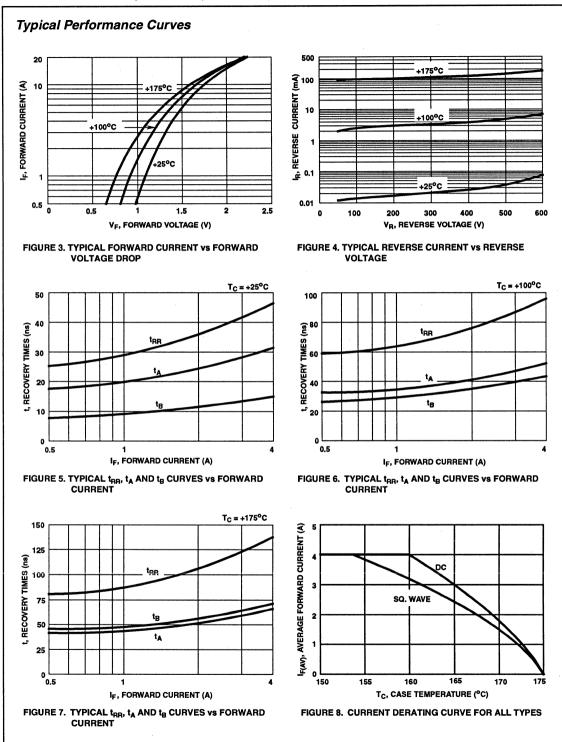
WAVL = Controlled avalanche energy (See Figures 9 and 10).

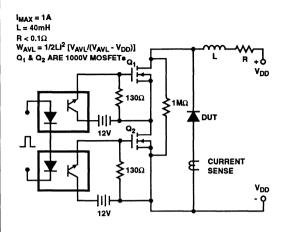
pw = pulse width.

D = duty cycle.



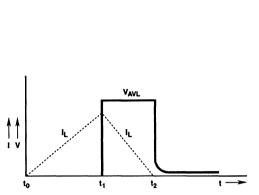








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## MUR810, RURP810, MUR815, RURP815, MUR820, RURP820

#### December 1993

#### Features

- Ultrafast Recovery Time (t<sub>RR</sub> < 35ns)
- Low Forward Voltage
- Low Thermal Resistance
- Planar Design
- Wire-Bonded Construction

#### Applications

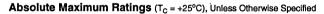
- General Purpose
- Power Switching Circuits to 100kHz
- Output Rectification in Switching Power Supplies

#### Description

MUR810, MUR815, MUR820 and RURP810, RURP815, RURP820 are low forward voltage drop ultrafast recovery rectifiers ( $t_{RR}$  < 35ns). They use a glass-passivated ion-implanted, epitaxial construction.

These devices are intended for use as output rectifiers and flywheel diodes in a variety of high-frequency pulse-width modulated switching regulators. Their low stored charge and attendant fast reverse-recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

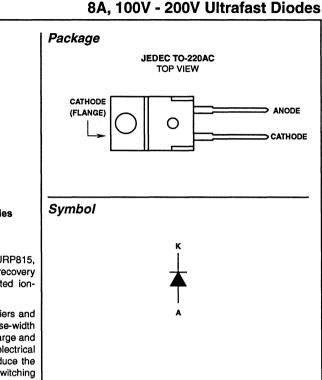
All are supplied in JEDEC TO-220AC packages.



	MUR810 RURP810	MUR815 RURP815	MUR820 RURP820	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100	150	200	v
Average Rectified Forward Current				
$T_A = +25^{\circ}C$ (No Heat Sink)I <sub>F(AV)</sub>	3	3	3	Α
T <sub>A</sub> = +25°C (With Heat Sink) Note 1I <sub>F(AV)</sub>	8	8	8	Α
$T_A = +150^{\circ}C$ I <sub>F(AV)</sub>	8	8	8	Α
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (8.3ms, <sup>1</sup> / <sub>2</sub> cycle)	100	100	100	A
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	°C
Maximum Lead Temperature During SolderTL (At distance > <sup>1</sup> / <sub>a</sub> inches (3.17mm) from case for 10s max)	+260	+260	+260	°C

#### NOTE:

1. Wakefield type 295 heat sink with convection cooling.



#### Specifications MUR810, MUR815, MUR820 RURP810, RURP815, RURP820

		MUR/RURP810			MUR/RURP815			MUR/RURP820			
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
VF	$I_F = 8A, T_C = +150^{\circ}C$	- 1	-	0.895	-	•	0.895	-	-	0.895	v
VF	$I_{\rm F} = 8$ A, $T_{\rm C} = +25^{\rm o}$ C	-	-	0.975	-	•	0.975	-	-	0.975	V
I <sub>R</sub>	V <sub>R</sub> = 100V, T <sub>C</sub> = +150°C	-	-	250	-		-	-	-	-	μΑ
	V <sub>R</sub> = 150V, T <sub>C</sub> = +150°C	-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 200V, T <sub>C</sub> = +150°C	- 1	-	-	•	•	-	-	•	250	μA
I <sub>R</sub>	V <sub>R</sub> = 100V, T <sub>C</sub> = +25°C	-	-	5	•	-	-	-	-	-	μΑ
	V <sub>R</sub> = 150V, T <sub>C</sub> = +25°C	-	-	-	-	•	5	-	-	-	μA
	$V_{\rm R} = 200V, T_{\rm C} = +25^{\rm o}{\rm C}$		-	-	-	-	-	-	-	5	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A (Note 1)	-	•	35	•	•	35	•	-	35	ns
R <sub>eJC</sub>		-	-	3	-	-	3	-	-	2	°C/M
R <sub>eja</sub>		-	-	60	-	-	60	-	-	60	°CM
Cj	$V_{\rm R} = 10V, I_{\rm F} = 0A$	-	40	-	-	40	-	-	40	-	pF

NOTE:

1.  $dI_F/dt = 50A/\mu s$ ,  $I_{RM (REC)} < 1A$ ,  $I_{RR} = 0.25A$ .

#### **Typical Performance Curves**

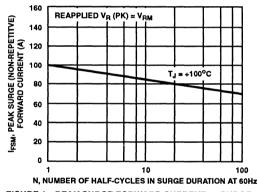
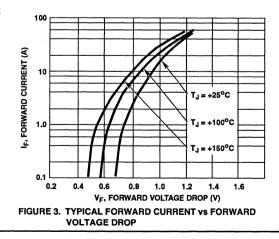


FIGURE 1. PEAK SURGE FORWARD CURRENT vs SURGE DURATION



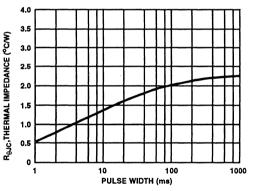
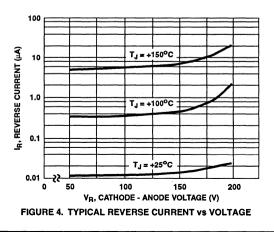


FIGURE 2. THERMAL IMPEDANCE vs PULSE WIDTH





## MUR840, RURP840, MUR850, RURP850, MUR860, RURP860

#### December 1993

#### Features

- Ultrafast Recovery Time (t<sub>RR</sub> < 50ns)
- Low Forward Voltage
- Low Thermal Resistance
- Hard Glass Passivation
- Wire-Bonded Construction

#### Applications

- General Purpose
- Power Switching Circuits to 100kHz
- Output Rectification in Switchng Power Supplies

#### Description

MUR840, MUR850, MUR860 and RURP840, RURP850, RURP860 are low forward voltage drop ultrafast recovery rectifiers ( $t_{RR}$  < 50ns). They use a glass-passivated ion-implanted, epitaxial construction.

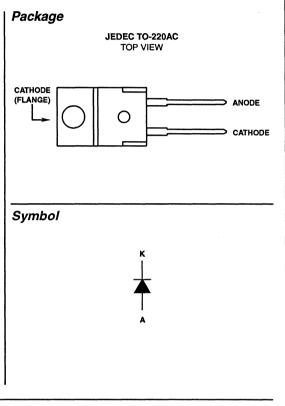
These devices are intended for use as output rectifiers and flywheel diodes in a variety of high-frequency pulse-width modulated switching regulators. Their low stored charge and attendant fast reverse-recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

All are supplied in JEDEC TO-220AC packages.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	MUR840 RURP840	MUR850 RURP850	MUR860 RURP860
Peak Repetitive Reverse VoltageV <sub>RRM</sub> Working Peak Reverse Voltage, VRWM DC Blocking Voltage, VR	400V	500V	600V
Average Rectified Forward Current $I_{F(AV)}$ Total Device, (Rated V <sub>R</sub> ), T <sub>C</sub> = +150°C	8A	8A	8A
Peak Repetitive Forward Curent $I_{FM}$ (Rated V <sub>R</sub> , Square Wave, 20kHz), T <sub>C</sub> = +150°C	16A	16A	16A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Surge Applied at Rated Load Conditions Halfwave, Single Phase, 60Hz)	100A	100A	100A
Operating and Storage Temperature $T_{STG}$ , $T_{J}$ -	65°C to +175°C	-65°C to +175°C	-65°C to +175°C
Maximum Lead Temperature During Solder	260°C	260°C	260°C

## 8A, 400V - 600V Ultrafast Diodes



## Specifications MUR840, MUR850, MUR860, RURP840, RURP850, RURP860

						LIMITS					
		MUR	840, RUF	RP840	MUR850, RURP850			MUR860, RURP860			
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 8A, T <sub>C</sub> = +150°C	-	-	1.0	-	-	1.2	-	-	1.2	v
	I <sub>F</sub> = 8A, T <sub>C</sub> = +25°C	-	-	1.3	-		1.5	-	-	1.5	v
IR at	V <sub>R</sub> = 400V	- 1	-	500	-	-	-	-	-	-	μА
T <sub>C</sub> ≈ +150°C	V <sub>R</sub> = 500V	-	-	-	-	-	500	-	-	-	μА
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	500	μA
IR at	V <sub>R</sub> = 400V	-	-	10	-	-	-	-	-	-	μА
T <sub>C</sub> = +25°C	V <sub>R</sub> = 500V	-	-	-	-	-	10	-	-	-	μA
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	10	μA
t <sub>RR</sub>	I <sub>F</sub> = 1A (Note 1)	-	-	60	-	-	60	-	-	60	ns
	I <sub>F</sub> = 0.5 (Note 2)	· ·	-	50	-	-	50	-	-	50	ns
R <sub>NC</sub>			-	2	-	-	2	-	-	2	°C/W

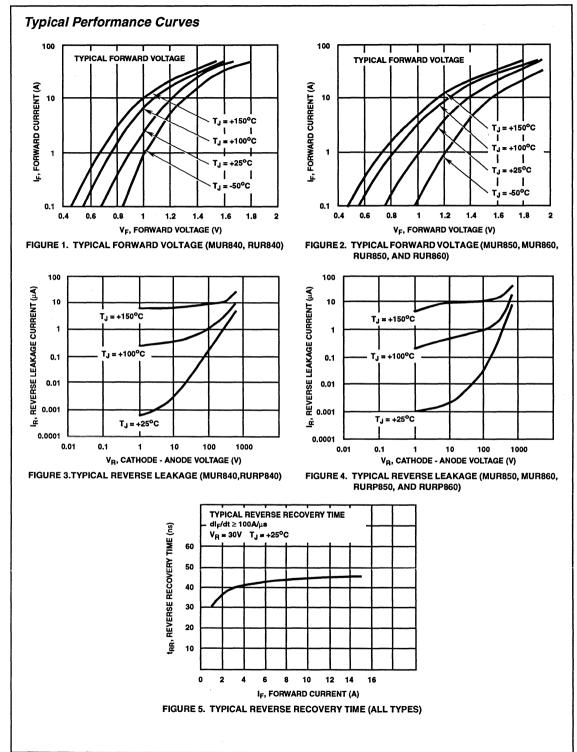
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

NOTES:

1. dl<sub>F</sub>/dt ≈ 50A/μs.

2.  $I_R = 1.0A$ ,  $I_{REC} = 0.25A$ .

ULTRAFAST **61** SINGLE DIODES





## MUR870E, MUR880E, MUR890E MUR8100E, RURP870, RURP880 RURP890, RURP8100

December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic ( $t_{RR} < 75ns$ )
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 1000V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

MUR870E, MUR880E, MUR890E, MUR8100E and RUR870, RUR880, RUR890, RUR8100 are ultrafast dual diodes ( $t_{RR}$  < 75ns) with soft recovery characteristics ( $t_A/t_B \approx 0.5$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

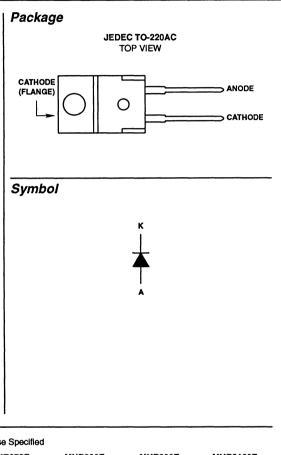
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC style TO-220AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	MUR870E RURP870	MUR880E RURP880	MUR890E RURP890	MUR8100E RURP8100
Peak Repetitive Reverse VoltageV <sub>BBM</sub>	700V	800V	900V	1000V
Working Peak Reverse VoltageVBWM	700V	800V	900V	1000V
DC Blocking VoltageV <sub>B</sub>	700V	800V	900V	1000V
Average Rectified Forward Current $I_{F(AV)}$ Total device forward current at rated $V_R$ and $T_C = +150^{\circ}C$ )	8A	8A	8 <b>A</b>	8A
Peak Forward Repetitive Currentl <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ)	16A	16A	16A	16A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	100A	100A	100A	100A
Operating and Storage Temperature $T_{STG},T_{J}$ -	55°C to +175°C	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

## 8A, 700V - 1000V Ultrafast Diodes



							L	MITS						
	TEST		IUR870 RURP87			UR880 URP88			UR890			UR8100		
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 8A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-	-	1.50	v
	I <sub>F</sub> = 8A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	-	-	1.80	-	-	1.80	v
I <sub>R</sub> at T <sub>C</sub> = +150°C	V <sub>R</sub> = 700V	-	-	500	-	-	-	-	-	-	-	-	-	μΑ
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	-	-	-	-	-	500	-	•	•	•	-	-	μΑ
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	500	-	-	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	•	-	•	-	500	μΑ
I <sub>R</sub> at	V <sub>R</sub> = 700V	•	-	25	•	-	-	-	-	-	•	-	-	μA
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-	-	-	-	25	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	25	-	-	-	μA
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	25	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	100	-	-	100	-	-	100	-	-	100	ns
	I <sub>F</sub> = 8A	-	-	110	-	-	110	-	-	110	-	-	110	ns
t <sub>A</sub>	I <sub>F</sub> = 1A	-	40	-	-	40	-	•	40	-	•	40	-	ns
	I <sub>F</sub> = 8A	-	45	-	•	45	-	•	45		•	45	-	ns
t <sub>B</sub>	I <sub>F</sub> = 1A	-	20	-	•	20	-	-	20	-	•	20	-	ns
	I <sub>F</sub> = 8A	-	20	-	-	20	-	•	20	-	•	20	-	ns
R <sub>elC</sub>		-	-	2.0	•	-	2.0	-	-	2.0	•	-	2.0	°C/W
WAVL	see Fig. 7 & 8	-	-	20	-	-	20	-	-	20	-	-	20	mj

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at  $dI_F/dt$  = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at dI<sub>F</sub>/dt = 100A/µs (See Figure 2).

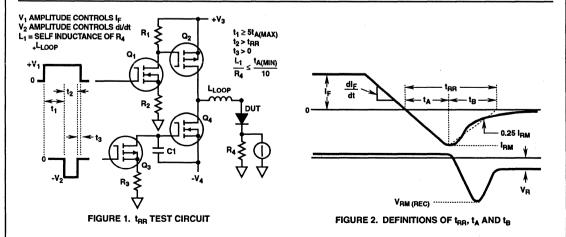
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

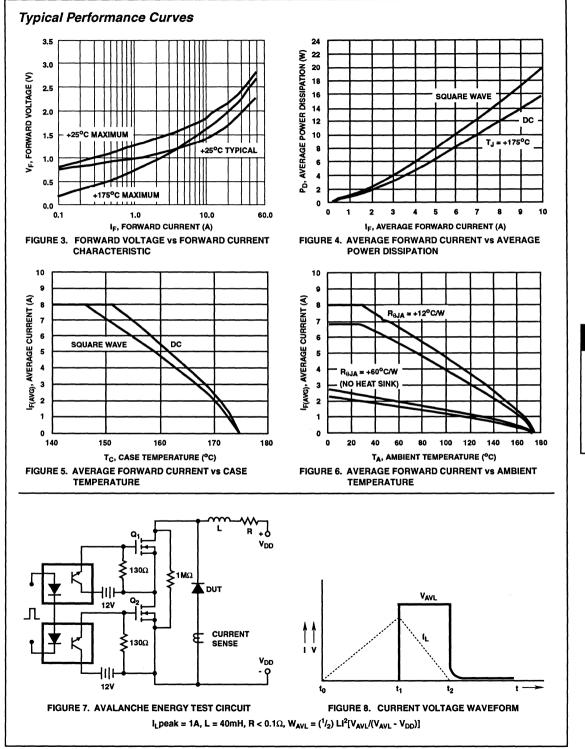
 $R_{\theta JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 30ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 200V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

MUR1510, MUR1515, MUR1520 and RUR1510, RUR1515, RUR1520 are ultrafast dual diodes ( $t_{RR}$  < 30ns) with soft recovery characteristics ( $t_A/t_B \approx 2$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

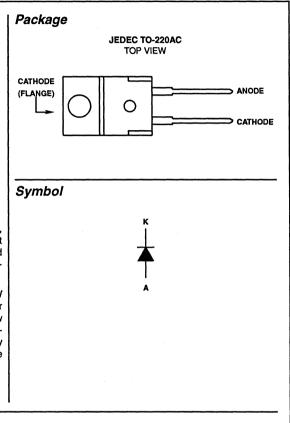
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	MUR1510 RURP1510	MUR1515 RURP1515	MUR1520 RURP1520
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100V	150V	200V
Working Peak Reverse Voltage	100V	150V	200V
DC Blocking Voltage	100V	150V	200V
Average Rectified Forward Current	15A	15A	15A
Peak Forward Repetitive CurrentI <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ)	30A	30A	30A
Nonrepetitive Peak Surge Current	200A	200A	200A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

#### 15A, 100V - 200V Ultrafast Diodes



						LIMITS					
	TEST	MUR	510, RUR	P1510	MUR	515, RUR	P1515	MUR			
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	l <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	0.85	-	-	0.85	-	-	0.85	v
	I <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.05	-	-	1.05	-	-	1.05	v
I <sub>R</sub> at	V <sub>R</sub> = 100V	-	-	500	-	-	-	-	-	•	μΑ
T <sub>C</sub> = +150°C	V <sub>R</sub> = 150V	-	•	-	•	-	500	-	-	-	μΑ
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	500	μΑ
T _ 1250C	V <sub>R</sub> = 100V	-	-	10	-	•	•	-	-	-	μΑ
	V <sub>R</sub> = 150V	-	-	-	-	-	10	-	-	•	μΑ
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	10	μΑ
t <sub>RR</sub>	l <sub>F</sub> = 1A	-	-	30	-	-	30	-	-	30	ns
	l <sub>F</sub> = 15A	-	-	35	-	-	35	-	-	35	ns
t <sub>A</sub>	I <sub>F</sub> = 1A	-	18	-	-	18	-	-	18	-	ns
	l <sub>F</sub> = 15A	-	20	-	-	20	-	-	20	-	ns
t <sub>B</sub>	l <sub>F</sub> = 1A	-	9	-	-	9	-	-	9	-	ns
	I <sub>F</sub> = 15A	-	10	-	-	10	-	•	10	-	ns
R <sub>elC</sub>		-	-	1.5	-	-	1.5	-	-	1.5	°C/W
WAVL	see Fig. 7 & 8	-	-	20	-	-	20	-	-	20	mj

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dl<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

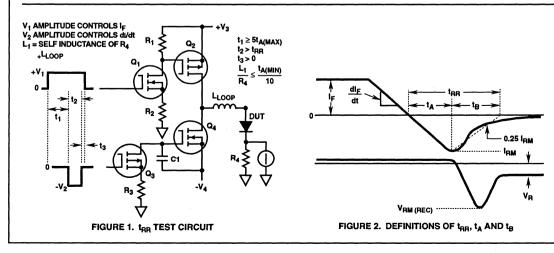
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

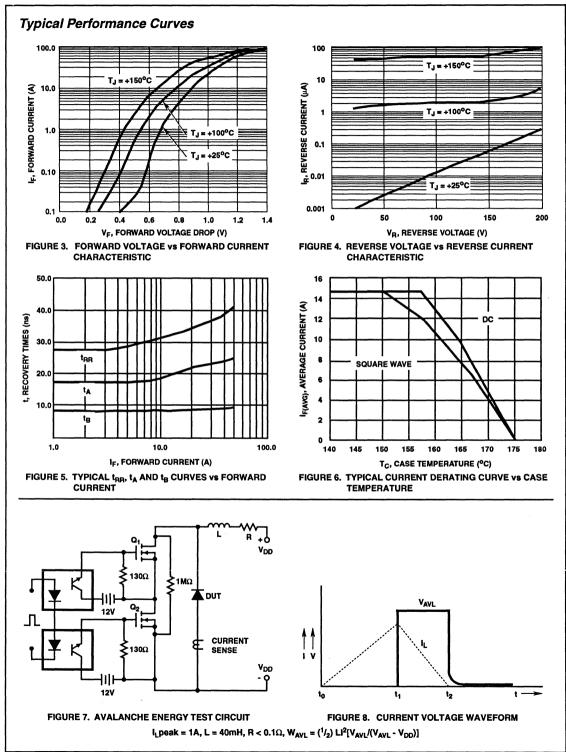
R<sub>eJC</sub> = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





# HARRIS MUR1540, RURP1540, MUR1550, RURP1550, MUR1560, RURP1560

#### December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 55ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 600V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

MUR1540, MUR1550, MUR1560 and RUR1540, RUR1550, RUR1560 are ultrafast dual diodes ( $t_{RR} < 55$ ns) with soft recovery characteristics ( $t_A/t_B \approx 2$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

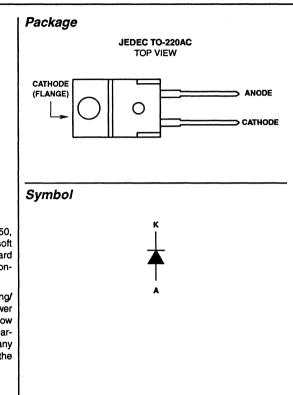
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

#### **Absolute Maximum Ratings** ( $T_c = +25^{\circ}C$ ), Unless Otherwise Specified

	MUR1540 RURP1540	MUR1550 RURP1550	MUR1560 RURP1560
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400V	500V	600V
Working Peak Reverse VoltageV <sub>RWM</sub>	400V	500V	600V
DC Blocking Voltage	400V	500V	600V
Average Rectified Forward Current	15A	15A	15A
Peak Forward Repetitive CurrentI <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ)	30A	30A	30A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	200A	200A	200A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

## 15A, 400V - 600V Ultrafast Diodes



#### Specifications MUR1540, MUR1550, MUR1560, RURP1540, RURP1550, RURP1560

						LIMITS					
	TEST	MUR	540, RUR	P1540	MUR	550, RUR	P1550	MUR1	560, RUR	P1560	1
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	1.12	-	-	1.20	-	-	1.20	v
	I <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.25	-	-	1.50	-	-	1.50	v
I <sub>R</sub> at	V <sub>R</sub> = 400V	-	-	500	-	-	-	-		-	μА
T <sub>C</sub> = +150°C	V <sub>R</sub> = 500V	-	-	-	-	-	500	-	-	-	μΑ
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	500	μΑ
$T_{0} = +25^{\circ}C$	V <sub>R</sub> = 400V	-		10	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V	-	-	-	-	-	10	-	-	-	μΑ
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	10	μA
t <sub>RR</sub>	l <sub>F</sub> = 1A	-	-	55	-	-	55	-	-	55	ns
	I <sub>F</sub> = 15A	-	-	60	-	-	60	-	-	60	ns
t <sub>A</sub>	I <sub>F</sub> = 1A	-	20	-	-	20	-	-	20	-	ns
	I <sub>F</sub> = 15A	-	30	-	-	30	-	-	30	-	ns
t <sub>B</sub>	I <sub>F</sub> = 1A	-	15	-	-	15	-	-	15	-	ns
	I <sub>F</sub> = 15A	-	17	-	-	17	-	-	20	-	ns
R <sub>eJC</sub>		-	-	1.5	-	-	1.5	-	•	1.5	°C/W
WAVL	see Fig. 7 & 8	-	-	20	-	• .	20	-	-	20	mj

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

#### DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs,D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at dI<sub>F</sub>/dt = 100A/µs (See Figure 2).

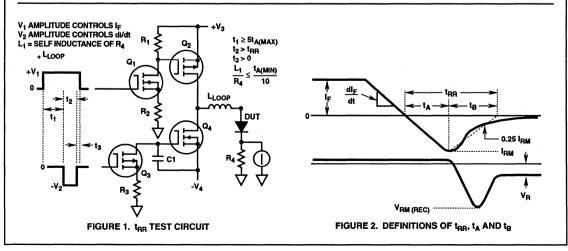
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

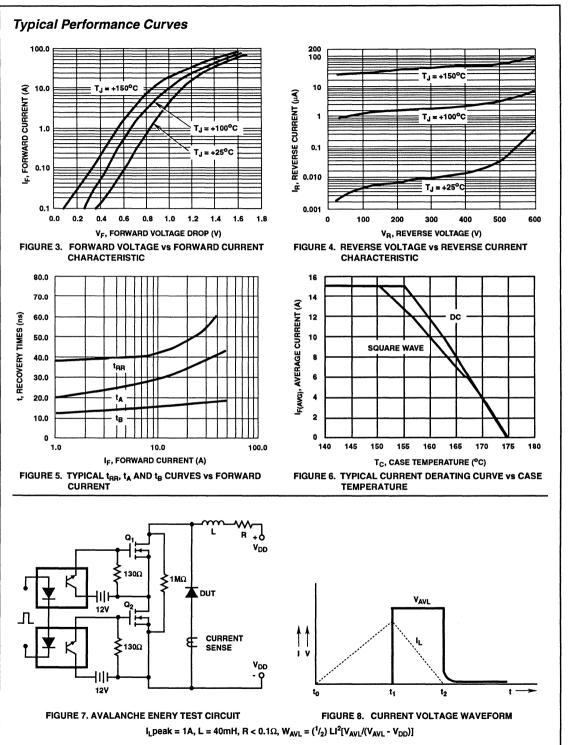
R<sub>BJC</sub> = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







# *RURP1570, RURP1580 RURP1590, RURP15100*

December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 100ns)
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 1000V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

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#### Description

RURP1570, RURP1580, RURP1590, RURP15100 are ultrafast diodes with soft recovery characteristics (t<sub>RR</sub> < 100ns). They have a low forward voltage drop and are silicon nitride passivated, ion-implanted, epitaxial construction.

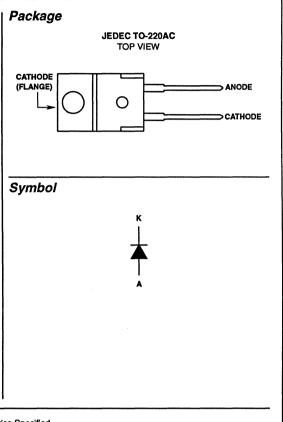
These devices are intended for use as freewheel/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

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Absolute Maximum Ratings (T <sub>c</sub> = +25°C), Unless Otherw	ise Specified			
	RURP1570	RURP1580	RURP1590	RURP15100
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	700V	800V	900V	1000V
Working Peak Reverse VoltageV <sub>RWM</sub>	700V	800V	900V	1000V
DC Blocking Voltage	700V	800V	900V	1000V
Average Rectified Forward CurrentI <sub>F(AV)</sub> (Total device forward current at rated $V_R$ and $T_C = +150^{\circ}C$ )	15 <b>A</b>	15 <b>A</b>	15A	15A
Peak Forward Repetitive Current	30A	30A	30A	30A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	200A	200A	200A	200A
Maximum Power Dissipation PD	100W	100W	100W	100W
Operating and Storage Temperature $\ldots \ldots T_{STG}, T_J$	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C

## 15A, 700V - 1000V Ultrafast Diodes



							LIM	ITS						
	TEST	R	URP157	0	R	URP158	30	R	URP159	90	RURP15100			
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	l <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-	-	1.50	v
	l <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.80	-	•	1.80	-	-	1.80	-	-	1.80	V
l <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	500	-	-	•	-	-	-	-	-	-	μΑ
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	-	-	-	-	-	500	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	•	-	•	-	-	500	-	-	-	μA
	V <sub>R</sub> = 1000V	-	-	-	-	•	•	-	•	-	-	-	500	μA
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	100	-	-	-	-	-	-	-	-	-	μA
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-		-	-	100	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	100	-	-	-	ns
	V <sub>R</sub> = 1000V	-	-	-	-	-	•	-	-	-	-	-	100	ns
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	100	-	-	100	-	-	100	-	-	100	ns
	l <sub>F</sub> = 15A	-	-	125	-	-	125	-	-	125	-	-	125	ns
t <sub>A</sub>	l <sub>F</sub> = 15A	-	75	-	-	75	-	-	75	•	•	75	-	ns
tB	I <sub>F</sub> = 15A	-	40	•	-	40	•	•	40	•	-	40	-	ns
R <sub>elC</sub>		-	-	1.5	-	•	1.5	-	-	1.5	-	-	1.5	°C/W
WAVL		-	-	20	-	-	20	-	•	20	•	•	20	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current .

 $t_{RR}$  = Reverse recovery time at  $dI_F/dt$  = 100A/µs (See Figure 2), summation of  $t_A$  +  $t_B$ .

 $t_{\text{A}}$  = Time to reach peak reverse current at dI\_F/dt = 100A/ $\mu s$  (See Figure 2).

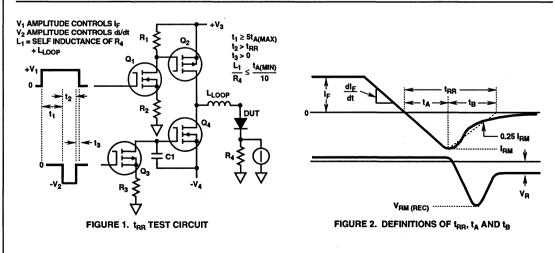
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

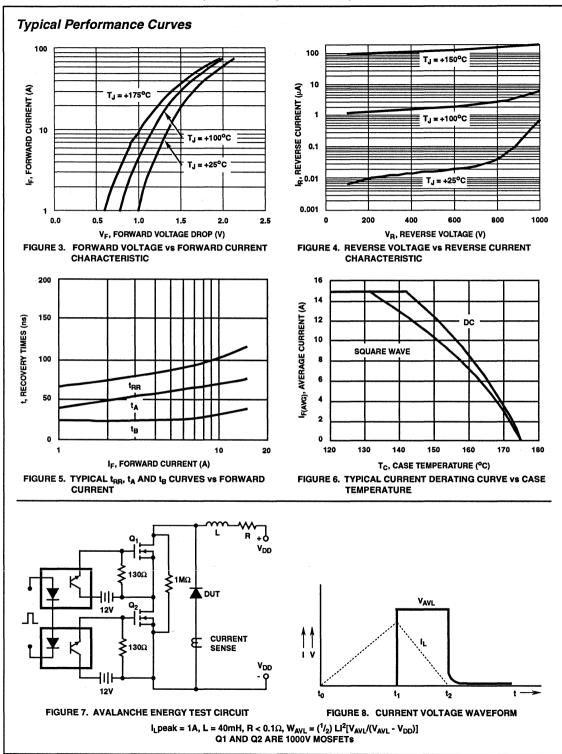
 $R_{\theta JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







# RURP3010, RURP3015 RURP3020

#### December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 45ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 200V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

RURP3010, RURP3015, RURP3020 are ultrafast diodes ( $t_{RR} < 45$ ns) with soft recovery characteristics ( $t_A/t_B \approx 1$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

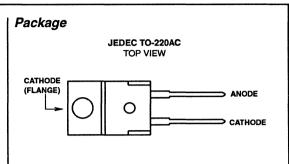
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

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ADSOLUTE MAXIMUM HATINGS (T <sub>C</sub> = +25°C), Unless Otherwise Specifie	ed		
	RURP3010	RURP3015	RURP3020
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100V	150V	200V
Working Peak Reverse VoltageV <sub>RWM</sub>	100V	150V	200V
DC Blocking Voltage V <sub>R</sub>	100V	150V	200V
Average Rectified Forward CurrentI <sub>F(AV)</sub> (Total device forward current at rated $V_R$ and $T_C = +150^{\circ}C$ )	30A	30A	30A
Peak Forward Repetitive CurrentI <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ)	70A	70Å	70A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	325A	325A	325A
Operating and Storage Temperature $\dots \dots \dots$	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

## 30A, 100V - 200V Ultrafast Diodes



Symbol



						LIMITS					
	TEST		RURP301	0	RURP3015			RURP3020			]
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	T -	-	0.85	-	-	0.85	-	-	0.85	V
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.00	•	-	1.00	-	-	1.00	V
I <sub>R</sub> at	V <sub>R</sub> = 100V	-	-	500	•	-	-	-	-	-	μА
T <sub>C</sub> = +150°C	V <sub>R</sub> = 150V	-	-	-	-	-	500	-	-	-	μΑ
	V <sub>R</sub> = 200V	•	-	-	•	-	-	-	-	500	μA
I <sub>R</sub> at	V <sub>R</sub> = 100V	-	-	30	•	-	-	-	-	-	μΑ
T <sub>C</sub> = +25	V <sub>R</sub> = 150V	-	-	-		-	30	-	-	-	μΑ
	V <sub>R</sub> = 200V	-	-	-	•	-	-	-	-	30	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	45	•	-	45	-	-	45	ns
	I <sub>F</sub> = 30A	•	-	50	-	-	50	-	-	50	ns
t <sub>A</sub>	I <sub>F</sub> = 1A	•	24	-	-	24	-	-	24	-	ns
	I <sub>F</sub> = 30A	-	28	-	-	28	-	-	28	-	ns
t <sub>B</sub>	I <sub>F</sub> = 1A	•	17	- 1	-	17	-	-	17	-	ns
	I <sub>F</sub> = 30A	-	20	•	-	20	-	-	20	-	ns
R <sub>elC</sub>	1	· ·	-	1.2	-	•	1.2	-	-	1.2	°C/W
WAVL	see Fig. 7 & 8	- 1	-	20	-	-	20	-	-	20	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_c/dt$  = 100A/µs (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

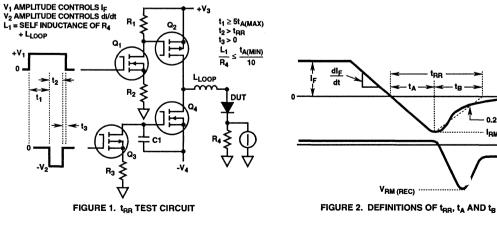
 $R_{\theta JC}$  = Thermal resistance junction to case.

WAVI = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

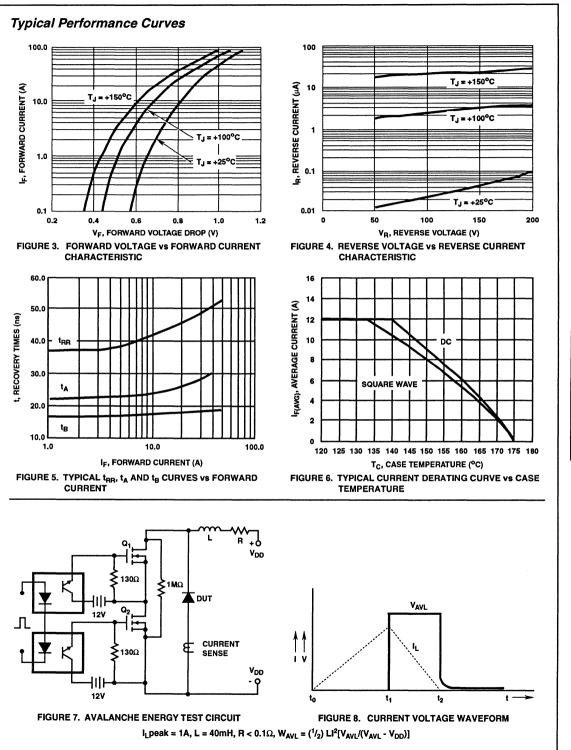




0.25 i<sub>RM</sub> IRM

A

V۵



ULTRAFAST SINGLE DIODES



# RURP3040, RURP3050 RURP3060

#### December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 55ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 600V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

RURP3010, RURP3015, RURP3020 are ultrafast diodes ( $t_{RR} < 55$ ns) with soft recovery characteristics ( $t_A/t_B \approx 1$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

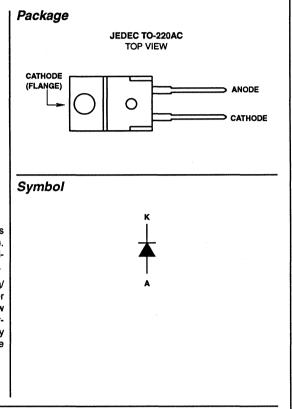
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RURP3040	RURP3050	RURP3060
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400V	500V	600V
Working Peak Reverse Voltage V <sub>RWM</sub>	400V	500V	600V
DC Blocking Voltage	400V	500V	600V
Average Rectified Forward Current	30A	30A	30A
Peak Forward Repetitive Current	70A	70A	70A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	325A	325A	325A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

## 30A, 400V - 600V Ultrafast Diodes



## Specifications RURP3040, RURP3050, RURP3060

						LIMITS					
	TEST	RURP3040			RURP3050			F	1		
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	1.30	-	-	1.30	-	-	1.30	V
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.50	-	-	1.50	-	-	1.50	v
I <sub>R</sub> at	V <sub>R</sub> = 400V	· ·	-	1	-	-	-	-	-	-	μΑ
$T_{C} = +150^{\circ}C$	V <sub>R</sub> = 500V	-	-	-	-	-	1	-	-	-	μΑ
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	1	μΑ
I <sub>R</sub> at	V <sub>R</sub> = 400V	1.	-	30	-	-	-	-	-	-	μΑ
$T_{C} = +25^{\circ}C$	V <sub>R</sub> = 500V	-	-	-	-	-	30	-	-	-	μΑ
	V <sub>R</sub> = 600V	-	-	-	-	-	•	-	-	30	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	55	•	-	55	-	-	55	ns
	I <sub>F</sub> = 30A	-	-	60	-	-	60	-	-	60	ns
t <sub>A</sub>	I <sub>F</sub> = 1A	-	20	-	-	20	-	-	20	-	ns
	I <sub>F</sub> = 30A	-	38	-	-	38	-	-	38	-	ns
t <sub>B</sub>	I <sub>F</sub> = 1A	· ·	15	-	-	15	-	-	15	-	ns
	I <sub>F</sub> = 30A	-	20	-	-	20	-	-	20	-	ns
R <sub>elc</sub>		-	-	1.2	•	•	1.2	•	-	1.2	°C/W
WAVL	see Fig. 7 & 8	-	-	20	-	-	20	•	-	20	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300 µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at  $dI_F/dt$  = 100A/µs (See Figure 2), summation of  $t_A$  +  $t_B$ .

 $t_{\text{A}}$  = Time to reach peak reverse current at dI\_F/dt = 100A/µs (See Figure 2).

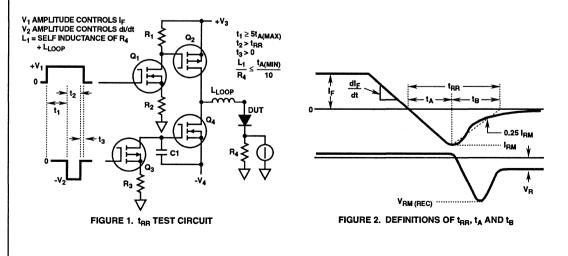
 $t_B$  = Time from peak  $I_{RM}$  to projected zero crossing of  $I_{RM}$  based on a straight line from peak  $I_{RM}$  through 25% of  $I_{RM}$  (See Figure 2).

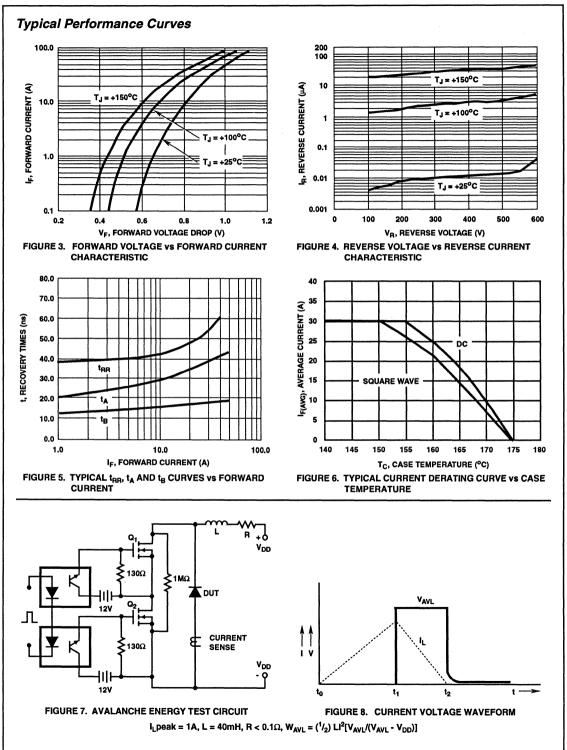
 $R_{\theta JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







# RURP3070, RURP3080 RURP3090, RURP30100

#### December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 110ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 1000V
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

RURP3070, RURP3080, RURP3090, RURP30100 are ultrafast diodes with soft recovery characteristics ( $t_{\rm RR}$  < 110ns). They have a low forward voltage drop and are silicon nitride passivated, ion-implanted, epitaxial construction.

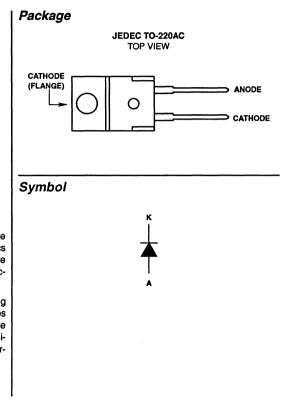
These devices are intended for use as flywheel/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-220AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RURP3070	RURP3080	RURP3090	RURP30100
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	700V	800V	900V	1000V
Working Peak Reverse VoltageV <sub>RWM</sub>	700V	800V	900V	1000V
DC Blocking Voltage V <sub>R</sub>	700V	800V	900V	1000V
Average Rectified Forward Current $I_{F(AV)}$ ( $T_C = +121^{\circ}C$ )	30A	30A	30A	30A
Peak Forward Repetitive CurrentI <sub>FRM</sub> (Square wave 20kHZ)	60A	60A	60A	60A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	300A	300A	300A	300A
Maximum Power Dissipation PD	125W	125W	125W	125W
Operating and Storage Temperature $\dots \dots T_{STG}$ , T <sub>J</sub> -	65°C to +175°C	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C

## 30A, 700V - 1000V Ultrafast Diodes



#### Specifications RURP3070, RURP3080, RURP3090, RURP30100

			LIMITS											
	TEST	RURP3070			RURP3080			RURP3090			RURP30100			
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	1.60	-	-	1.60	-	-	1.60	-	-	1.60	v
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	-	-	1.80	-	-	1.80	v
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	1	-	-	-	-	-	•	-	-	-	mA
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	-	-	-	-	-	1	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	1		-	-	mA
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	•	-	-	•	-	1	mA
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	100	-	-	-	-	-	-	-	-	-	μA
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-	-	-	-	100	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	100	-	-	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	100	μA
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	110	-	-	110	-	-	110	-	-	110	ns
	I <sub>F</sub> = 30A	-	-	150	-	-	150	-	-	150	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A	-	90	-	-	90	-	-	90	-	-	90	-	ns
tg	I <sub>F</sub> = 30A	-	45	-	-	45	-	-	45	-	-	45	-	ns
R <sub>ec</sub>		-	-	1.2	-	-	1.2	-	-	1.2	-	-	1.2	°C/W
WAVL			-	20	-	-	20	-	-	20	-	-	20	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs,D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

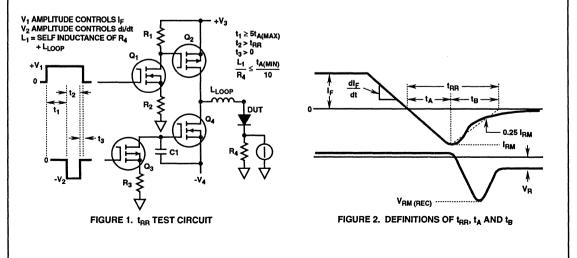
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

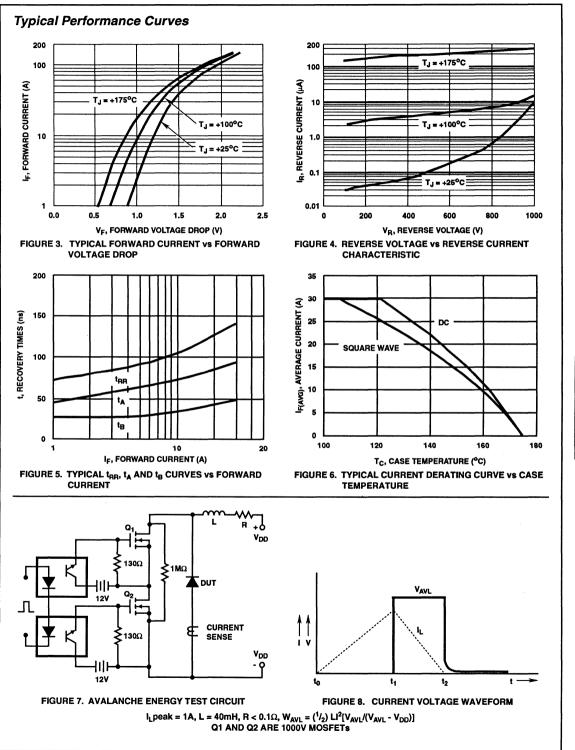
R<sub>eJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



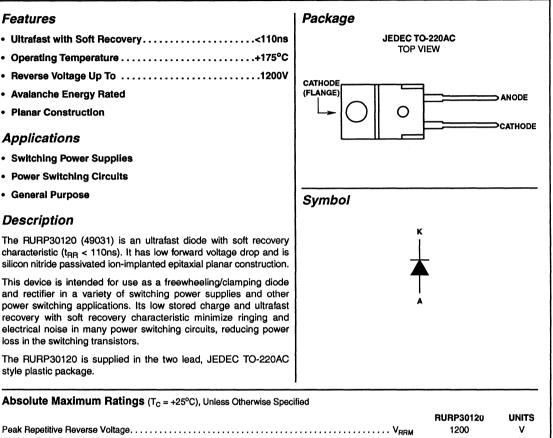


ULTRAFAST SINGLE DIODES



# RURP30120

## 30A. 1200V Ultrafast Diode



Peak Repetitive Reverse VoltageV <sub>RRM</sub>	1200	v
Working Peak Reverse VoltageV <sub>RWM</sub>	1200	v
DC Blocking VoltageV <sub>B</sub>	1200	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>C</sub> = +110°C)	30	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	60	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	300	A
Maximum Power Dissipation	125	W
Avalanche Energy (L = 40mH)W <sub>AVL</sub>	30	mj
Operating and Storage Temperature	-65 to +175	°C

December 1993

- Reverse Voltage Up To .....1200V
- Planar Construction
- General Purpose

## Specifications RURP30120

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

			LIMITS		
SYMBOL	TEST CONDITION	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	2.1	v
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	-	-	1.9	v
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +25°C	-	-	100	μА
IR	V <sub>R</sub> = 1200V, T <sub>C</sub> = +150°C	-	-	1	mA
t <sub>RR</sub>	$I_{F} = 1A, dI_{F}/dt = 100A/\mu s$	-	-	110	ns
	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	90	-	ns
t <sub>B</sub>	l <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	45	-	ns
R <sub>eJC</sub>		-	-	1.2	°C/W

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time(See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

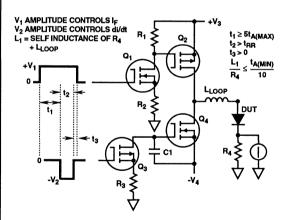
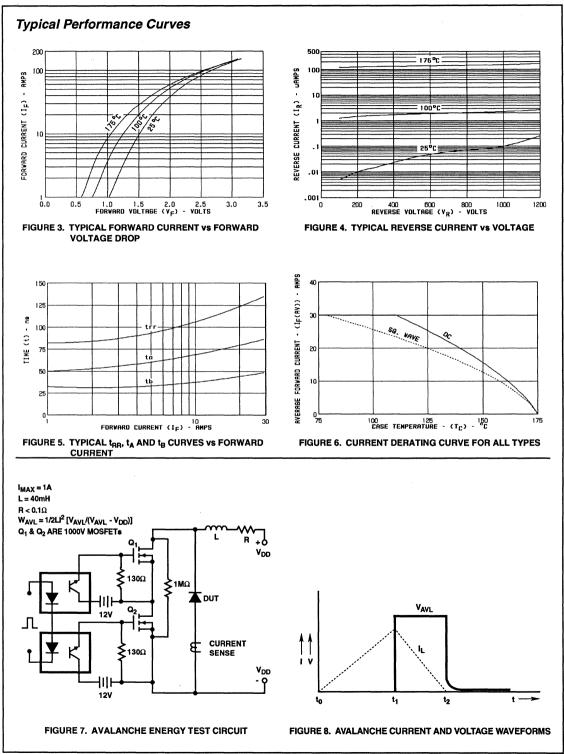


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT

0.25 IRM IF dt 0.25 IRM IRM VRM (REC)

FIGURE 2. t<sub>BR</sub> WAVEFORMS AND DEFINITIONS





# RURG3010, RURG3015 **RURG3020**

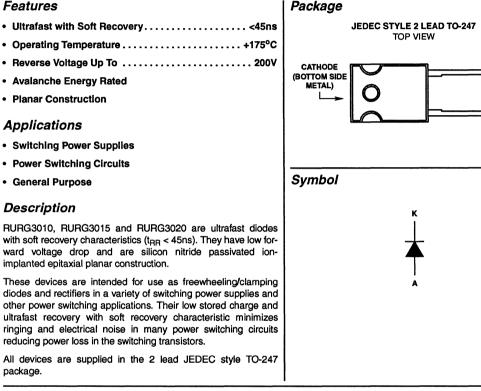
January 1994

package.

## 30A, 100V - 200V Ultrafast Diodes

ANODE

CATHODE



#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RURG3010	RURG3015	RURG3020	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100	150	200	v
Working Peak Reverse VoltageVRWM	100	150	200	v
DC Blocking Voltage V <sub>R</sub>	100	150	200	v
Average Rectified Forward Current $\dots I_{F(AV)}$ (T <sub>c</sub> = +145°C)	30	30	30	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	70	70	70	Α
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	325	325	325	A
Maximum Power Dissipation PD	125	125	125	W
Avalanche Energy (L = 40mH) W <sub>AVL</sub>	20	20	20	mj
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	°C

			LIMITS										
		RURG3010			RURG3015			F	1				
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS		
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	1.0	-	-	1.0	-	-	1.0	v		
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	` <b>-</b>	-	0.85	-	-	0.85	-	-	0.85	v		
I <sub>R</sub>	V <sub>R</sub> = 100V, T <sub>C</sub> = +25°C	-	-	30	-	-	-	-	·-	-	μA		
	V <sub>R</sub> = 150V, T <sub>C</sub> = +25°C	-	-	-	-	-	30	-	-	-	μΑ		
	V <sub>R</sub> = 200V, T <sub>C</sub> = +25°C	-		-	-	-	-	-	-	30	μΑ		
I <sub>R</sub>	V <sub>R</sub> = 100V, T <sub>C</sub> = +150°C	-	-	500	-	-	-	-	-	-	μΑ		
	V <sub>R</sub> = 150V, T <sub>C</sub> = +150°C	-	-	-	-	-	500	-	-	-	μΑ		
	$V_{R} = 200V, T_{C} = +150^{\circ}C$	-	-	-	-	-	-	-	-	500	μА		
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	45	-	-	45	-	-	45	ns		
	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	-	50	-	-	50	-	-	50	ns		
t <sub>A</sub>	l <sub>F</sub> = 30A, dI <sub>F</sub> /dt= 100A/μs	-	20	-	-	20	-	-	20	-	ns		
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	15	-	-	15	-	-	15	-	ns		
R <sub>eJC</sub>		-	-	1.2	-	-	1.2	-	-	1.2	°C/W		

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BB}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

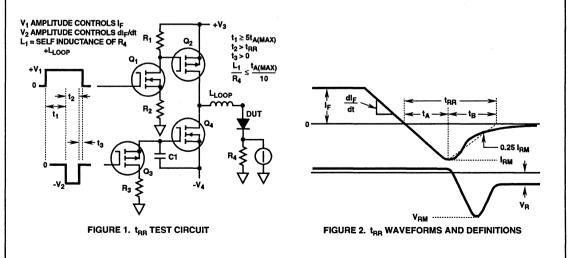
t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

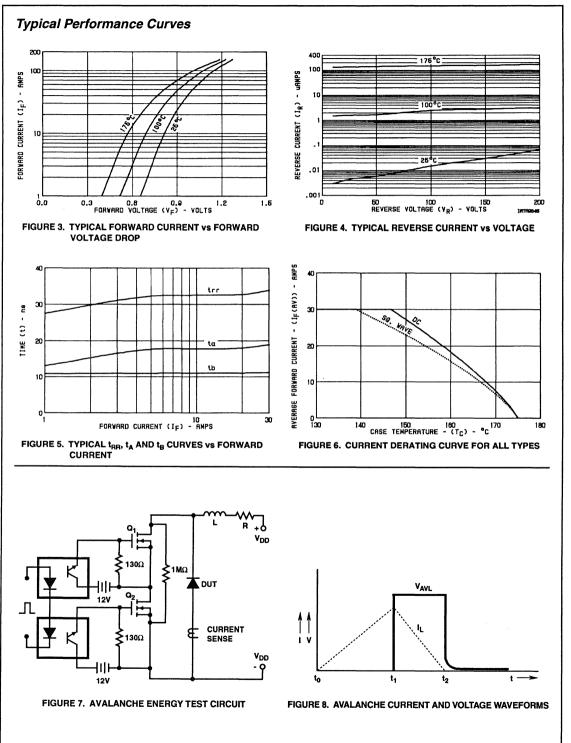
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.





5

SINGLE DIODES

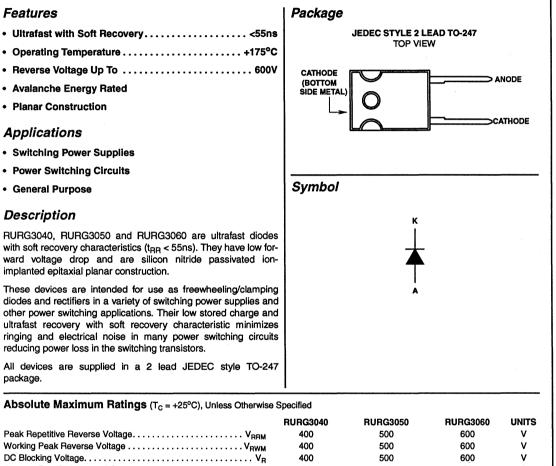
ULTRAFAST



# RURG3040, RURG3050 RURG3060

#### January 1994

## 30A, 400V - 600V Ultrafast Diodes



Average Rectified Forward Current $I_{F(AV)}$ (T <sub>C</sub> = +145°C)	30	30	30	Α
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	70	70	70	Α
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	325	325	325	Α
Maximum Power Dissipation P <sub>D</sub>	125	125	125	w
Avalanche Energy (L = 40mH) W <sub>AVL</sub>	20	20	20	mj
Operating and Storage Temperature $T_{STG},T_{J}$	-65 to +175	-65 to +175	-65 to +175	°C

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						LIMITS					
		RURG3040			RURG3050			RURG3060			I
SYMBOL	TEST CONDITION	MIN	ТҮР	МАХ	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	1.5	-	-	1.5	-	-	1.5	v
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	-	-	1.3	-	-	1.3	-	-	1.3	v
IR	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	30	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	30	-	-	-	μA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	30	μΑ
IR	V <sub>R</sub> = 400V, T <sub>C</sub> = +150°C	-	-	1	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V, T <sub>C</sub> = +150°C	-	-	-	-	-	1	-	-	-	μA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	1	μA
t <sub>RR</sub>	$I_F = 1A$ , $dI_F/dt = 100A/\mu s$	-	-	55	-	-	55	-	-	55	ns
	l <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	-	60	-	-	60	-	-	60	ns
t <sub>A</sub>	l <sub>F</sub> = 30A, dI <sub>F</sub> /dt= 100A/μs	-	30	-		30	-	-	30	-	ns
t <sub>B</sub>	l <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	20	-	-	20	-	-	20	-	ns
R <sub>eJC</sub>		-	-	1.2		-	1.2	-	-	1.2	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dl<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_{\text{A}}$  = Time to reach peak reverse current at dI\_F/dt = 100A/µs (See Figure 2).

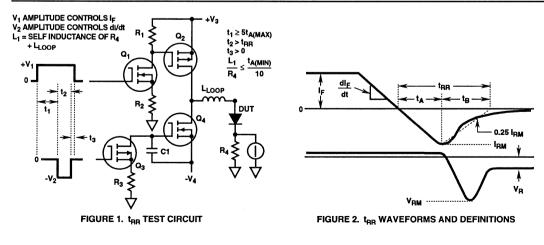
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

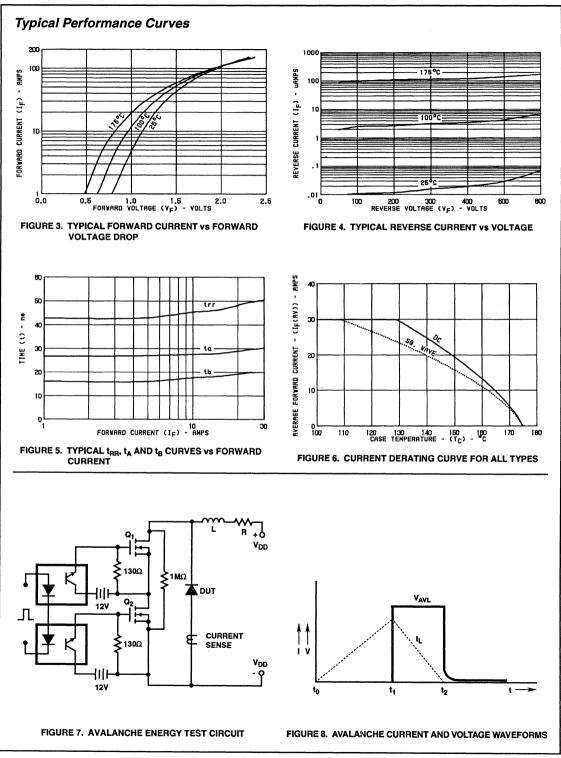
 $R_{\theta JC}$  = Thermal resistance junction to case.

 $W_{\text{AVL}}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



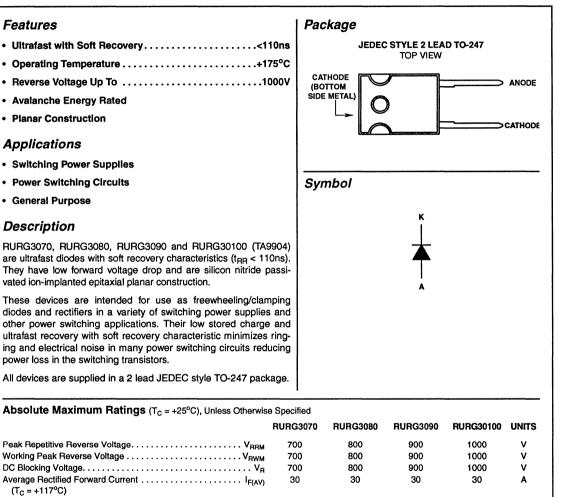




# RURG3070, RURG3080 RURG3090, RURG30100

#### December 1993

## 30A, 700V - 1000V Ultrafast Diodes



60

300

125

30

60

300

125

30

-65 to +175

60

300

125

30

-65 to +175

(Square Wave, 20kHz)

(Halfwave, 1 phase, 60Hz)

Repetitive Peak Surge Current. ..... IFSM

Nonrepetitive Peak Surge Current ...... IFSM

Maximum Power Dissipation ..... PD

Avalanche Energy ...... W<sub>AVL</sub>

60

300

125

30

-65 to +175

Δ

w

mj

°C

#### Specifications RURG3070, RURG3080, RURG3090, RURG30100

		LIMITS												
	TEST CONDITION	RURG3070			RURG3080			RURG3090			RURG30100			
SYMBOL		MIN	ТҮР	MAX	MIN	түр	МАХ	MIN	ТҮР	МАХ	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	1.8	-	-	1.8	-	-	1.8	-	-	1.8	v
VF	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	-	-	1.6	-	-	1.6	-	-	1.6	-	-	1.6	v
I <sub>R</sub>	V <sub>R</sub> = 700V, T <sub>C</sub> = +25°C	-	-	100	-	-	-	-	-	-	-	-	-	μA
	V <sub>R</sub> =800V, T <sub>C</sub> = +25°C	-	-	-	-	-	100	-	-	-	-	-	-	μA
	$V_{R} = 900V, T_{C} = +25^{\circ}C$	-	-	-	-	-	-	-	-	100	-	-	-	μA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	-	-	-	100	μA
l <sub>R</sub>	$V_{R} = 700V, T_{C} = +150^{\circ}C$	-	-	1	-	-	-	-	-	-	-	-	-	mA
	$V_{R} = 800V, T_{C} = +150^{\circ}C$	-	-	-	-	-	1	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	1	-	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	-	-	-	1	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	110	-	-	110	-	-	110	-	-	110	ns
	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	-	150	-	-	150	-	-	150	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /d t= 100A/μs	-	90	-	-	90	-	-	90	-	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	45	-	-	45	-	-	45	-		45	-	ns
R <sub>eJC</sub>		-	-	1.2	-	-	1.2	-	-	1.2		-	1.2	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

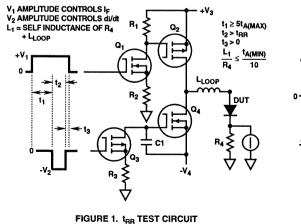
t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

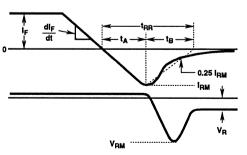
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

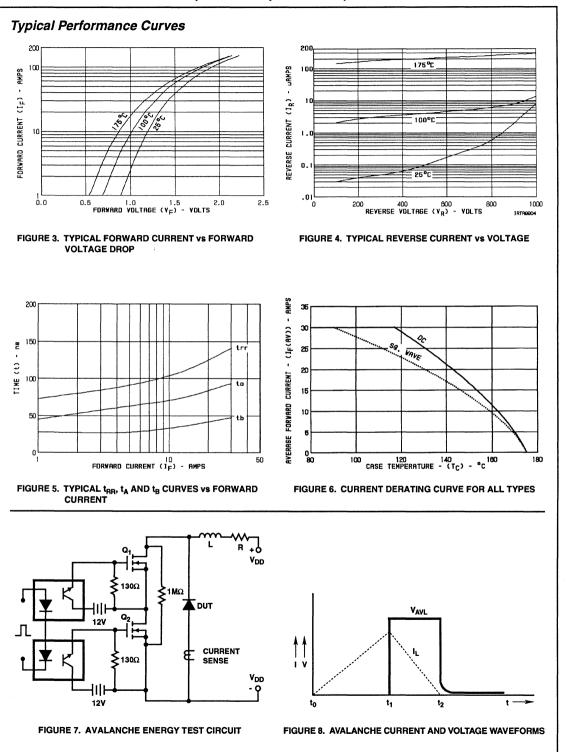
D = duty cycle.





#### FIGURE 2. t<sub>RR</sub> WAVEFORMS AND DEFINITIONS

## RURG3070, RURG3080, RURG3090, RURG30100



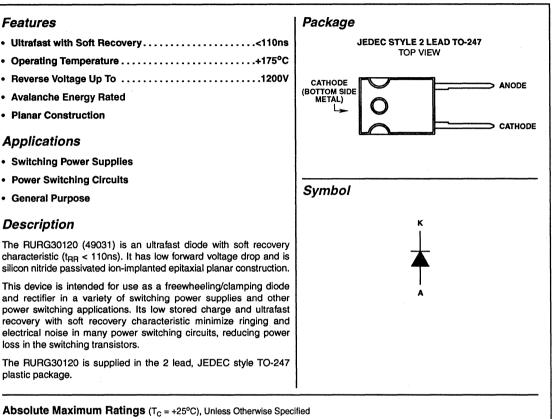
ULTRAFAST SINGLE DIODES



December 1993

# RURG30120

## 30A, 1200V Ultrafast Diode



#### RURG30120 1200 1200 1200 Average Rectified Forward Current 30 $(T_{C} = +110^{\circ}C)$ Repetitive Peak Surge Current......IFSM 60 (Square Wave, 20kHz) Nonrepetitive Peak Surge Current ...... I<sub>FSM</sub> 300 (Halfwave, 1 phase, 60Hz) 125 Avalanche Energy (L = 40mH) ..... Wavi 30 Operating and Storage Temperature

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UNITS

ν

v

v

A

A

A

w

mj

°C

-65 to +175

## Specifications RURG30120

SYMBOL	TEST CONDITION	MIN	ТҮР	МАХ	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	2.1	V	
V <sub>F</sub>	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	-	-	1.9	v	
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +25°C	-	-	100	μΑ	
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +150°C	-	-	1	mA	
t <sub>RR</sub>	$I_F = 1A$ , $dI_F/dt = 100A/\mu s$	-	-	110	ns	
	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs	-	-	150	ns	
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt= 100A/μs	-	90	-	ns	
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/µs	-	45	-	ns	
R <sub>eJC</sub>		-	-	1.2	°C/W	

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current (pw = 300µs, D = 2%).

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>eJC</sub> = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.

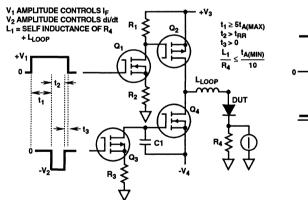
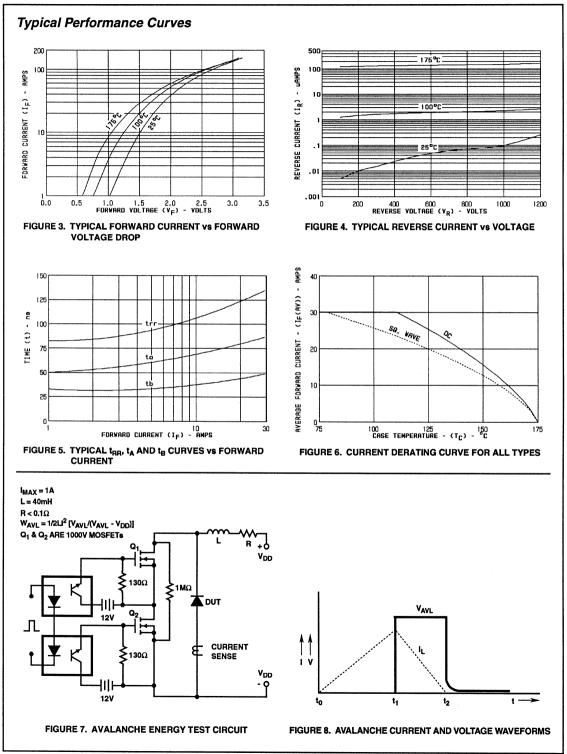


FIGURE 1. t<sub>BB</sub> TEST CIRCUIT



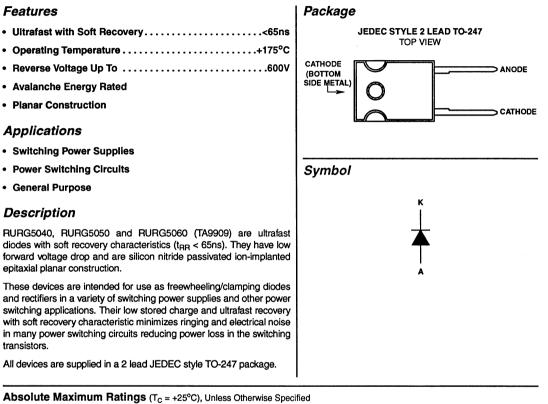


December 1993

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## RURG5040, RURG5050 RURG5060

## 50A, 400V - 600V Ultrafast Diodes



#### **RURG5040 RURG5050 RURG5060** UNITS Peak Repetitive Reverse Voltage ......VBBM 400 500 600 v Working Peak Reverse Voltage ..... VRWM 400 500 600 v DC Blocking Voltage.....V<sub>R</sub> 400 500 600 v Average Rectified Forward Current ..... IF(AV) 50 50 50 A (T<sub>c</sub> = +102°C) Repetitive Peak Surge Current..... I<sub>FSM</sub> 100 100 100 A (Square Wave, 20kHz) Nonrepetitive Peak Surge Current ..... I<sub>FSM</sub> 500 500 500 Δ (Halfwave, 1 phase, 60Hz) Maximum Power Dissipation ......Pn 150 150 150 w 40 40 40 mj °C -65 to +175 -65 to +175 -65 to +175

### Specifications RURG5040, RURG5050, RURG5060

						LIMITS					
		F	RURG504	0	F	RURG5050			RURG5060		
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 50A, T <sub>C</sub> = +25°C	-	-	1.6	-	-	1.6	-	-	1.6	v
V <sub>F</sub>	I <sub>F</sub> = 50A, T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	v
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C		-	250	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	μΑ
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	•	-	-	-	-	250	μA
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = 150°C	-	•	1.5	-	- 1	-	-	-	-	mA
	V <sub>R</sub> = 500V, T <sub>C</sub> = 150°C	-	-	-	-	-	1.5	-	-	-	mA
	V <sub>R</sub> = 600V, T <sub>C</sub> = 150°C	-	-	-	-	-	-	-	-	1.5	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	65	-	-	65	-	-	65	ns
	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	-	75	-	-	75	-	· -	75	ns
t <sub>A</sub>	l <sub>F</sub> = 50A, dI <sub>F</sub> /dt= 100A/μs	-	30	-	-	30	-	-	30	-	ns
t <sub>B</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	20	-	-	20	-	-	20	-	ns
R <sub>eJC</sub>		-		1	-	-	1	-	-	1	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt = 100A/\mu s$  (See Figure 2).

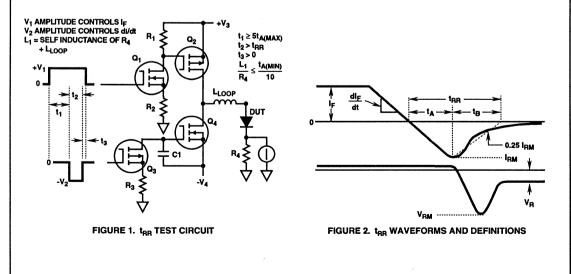
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

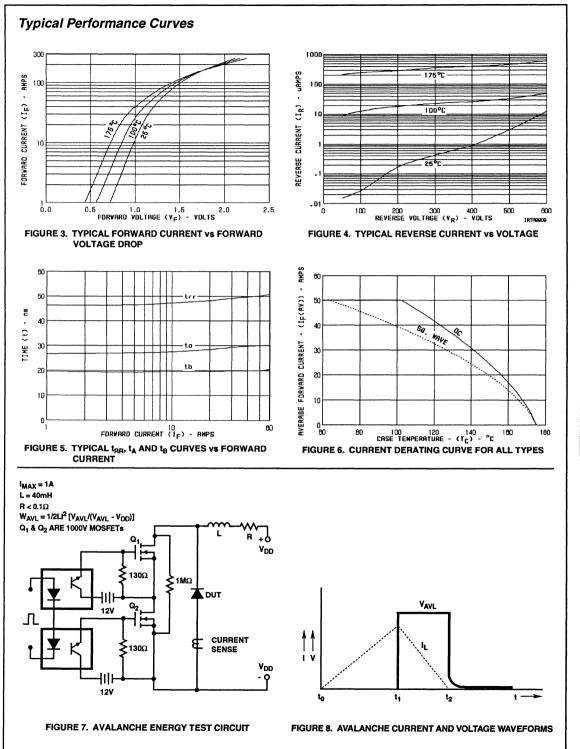
R<sub>BJC</sub> = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





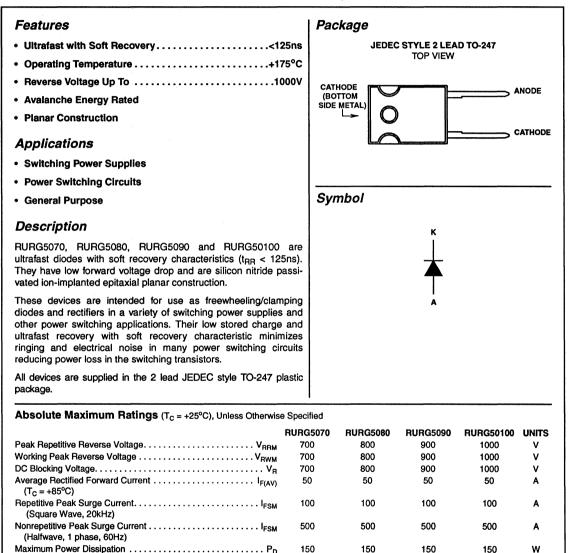
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## *RURG5070, RURG5080 RURG5090, RURG50100*

#### December 1993

## 50A, 700V - 1000V Ultrafast Diodes



Avalanche Energy ..... WAVL

40

-65 to +175

mj

°C

40

40

-65 to +175

40

-65 to +175

### Specifications RURG5070, RURG5080, RURG5090, RURG50100

							LIM	ITS						
		R	URG50	70	R	URG50	B0	RURG5090			RURG50100			
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
VF	I <sub>F</sub> = 50A, T <sub>C</sub> = +25°C	-	-	1.9	-	-	1.9	-	-	1.9	-	-	1.9	v
V <sub>F</sub>	I <sub>F</sub> = 50A, T <sub>C</sub> = +150°C	-	-	1.7	-	-	1.7	-	-	1.7	-	-	1.7	v
I <sub>R</sub>	V <sub>R</sub> = 700V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	-	-	-	μΑ
	V <sub>R</sub> =800V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 900V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	-	-	-	μΑ
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	-	-	-	250	μΑ
I <sub>R</sub>	V <sub>R</sub> = 700V, T <sub>C</sub> = +150°C	-	-	1.5	-	-	-	-	-	-	-	-	-	mA
	V <sub>R</sub> = 800V, T <sub>C</sub> = +150°C	-	-	-	-	-	1.5	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	1.5	-	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	-	-	-	1.5	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	125	-	-	125	-	-	125	-	-	125	ns
	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	-	200	-	-	200	-	-	200	-	-	200	ns
t <sub>A</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt= 100A/μs	-	90	-	-	90	-	-	90	-	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	40	-	-	40	-	-	40	-	-	40	-	ns
R <sub>eJC</sub>		-	-	1.0	-	-	1.0	-	-	1.0	-	-	1.0	°C/V

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt = 100A/\mu s$  (See Figure 2).

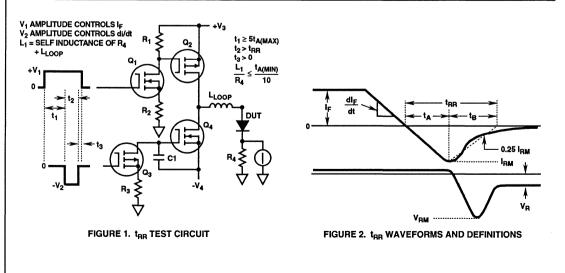
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

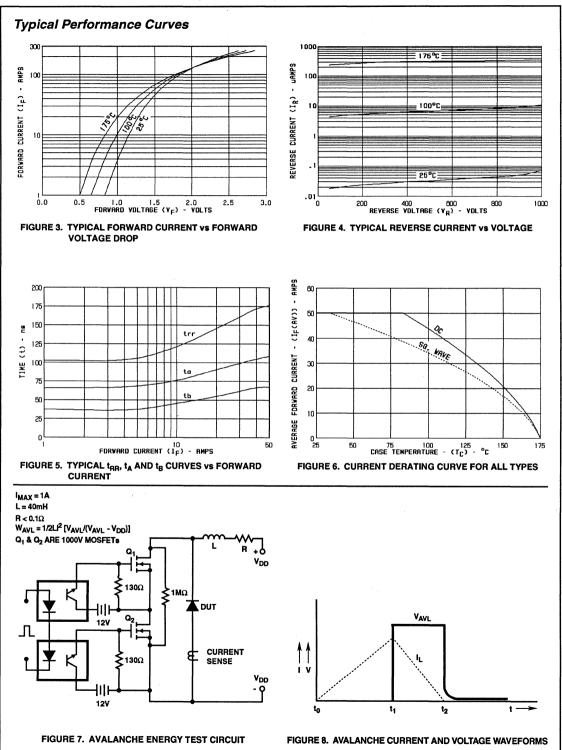
R<sub>0JC</sub> = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



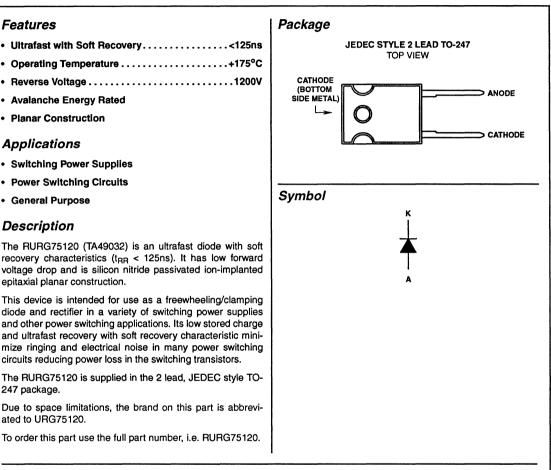




# RURG75120

#### December 1993

## 75A, 1200V Ultrafast Diode



#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RURG75120	UNITS	
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	1200	v	
Working Peak Reverse Voltage	1200	v	
DC Blocking Voltage	1200	v	
Average Rectified Forward Current $I_{F(AV)}$ ( $T_C = +54.75^{\circ}C$ )	75	Α	
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	150	Α	
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	500	Α	
Maximum Power Dissipation	190	w	
Avalanche Energy (L = 40mH)	50	mj	
Operating and Storage Temperature	-65 to +175	°C	

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### Specifications RURG75120

				LIMITS			
SYMBOL	TE	ST CONDITION	MIN	ТҮР	МАХ	UNITS	
V <sub>F</sub>	l <sub>F</sub> = 75A		-	-	2.1	v	
V <sub>F</sub>	l <sub>F</sub> = 75A	$T_{\rm C} = +150^{\rm o}{\rm C}$	-	-	1.9	v	
I <sub>R</sub>	V <sub>R</sub> = 1200V			-	250	μA	
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C			2	mA	
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	125		
t <sub>RR</sub>	l <sub>F</sub> = 75A, dl <sub>F</sub> /dt = 1	00A/µs	-	-	200		
t <sub>A</sub>	l <sub>F</sub> = 75A, dl <sub>F</sub> /dt = 1	00A/µs	-	90	-	ns	
t <sub>B</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 1	00A/µs	-	65	-		
R <sub>NC</sub>			-	-	0.8	°C/W	

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>OJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

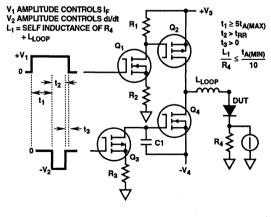
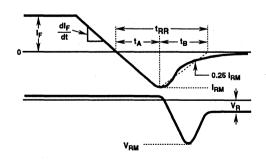
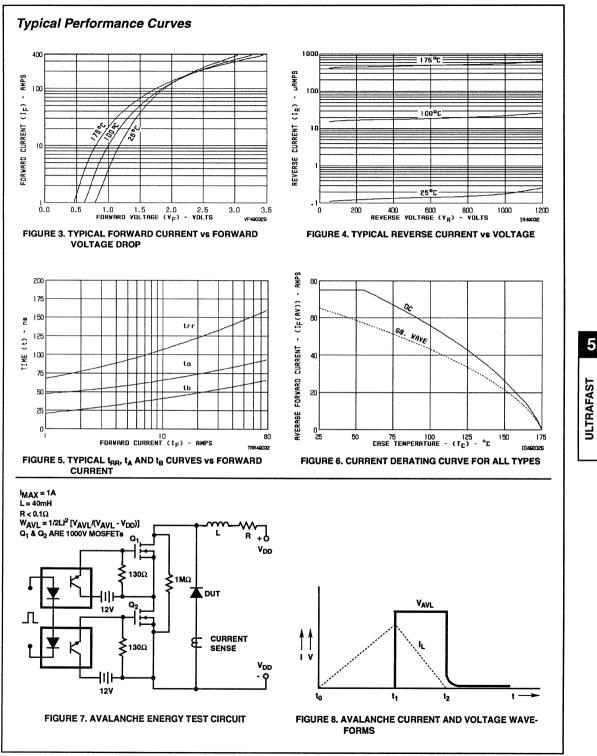


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





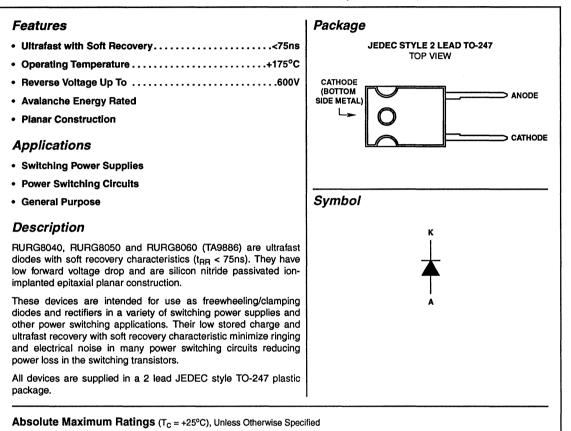
SINGLE DIODES



## RURG8040, RURG8050 RURG8060

#### December 1993

## 80A, 400V - 600V Ultrafast Diodes



	RURG8040	RURG8050	RURG8060	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400	500	600	v
Working Peak Reverse Voltage V <sub>RWM</sub>	400	500	600	V
DC Blocking VoltageV <sub>R</sub>	400	500	600	V
Average Rectified Forward CurrentI <sub>F(AV)</sub> (T <sub>C</sub> = +72°C)	80	80	80	A
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	160	160	160	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	800	800	800	A
Maximum Power DissipationPD	180	180	180	w
Avalanche Energy (L = 40mH)WAVL	50	50	50	mj
Operating and Storage TemperatureT <sub>STG</sub> ,T <sub>J</sub>	-65 to +175	-65 to +175	-65 to +175	°Ċ

						LIMITS					
		F	RURG804	0	F	RURG805	i0	RURG8060			
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = +25°C	-	-	1.6	-	-	1.6	-	-	1.6	v
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	v
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-		-	μA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	μA
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +150°C	-	-	2.0	-	-	-	-	-	-	mA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +150°C	-	-	-	-	-	2.0	-	-	-	mA
	$V_{R} = 600V, T_{C} = +150^{\circ}C$	-	-	-	-	-	-	-	-	2.0	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	75	-	-	75	-	-	75	ns
	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	-	85	-		85	-	-	85	ns
t <sub>A</sub>	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt= 100A/μs	-	40	-	-	40	-	-	40	-	ns
t <sub>B</sub>	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	25	-	-	25	-	-	25	-	ns
R <sub>eJC</sub>		-	-	0.83	-	-	0.83	-	-	0.83	°C/W

#### . . . . . ... - -\_.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

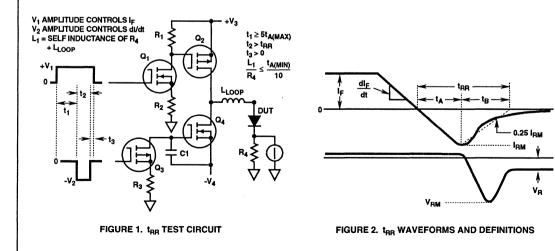
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>BJC</sub> = Thermal resistance junction to case.

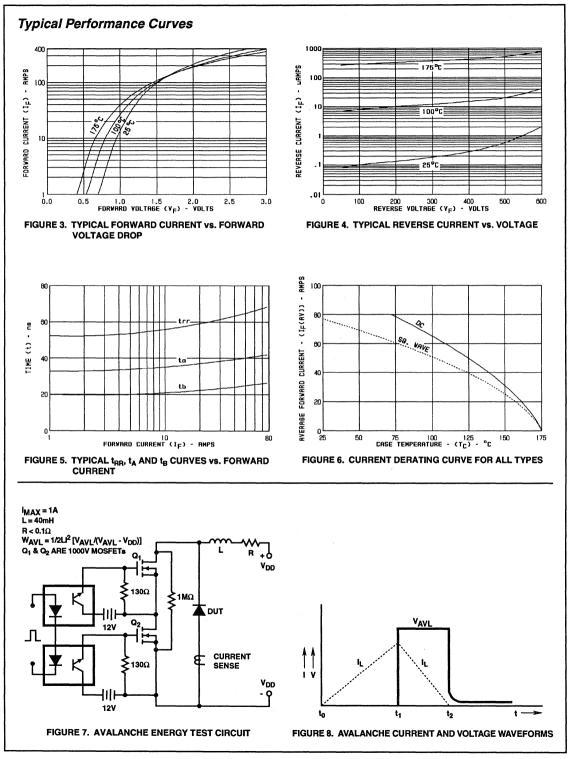
W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



5





## RURG8070, RURG8080 RURG8090, RURG80100

#### December 1993

transistors.

age.

## 80A, 700V - 1000V Ultrafast Diodes

#### Features Package JEDEC STYLE 2 LEAD TO-247 TOP VIEW Operating Temperature .....+175°C Reverse Voltage Up To ......1000V CATHODE **Avalanche Energy Rated** (BOTTOM SIDE METAL) Planar Construction Applications CATHODE Switching Power Supplies Power Switching Circuits General Purpose Symbol Description RURG8070, RURG8080, RURG8090 and RURG80100 are ultrafast diodes with soft recovery characteristics (t<sub>BB</sub> < 125ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction. These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching All devices are supplied in the 2 lead JEDEC style TO-247 plastic pack-Absolute Maximum Ratings (Tc = +25°C), Unless Otherwise Specified **RURG8070 RURG8080** RURG8090 RURG80100 UNITS Peak Repetitive Reverse Voltage...... V<sub>RRM</sub> 700 900 1000 800 v

800 900 1000 V	700	Working Peak Reverse VoltageV <sub>RWM</sub>
800 900 1000 V	700	DC Blocking Voltage V <sub>R</sub>
80 80 80 A	80	Average Rectified Forward Current $I_{F(AV)}$ (T <sub>C</sub> = +53°C)
160 160 160 A	160	Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)
500 500 500 A	500	Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)
180 180 180 W	180	Maximum Power Dissipation PD
50 50 50 mj	50	Avalanche Energy (L = 40mH) WAVL
-65 to +175 -65 to +175 -65 to +175 °C	-65 to +175	Operating and Storage Temperature
500 500 500 A 180 180 180 W 50 50 50 mj	500 180 50	Repetitive Peak Surge Current.       IFSM         (Square Wave, 20kHz)       IFSM         Nonrepetitive Peak Surge Current       IFSM         (Halfwave, 1 phase, 60Hz)       IFSM         Maximum Power Dissipation       PD         Avalanche Energy (L = 40mH)       WavL

### Specifications RURG8070, RURG8080, RURG8090, RURG80100

							LIM	ITS						
		R	URG80	70	R	URG80	B0 ·	R	URG80	90	RL	JRG801	00	
SYMBOL	TEST CONDITION	MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	UNITS
VF	I <sub>F</sub> = 80A, T <sub>C</sub> = +25°C	-	-	1.9	-	-	1.9	-	-	1.9	-	-	1.9	V
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = +150°C	-	-	1.7	-	-	1.7	-		1.7	-	-	1.7	v
I <sub>R</sub>	V <sub>R</sub> = 700V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	-	-	-	μA
	V <sub>R</sub> =800V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 900V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	-	-	-	μA
[	V <sub>R</sub> = 1000V, T <sub>C</sub> = +25°C	-	-	- `	-	-	-	-	-	-	-	-	250	μA
IR	V <sub>R</sub> = 700V, T <sub>C</sub> = +150°C	-	-	2	-	-	-	-	-	-	-	-	-	mA
	V <sub>R</sub> = 800V, T <sub>C</sub> = +150°C	-	-	-	-	-	2	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	2	-	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	-	-	-	2	mA
t <sub>RR</sub>	$I_F = 1A$ , $dI_F/dt = 100A/\mu s$	-	-	125	-	-	125	-	-	125	-	-	125	ns
	I <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	-	200	-	-	200	-	-	200	-	-	200	ns
t <sub>A</sub>	I <sub>F</sub> = 80A, dI <sub>F</sub> /d t= 100A/μs	-	90	-	-	90	-	-	90	-	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	•	65	-	-	65	-	-	65	-	-	65	-	ns
R <sub>eJC</sub>		•	-	0.83	-	•	0.83	-	-	0.83	-	-	0.83	°C/W

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = instantaneous forward voltage (pw = 300 µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

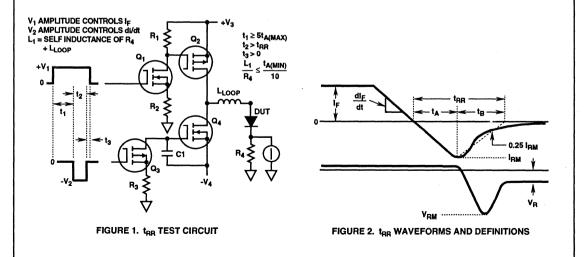
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

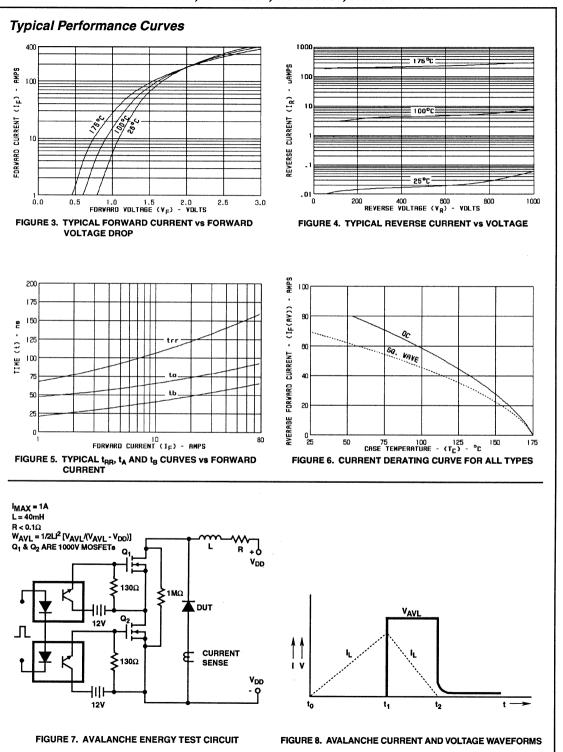
W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



#### RURG8070, RURG8080, RURG8090, RURG80100



ULTRAFAST SINGLE DIODES

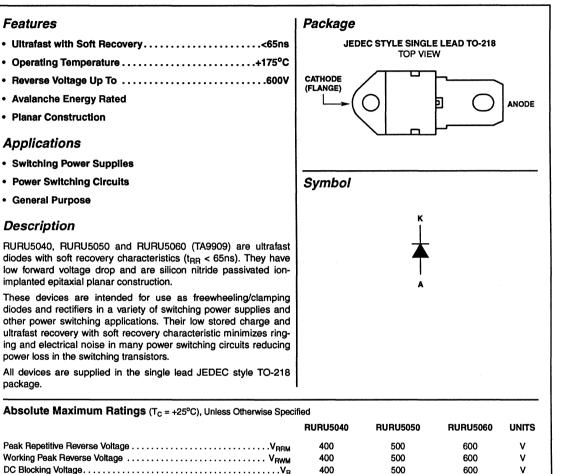
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## RURU5040, RURU5050 RURU5060

#### December 1993

## 50A, 400V - 600V Ultrafast Diodes



400

50

100

500

150

40

-65 to +175

500

50

100

500

150

40

-65 to +175

600

50

100

500

150

40

-65 to +175

v

А

Δ

Α

w

mj

°C

 $(T_{C} = +102^{\circ}C)$ 

(Square Wave, 20kHz)

(Halfwave, 1 phase, 60Hz)

Average Rectified Forward Current ......IF(AV)

Repetitive Peak Surge Current ..... IFSM

Nonrepetitive Peak Surge Current ...... IFSM

Maximum Power Dissipation ......Pp

## Specifications RURU5040, RURU5050, RURU5060

						LIMITS					
		F	RURU504	0	F	RURU505	0	F	RURU506	0	
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	UNITS
VF	I <sub>F</sub> = 50A, T <sub>C</sub> = +25°C	-	-	1.6	-	-	1.6	-	-	1.6	v
V <sub>F</sub>	I <sub>F</sub> = 50A, T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	v
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C		-	-	-	-	-	-	-	250	μΑ
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +150°C	-	-	1.5	-	-	-	-	-	-	mA
	$V_{\rm R} = 500 V, T_{\rm C} = +150^{\rm o} {\rm C}$	-	-	-	-	-	1.5	-	-	-	mA
	$V_{\rm R} = 600V, T_{\rm C} = +150^{\rm o}{\rm C}$	-	-	-	-	-	-	-	-	1.5	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	65	-	-	65	-	-	65	ns
	l <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	-	75	-	-	75	-	-	75	ns
t <sub>A</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt= 100A/μs	-	30	-	-	30	-	-	30	-	ns
t <sub>B</sub>	l <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	20	-	-	20	-	-	20	-	ns
R <sub>eJC</sub>		-	-	1	-	-	1	-	-	1	°C/W

#### Electrical Specifications Case Temperature (T<sub>c</sub>) = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>BM</sub> to projected zero crossing of I<sub>BM</sub> based on a straight line from peak I<sub>BM</sub> through 25% of I<sub>BM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

- pw = pulse width.
- D = duty cycle.

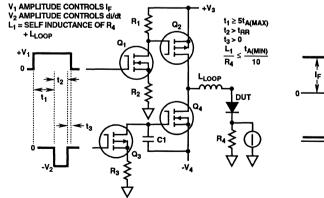
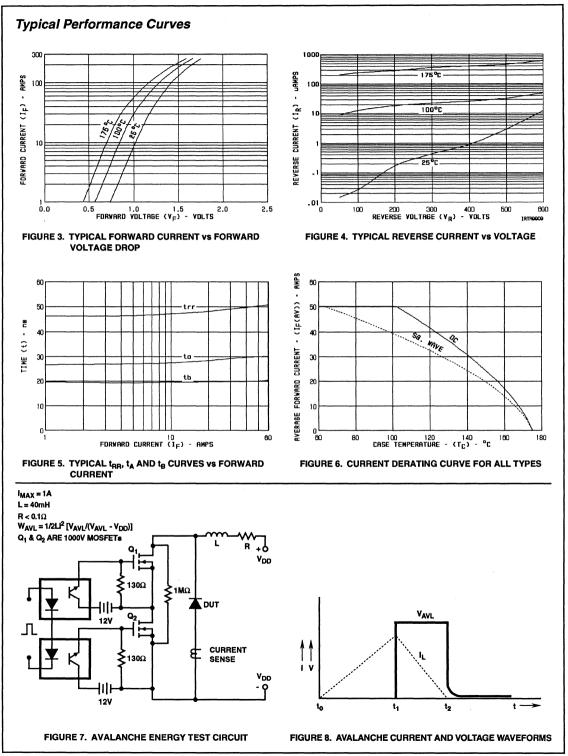


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT

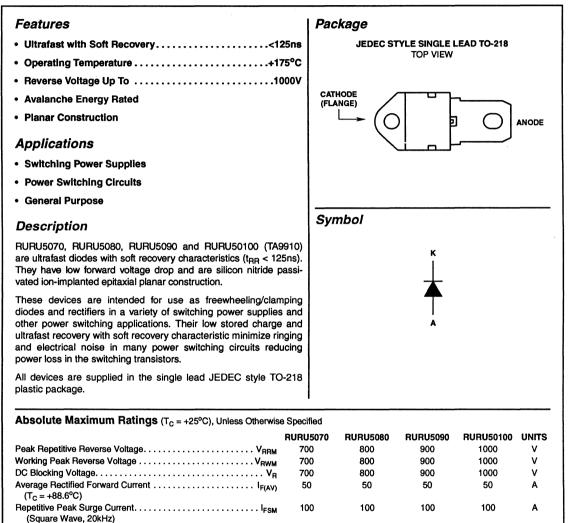




## RURU5070, RURU5080 RURU5090, RURU50100

#### December 1993

## 50A, 700V - 1000V Ultrafast Diodes



5

(Halfwave, 1 phase, 60Hz)

Nonrepetitive Peak Surge Current ..... IESM

Maximum Power Dissipation ..... PD

Avalanche Energy (L = 40mH) ..... W<sub>AVL</sub>

500

150

40

-65 to +175

Δ

w

mi

°C

500

150

40

-65 to +175

500

150

40

500

150

40

-65 to +175

### Specifications RURU5070, RURU5080, RURU5090, RURU50100

							LIM	ITS						
		R	URU50	70	R	URU50	80	R	URU50	€0	RL	JRU501	00	
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	l <sub>F</sub> = 50A	-	-	1.9	-	-	1.9	-	-	1.9	-	-	1.9	v
V <sub>F</sub>	I <sub>F</sub> = 50A, T <sub>C</sub> = 150°C	-	-	1.7	-	-	1.7	-	-	1.7	-	-	1.7	v
1 <sub>R</sub>	V <sub>R</sub> = 700V	-	-	250	-	-	-	-	-	-	-	-	-	μA
	V <sub>R</sub> =800V	-	-	-	-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	250	-	•	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	250	μA
IR	V <sub>R</sub> = 700V, T <sub>C</sub> = 150°C	-	-	1.5	-	-	-	-	-	-	-	-	-	mA
	V <sub>R</sub> = 800V, T <sub>C</sub> = 150°C	-	-	-	-	-	1.5	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = 150°C	-	-	-	-	-	-	-	-	1.5	-	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = 150°C	-	-	-	-	-	-	-	-	-	-	-	1.5	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	125	-	-	125	-	-	125	-	-	125	ns
	$I_F = 50A$ , $dI_F/dt = 100A/\mu s$	-	-	200	-	-	200	-	-	200	-	-	200	ns
t <sub>A</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt= 100A/μs	-	90	-	-	90	-	-	90	-	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /dt = 100A/μs	-	40	-	-	40	-	-	40	-	-	40	-	ns
R <sub>eJC</sub>		-	-	1.0	-	-	1.0	-	-	1.0	-	-	1.0	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

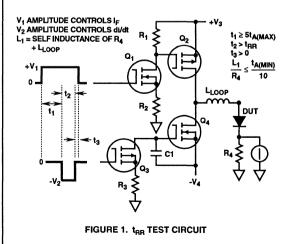
t<sub>B</sub> = Time from peak I<sub>BM</sub> to projected zero crossing of I<sub>BM</sub> based on a straight line from peak I<sub>BM</sub> through 25% of I<sub>BM</sub> (See Figure 2).

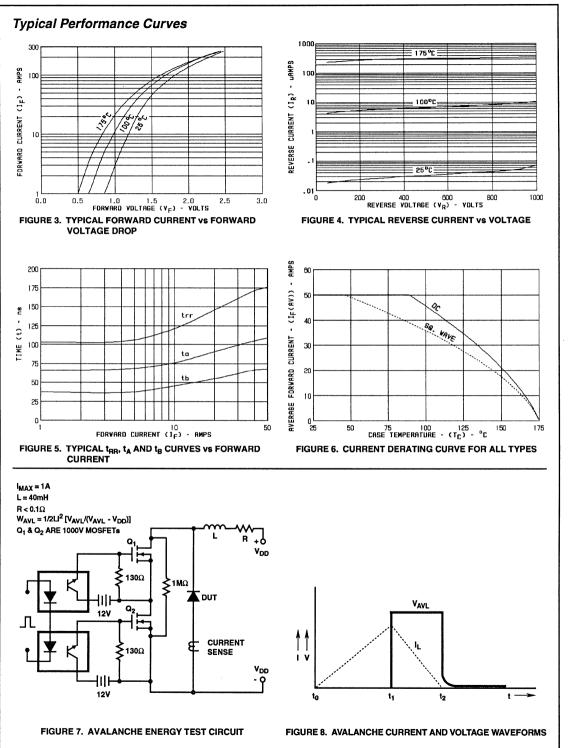
 $R_{\theta JC}$  = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





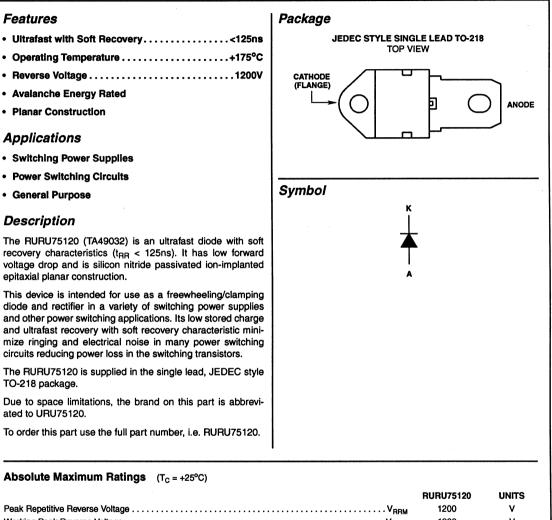
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# RURU75120

#### December 1993

## 75A, 1200V Ultrafast Diode



Working Peak Reverse VoltageV <sub>RWM</sub>	1200	v
DC Blocking VoltageV <sub>R</sub>	1200	v
Average Rectified Forward Current I <sub>F(AV)</sub>	75	Α
(T <sub>C</sub> = +56.75°C)		
Repetitive Peak Surge CurrentI <sub>FSM</sub>	150	Α
(Square Wave, 20kHz)		
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub>	500	Α
(Halfwave, 1 Phase, 60Hz)		
Maximum Power Dissipation	190	w
Avalanche Energy (L = 40mH)	50	mj
Operating and Storage Temperature	-65 to +175	°C

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## Specifications RURU75120

				LIMITS					
SYMBOL	c	TEST ONDITION	MIN	ТҮР	МАХ	UNITS			
V <sub>F</sub>	I <sub>F</sub> = 75A		-	-	2.1	v			
V <sub>F</sub>	I <sub>F</sub> = 75A	T <sub>C</sub> = +150°C	-	-	1.9	v			
IR	V <sub>R</sub> = 1200V		-	-	250	μA			
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	2	mA			
t <sub>RR</sub>	$I_{\rm F} = 1$ A, d $I_{\rm F}$ /dt = 100A	Vµs	-	-	125				
t <sub>RR</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 100	)A/μs	-	-	200				
t <sub>A</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 100	)A/μs		90	-	ns			
t <sub>B</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 100	)A/μs	-	65	-				
R <sub>IJC</sub>			-	-	0.8	°C/W			

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

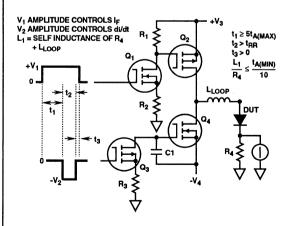
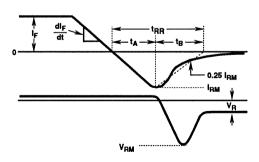
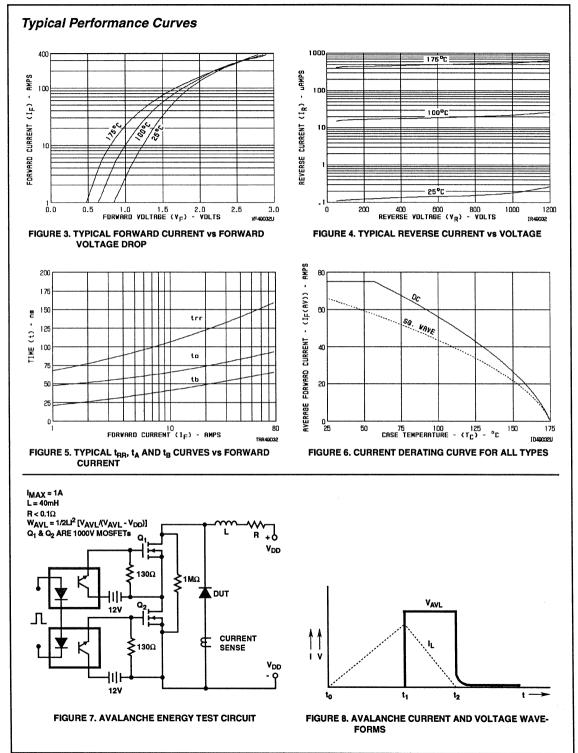


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT







## RURU8040, RURU8050 RURU8060

#### December 1993

## 80A, 400V - 600V Ultrafast Diodes

#### Features

- Operating Temperature ......+175°C
- Reverse Voltage Up To ......600V
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

### Description

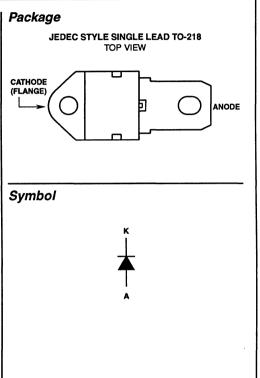
RURU8040, RURU8050 and RURU8060 (TA9886) are ultrafast diodes with soft recovery characteristics ( $t_{RR}$  < 75ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

All devices are supplied in the single lead JEDEC style TO-218 package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	RURU8040	RURU8050	RURU8060	UNITS
Peak Repetitive Reverse Voltage	400	500	600	v
Working Peak Reverse Voltage V <sub>RWM</sub>	400	500	600	v
DC Blocking VoltageV <sub>B</sub>	400	500	600	v
Average Rectified Forward CurrentIF(AV) (T <sub>C</sub> = +84°C)	80	80	80	Α
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	160	160	160	Α
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	800	800	800	Α
Maximum Power DissipationPp	180	180	180	w
Avalanche Energy (L = 40mH)Wave	50	50	50	mj
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	°C



5

SINGLE DIODES

ULTRAFAST

		LIMITS									
		RURU8040			RURU8050			RURU8060			1
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = +25°C	-	-	1.6	-	-	1.6	-	-	1.6	v
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	v
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	μΑ
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	μА
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +150°C	-	-	2.0	-	-	-	-	-	-	mA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +150°C	-	-	-	-	- 1	2.0	-	-	-	mA
	V <sub>R</sub> = 600V, T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	2.0	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	75	-	-	75	-	-	75	ns
	I <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	-	85	-	-	85	-	-	85	ns
t <sub>A</sub>	I <sub>F</sub> = 80A, dI <sub>F</sub> /dt= 100A/μs	-	40	-	-	40	-	-	40	-	ns
t <sub>B</sub>	I <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	25	-	-	25	-	-	25	-	ns
R <sub>eJC</sub>		-	-	0.83	-	-	0.83	-	-	0.83	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current .

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

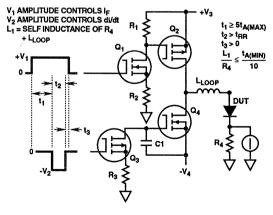
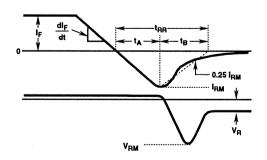
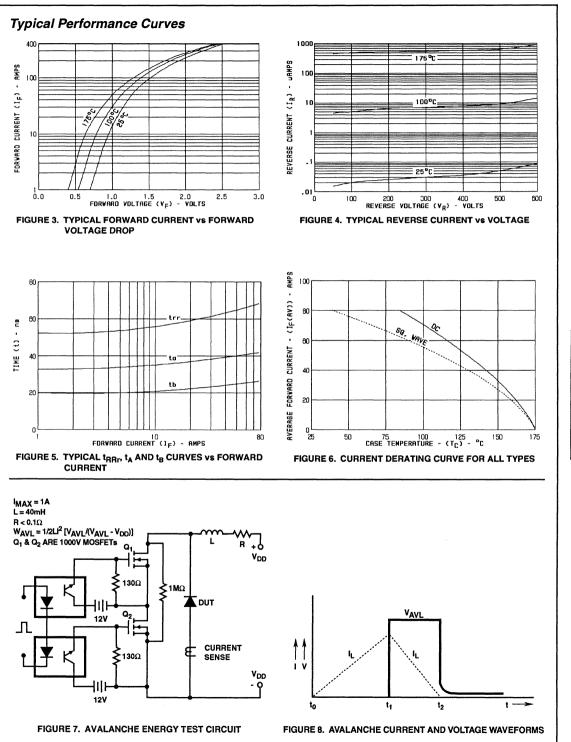


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





5

SINGLE DIODES

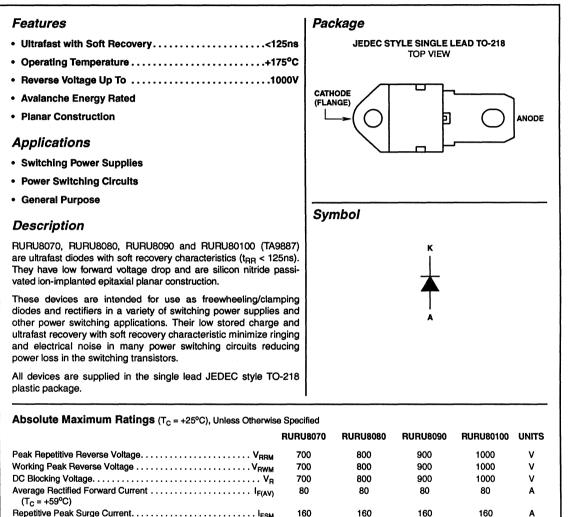
ULTRAFAST



## RURU8070, RURU8080 RURU8090, RURU80100

#### December 1993

## 80A, 700V - 1000V Ultrafast Diodes



(Square Wave, 20kHz)

(Halfwave, 1 phase, 60Hz)

Nonrepetitive Peak Surge Current ..... IESM

Maximum Power Dissipation ..... PD

Avalanche Energy (L = 40mH) ..... WAVL

500

180

50

-65 to +175

А

w

mi

°C

500

180

50

500

180

50

-65 to +175

500

180

50

-65 to +175

### Specifications RURU8070, RURU8080, RURU8090, RURU80100

SYMBOL		LIMITS												
		RURU8070			RURU8080			RURU8090			RURU80100			1
	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 80A	-	-	1.9	-	-	1.9	-	-	1.9	-	-	1.9	V
V <sub>F</sub>	I <sub>F</sub> = 80A, T <sub>C</sub> = 150°C	-	-	1.7	-	-	1.7	-	-	1.7	-	-	1.7	V
IR	V <sub>R</sub> = 700V	-	-	250	-	-	-	-	-	-	-	-	-	μA
	V <sub>R</sub> =800V	-	-	-	-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	250	-	-	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	250	μΑ
IR	V <sub>R</sub> = 700V, T <sub>C</sub> = 150°C	-	-	2	-	-	-	-	-	-	-	-	-	mA
	V <sub>R</sub> = 800V, T <sub>C</sub> = 150°C	-	-	-	-	-	2	-	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = 150°C	-	-	-	-	-	-	-	-	2	-	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = 150°C	-	-	-	-	-	-	-	-	-	-	-	2	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	125	-	-	125	-	-	125	-	-	125	ns
	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	-	200	-	-	200	-	-	200	-	-	200	ns
t <sub>A</sub>	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt= 100A/μs	-	90	-	-	90	-	-	90	-	-	90	-	ns
tB	l <sub>F</sub> = 80A, dI <sub>F</sub> /dt = 100A/μs	-	65	•	-	65	-	-	65	-	-	65	-	ns
R <sub>eJC</sub>		-	-	0.83	-	•	0.83	-	-	0.83	-	-	0.83	°C/M

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_{\rm F}$  = Instantaneous forward voltage (pw = 300 µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta,JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

- pw = pulse width.
- D = duty cycle.

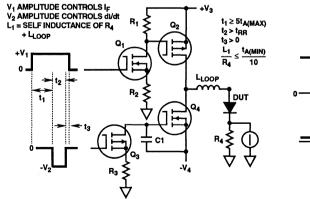
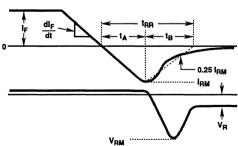
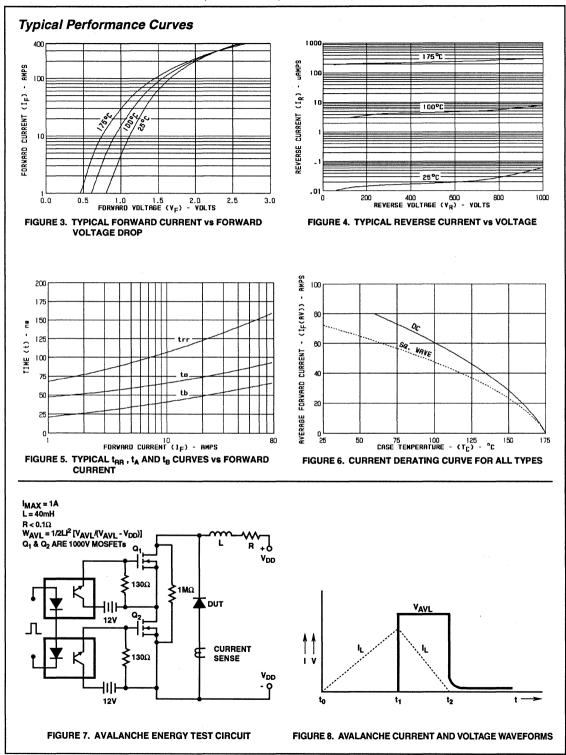


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





## HARRIS RURU10040, RURU10050 RURU10060

#### December 1993

## 100A, 400V - 600V Ultrafast Diodes

#### Features

- Ultrafast with Soft Recovery......<80ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RURU10040, RURU10050 and RURU10060 (TA49019) are ultrafast diodes with soft recovery characteristics ( $t_{RR}$  < 80ns).They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

All devices are supplied in the single lead, JEDEC style TO-218 package.

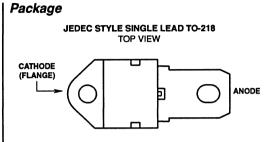
Due to space limitations, the brand on this part is abbreviated to URU10040, URU10050 or URU10060.

To order this part use the full part number, e.g. RURU10040.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RURU10040	RURU10050	RURU10060	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400	500	600	v
Working Peak Reverse VoltageV <sub>RWM</sub>	400	500	600	v
DC Blocking VoltageV <sub>R</sub>	400	500	600	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>C</sub> = +68.2°C)	100	100	100	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	200	200	200	A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	1000	1000	1000	A
Maximum Power DissipationPD	210	210	210	w
Avalanche Energy (L = 40mH) WAVL	50	50	50	mj
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	°C

ULTRAFAST G





CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1992

### Specifications RURU10040, RURU10050, RURU10060

			RURU10040 LIMITS			RURU10050 LIMITS			RURU10060 LIMITS			
SYMBOL		TEST CONDITION		MIN TYP	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 100A		-	-	1.6	-	-	1.6	-	-	1.6	
V <sub>F</sub>	I <sub>F</sub> = 100A	T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	v
I <sub>R</sub>	$V_{R} = 400V$ $V_{R} = 500V$ $V_{R} = 600V$			- - -	250 - -	- - -	-	- 250 -	-	-	- - 250	μA
I <sub>R</sub>	$V_{R} = 400V$ $V_{R} = 500V$ $V_{R} = 600V$	T <sub>C</sub> = +150°C		-	2.0 - -		-	2.0	-	-	- - 2.0	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dl <sub>F</sub> /di	t = 100A/μs	-	-	80	-		80	-	-	80	
t <sub>RR</sub>	l <sub>F</sub> = 100A, dl <sub>F</sub>	-/dt = 100A/μs	-	-	100	-	-	100	-	-	100	
t <sub>A</sub>	l <sub>F</sub> = 100A, dl <sub>F</sub>	/dt = 100A/µs	-	45	-	-	45	-	-	45	-	ns
t <sub>B</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub>	/dt = 100A/μs	-	25	-	-	25	-	-	25	-	
R <sub>eJC</sub>			-	-	0.71	-	-	0.71	-	-	0.71	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time summation of  $t_{A} + t_{B}$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

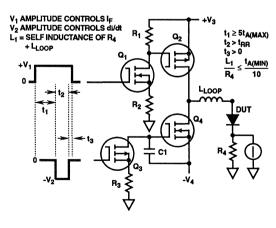
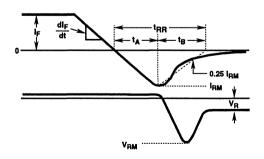
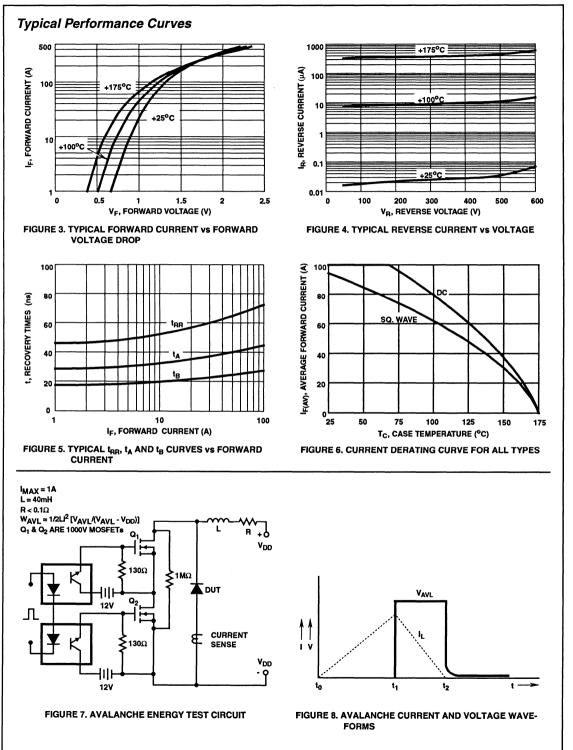


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





5

SINGLE DIODES

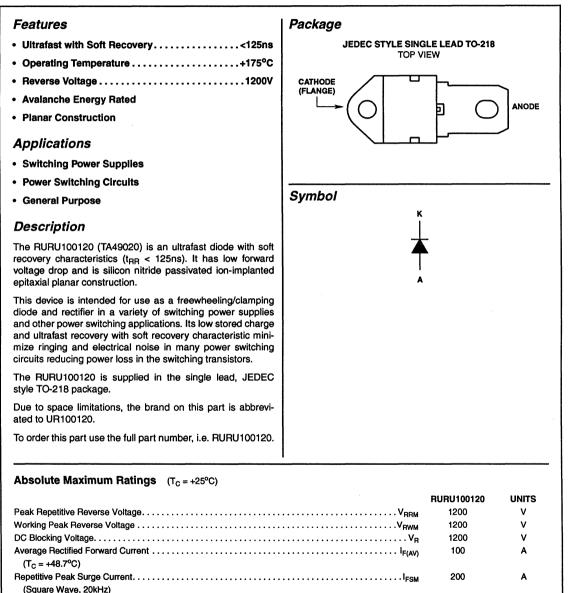
ULTRAFAST



# RURU100120

December 1993

### 100A, 1200V Ultrafast Diode



Nonrepetitive Peak Surge Current ......IrsM

(Halfwave, 1 Phase, 60Hz)

Α

w

mi

°C

500

210

50

-65 to +175

#### Specifications RURU100120

				LIMITS					
SYMBOL	ТЕ	ST CONDITION	MIN	ТҮР	MAX	UNITS			
V <sub>F</sub>	I <sub>F</sub> = 100A		-	-	2.1	v			
V <sub>F</sub>	$I_{\rm F} = 100{\rm A}$ $T_{\rm C} = +150^{\circ}{\rm C}$		-	-	1.9	Ì			
I <sub>R</sub>	V <sub>R</sub> = 1200V		-	-	250	μА			
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	2	mA			
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	125				
t <sub>RR</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt =	100A/µs	-	-	200				
t <sub>A</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt =	100A/µs	-	90	-	ns			
t <sub>B</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt = 100A/μs		-	65	-				
R <sub>eJC</sub>			-	-	0.71	°C/W			

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta,JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

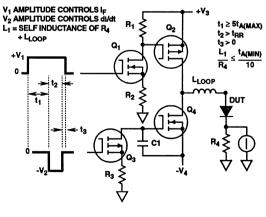


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT

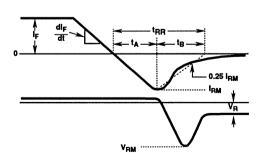
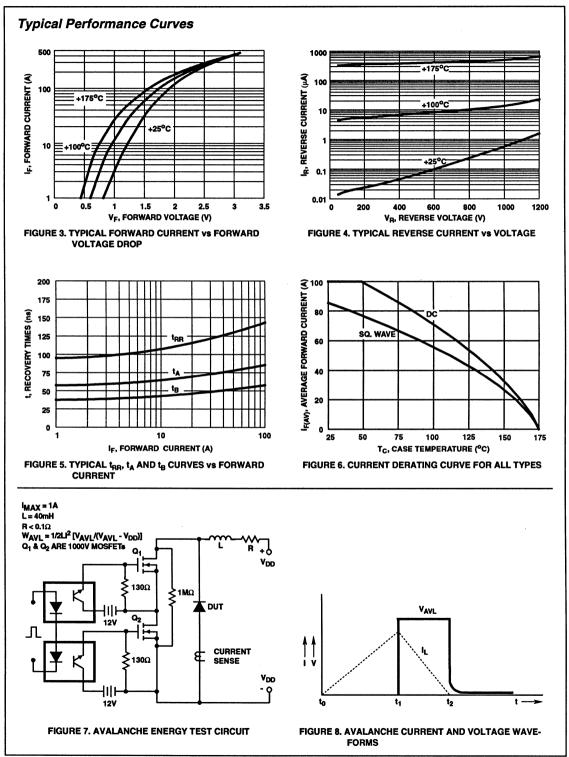


FIGURE 2. t<sub>RR</sub> WAVEFORMS AND DEFINITIONS

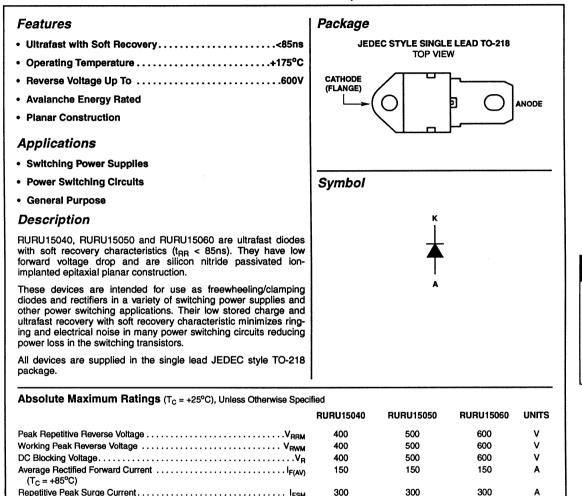




# RURU15040, RURU15050 RURU15060

#### December 1993

#### 150A, 400V - 600V Ultrafast Diodes



(Square Wave, 20kHz)

(Halfwave, 1 phase, 60Hz)

Nonrepetitive Peak Surge Current ..... IESM

Maximum Power Dissipation ......PD

Avalanche Energy (L = 40mH) ..... Wavi

Operating and Storage Temperature ......T<sub>STG</sub>,TJ

1500

375

50

-65 to +175

Α

w

mi

°C

1500

375

50

-65 to +175

1500

375

50

-65 to +175

5

SINGLE DIODES

ULTRAFAST

#### Specifications RURU15040, RURU15050, RURU15060

		LIMITS									
	TEST CONDITION	RURU15040			RURU15050			RURU15060			
SYMBOL		MIN	түр	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 150A, T <sub>C</sub> = +25°C	-	-	1.6	-	-	1.6	-	-	1.6	V
V <sub>F</sub>	I <sub>F</sub> = 150A, T <sub>C</sub> = +150°C	-	-	1.4	-	-	1.4	-	-	1.4	, v
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V, T <sub>C</sub> = +25°C	-	-	-	-	-	250	-	-	-	μΑ
	V <sub>R</sub> = 600V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	μΑ
I <sub>R</sub>	V <sub>R</sub> = 400V, T <sub>C</sub> = 150°C	-	-	3.0	-	-	-	-	-	-	mA
	V <sub>R</sub> = 500V, T <sub>C</sub> = 150°C	-	-	-	-	-	3.0	-	-	-	mA
	$V_{\rm R} = 600 V, T_{\rm C} = 150^{\circ} {\rm C}$	-	-	-	-	-	-	-	-	3.0	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	85	•	-	85	-	-	85	ns
	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/μs	-	-	100	-	-	100	-	-	100	ns
t <sub>A</sub>	l <sub>F</sub> = 150A, dI <sub>F</sub> /dt= 100A/μs	-	60	-	-	60	-	-	60	-	ns
t <sub>B</sub>	l <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/μs	-	30	-	-	30	-	-	30	-	ns
R <sub>eJC</sub>		-	-	0.4	-	-	0.4	-	-	0.4	°C/W

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_{A} + t_{B}$ .

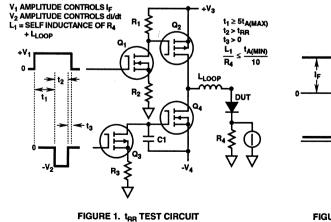
t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

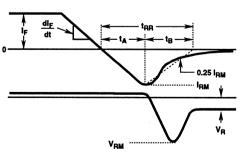
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>eJC</sub> = Thermal resistance junction to case.

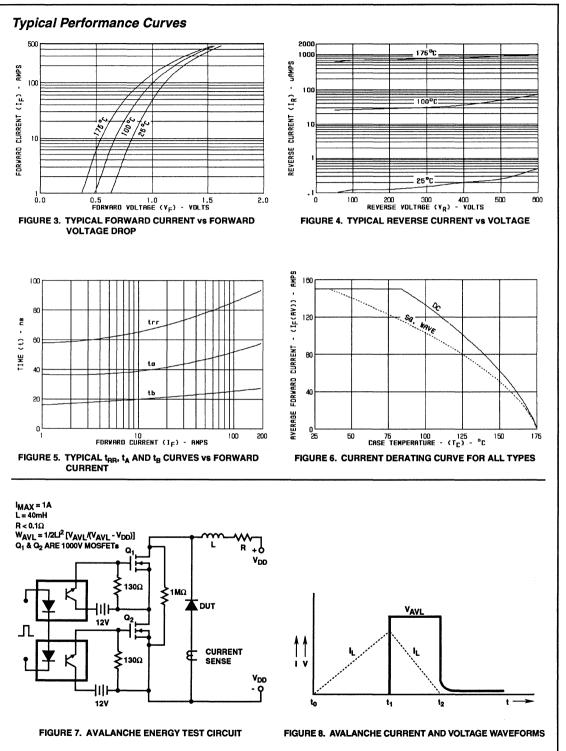
pw = pulse width.

D = duty cycle.





#### FIGURE 2. t<sub>RR</sub> WAVEFORMS AND DEFINITIONS

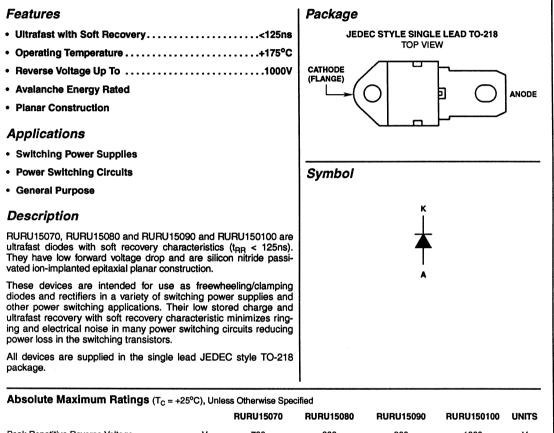




# RURU15070, RURU15080 RURU15090, RURU150100

#### December 1993

#### 150A, 700V - 1000V Ultrafast Diodes



			11011010000		011110
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	700	800	900	1000	v
Working Peak Reverse Voltage VRWM	700	800	900	1000	V
DC Blocking VoltageV <sub>R</sub>	700	800	900	1000	v
Average Rectified Forward Current $\dots I_{F(AV)}$ (T <sub>c</sub> = +65°C)	150	150	150	150	Α
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	300	300	300	300	Α
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	1500	1500	1500	1500	Α
Maximum Power DissipationPD	375	375	375	375	w
Avalanche Energy (L = 40mH) W <sub>AVL</sub>	50	50	50	50	mj
Operating and Storage TemperatureT <sub>STG</sub> , $T_J$	-65 to +175	-65 to +175	-65 to +175	-65 to +175	°C

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			LIMITS											
		RU	RURU15070		RURU15080		RURU15090			RURU150100			l	
SYMBOL	TEST CONDITION	MIN	TYP	МАХ	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 150A, T <sub>C</sub> = +25°C	-	-	1.9	-	-	1.9	-	-	1.9	-	-	1.9	v
V <sub>F</sub>	I <sub>F</sub> = 150A, T <sub>C</sub> = +150°C	-	-	1.7	-	-	1.7	-	-	1.7	-	-	1.7	v
IR	V <sub>R</sub> = 700V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	-	-	-	-	-	-	μA
	V <sub>R</sub> = 800V, T <sub>C</sub> = +25°C	-	-	-	· -	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V, T <sub>C</sub> = +25°C	-	-	-	-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +25°C												250	μA
I <sub>R</sub>	V <sub>R</sub> = 700V, T <sub>C</sub> = +150°C	-	-	3.0	-	-	-	-	-	-	-	-	-	mA
	V <sub>R</sub> = 800V, T <sub>C</sub> = +150°C	-	-	-	-	-	3.0	•	-	-	-	-	-	mA
	V <sub>R</sub> = 900V, T <sub>C</sub> = +150°C	•	-	-	-	-	-	-	-	3.0	•	-	-	mA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +150°C	-	-	-	-	-	•	-	-	-	•	-	3.0	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	125	-	-	125	-	-	125	•	-	125	ns
	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/µs	-	-	200	-	-	200	-	-	200	-	-	200	ns
t <sub>A</sub>	I <sub>F</sub> = 150A, dI <sub>F</sub> /d t= 100A/μs	-	100	-	-	100	-	-	100	-	•	100	-	ns
t <sub>B</sub>	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/µs	-	75	-	-	75	-	-	75	-	-	75	-	ns
R <sub>eJC</sub>		-	-	0.4	-	-	0.4	-	-	0.4	-	-	0.4	°C/W

#### Electrical Specifications $T_{C} = +25^{\circ}C$ , Unless Otherwise Specified

#### DEFINITIONS

 $V_{F}$  = Instantaneous forward voltage (pw = 300 $\mu$ s, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_{A} + t_{B}$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

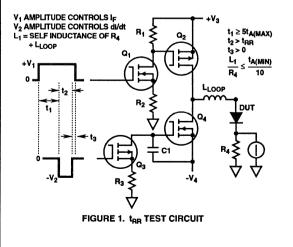
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

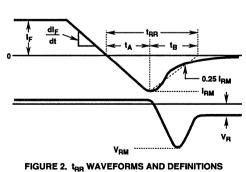
 $R_{\theta JC}$  = Thermal resistance junction to case.

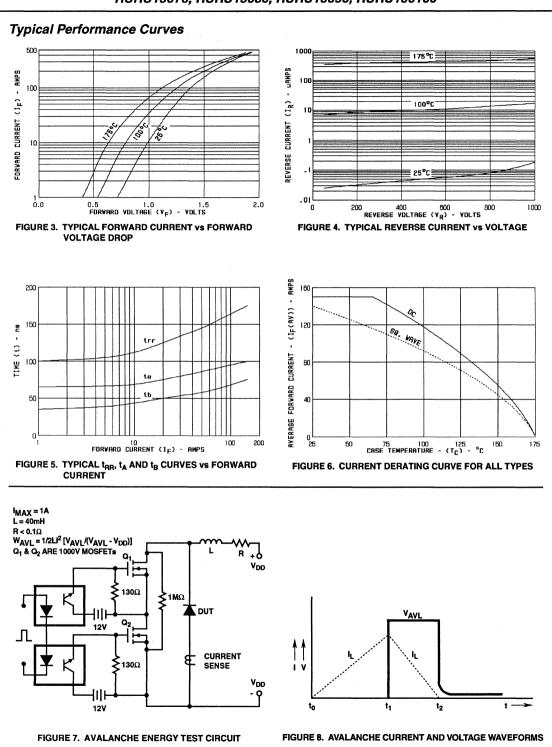
 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







#### RURU15070, RURU15080, RURU15090, RURU150100

# MCT/IGBT/DIODES

### **ULTRAFAST DUAL DIODES**

6

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### Selection Guide

#### HARRIS DUAL ULTRAFAST RECOVERY RECTIFIER PRODUCT LINE

\_\_\_\_\_

	то-220АВ	TO-218AC			247	TO-204AA
	IF(AVG)	IF(AVG)		I <sub>F(#</sub>	I <sub>F(AVG)</sub>	
VRRM	8Ax2	15Ax2	30Ax2	15Ax2	30Ax2	16Ax2
100V	MUR1610CT BYW51100 RURP810CC	MUR3010PT RURH1510CC	RURH3010CC	RURG1510CC	RURG3010CC	RURM1610CC
150V	MUR1615CT BYW51150 RURP815CC	MUR3015PT RURH1515CC	RURH3015CC	RURG1515CC	RURG3015CC	RURM1615CC
200V	MUR1620CT BYW51200 RURP820CC	MUR3020PT RURH1520CC	RURH3020CC	RURG1520CC	RURG3020CC	RURM1620CC
400V	RURP840CC	MUR3040PT RURH1540CC	RURH3040CC	RURG1540CC	RURG3040CC	
500V	RURP850CC	MUR3050PT RURH1550CC	RURH3050CC	RURG1550CC	RURG3050CC	
600V	RURP860CC	MUR3060PT RURH1560CC	RURH3060CC	RURG1560CC	RURG3060CC	
700V	RURP870CC	RURH1570CC	RURH3070CC	RURG1570CC	RURG3070CC	
800V	RURP880CC	RURH1580CC	RURH3080CC	RURG1580CC	RURG3080CC	
900V	RURP890CC	RURH1590CC	RURH3090CC	RURG1590CC	RURG3090CC	
1000V	RURP8100CC	RURH15100CC	RURH30100CC	RURG15100CC	RURG30100CC	
1200V	RURP8120CC			RURG15120CC	RURG30120CC	

SHADING = Future Product Offerings

6

ULTRAFAST DUAL DIODES

C.



## **BYW51-100** BYW51-150, BYW51-200

#### 8A, 100V - 200V Ultrafast Dual Diodes

JEDEC TO-220AB TOP VIEW

к

A 2

Package

CATHODE

(FLANGE)

Symbol

December 1993

#### Features

- Ultra Fast Recovery Time (<35 ns)
- Low Forward Voltage
- · Low Thermal Resistance
- Planar Design
- Wire-Bonded Construction

#### Applications

- General Purpose
- Power Switching Circuits to 100kHz
- Full-Wave Rectification

#### Description

The BYW51 series devices are low forward voltage drop, ultra-fast-recovery rectifiers (t<sub>BB</sub> < 35ns). They use a planar ion-implanted epitaxial construction.

These devices are intended for use as output rectifiers and fly-wheel diodes in a variety of high-frequency pulse-widthmodulated and switching regulators. Their low stored charge and attendant fast reverse-recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

All are supplied in JEDEC TO-220AB plastic packages.

#### Absolute Maximum Ratings Per Junction

	BYW51-100	BYW51-150	BYW51-200
Maximum Peak Repetitive Reverse Voltage V <sub>RRM</sub>	100	150	200
Maximum Peak Surge Voltage	110	165	220
Repetitive Peak Surge CurrentI <sub>FRM</sub> , t <sub>P</sub> < 10µs	100	100	100
Nonrepetitive Peak Surge Current I <sub>F</sub> (RMS), Total	20	20	20
Average Rectified forward Current	20	20	20
Repetitive Peak Surge Current $I_{FSM}$ $t_P = 10ms$ , Sinusoidal	100	100	100
Maximum Power DissipationP <sub>D</sub> ,T <sub>C</sub> = +125°C	20	20	20
Operating and Storage Temperature	-40 + 150	-40 + 150	-40 + 150
$T_L$ (Lead Temperature During Soldering)	260	260	260



ANODE 1

CATHODE

ANODE 2

UNITS

ν

ν

A

A

Δ

Δ

w

°C °C

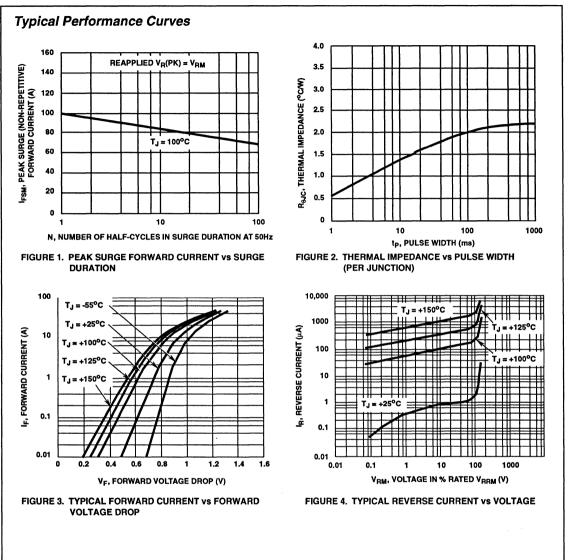
### Specifications BYW51-100, BYW51-150, BYW51-200

	· ·	TEST CONDIT	IONS	LIMITS							
	_	VOLTAGE	CURRENT	BYW	51-100	BYW	51-150	BYW51-200		1	
SYMBOL		V <sub>R</sub> V		MIN	МАХ	MIN	MAX	MIN	MAX	UNITS	
I <sub>R</sub>	25	100	-	-	5	-	•	-	-	μA	
		150	-	-	-	-	5	-	-	μA	
		200	-	-	-	-	-	-	5	μΑ	
	100	100	-	-	1	-	-	-	-	mA	
		150	-	-	-	-	1	-	-	mA	
		200	-	-	-	•	-	-	1	mA	
V <sub>F</sub>	25	-	8	-	0.95	-	0.95	-	0.95	v	
	100	-	8	-	0.89	-	0.89	-	0.89	v	
t <sub>RR</sub>	25	-	1 (Note 1)	-	35	-	35	-	35	ns	
R <sub>eJC</sub> , Per Leg		-	-	-	2.5	-	2.5	-	2.5	°C/W	
R <sub>eJC</sub> , Total	1	-	-	-	1.3	-	1.3	•	1.3	°C/M	
R <sub>eja</sub>	1	-	-	-	60	-	60	-	60	°C/M	
CJ	25	10	0			All types	s (typ.) 40	<b></b>	•	pF	

NOTE:

1. dl<sub>F</sub>/dt > 50A/μs, I<sub>RM</sub>(rec) <1A, I<sub>RR</sub> = 0.25A.

#### BYW51-100, BYW51-150, BYW51-200



6



## RURP810CC RURP815CC, RURP820CC

#### December 1993

#### Features

- Ultrafast Recovery Time (t<sub>RR</sub> < 35ns)</li>
- Low Forward Voltage
- Low Thermal Resistance
- Planar Design
- Wire-Bonded Construction

#### Applications

- General Purpose
- · Power Switching Circuits to 100kHz
- Full-Wave Rectification

#### Description

RURP810CC, RURP815CC, RURP820CC are low forward voltage drop ultrafast rectifiers ( $t_{RR}$  < 35ns). They use an ion-implanted planar epitaxial construction.

These devices are intended for use as output rectifiers and flywheel diodies in a variety of high frequency pulse width modulated and switching regulators. Their low stored charge and attendant fast reverse recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

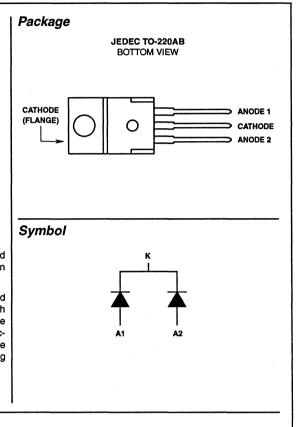
All are supplied in JEDEC TO-220AB plastic packages.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RURP810CC	RURP815CC	RURP820CC
Peak Repetitive Reverse Voltage V <sub>RRM</sub>	100V	150V	200V
Average Rectified Forward Current (Per Leg) $T_A = +25^{\circ}C$ (No Heat Sink) $T_A = +25^{\circ}C$ (With Heat Sink)* $T_C = +125^{\circ}C$ $I_{F(AV)}$ $I_{F(AV)}$	3A 8A 8A	3A 8A 8A	3A 8A 8A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (8.3ms, <sup>1</sup> / <sub>2</sub> cycle)	100A	100A	100A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C
Maximum Lead Temperature During SolderTL (At distance > 1/8" (3.17mm) from case or 10s max)	260°C	260°C	260°C

\*Wakefield type 295 heat sink with convection cooling.

#### 8A, 100V - 200V Ultrafast Dual Diodes



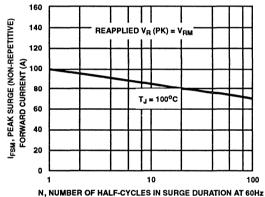
#### Specifications RURP810CC, RURP815CC, RURP820CC

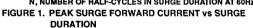
	TEST CONDITION	R	URP8100	20	RURP815CC			RURP820CC			
SYMBOL		MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 8A, T <sub>C</sub> = +150°C	-	-	0.895	-	-	0.895	-	-	0.895	v
	I <sub>F</sub> = 8A, T <sub>C</sub> = +25°C	•	-	0.975	-	-	0.975	-	-	0.975	v
I <sub>R</sub> at T <sub>C</sub> = +150⁰C	V <sub>R</sub> = 100V	-	-	250	-	-	-	-	•	-	μΑ
	V <sub>R</sub> = 150V	-	-	-	-	-	250	-	•	-	μΑ
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	250	μΑ
I <sub>R</sub> at	V <sub>R</sub> = 100V	-	•	5	-	-	-	-	•	-	μΑ
T <sub>C</sub> = +25°C	V <sub>R</sub> = 150V	-	-	-	-	-	5	-	-	-	μA
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	5	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 8A*	-	-	35	-	-	35	-	-	35	ns
ReJC		-	-	2.25	-	-	2.25	-	-	2.25	°C/W
R <sub>eja</sub>		-	-	60	-	-	60	-	-	60	°C/W
Cj	$V_{\rm R} = 10V, I_{\rm F} = 0A$		40	-	-	40	-	-	40	-	pF

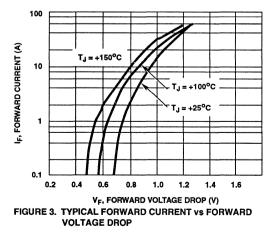
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

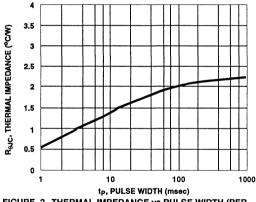
 $d_{\rm F}/dt = 50 {\rm A}/{\rm \mu s}$ ,  $l_{\rm RM}$  (rec) < 1A,  $l_{\rm RR} = 0.25 {\rm A}$ .

#### Typical Performance Curves.

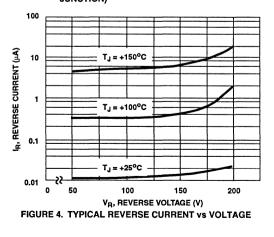












6



### RURG1510CC RURG1515CC, RURG1520CC

#### December 1993

#### 15A, 100V - 200V Ultrafast Dual Diodes

#### Features Package Ultrafast with Soft Recovery.....<30ns JEDEC STYLE TO-247 TOP VIEW Operating Temperature .....+175°C CATHODE (BOTTOM SIDE > ANODE 1 METAL) Avalanche Energy Rated CATHODE Planar Construction ANODE 2 Applications Switching Power Supplies Power Switching Circuits Symbol General Purpose Description RURG1510CC. RURG1515CC and BURG1520CC (TA9926) are ultrafast dual diodes with soft recovery characteristics (t<sub>RR</sub> < 30ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction. These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors. All devices are supplied in the JEDEC Style TO-247 package. Due to space limitations, the brand on this part is abbreviated to UR1510CC, UR1515CC or UR1520CC.. To order this part use the full part number, e.g. RURG1510CC. Absolute Maximum Ratings $(T_c = +25^{\circ}C)$

	RURG1510CC	RURG1515CC	RURG1520CC	UNITS	
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100	150	200	v	
Working Peak Reverse VoltageV <sub>RWM</sub>	100	150	200	v	
DC Blocking Voltage V <sub>R</sub>	100	150	200	v	
Average Rectified Forward Current (Per Leg) $I_{F(AV)}$ ( $T_C = +145^{\circ}C$ )	15	15	15	A	
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	30	30	30	A	
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	200	200	200	A	
Maximum Power Dissipation PD	100	100	100	w	
Avalanche Energy	20	20	20	mj	
Operating and Storage Temperature $T_{STG},T_{J}$	-65 to +175	-65 to +175	-65 to +175	°C	

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1992

#### Specifications RURG1510CC, RURG1515CC, RURG1520CC

	_		RURG	1510CC	LIMITS	RURG	1515CC	LIMITS	RURG	1520CC I	LIMITS	
SYMBOL		EST DITION	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 15A		-	-	1.05	-	-	1.05	-	-	1.05	v
V <sub>F</sub>	I <sub>F</sub> = 15A	T <sub>C</sub> = +150°C	-	-	0.85	-	-	0.85	-	-	0.85	v
I <sub>R</sub>	V <sub>R</sub> = 100V		-	-	10	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 150V		-	-	-	-	-	10	-	-	-	μА
	V <sub>R</sub> = 200V		-	-	-	•	-	-	-	-	10	μА
l <sub>R</sub>	V <sub>R</sub> = 100V	T <sub>C</sub> = +150°C	-	-	500	-	-	-	-	-	-	μА
	V <sub>R</sub> = 150V	T <sub>C</sub> = +150°C	-	-	-	-	-	500	-	-	-	μА
	V <sub>R</sub> = 200V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	500	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /d	lt = 100A/μs	-	-	30	-	-	30	-	-	30	ns
t <sub>RR</sub>	I <sub>F</sub> = 15A, dI <sub>F</sub> /	/dt = 100A/µs	-	-	35	-	•	35	-	-	35	ns
t <sub>A</sub>	l <sub>F</sub> = 15A, dl <sub>F</sub> /dt = 100A/μs		-	20	-	-	20	-	-	20	-	ns
t <sub>B</sub>	I <sub>F</sub> = 15A, dI <sub>F</sub> /	/dt = 100A/μs	-	10	-	-	10	-	-	10	-	ns
R <sub>NC</sub>			-	-	1.5	-	-	1.5	-	-	1.5	°C/M

#### . . . . .

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

t<sub>RR</sub> = Reverse recovery time (See Figure 2), summation of t<sub>A</sub> + t<sub>B</sub>.

 $t_A$  = Time to reach peak reverse current (See Figure 2).

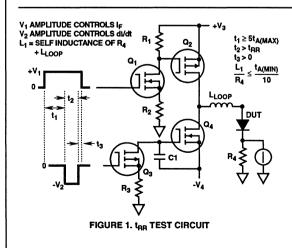
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

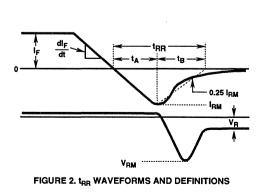
R<sub>BJC</sub> = Thermal resistance junction to case.

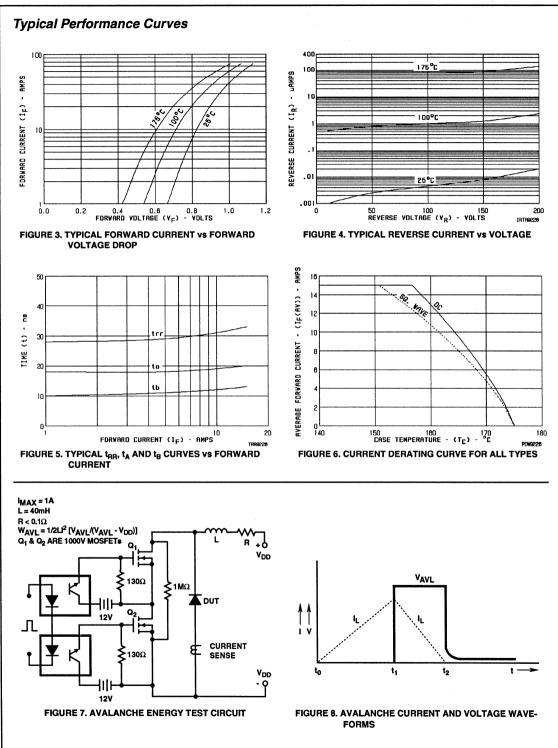
WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.









## RURG1540CC RURG1550CC, RURG1560CC

#### December 1993

#### 15A. 400V - 600V Ultrafast Dual Diodes

Features

- Ultrafast with Soft Recovery.....<
  55ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RURG1540CC. RURG1550CC and RURG1560CC (TA9905) are ultrafast dual diodes with soft recovery characteristics (t<sub>RR</sub> < 55ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

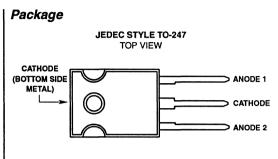
All devices are supplied in the JEDEC Style TO-247 package.

Due to space limitations, the brand on this part is abbreviated to UR1540CC, UR1550CC or UR1560CC.

To order this part use the full part number, e.g. RURG1540CC.

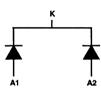
#### Absolute Maximum Ratings $(T_c = +25^{\circ}C)$

	1010134000
Peak Repetitive Reverse Voltage V <sub>RRM</sub>	400V
Working Peak Reverse VoltageV <sub>RWM</sub>	400V
DC Blocking VoltageV <sub>R</sub>	400V
Average Rectified Forward Current (Per Leg) $I_{F(AV)}$ (T <sub>c</sub> = +145°C)	15A
Repetitive Peak Surge Current	30A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	200A
Maximum Power Dissipation	100W
Avalanche EnergyW <sub>AVL</sub> (L = 40mH)	20mj
Operating and Storage Temperature $\ldots \ldots T_{STG}, T_J$	-65°C to +175°C





RURG1540CC



RURG1550CC

500V

500V

500V

15A

30A

200A

100W

20mj

-65°C to +175°C



6

RURG1560CC

600V

600V

600V

15A

30A

200A

100W

20mj

-65°C to +175°C

#### Specifications RURG1540CC, RURG1550CC, RURG1560CC

		EST	RURG	1540CC	LIMITS	RURG	1550CC	LIMITS	RURG	1560CC	LIMITS	
SYMBOL	1	CONDITION			MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
VF	I <sub>F</sub> = 15A		-	-	1.5	-	-	1.5	-	-	1.5	V
VF	I <sub>F</sub> = 15A	T <sub>C</sub> = +150°C	-	-	1.3	-	-	1.3	-	-	1.3	v
IR	V <sub>R</sub> = 400V		-	-	10	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V		-	-	-	-	-	10	-	-	-	μА
	V <sub>R</sub> = 600V		-	-	-	-	-	-	-	-	10	μΑ
I <sub>R</sub>	V <sub>R</sub> = 400V	T <sub>C</sub> = +150°C	-	-	500	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V	T <sub>C</sub> = +150°C	-	-	-		-	500	•	-	-	μΑ
	V <sub>R</sub> = 600V	T <sub>C</sub> = +150°C	-	-	-	•	-	-	-	-	500	μА
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /d	t = 100A/μs	-	-	55	-	•	55	-	-	55	ns
t <sub>RR</sub>	I <sub>F</sub> = 15A, dI <sub>F</sub> /	/dt = 100A/μs	-	-	60	-	-	60	-	-	60	ns
t <sub>A</sub>	I <sub>F</sub> = 15A, dI <sub>F</sub> /dt = 100A/μs		-	30	-	-	30	-	-	30	-	ns
t <sub>B</sub>	l <sub>F</sub> = 15A, dl <sub>F</sub> /	/dt = 100A/μs	-	17	-	-	17	·	-	17	-	ns
R <sub>eJC</sub>			-		1.5	-	-	1.5		-	1.5	°C/W

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

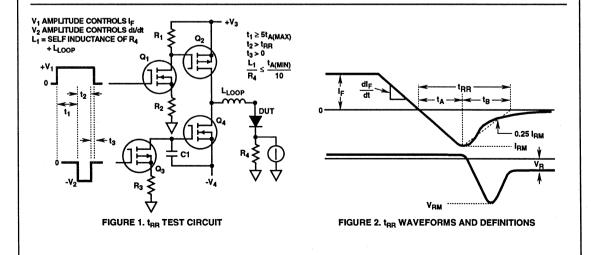
t<sub>B</sub> = Time from peak I<sub>BM</sub> to projected zero crossing of I<sub>BM</sub> based on a straight line from peak I<sub>BM</sub> through 25% of I<sub>BM</sub> (See Figure 2).

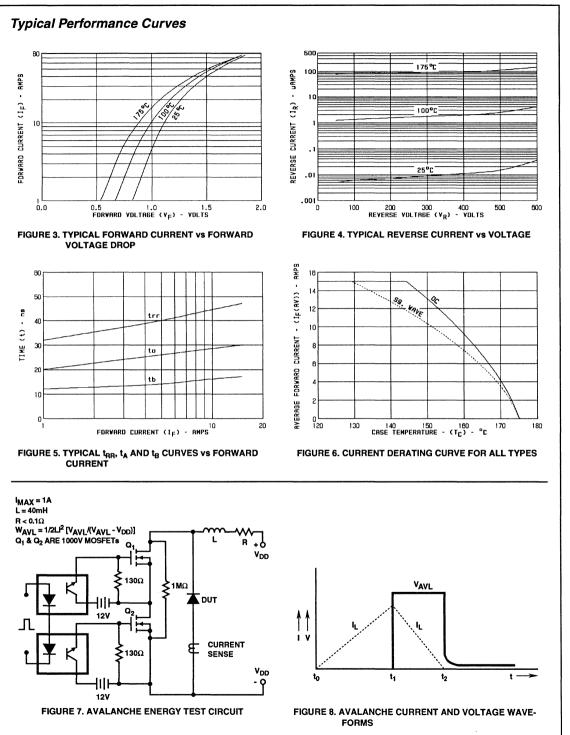
ReJC = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





6

ULTRAFAST DUAL DIODES



### RURG1570CC, RURG1580CC RURG1590CC, RURG15100CC

#### December 1993

#### 15A, 700V - 1000V Dual Ultrafast Diodes

#### Features Package JEDEC STYLE TO-247 TOP VIEW Operating Temperature .....+175°C CATHODE Avalanche Energy Rated (BOTTOM SIDE > ANODE 1 METAL) Planar Construction CATHODE Applications ANODE 2 Switching Power Supplies Power Switching Circuits General Purpose Symbol Description RURG1570CC. RURG1580CC. RURG1590CC and RUR15100CC are ultrafast dual diodes with soft recovery characteristics (t<sub>BB</sub> < 100ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction. These devices are intended for use as freewheel/clamping diode and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors. All devices are supplied in the JEDEC Style TO-247 package. Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified RURG1570CC RURG1580CC RURG1590CC RURG15100CC Peak Repetitive Reverse Voltage......VRRM 700V 800V 900V 1000V Working Peak Reverse Voltage ......V<sub>BWM</sub> 800V 900V 1000V 700V DC Blocking Voltage. ..... V<sub>B</sub> 700V 800V 900V 1000V Average Rectified Forward Current (Per Leg) ......IF(AV) 15A 15A 15A 15A (Total device forward current at rated V<sub>B</sub> and T<sub>C</sub> = +150°C) Peak Forward Repetitive Current ...... IFRM 30A 30A 30A 30A (Rated V<sub>B</sub>, square wave 20kHZ) Nonrepetitive Peak Surge Current ...... I<sub>FSM</sub> 200A 200A 200A 200A (Surge applied at rated load condition halfwave 1 phase 60Hz) 100W 100W 100W 100W

							LIM	ITS						1
	TEST	RURG1570CC			RU	RG1580	CC	RU	RG1590	cc	RU	RG1510	000	1
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-	-	1.50	V
	I <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	-	-	1.80	•	-	1.80	v
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	500	-	-	-	-	-	-	-	-	-	μΑ
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	-	-	-	-	-	500	-	•	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	•	500	-	-	-	μA
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	•	•	-	-	500	μA
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	100	-	-	-	-	-	-	-	-	-	μA
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-	-	-	-	100	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 900V	-	-	-	-	-	-	-	-	100	-	-	-	μA
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	100	μA
t <sub>RR</sub>	l <sub>F</sub> = 1A	-	-	100	-	-	100	-	-	100	-	-	100	ns
	I <sub>F</sub> = 15A	-	-	125	-	-	125	•	-	125	-	-	125	ns
t <sub>A</sub>	I <sub>F</sub> = 15A	-	75	-	-	75	-	•	75	-	-	75	-	ns
t <sub>B</sub>	l <sub>F</sub> = 15A	-	40	-	•	40	•	-	40	-	-	40	-	ns
Reic		-	-	1.5	-	-	1.5	-	-	1.5	-	-	1.5	°C/W
WAVL		-	-	20	•	-	20	•		20	-	-	20	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_{\text{A}}$  = Time to reach peak reverse current at dI\_F/dt = 100A/µs (See Figure 2).

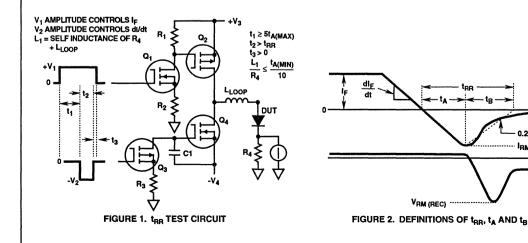
 $t_B$  = Time from peak  $I_{RM}$  to projected zero crossing of  $I_{RM}$  based on a straight line from peak  $I_{RM}$  through 25% of  $I_{RM}$  (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

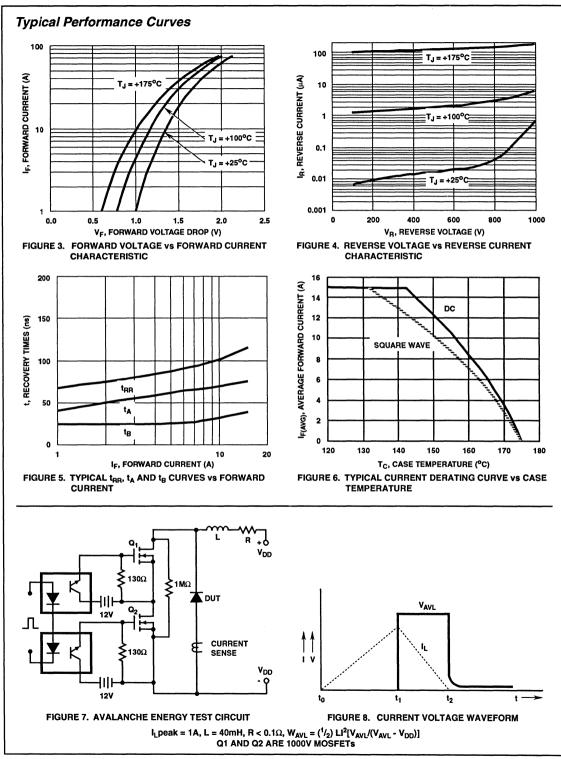




0.25 I<sub>RM</sub> I<sub>RM 1</sub>

V۵

#### RURG1570CC, RURG1580CC, RURG1590CC, RURG15100CC





## RURG3010CC RURG3015CC, RURG3020CC

Package

CATHODE

(BOTTOM SIDE

METAL)

Symbol

### 30A. 100V - 200V Ultrafast Dual Diodes

JEDEC STYLE TO-247 TOP VIEW

December 1993

Features

- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RURG3010CC, RURG3015CC and RURG3020CC (TA9645) are ultrafast dual diodes with soft recovery characteristics (t<sub>RR</sub> < 45ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

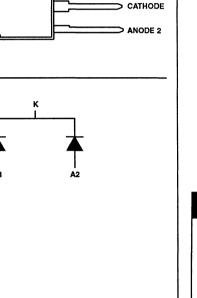
All devices are supplied in the JEDEC Style TO-247 package.

Due to space limitations, the brand on this part is abbreviated to UR3010CC, UR3015CC or UR3020CC,

To order this part use the full part number, e.g. RURG3010CC.

#### Absolute Maximum Ratings $(T_c = +25^{\circ}C)$

RURG3010CC	RURG3015CC	RURG3020CC	UNITS
100	150	200	v
100	150	200	v
a 100	150	200	v
) 30	30	30	Α
, 70	70	70	A
325	325	325	A
125	125	125	w
20	20	20	mj
-65 to +175			°C
	325 D 125 L 20	, 325 325 D 125 125 L 20 20	, 325 325 325 D 125 125 125 L 20 20 20



ANODE 1

6

#### Specifications RURG3010CC, RURG3015CC, RURG3020CC

	_	EST	RURG	3010CC	LIMITS	RURG3015CC LIMITS			RURG			
SYMBOL	CON	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 30A		-	-	1.0	-	-	1.0	-	-	1.0	v
V <sub>F</sub>	I <sub>F</sub> = 30A	T <sub>C</sub> = +150°C	-	-	0.85	-	-	0.85	-	-	0.85	v
I <sub>R</sub>	V <sub>R</sub> = 100V		-	-	30	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 150V			-	-	-	-	30	-	-	-	μА
	V <sub>R</sub> = 200V		-	-	-	-	-	-	-	-	30	μA
I <sub>R</sub>	V <sub>R</sub> = 100V	T <sub>C</sub> = +150°C	-	-	500	-	-	-	-	-	-	μА
	V <sub>R</sub> = 150V	T <sub>C</sub> = +150°C	-	-	-	-	-	500	-	-	-	μA
	V <sub>R</sub> = 200V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	500	μA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dl <sub>F</sub> /d	t = 100A/μs	-	-	45	-	-	45	-	-	45	ns
t <sub>RR</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /	dt = 100A/μs	-	-	50	-	-	50	-	-	50	ns
t <sub>A</sub>	l <sub>F</sub> = 30A, dl <sub>F</sub> /dt = 100A/μs		-	20	-	-	20	-	-	20	-	ns
t <sub>B</sub>	$l_F = 30A$ , $dl_F/dt = 100A/\mu s$		-	15	-	-	15	-	-	15	-	ns
R <sub>eJC</sub>			-	-	1.2	-	-	1.2	-	-	1.2	°C/W

#### DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

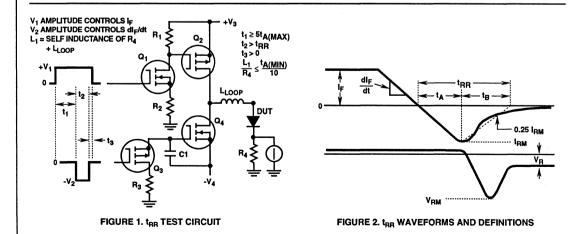
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>OJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

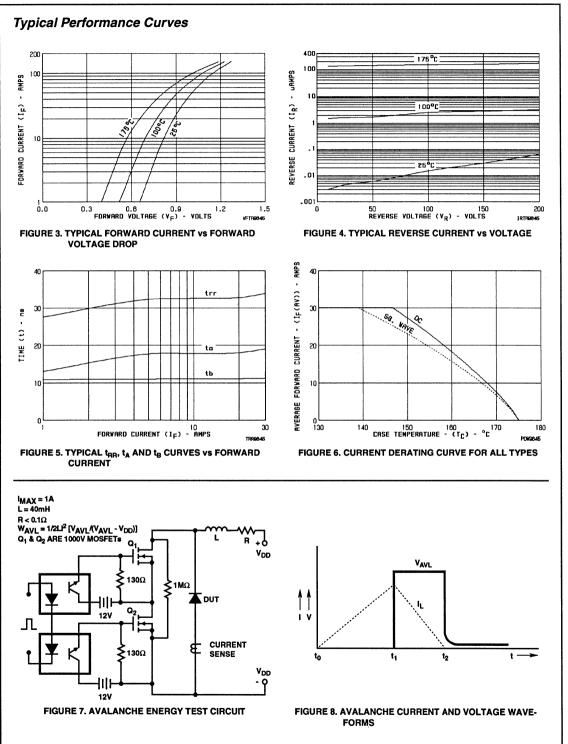
pw = pulse width.

D = duty cycle.



6-20

#### RURG3010CC, RURG3015CC, RURG3020CC



6

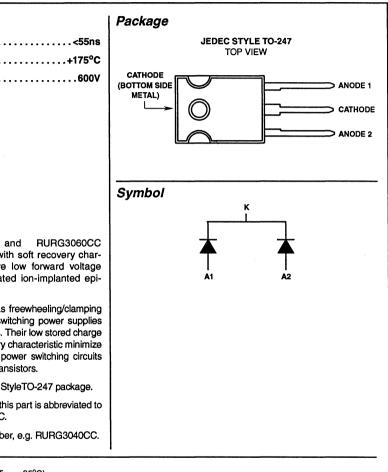
ULTRAFAST DUAL DIODES



### RURG3040CC RURG3050CC, RURG3060CC

#### December 1993

#### 30A, 400V - 600V Ultrafast Dual Diodes



### Features

- Ultrafast with Soft Recovery.....<55ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### **Applications**

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RURG3040CC, RURG3050CC and RURG3060CC (TA9903) are ultrafast dual diodes with soft recovery characteristics ( $t_{RR}$  < 55ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

All devices are supplied in the JEDEC StyleTO-247 package.

Due to space limitations, the brand on this part is abbreviated to UR3040CC, UR3050CC or UR3060CC.

To order this part use the full part number, e.g. RURG3040CC.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

RURG3040CC	RURG3050CC	RURG3060CC	UNITS
400	500	600	v
400	500	600	v
400	500	600	v
30	30	30	Α
70	70	70	A
325	325	325	A
125	125	125	w
20	20	20	mj
-65 to +175	-65 to +175	-65 to +175	°C
	400 400 30 70 325 125 20	400         500           400         500           400         500           30         30           70         70           325         325           125         125           20         20	400         500         600           400         500         600           400         500         600           400         500         600           30         30         30           70         70         70           325         325         325           125         125         125           20         20         20

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#### Specifications RURG3040CC, RURG3050CC, RURG3060CC

		EST	RURG	3040CC	LIMITS	RURG3050CC LIMITS			RURG	LIMITS		
SYMBOL	CON	MIN	түр	МАХ	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 30A		-	-	1.5	-	-	1.5	-	-	1.5	v
V <sub>F</sub>	I <sub>F</sub> = 30A	T <sub>C</sub> = +150°C		-	1.3		-	1.3	-	-	1.3	v
I <sub>R</sub>	V <sub>R</sub> = 400V		-	-	30	-	-	-	-	-	-	μА
	V <sub>R</sub> = 500V		-	-	-	-	-	30	-	-	-	μA
	V <sub>R</sub> = 600V	V <sub>R</sub> = 600V		-	-	-	-	-	-	-	30	μA
1 <sub>R</sub>	V <sub>R</sub> = 400V	T <sub>C</sub> = +150°C	-	-	1.0	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V	T <sub>C</sub> = +150°C	-	-	-	-	-	1.0	-	-	-	μA
	V <sub>R</sub> = 600V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	1.0	μΑ
t <sub>RR</sub>	l <sub>F</sub> = 1A, dl <sub>F</sub> /d	lt = 100Α/μs	-	-	55	-	-	55	-	-	55	ns
t <sub>RR</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /	/dt = 100A/μs	-	-	60	•	-	60	-	-	60	ns
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs		-	30	-	-	30	-	-	30	-	ns
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs		-	20	-	-	20	-	-	20	-	ns
R <sub>eJC</sub>			-	-	1.2		-	1.2	-	-	1.2	°C/W

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs,D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

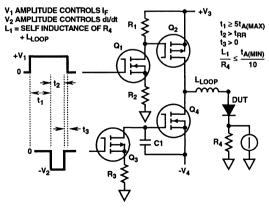
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>OJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

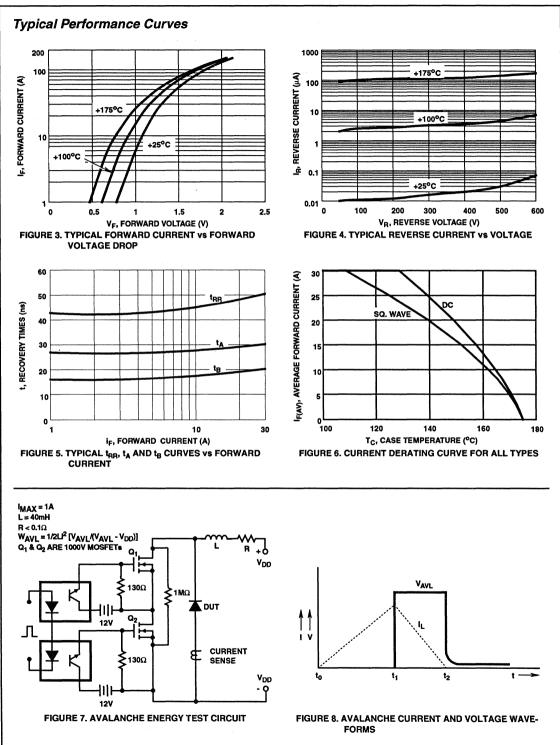


di<sub>F</sub> RR dt Îμ 0.25 I<sub>RM</sub> IRM ٧n . . . . . . . . . . . . VRM

#### FIGURE 1. t<sub>RR</sub> TEST CIRCUIT



#### RURG3040CC, RURG3050CC, RURG3060CC



### 

## RURG3070CC, RURG3080CC RURG3090CC, RURG30100CC

Package

Symbol

CATHODE

(BOTTOM SIDE METAL)

#### December 1993

#### 30A, 700V - 1000V Ultrafast Dual Diodes

JEDEC STYLE TO-247 TOP VIEW

ANODE 1

CATHODE

ANODE 2

### Features

- Operating Temperature .....+175°C
- Reverse Voltage Up to ......1000V
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RURG3070CC, RURG3080CC, RURG3090CC and RURG30100CC are ultrafast dual diodes with soft recovery characteristics ( $t_{\rm RR}$  < 110ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheel/clamping diode and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

All devices are supplied in the JEDEC Style TO-247 package.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C), Unless Otherwise Specified

	RURG3070CC	RURG3080CC	RURG3090CC	RURG30100CC	UNITS
Peak Repetitive Reverse VoltageV <sub>RF</sub>	M 700	800	900	1000	v
Working Peak Reverse VoltageVRW	M 700	800	900	1000	v
DC Blocking Voltage.	/ <sub>R</sub> 700	800	900	1000	v
Average Rectified Forward Current (Per Leg) I <sub>F(A</sub> (T <sub>C</sub> = +117°C)	v) 30	30	30	30	Α
Repetitive Peak Surge CurrentI <sub>FS</sub> (Square Wave, 20kHz)	м 60	60	60	60	A
Nonrepetitive Peak Surge Current	м 300	300	300	300	A
Maximum Power Dissipation F	P <sub>D</sub> 125	125	125	125	w
Operating and Storage Temperature	Γ <sub>J</sub> -65 to +175	-65 to +175	-65 to +175	-65 to +175	°C

# A1 A2

CAUTION: These devices are sensitive to electrostatic discharge. Users should follow proper I.C. Handling Procedures. Copyright © Harris Corporation 1992 6-25

							LIM	ITS						
	TEST	RURDG3070CC			RU	RG3080	CC	RU	RG3090	occ	RUI	RG3010	occ	1
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-	-	1.50	v
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	•	-	1.80	-	-	1.80	v
I <sub>R</sub> at	V <sub>R</sub> = 700V	•	-	1	-	-	-	-	-	-	-	-	-	μA
$T_{C} = +150^{\circ}C$	V <sub>R</sub> =800V	-	-	•	-	-	1	-	•	-	-	-	-	μA
	V <sub>R</sub> = 900V	•	-	-	-	-	-	-	-	1	-	-	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	-	•	-	-	-	-	-	-	1	μΑ
l <sub>R</sub> at T <sub>C</sub> = +25℃	V <sub>R</sub> = 700V	•	-	100	-	-	-	-	•	-	-	-	-	μΑ
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-	•	•	-	100	-	•	-	-	-	-	μΑ
	V <sub>R</sub> = 900V	-	-	-	•	-	-	-	•	100	•	-	-	μΑ
	V <sub>R</sub> = 1000V	-	-	-	•	-	-	-	-	-	-	-	100	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	110	-	-	110	-	-	110	•	-	110	ns
	I <sub>F</sub> = 30A	-	-	150	-	-	150	-	•	150	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A	-	90	-	-	90	-	-	90	-	-	90	-	ns
tg	I <sub>F</sub> = 30A	-	45	-	-	45	-	-	45	-	•	45	•	ns
R <sub>ejc</sub>		-	-	1.2	-	-	1.2	-	-	1.2	-	-	1.2	°C/W
WAVL		-	-	30		-	30	-	-	30		-	30	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), at dI<sub>F</sub>/dt = 100A/µs summation of t<sub>A</sub> + t<sub>B</sub>.

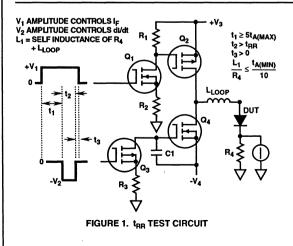
 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

 $t_B$  = Time from peak  $I_{RM}$  to projected zero crossing of  $I_{RM}$  based on a straight line from peak  $I_{RM}$  through 25% of  $I_{RM}$  (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.



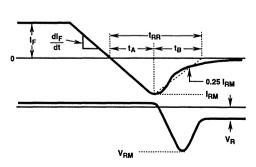
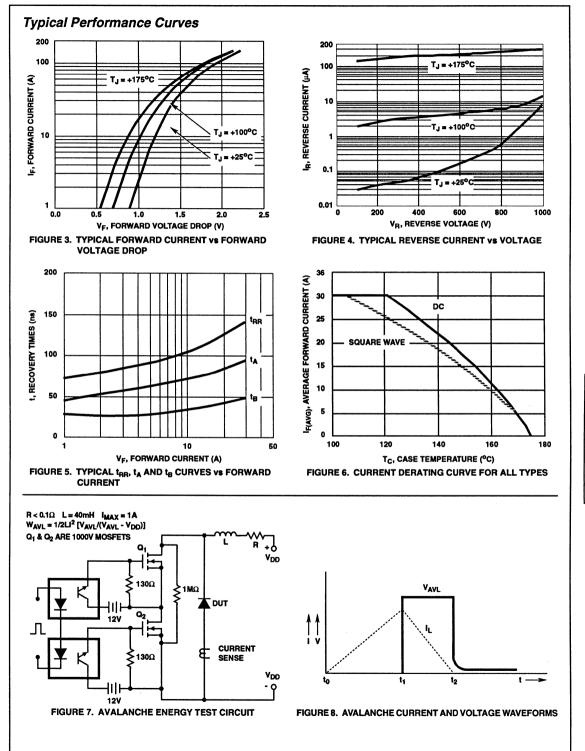


FIGURE 2. t<sub>RR</sub> WAVEFORMS AND DEFINITIONS



6

ULTRAFAST DUAL DIODES



## RURG30120CC

#### December 1993

#### 30A, 1200V Ultrafast Dual Diode

## Package JEDEC STYLE TO-247 TOP VIEW CATHODE ANODE 1 (BOTTOM SIDE METAL) CATHODE ANODE 2 Symbol Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RURG30120CC	UNITS
Peak Repetitive Reverse Voltage	1200	v
Working Peak Reverse Voltage	1200	v
DC Blocking VoltageV <sub>R</sub>	1200	v
Average Rectified Forward Current (Per Leg)	30	Α
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	60	Α
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	300	Α
Maximum Power Dissipation	125	w
Avalanche Energy (L = 40mH)	30	mj
Operating and Storage Temperature	-65 to +175	°C

#### Features

- Ultrafast with Soft Recovery......<110ns
- Operating Temperature .....+175°C
- Reverse Voltage Up To ......1200V
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

The RURG30120CC (49031) is an ultrafast dual diode with soft recovery characteristic (t<sub>BB</sub> < 110ns). It has low forward voltage drop and is silicon nitride passivated ion-implanted epitaxial planar construction.

This device is intended for use as a freewheeling/clamping diode and rectifier in a variety of switching power supplies and other power switching applications. Its low stored charge and ultrafast recovery with soft recovery characteristic minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

The RURG30120CC is supplied in the JEDEC Style TO-247 plastic package.

#### Specifications RURG30120CC

SYMBOL	TEST CONDITION	MIN	ТҮР	МАХ	
VF	I <sub>F</sub> = 30A, T <sub>C</sub> = +25°C	-	-	2.1	v
VF	I <sub>F</sub> = 30A, T <sub>C</sub> = +150°C	-	-	1.9	v
l <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +25°C	-	-	100	μΑ
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +150°C	-	-	1	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	110	ns
	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/µs	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt= 100A/μs	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/µs		45	-	ns
R <sub>evc</sub>		-	-	1.2	°C/W

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A$  +  $t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.

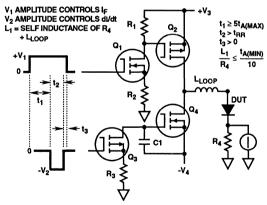
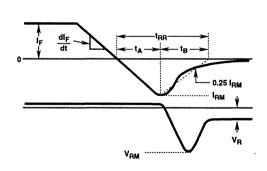
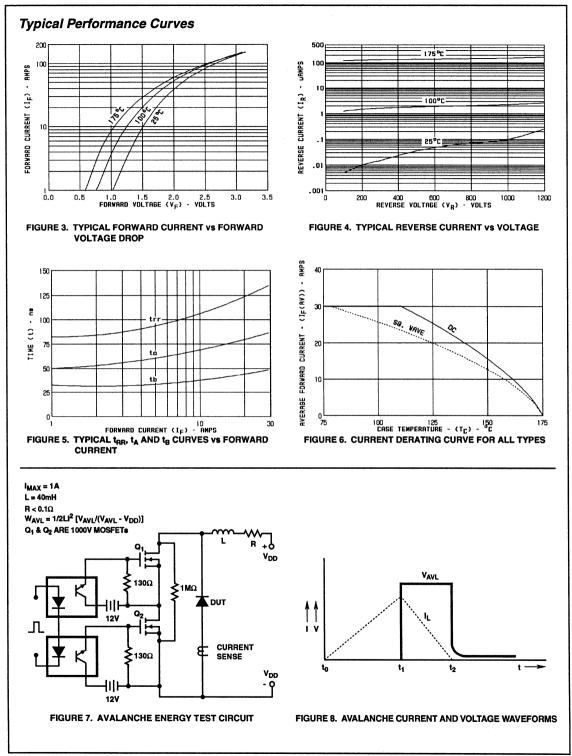


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT



#### FIGURE 2. t<sub>BB</sub> WAVEFORMS AND DEFINITIONS

#### RURG30120CC





## RURH1570CC, RURH1580CC RURH1590CC, RURH15100CC

#### December 1993

#### 15A, 700V - 1000V Ultrafast Dual Diodes

#### Features

- Operating Temperature ......+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

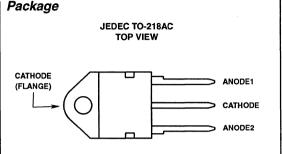
RURH1570CC, RURH1580CC, RURH1590CC and RURH15100CC are ultrafast dual diodes with soft recovery characteristics ( $t_{RR}$  < 100ns). They have low forward voltage drop and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheel/clamping diode and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristic minimizes ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

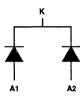
All devices are supplied in the JEDEC TO-218AC package.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C) Unless Otherwise Specified

	RURH1570CC	RURH1580CC	RURH1590CC	RURH15100CC
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	700V	800V	900V	1000V
Working Peak Reverse Voltage	700V	800V	900V	1000V
DC Blocking Voltage	700V	800V	900V	1000V
Average Rectified Forward Current (Per Leg) $\ldots I_{F(AV)}$ (T <sub>C</sub> = +141.25°C)	15A	15A	15A	15 <b>A</b>
Repetitive Peak Surge CurrentI <sub>FRM</sub> (Square Wave 20kHZ)	30A	30A	30A	30A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase 60Hz)	200A	200A	200A	200A
Maximum Power Dissipation P <sub>D</sub>	100W	100W	100W	100W
Operating and Storage Temperature	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C



Symbol



#### Specifications RURH1570CC, RURH1580CC, RURH1590CC, RURH15100CC

		LIMITS												
	TEST	RURH1570CC			RURH1580CC			RURH1590CC			RURH15100CC			
SYMBOL	CONDITION	MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	l <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-		1.50	v
	l <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	-	-	1.80	-	-	1.80	v
l <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	500	-	-	-	-	-	•	-	-	-	μA
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	-	-	-	•	-	500	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	•	-	-	-	500	-	-	-	μA
	V <sub>R</sub> = 1000V	•	-	-	-	-	-	-	-	-	-	-	500	μA
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	100	-	-	-	-	-	-	-	-	-	μA
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	-	-	-	-	-	100	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	-	-	-	-	-	•	-	-	100	-	-	-	μA
	V <sub>R</sub> = 1000V	-	-	-	-	-	-	-	-	-	-	-	100	μΑ
t <sub>RR</sub>	l <sub>F</sub> = 1A	-	-	100	-	-	100	-	-	100	-	-	100	ns
	I <sub>F</sub> = 15A	-	-	125	•	-	125	-	-	125	-	-	125	ns
t <sub>A</sub>	l <sub>F</sub> = 15A	•	75	-	•	75	-	-	75	-	-	75	-	ns
t <sub>B</sub>	l <sub>F</sub> = 15A	-	40	•	•	40	-	-	40	•	-	40	-	ns
Reic		-	-	1.5	-	-	1.5	-	-	1.5	-	-	1.5	°C/W
WAVL		-	-	20	•	-	20	-	•	20	-	-	20	mj

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A$  +  $t_B$ .

 $t_A$  = Time to reach peak reverse current at dI<sub>F</sub>/dt = 100A/µs (See Figure 2).

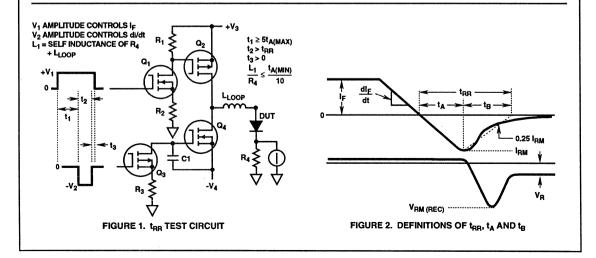
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

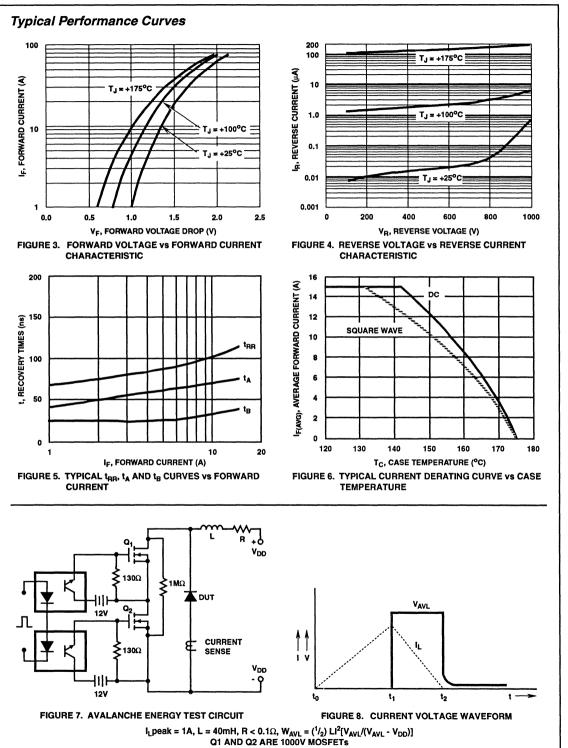
R<sub>eJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





6

ULTRAFAST DUAL DIODES



## **MUR1610CT** MUR1615CT, MUR1620CT

16A. 100V - 200V Ultrafast Dual Diodes

#### December 1993

#### Features

- Ultrafast Recovery Time (t<sub>RR</sub> < 35ns)</li>
- Low Forward Voltage
- Low Thermal Resistance
- Hard Glass Passivation
- Wire-Bonded Construction

#### Applications

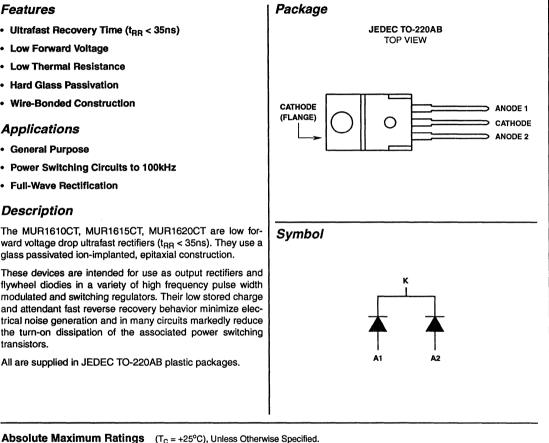
- General Purpose
- · Power Switching Circuits to 100kHz
- Full-Wave Rectification

#### Description

The MUR1610CT, MUR1615CT, MUR1620CT are low forward voltage drop ultrafast rectifiers (t<sub>BB</sub> < 35ns). They use a glass passivated ion-implanted, epitaxial construction.

These devices are intended for use as output rectifiers and flywheel diodies in a variety of high frequency pulse width modulated and switching regulators. Their low stored charge and attendant fast reverse recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

All are supplied in JEDEC TO-220AB plastic packages.



	MUR1610CT	MUR1615CT	MUR1620CT
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100V	150V	200V
Working Peak Reverse VoltageV <sub>RWM</sub>	100V	150V	200V
DC Blocking Voltage V <sub>R</sub>	100V	150V	200V
Average Rectified Forward Current (Per Leg) $I_{F(AV)}$ (Total device, (rated $V_R$ ), $T_C = +150^{\circ}C$	8A 16A	8A 16A	8A 16A
Peak Forward Repetitive Current (Per Diode Leg)I <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ) T <sub>C</sub> = +150°C	16A	16A	16A
Nonrepetitive Peak Surge Current	100A	100A	100A
Operating and Storage Temperature	-65°C to +175°C	-65°C to +175°C	-65°C to +175°C
Maximum Lead Temperature During Soldering	260°C	260°C	260°C

#### Copyright C Harris Corporation 1993

#### Specifications MUR1610CT, MUR1615CT, MUR1620CT

	Decifications	1C - +20		S Otherwise	sopecine								
			LIMITS										
		MUR1610CT			Ņ	AUR16150	т	N					
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	түр	МАХ	UNITS		
V <sub>F</sub>	I <sub>F</sub> = 8A T <sub>C</sub> = +150°C	-	-	0.895	-	-	0.895	-	-	0.895	v		
	I <sub>F</sub> = 8A T <sub>C</sub> = +25°C	-	-	0.975	-	•	0.975	-	-	0.975	v		
$\frac{IR \text{ at}}{T_{C} = +150^{\circ}C} \qquad \frac{V_{R} = 100V}{V_{R} = 150V}$ $\frac{V_{R} = 150V}{V_{R} = 200V}$	-	-	250		•	-	-	-	•	μΑ			
	V <sub>R</sub> = 150V	-	-	-	-	-	250	-	-		μΑ		
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	250	μA		
IR at	V <sub>R</sub> = 100V	•	-	5	-		-	-	-	-	μΑ		
T <sub>C</sub> = +25°C	V <sub>R</sub> = 150V	-	-	-	-	-	5	-	-	-	μΑ		
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	5	μΑ		
t <sub>RR</sub>	I <sub>F</sub> = 1A (Note 1)	•	-	35	-	-	35	-	-	35	ns		
	l <sub>F</sub> = 0.5 (Note 2)		-	25	-	-	25		-	25	ns		
R <sub>eJC</sub>		-	-	3	-		3	-	•	3	°C/W		

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

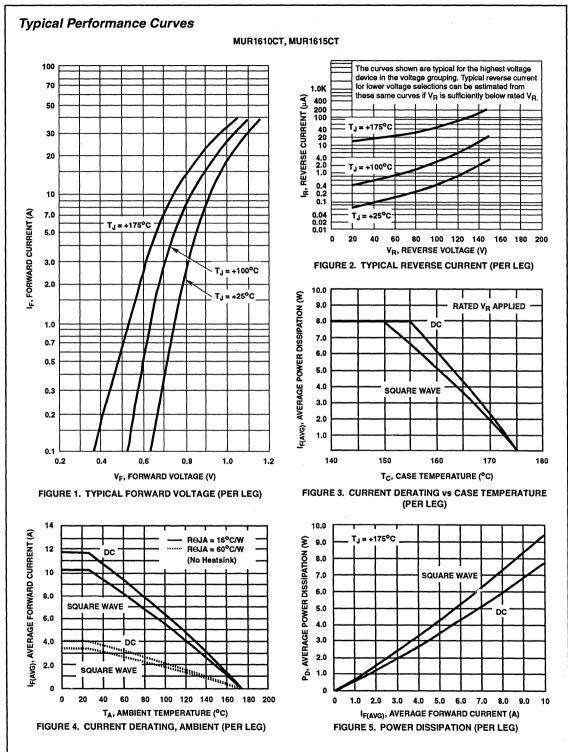
NOTES:

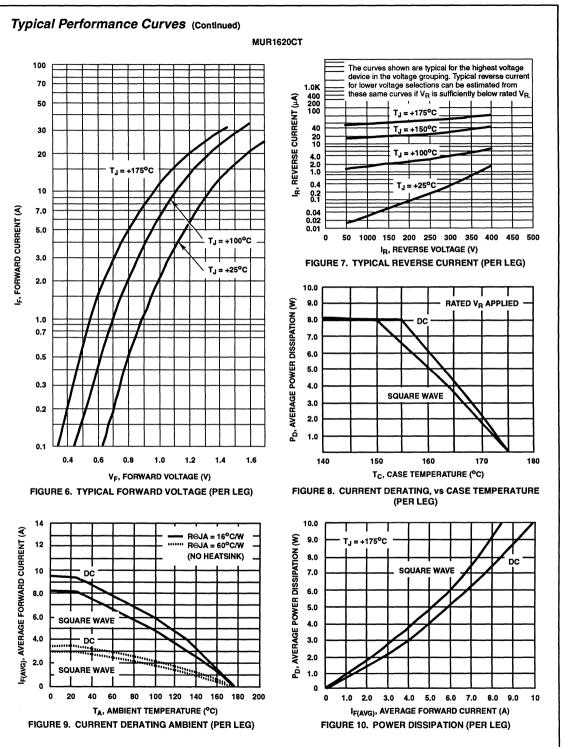
1.  $dI_F/dt = 50A/\mu s$ 

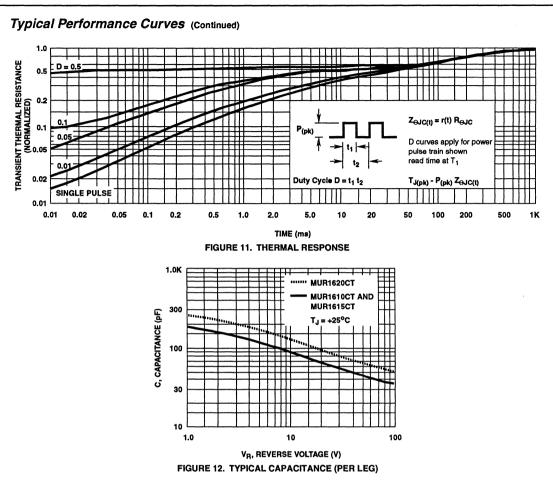
2. I<sub>R</sub> =1.0A, I<sub>REC</sub> = 0.25A.

6

ULTRAFAST DUAL DIODES









#### MUR3010PT, RURH1510CC MUR3015PŤ, RURH1515CC MUR3020PT. RURH1520CC

#### 15A, 100V - 200V Ultrafast Dual Diodes

JEDEC TO-218AC

TOP VIEW

ANODE1

CATHODE

ANODE2

Package

CATHODE

(FLANGE)

Symbol

December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 30ns)
- +175°C Rated Junction Temperature
- · Reverse Voltage Up to 200V
- Avalanche Energy Rated

#### **Applications**

- · Switching Power Supply
- · Power Switching Circuits
- General Purpose

#### Description

MUR3010PT. MUR3015PT. MUR3020PT and RURH1510CC, RURH1515CC, RURH1520CC are ultrafast dual diodes (t<sub>RR</sub> < 30ns) with soft recovery characteristics  $(t_A/t_B \approx 1)$ . They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-218AC packages.

#### Absolute Maximum Ratings $(T_{C} = +25^{\circ}C)$

	MUR3010PT RURH1510CC	MUR3015PT RURH1515CC	MUR3020PT RUR1520CC
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100V	150V	200V
Working Peak Reverse VoltageV <sub>RWM</sub>	100V	150V	200V
DC Blocking Voltage	100V	150V	200V
Average Rectified Forward Current $I_{F(AV)}$ (Total device forward current at rated $V_R$ and $T_C = 150^{\circ}C$ )	15A	15A	15A
Peak Forward Repetitive CurrentI <sub>FRM</sub> (Rated V <sub>R</sub> , square wave 20kHZ)	30A	30A	30A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Surge applied at rated load condition halfwave 1phase 60Hz)	200A	200A	200A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

#### MUR3010PT, MUR3015PT, MUR3020PT, RURH1510CC, RURH1515CC, RURH1520CC

		LIMITS									
	TEST	MUR301	OPT, RUR	H1510CC	MUR301	5PT, RUR	H1515CC	MUR302			
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	0.85	-	-	0.85	-	-	0.85	v
	I <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.05	-	-	1.05	-	-	1.05	v
IR at V <sub>R</sub> = 100	V <sub>R</sub> = 100V	<u> </u>	-	500	-	-	-	-	-	· -	μA
T <sub>C</sub> = +150°C	V <sub>R</sub> = 150V	· ·	-	-	·-	-	500	-	· -		μΑ
	V <sub>R</sub> = 200V	<u> </u>	-		-	-	-	-	-	500	μA
IR at $V_R = 100V$ TC = +25°C $V_R = 150V$	V <sub>R</sub> = 100V	-	-	10	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 150V	·	-	-		-	10	-	- 1	-	μΑ
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	10	μΑ
t <sub>RR</sub>	l <sub>F</sub> = 1A	<u> </u>	-	30	-	-	30	-	-	30	ns
	I <sub>F</sub> = 15A	-	-	35	-	-	35	-	•	35	ns
t <sub>A</sub>	l <sub>F</sub> = 1A	- 1	18	-	-	18	-	-	18	-	ns
	l <sub>F</sub> = 15A	<u> </u>	20	-	-	20	-	-	20	-	ns
t <sub>B</sub>	I <sub>F</sub> = 1A	-	9	-	-	9	-	-	9	-	ns
	l <sub>F</sub> = 15A	-	10	-	-	10	-	-	10	-	ns
Rejc		-	-	1.5	-	-	1.5	-	-	1.5	°C/W
WAVL	see Fig. 7, 8	- 1	-	20	-	-	20	-	- 1	20	mj

Electrical Specifications Case Temperature (T<sub>C</sub>) = +25°C, Unless Otherwise Specified

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

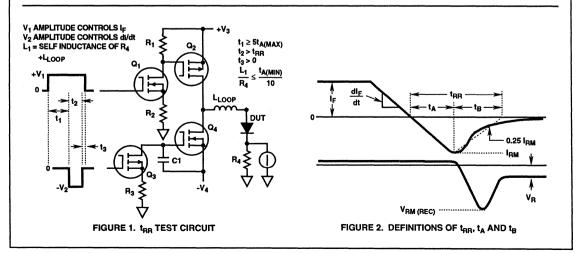
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

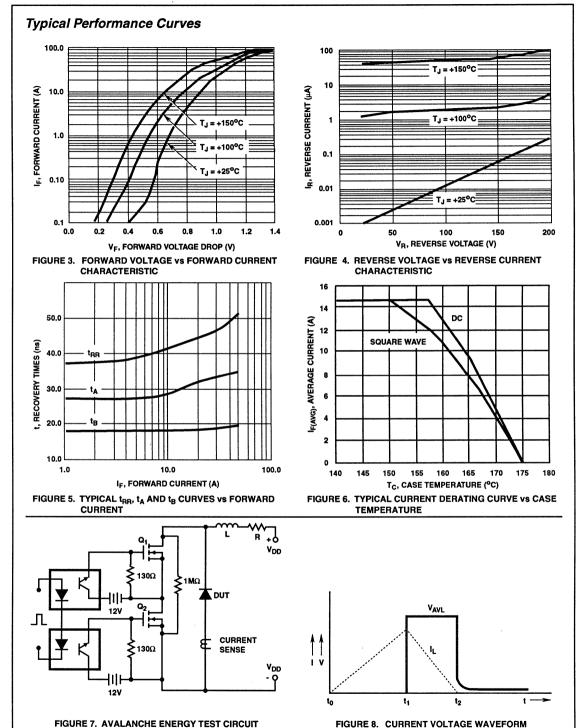
R<sub>OJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







ULTRAFAST DUAL DIODES



#### December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 55ns)
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 600V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

MUR3040PT, MUR3050PT, MUR3060PT and RURH1540CC, RURH1550CC, RURH1560CC are ultrafast dual diodes ( $t_{RR} < 55$ ns) with soft recovery characteristics ( $t_A/t_B \approx 1$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

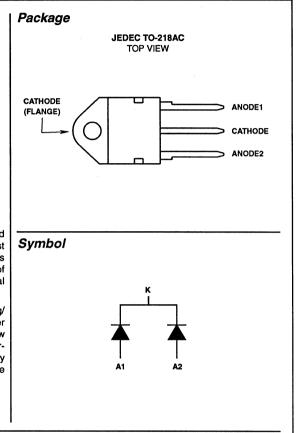
All are supplied in JEDEC TO-218AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified.

	MUR3040PT RURH1540CC	MUR3050PT RURH1550CC	MUR3060PT RURH1560CC
Peak Repetitive Reverse VoltageV <sub>RR</sub> M	400V	500V	600V
Working Peak Reverse VoltageV <sub>RWM</sub>	400V	500V	600V
DC Blocking Voltage	400V	500V	600V
Average Rectified Forward Current	15 <b>A</b>	15A	15A
Peak Forward Repetitive Current	42	42	30A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Surge applied at rated load condition halfwave 1phase 60Hz)	200A	200A	200A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

## MUR3040PT, RURH1540CC MUR3050PT, RURH1550CC MUR3060PT, RURH1560CC

#### 15A, 400V - 600V Ultrafast Dual Diodes



		LIMITS										
	TEST	MUR304	OPT, RUR	H1540CC	MUR305	OPT, RUR	H1550CC	MUR306				
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 15A T <sub>C</sub> = +150°C	-	-	1.12	-	-	1.20	-	-	1.20	v	
	I <sub>F</sub> = 15A T <sub>C</sub> = +25°C	-	-	1.25	-	-	1.50	-	-	1.50	v	
IR at	V <sub>R</sub> = 400V	· ·	•	500	-	•	•	•	-	-	μΑ	
T <sub>C</sub> = +150°C	V <sub>R</sub> = 500V	•	-	-	-	-	500	-	-	-	μΑ	
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	500	μA	
$\begin{array}{c} \text{IR at} \\ \text{TC} = +25^{\circ}\text{C} \end{array} \qquad $	V <sub>R</sub> = 400V	·	-	10	-	-	•	-	-	-	μA	
	V <sub>R</sub> = 500V	-	-	-	•	-	10	•	-	-	μΑ	
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	10	μΑ	
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	55	-	-	55	-	-	55	ns	
	I <sub>F</sub> = 15A	-	-	60	•	-	60	-	-	60	ns	
t <sub>A</sub>	I <sub>F</sub> = 1A	- 1	20	-	-	20	-	-	20	-	ns	
	l <sub>F</sub> = 15A	-	30	-	-	30	-	-	30	-	ns	
t <sub>B</sub>	I <sub>F</sub> = 1A	-	15	-	-	15	-	-	15		ns	
	I <sub>F</sub> = 15A	-	17	-	-	17	-	-	20	-	ns	
R <sub>eJC</sub>	1	- 1	-	1.5	•	-	1.5	-	-	1.5	°C/W	
WAVL	see Fig. 7, 8	-	-	20	-	-	20	-	-	20	mj	

Electrical Specifications Case Temperature (T<sub>C</sub>) = +25°C, Unless Otherwise Specified.

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt = 100A/\mu s$  (See Figure 2).

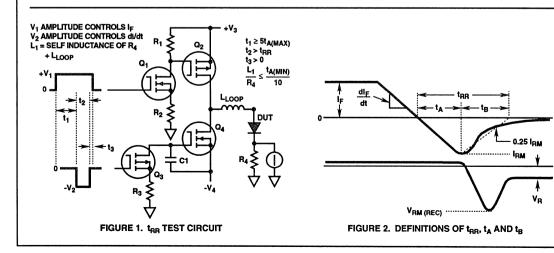
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

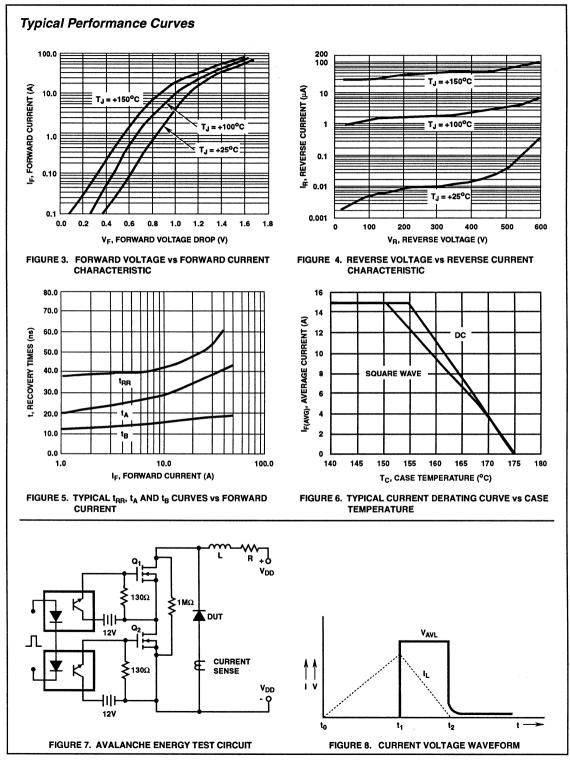
R<sub>BJC</sub> = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.







## RURH3010CC RURH3015CC, RURH3020CC

December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 45ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 200V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

RURH3010CC, RURH3015CC, RURH3020CC are ultrafast dual diodes ( $t_{RR}$  < 45ns) with soft recovery characteristics ( $t_A/t_B \approx 1$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

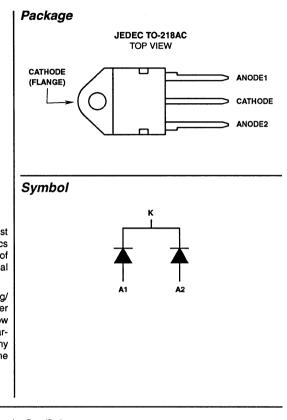
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-218AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified.

	RURH3010CC	RURH3015CC	RURH3020CC
Peak Repetitive Reverse Voltage V <sub>RRM</sub>	100V	150V	200V
Working Peak Reverse Voltage V <sub>RWM</sub>	100V	150V	200V
DC Blocking Voltage	100V	150V	200V
Average Rectified Forward Current (Per Leg) $\dots I_{F(AV)}$ (Total device forward current at rated V <sub>R</sub> and T <sub>C</sub> = +150°C)	30A	30A	30A
Peak Forward Repetitive Current	70A	70A	70A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	325A	325A	325A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

#### 30A, 100V - 200V Ultrafast Dual Diodes



#### Specifications RURH3010CC, RURH3015CC, RURH3020CC

			LIMITS									
	TEST	RURH3010CC			RURH3015CC			RURH3020CC			1	
SYMBOL	CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	0.85	•	-	0.85	-	-	0.85	v	
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	•	•	1.00	•	•	1.00	-	•	1.00	V	
l <sub>R</sub> at	15000	-	•	500	-	-	•	-	•	-	μA	
T <sub>C</sub> = +150°C	V <sub>R</sub> = 150V	-	•	-	-	-	500	-	-	-	μΑ	
V <sub>R</sub> = 2	V <sub>R</sub> = 200V	•	-	-	-	- 1	-	-	-	500	μΑ	
I <sub>R</sub> at V <sub>R</sub> =	V <sub>R</sub> = 100V	•	-	30	-	-	•	-	-	-	μA	
T <sub>C</sub> = +25°C	V <sub>R</sub> = 150V	-	•	-	-	-	30	-	-	-	μA	
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	30	μΑ	
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	45	•	-	45	-	-	45	ns	
	I <sub>F</sub> = 30A	-	-	50	-	-	50	-	-	50	ns	
t <sub>A</sub>	l <sub>F</sub> = 1A	-	24	-	-	24	-	-	24	- 1	ns	
	l <sub>F</sub> = 30A	· 1	28	•	-	28	•	-	28	-	ns	
t <sub>B</sub>	I <sub>F</sub> = 1A	· ·	17	-	•	17	-	•	17	-	ns	
	I <sub>F</sub> = 30A	•	20	-	•	20	•	•	20	-	ns	
Reic		•	•	1.2	•	-	1.2	•	-	1.2	°C/W	
WAVL	see Fig. 7 & 8	-	-	20	-	-	20	-	-	20	mj	

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified.

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>B</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at dI<sub>F</sub>/dt = 100A/µs (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

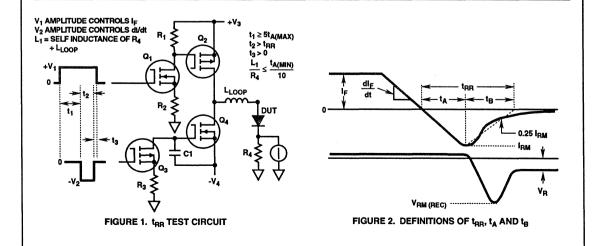
t<sub>B</sub> = Time from peak I<sub>BM</sub> to projected zero crossing of I<sub>BM</sub> based on a straight line from peak I<sub>BM</sub> through 25% of I<sub>BM</sub> (See Figure 2).

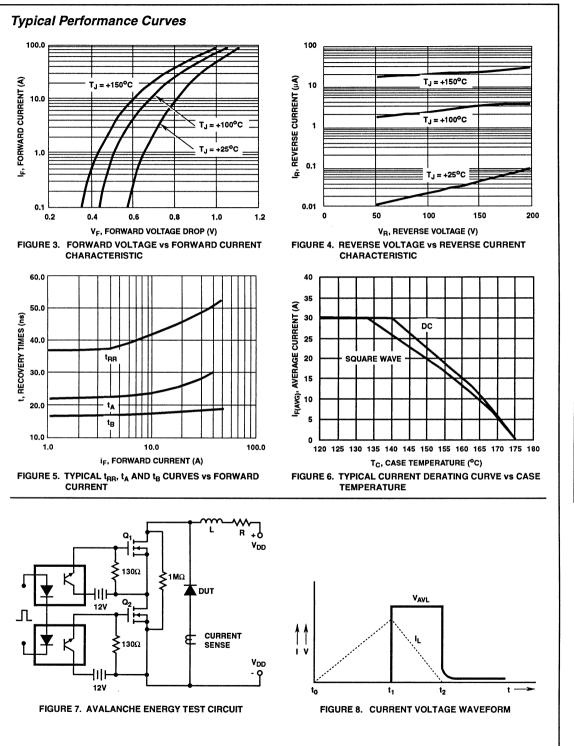
R<sub>9JC</sub> = Thermal resistance junction to case.

 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





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ULTRAFAST DUAL DIODES



## RURH3040CC RURH3050CC, RURH3060CC

December 1993

#### Features

- Ultrafast with Soft Recovery Characteristic (t<sub>RR</sub> < 55ns)</li>
- +175°C Rated Junction Temperature
- Reverse Voltage Up to 600V
- Avalanche Energy Rated

#### Applications

- Switching Power Supply
- Power Switching Circuits
- General Purpose

#### Description

RURH3040CC, RURH3050CC, RURH3060CC are ultrafast dual diodes ( $t_{RR} < 55ns$ ) with soft recovery characteristics ( $t_A/t_B \approx 1$ ). They have a low forward voltage drop and are of planar, silicon nitride passivated, ion-implanted, epitaxial construction.

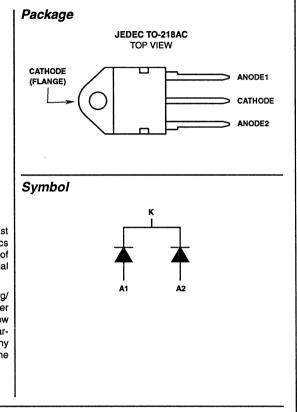
These devices are intended for use as energy steering/ clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and ultrafast recovery with soft recovery characteristics minimizes ringing and electrical noise in many power switching circuits thus reducing power loss in the switching transistor.

All are supplied in JEDEC TO-218AC packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified.

	RURH3040CC	RURH3050CC	RURH3060CC
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400V	500V	600V
Working Peak Reverse VoltageV <sub>RWM</sub>	400V	500V	600V
DC Blocking Voltage	400V	500V	600V
Average Rectified Forward Current (Per Leg) $\dots I_{F(AV)}$ (Total device forward current at rated V <sub>R</sub> and T <sub>C</sub> = +150°C)	30A	30A	30A
Peak Forward Repetitive Current	70A	70A	70A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Surge applied at rated load condition halfwave 1 phase 60Hz)	325A	325A	325A
Operating and Storage Temperature	-55°C to +175°C	-55°C to +175°C	-55°C to +175°C

#### 30A, 400V - 600V Ultrafast Dual Diodes



#### Specifications RURH3040CC, RURH3050CC, RURH3060CC

			LIMITS									
	TEST CONDITION	RURH3040CC			RURH3050CC			RURH3060CC			1	
SYMBOL		MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS	
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	1.30	-	-	1.30	-	-	1.30	V	
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.50	-	-	1.50	-	•.	1.50	V	
I <sub>R</sub> at	V <sub>R</sub> = 400V	-	-	1	-	-	-	-	-	-	μΑ	
$T_{C} = +25^{\circ}C$	V <sub>R</sub> = 500V	- 1	-	-	-		1	-	-	-	μΑ	
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	1	μA	
I <sub>R</sub> at	V <sub>R</sub> = 400V	-	-	30	-	-	-	-	-	-	μA	
T <sub>C</sub> = +150°C	V <sub>R</sub> = 500V	-	-	-	-	-	30	-	-	-	μA	
	V <sub>R</sub> = 600V	-	-	-	-	-	-	-	-	30	μA	
t <sub>RR</sub>	I <sub>F</sub> = 1A	•	-	55	-	-	55	-	-	55	ns	
	I <sub>F</sub> = 30A	-	-	60	-	-	60	-	-	60	ns	
t <sub>A</sub>	I <sub>F</sub> = 1A	-	20	-	•	20	-	-	20	-	ns	
	I <sub>F</sub> = 30A	-	38	-	-	38	-	-	38	-	ns	
t <sub>B</sub>	I <sub>F</sub> = 1A	•	15	-	•	15	-	•	15	-	ns	
	I <sub>F</sub> = 30A	-	20	-	•	20	-	-	20	-	ns	
Reic		-	-	1.2	-	-	1.2	-	-	1.2	°C/W	
WAVL	see Fig. 7 & 8	1.	-	20		-	20	-	-	20	mj	

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time at  $dI_{F}/dt$  = 100A/µs (See Figure 2), summation of  $t_{A} + t_{B}$ .

 $t_{\text{A}}$  = Time to reach peak reverse current at dl\_r/dt = 100A/µs (See Figure 2).

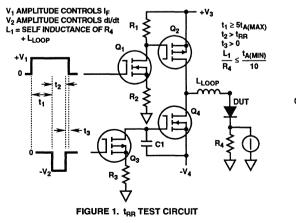
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

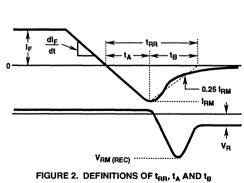
R<sub>OJC</sub> = Thermal resistance junction to case.

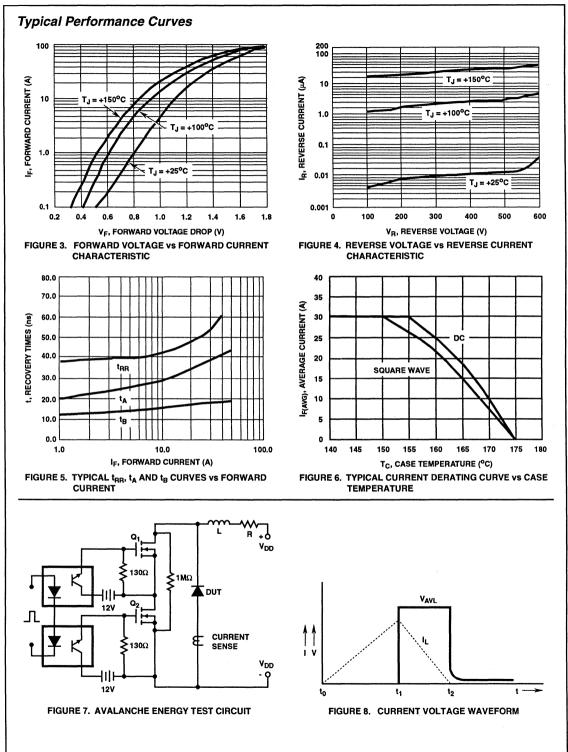
WAVL = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





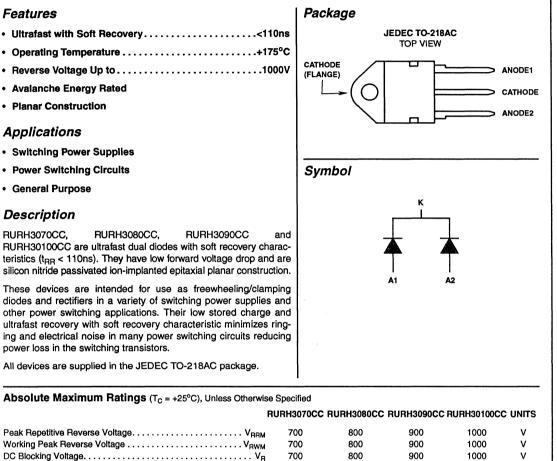




## RURH3070CC, RURH3080CC RURH3090CC, RURH30100CC

#### December 1993

#### 30A, 700V - 1000V Ultrafast Dual Diodes



Working Peak Reverse Voltage V <sub>RWM</sub>	700	800	900	1000	
DC Blocking Voltage V <sub>R</sub>	700	800	900	1000	
Average Rectified Forward Current (Per Leg) $I_{F(AV)}$ (T <sub>c</sub> = +121°C)	30	30	30	30	
Repetitive Peak Surge Current	60	60	60	60	
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	300	300	300	300	
Maximum Power Dissipation PD	125	125	125	125	
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	-65 to +175	

ULTRAFAST DUAL DIODES

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							LIM	ITS						
	TEST CONDITION	RURH3070CC		RURH3080CC			RURH3090CC			RURH30100CC				
SYMBOL		MIN	ТҮР	MAX	MIN	ТҮР	MAX	MIN	TYP	MAX	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 30A T <sub>C</sub> = +150°C	-	-	1.50	-	-	1.50	-	-	1.50	-	-	1.50	V
	I <sub>F</sub> = 30A T <sub>C</sub> = +25°C	-	-	1.80	-	-	1.80	-	-	1.80	-	-	1.80	v
I <sub>R</sub> at	V <sub>R</sub> = 700V	-	-	1	•	-	-	-	-	-	-	-	-	μΑ
T <sub>C</sub> = +25°C	V <sub>R</sub> = 800V	•	-	-	-	•	1	-	•	•	-	-	-	μΑ
	V <sub>R</sub> = 900V	•	-	-	-	-	-	-	-	1	-	-	-	μΑ
	V <sub>R</sub> = 1000V	•	-	-	-	•	-	-	-	-	-	-	1	μA
I <sub>R</sub> at	V <sub>R</sub> = 700V	•	-	1000	-	-	-	-	-	-	-	-	-	μA
T <sub>C</sub> = +150°C	V <sub>R</sub> = 800V	•	-	-	-	-	1000	-	-	-	-	-	-	μA
	V <sub>R</sub> = 900V	•	-	-	-	-	-	-	-	1000	-	-	-	μA
	V <sub>R</sub> = 1000V	•	-	-	-	-	-	-	-	-	-	-	1000	μA
t <sub>RR</sub>	I <sub>F</sub> = 1A	-	-	110	-	-	110	-	-	110	-	-	110	ns
	I <sub>F</sub> = 30A	•	-	150	•	-	150	-	-	150	-	-	150	ns
t <sub>A</sub>	I <sub>F</sub> = 30A	-	90	-	-	90	-	-	90	-	-	90	-	ns
t <sub>B</sub>	I <sub>F</sub> = 30A	•	45	-	-	45	•	•	45	-	-	45	-	ns
R <sub>eJC</sub>		•	-	1.2	-	-	1.2	•	-	1.2	-	-	1.2	°C/W
WAVL		•		30	-	-	30		-	30			30	mj

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), at dI<sub>F</sub>/dt = 100A/µs summation of  $t_A$  +  $t_B$ .

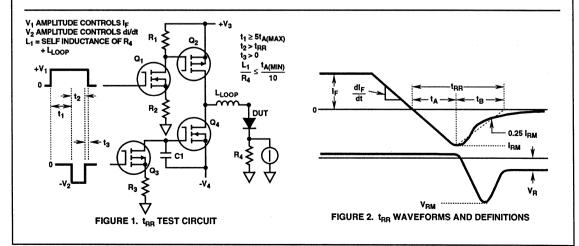
 $t_A$  = Time to reach peak reverse current at  $dI_F/dt$  = 100A/µs (See Figure 2).

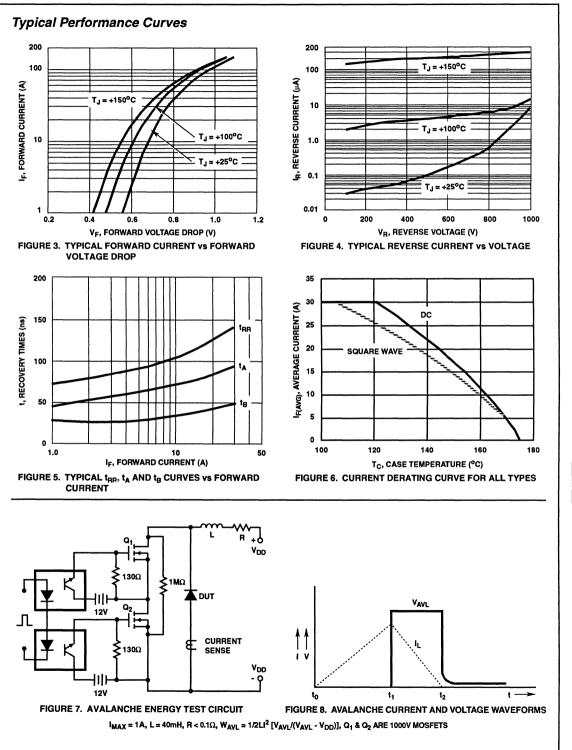
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

R<sub>eJC</sub> = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.





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ULTRAFAST DUAL DIODES



## RURM1610CC RURM1615CC, RURM1620CC

December 1993

#### Features

- Ultrafast Recovery Time (t<sub>RR</sub> < 35ns)
- Low Forward Voltage
- Low Thermal Resistance
- Planar Design
- Wire-Bonded Construction

#### Applications

- General Purpose
- Power Switching Circuits to 100kHz
- Full-Wave Rectification

#### Description

RURM1610CC, RURM1615CC, RURM1620CC are low forward voltage drop ultrafast rectifiers (t<sub>BB</sub> < 35ns). They use an ion-implanted planar epitaxial construction.

These devices are intended for use as output rectifiers and flywheel diodies in a variety of high frequency pulse width modulated and switching regulators. Their low stored charge and attendant fast reverse recovery behavior minimize electrical noise generation and in many circuits markedly reduce the turn-on dissipation of the associated power switching transistors.

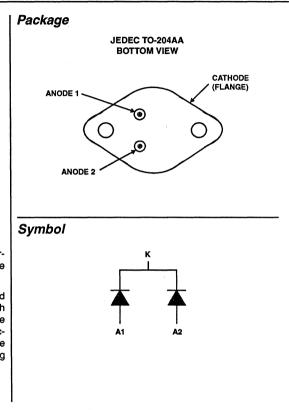
All are supplied in JEDEC TO-204AA hermetic packages.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified.

	RURM1610CC	RURM1615CC	RURM1620CC
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	100V	150V	200V
$ \begin{array}{l} \mbox{Average Rectified Forward Current (Per Leg)} \\ T_A = +25^\circ C \ (No \ Heat \ Sink) \ \dots \ I_{F(AV)} \\ T_A = +25^\circ C \ (With \ Heat \ Sink)^* \ \dots \ I_{F(AV)} \\ T_C = +125^\circ C \ \dots \ I_{F(AV)} \end{array} $	6A 16A 16A	6A 16A 16A	6A 16A 16A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (8.3ms, <sup>1</sup> / <sub>2</sub> cycle)	275A	275A	275A
Thermal Resistance Junction-to-Case	1.5°C/W	1.5°C/W	1.5°C/W
Thermal Resistance Junction-to-Case (Total)	1.2°C/W	1.2°C/W	1.2°C/W
Thermal Resistance Junction-to-Ambient.	30°C/W	30°C/W	30°C/W
Operating and Storage Temperature	-55°C to +150°C	-55°C to +150°C	-55°C to +150°C
Maximum Lead Temperature During SolderTL (At distance > $1/_8$ " (3.17mm) from case or 10s max)	260°C	260°C	260°C
*Wakefield type 621 heat sink with convection cooling.			

621 neat sink with convection cooling.

#### 16A .100V - 200V Ultrafast Dual Diodes

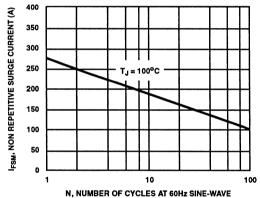


#### Specifications RURM1610CC, RURM1615CC, RURM1620CC

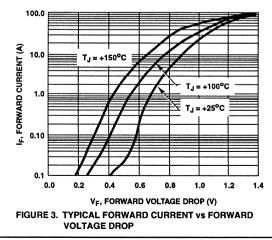
		RURM1610CC			RURM1615CC			RL			
SYMBOL	TEST CONDITION	MIN	түр	мах	MIN	түр	мах	MIN	түр	мах	UNITS
V <sub>F</sub>	I <sub>F</sub> = 16A, T <sub>C</sub> = +150°C	-	-	0.895	-	-	0.895	-	-	0.895	V
	I <sub>F</sub> = 16A, T <sub>C</sub> = +25°C	-	-	0.975	-	-	0.975	-	-	0.975	V
I <sub>R</sub> at	V <sub>R</sub> = 100V	-	-	500	-	-	-	-	-	-	μA
$T_{C} = +150^{\circ}C$	V <sub>R</sub> = 150V	-	-	-	-	-	500	-	-	-	μA
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	500	μA
l <sub>R</sub> at	V <sub>R</sub> = 100V	-	-	15	-	-	-	-	-	-	μΑ
T <sub>C</sub> = +25°C	V <sub>R</sub> = 150V	-	-	-	-	-	15	-	- 1	-	μΑ
	V <sub>R</sub> = 200V	-	-	-	-	-	-	-	-	15	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 4A*	-	-	35	-	-	35	-	-	35	ns
R <sub>eJC</sub>		-	-	1.5	-	-	1.5	-	-	1.5	°C/W
R <sub>eja</sub>		-	-	30	-	-	30	-	-	30	°C/W
Cj	V <sub>R</sub> = 10V, I <sub>F</sub> = 0A	-	80	-	-	80	-	-	80	-	pF

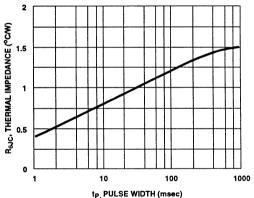
#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

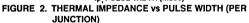
#### **Typical Performance Curves**

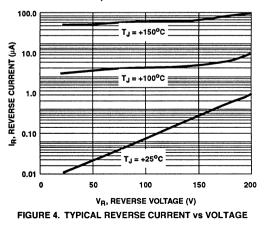












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# MCT/IGBT/DIODES

## HYPERFAST SINGLE AND DUAL DIODES

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HYPERFAST DIODES

### ----- Selection Guide -

#### HARRIS DUAL HYPERFAST RECOVERY RECTIFIER PRODUCT LINE

		TO-247						
	ТО-220АВ  I <sub>F(AVG)</sub>		-24 <i>1</i>  AVG)					
V <sub>RRM</sub>	8Ax2	15Ax2	30Ax2					
400V	RHRP840CC	RHRG1540CC	RHRG3040CC					
500V	RHRP850CC	RHRG1550CC	RHRG3050CC					
600V	RHRP860CC	RHRG1560CC	RHRG3060CC					
700V	RHRP870CC	RHRG1570CC	RHRG3070CC					
800V	RHRP880CC	RHRG1580CC	RHRG3080CC					
900V	RHRP890CC	RHRG1590CC	RHRG3090CC					
1000V	RHRP8100CC	RHRG15100CC	RHRG30100CC					
1200V	RHRP8120CC	RHRG15120CC	RHRDG30120CC					

SHADING = FUTURE PRODUCT OFFERINGS

#### HARRIS HYPERFAST RECOVERY RECTIFIER PRODUCT LINE

	ТО	-251	то	-252		TO-220AC		2	2 LEAD TO-247 SINGLE LEAD TO-218					
	I <sub>F(/</sub>	AVG)	I <sub>F(</sub> ,	AVG)		I <sub>F(AVG)</sub>			I <sub>F(AVG)</sub>			I,	(AVG)	
VRRM	4A	6A	4A	6A	8A	15A	30A	30A	50A	75A	50A	75A	100A	150A
400V	RHRD440	RHRD640	RHRD440S	RHRD640S	RHRP840	RHRP1540	RHRP3040	RHRG3040	RHRG5040	RHRG7540	RHRU5040	RHRU7540	RHRU10040	RHRU15040
500V	RHRD450	RHRD650	RHRD450S	RHRD650S	RHRP850	RHRP1550	RHRP3050	RHRG3050	RHRG5050	RHRG7550	RHRU5050	RHRU7550	RHRU10050	RHRU15050
600V	RHRD460	RHRD660	RHRD460S	RHRD660S	RHRP860	RHRP1560	RHRP3060	RHRG3060	RHRG5060	RHRG7560	RHRU5060	RHRU7560	RHRU10060	RHRU15060
700V					RHRP870	RHRP1570	RHRP3070	RHRG3070	RHRG5070	RHRG7570	RHRU5070	RHRU7570		
800V					RHRP880	RHRP1580	RHRP3080	RHRG3080	RHRG5080	RHRG7580	RHRU5080	RHRU7580		
900V					RHRP890	RHRP1590	RHRP3090	RHRG3090	RHRG5090	RHRG7590	RHRU5090	RHRU7590		RHRU15090
1000V					RHRP8100	RHRP15100	RHRP30100	RHRG30100	RHRG50100	RHRG75100	RHRU50100	RHRU75100		RHRU150100
1200V	RHRD4120	RHRD6120	RHRD4120S	RHRD6120S	RHRP8120	RHRP15120	RHRP30120	RHRG30120	RHRG50120	RHRG75120	RHRU50120	RHRU75120	RHRU100120	RHRU150120

Selection Guide (continued)

SHADING = FUTURE PRODUCT OFFERINGS

#### HYPERFAST DIODES

## HARRIS RHRD440, RHRD450, RHRD460 SEMICONDUCTOR RHRD440S, RHRD450S, RHRD460S

Package

Symbol

CATHODE (FLANGE)

CATHODE

(FLANGE)

December 1993

#### 4A, 400V - 600V Hyperfast Diodes

ANODE

CATHODE

JEDEC STYLE TO-251 TOP VIEW

JEDEC STYLE TO-252 TOP VIEW

#### Features

- Hyperfast with Soft Recovery......<30ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RHRD440, RHRD450, RHRD460, RHRD440S, RHRD450S, and RHRD460S (TA49055) are hyperfast diodes with soft recovery characteristics ( $t_{RR}$  < 30ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

The RHRD440, RHRD450 and RHRD460 are supplied in the JEDEC style 2 lead TO-251 package and the RHRD440S, RHRD450S and RHRD460S are supplied in the JEDEC style 2 lead TO-252 package.

Due to space limitations, the brand on this part is abbreviated to HR440, HR450 or HR460.

To order this part use the full part number, e.g. RHRD460.

Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RHRD440 RHRD440S	RHRD450 RHRD450S	RHRD460 RHRD460S	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	400	500	600	v
Working Peak Reverse Voltage V <sub>RWM</sub>	400	500	600	v
DC Blocking Voltage V <sub>R</sub>	400	500	600	v
Average Rectified Forward Current $I_{F(AV)}$ (T <sub>C</sub> = +157°C)	4	4	4	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	8	8	8	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	40	40	40	A
Maximum Power DissipationPD	50	50	50	w
Avalanche Energy (L = 40mH)	10	10	10	mj
Operating and Storage Temperature	-65 to +175	-65 to +175	-65 to +175	°C

HYPERFAST DIODES

							LIMITS					
	т		RHRD440 RHRD440S			RHRD450 RHRD450S			RHRD460 RHRD460S			
SYMBOL	CONDITION		MIN	TYP	MAX	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 4A	T <sub>C</sub> = +25°C	-	-	2.1	-	-	2.1	-	-	2.1	۷
V <sub>F</sub>	I <sub>F</sub> = 4A	T <sub>C</sub> = +150°C	-	-	1.7	-	-	1.7	-	-	1.7	V
I <sub>R</sub>	V <sub>R</sub> = 400V	T <sub>C</sub> = +25°C	•	•	5	-	•	•	-	-	•	μA
	V <sub>R</sub> = 500V	T <sub>C</sub> = +25°C	-	-	-	•	-	5	-	-	-	μA
	V <sub>R</sub> = 600V	T <sub>C</sub> = +25°C	-	-	-	-	-	-		-	5	μA
IR	V <sub>R</sub> = 400V	T <sub>C</sub> = +150°C	-	-	250	-	-	-	-	-	-	μΑ
	V <sub>R</sub> = 500V	T <sub>C</sub> = +150°C	-	-	-	-	•	250	-	-	-	μA
	V <sub>R</sub> = 600V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	250	μΑ
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /d	t = 100A/µs	-	-	30	-	-	30	-	-	30	ns
	I <sub>F</sub> = 4A, dI <sub>F</sub> /d	t = 100A/μs	-	-	35	-	-	35	•	-	35	ns
t <sub>A</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /d	t = 100A/µs	-	19	-	-	19	-	-	19	-	ns
t <sub>B</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /d	t = 100A/µs	•	11	-	•	11	-	-	11	-	ns
Q <sub>RR</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /d	t = 100A/µs	•	15	-		15			15		nC
CJ	V <sub>R</sub> = 10V, I <sub>F</sub> :	= 0A	-	15	-		15			15		pf
R <sub>eJC</sub>			•	-	3	•	-	3	•	- 1	3	°C/W

Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

t<sub>RR</sub> = Reverse recovery time (See Figure 2), summation of t<sub>A</sub> + t<sub>B</sub>.

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

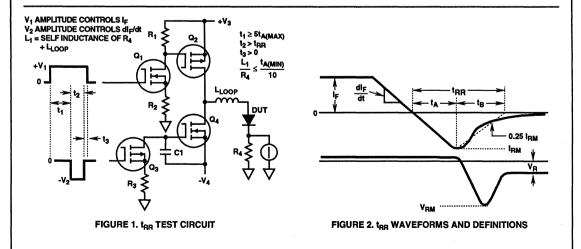
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

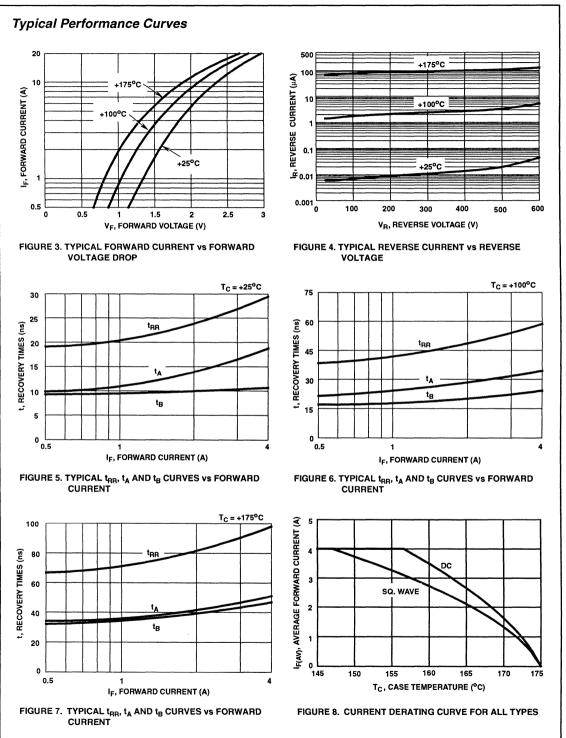
R<sub>OJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 9 and 10).

pw = pulse width.

D = duty cycle.

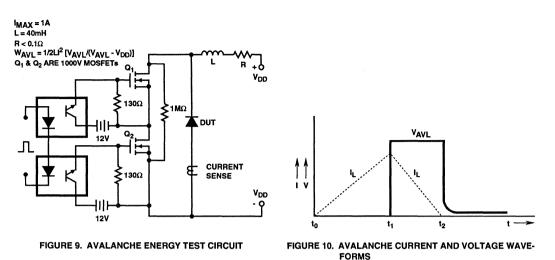




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HYPERFAST DIODES

#### RHRD440, RHRD450, RHRD460, RHRD440S, RHRD450S, RHRD460S





### *RHRD4120 RHRD4120S*

#### 4A, 1200V Hyperfast Diodes

ANODE

> ANODE

> CATHODE

JEDEC STYLE TO-251 TOP VIEW

JEDEC STYLE TO-252

TOP VIEW

December 1993

#### Features

- Hyperfast with Soft Recovery......<60ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RHRD4120 and RHRD4120S (TA49056) are hyperfast diodes with soft recovery characteristics ( $t_{RR} < 60$ ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

The RHRD4120 is supplied in the JEDEC style 2 lead TO-251 package and the RHRD4120S is supplied in the JEDEC style 2 lead TO-252 package.

Due to space limitations, the brand on this part is abbreviated to H4120.

To order this part use the full part number, e.g. RHRD4120.

#### Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RHRD4120 RHRD4120S	UNITS
Peak Repetitive Reverse Voltage	1200	v
Working Peak Reverse VoltageV <sub>RWM</sub>	1200	v
DC Blocking Voltage	1200	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>c</sub> = +147.5°C)	4	Α
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	8	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	40	Α
Maximum Power Dissipation	50	w
Avalanche Energy (L = 40mH)	10	mj
Operating and Storage Temperature	-65 to +175	°C

Package

Symbol

CATHODE (FLANGE)

> CATHODE (FLANGE)



HYPERFAST DIODES

#### Specifications RHRD4120, RHRD4120S

		RHF	RHRD4120, RHRD4120S				
SYMBOL	TEST CONDITION	MIN	ТҮР	МАХ	UNITS		
V <sub>F</sub>	I <sub>F</sub> = 4A, T <sub>C</sub> = +25°C	- T	-	3.2	v		
V <sub>F</sub>	$I_F = 4A, T_C = +150^{\circ}C$	-	-	2.6	v		
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +25°C	-	-	10	μΑ		
I <sub>R</sub>	V <sub>R</sub> = 1200V, T <sub>C</sub> = +150°C	-	-	250	μΑ		
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	-	-	60	ns		
	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	-	85	ns		
t <sub>A</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	50	-	ns		
t <sub>B</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	30	-	ns		
Q <sub>RR</sub>	I <sub>F</sub> = 4A, dI <sub>F</sub> /dt = 100A/μs	-	120	-	nC		
Cj	V <sub>R</sub> = 10V, I <sub>F</sub> = 0A	•	15	-	pF		
R <sub>eJC</sub>		-		3	°C/W		

#### Electrical Specifications T<sub>C</sub> = +25°C, Unless Otherwise Specified

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BB}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

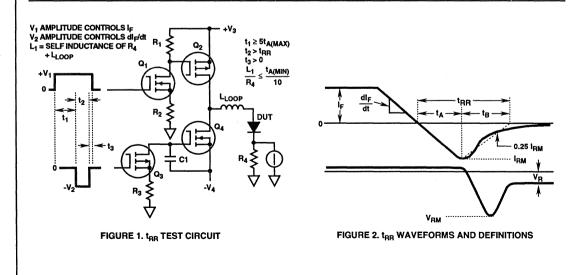
 $t_{B}$  = Time from peak  $I_{BM}$  to projected zero crossing of  $I_{BM}$  based on a straight line from peak  $I_{BM}$  through 25% of  $I_{BM}$  (See Figure 2).

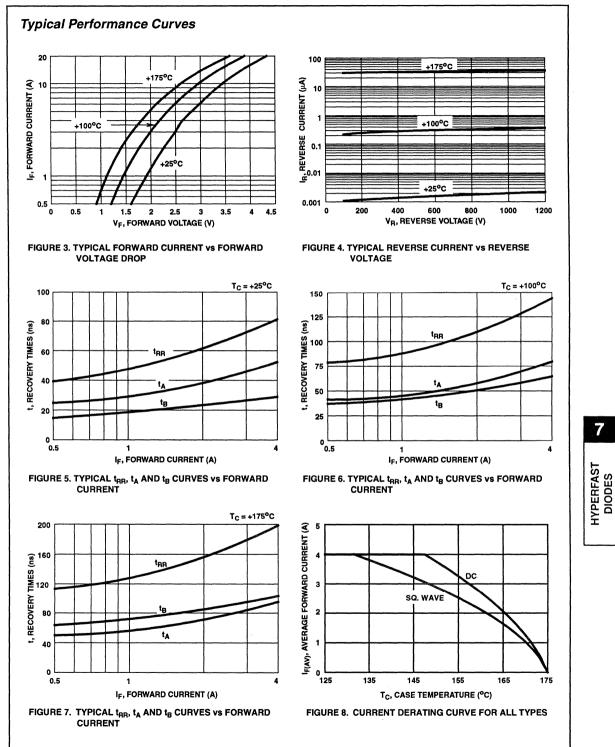
R<sub>eJC</sub> = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 9 and 10).

pw = pulse width.

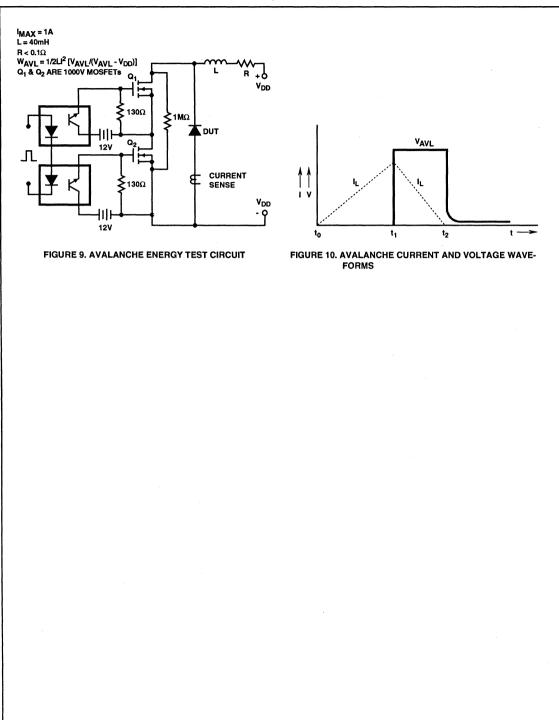
D = duty cycle.





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#### RHRD4120, RHRD4120S





## RHRG30120

#### 30A, 1200V Hyperfast Diode

ANODE

CATHODE

JEDEC STYLE 2 LEAD TO-247 TOP VIEW

December 1993

#### Features

- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

The RHRG30120 (TA49041) is a hyperfast diode with soft recovery characteristics ( $t_{RR} < 65$ ns). It has half the recovery time of ultrafast diodes and is silicon nitride passivated ion-implanted epitaxial planar construction.

This device is intended for use as a freewheeling/clamping diode and rectifier in a variety of high frequency switching power supplies and other power switching applications. Its low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

The RHRG30120 is supplied in the JEDEC style two lead, TO-247 package.

Due to space limitations, the brand on this part is abbreviated to RH30120.

To order this part use the full part number, i.e. RHRG30120.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RHRG30120	UNITS
Peak Repetitive Reverse Voltage	1200	v
Working Peak Reverse Voltage	1200	v
DC Blocking VoltageV <sub>R</sub>	1200	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>C</sub> = +78°C)	30	A
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	60	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1Phase, 60Hz)	300	A
Maximum Power Dissipation	125	W
Avalanche Energy	30	mj
Operating and Storage TemperatureT <sub>STG</sub> ,T <sub>J</sub>	-65 to +175	°C

Package

CATHODE (BOTTOM SIDE

METAL)

Symbol

HYPERFAST

DIODES

#### Specifications RHRG30120

				LIMITS					
SYMBOL	TE	ST CONDITION	MIN	ТҮР	МАХ	UNITS			
V <sub>F</sub>	I <sub>F</sub> = 30A		-	-	3.2	l v			
٧ <sub>F</sub>	I <sub>F</sub> = 30A	T <sub>C</sub> = +150°C	-	-	2.6				
I <sub>R</sub>	V <sub>R</sub> = 1200V		-	-	100	μA			
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	1	mA			
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	65				
t <sub>RR</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/µs	-	-	75				
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/µs	-	48	-	ns			
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/µs	-	22	-	]			
R <sub>NC</sub>	1		-	-	1.2	°C/W			

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BB}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



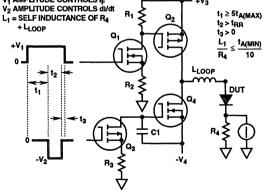
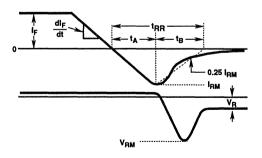
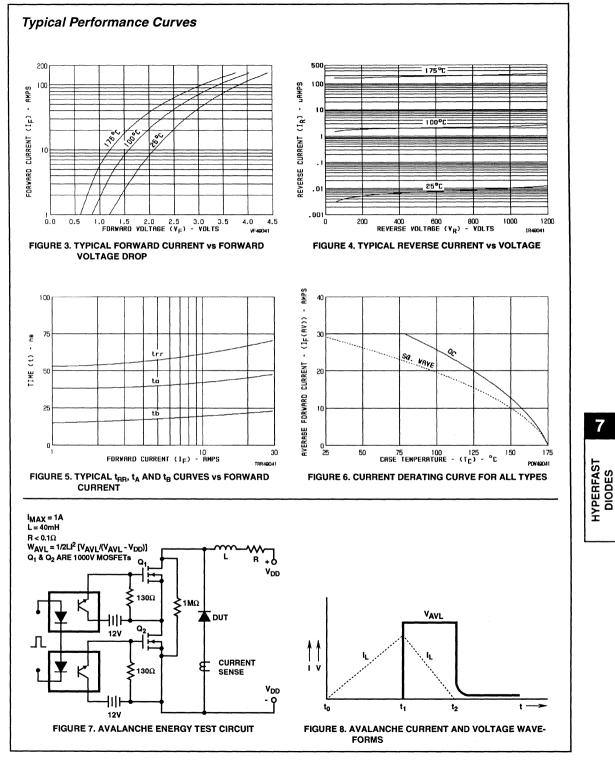


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





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## RHRP30120

#### December 1993

Features

#### 30A, 1200V Hyperfast Diode

	r uonugo
Hyperfast with Soft Recovery<65ns	JEDEC TO-220AC TOP VIEW
Operating Temperature+175°C	
Reverse Voltage1200V	
Avalanche Energy Rated	(FLANGE) ANODE
Planar Construction	
Applications	
Switching Power Supplies	
Power Switching Circuits	-
General Purpose	Symbol
Description	к 
The RHRP30120 (TA49041) is a hyperfast diode with soft recovery characteristics ( $t_{\rm RR}$ < 65ns).It has half the recovery time of ultrafast diodes and is silicon nitride passivated ion-implanted epitaxial planar construction.	
This device is intended for use as a freewheeling/clamping diode and rectifier in a variety of high frequency switching power supplies and other power switching applications. Its low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.	
The RHRP30120 is supplied in the JEDEC two lead, TO-220 package.	
Due to space limitations, the brand on this part is abbreviated to H30120.	
To order this part use the full part number, i.e. RHRP30120.	
Absolute Maximum Ratings (T <sub>c</sub> = +25°C)	
	RHRP30120 UNITS
Peak Repetitive Reverse Voltage	
DC Blocking Voltage	
Average Rectified Forward Current	
(T <sub>C</sub> = +78°C)	
Repetitive Peak Surge Current	I <sub>FSM</sub> 60 A
(Square Wave, 20kHz) Nonrepetitive Peak Surge Current	
(Halfwave, 1 Phase, 60Hz)	
Maximum Power Dissipation	-
Avalanche Energy (L = 40mH)	
Operating and Storage Temperature	۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰

| Package

#### Specifications RHRP30120

				LIMITS							
SYMBOL	TEST CONDITION		MIN	ТҮР	МАХ	UNITS					
V <sub>F</sub>	I <sub>F</sub> = 30A		-	-	3.2	v					
V <sub>F</sub>	I <sub>F</sub> = 30A	T <sub>C</sub> = +150°C	-	-	2.6	v					
IR	V <sub>R</sub> = 1200V		I <sub>R</sub> V <sub>R</sub> = 1200V	V <sub>R</sub> = 1200V	V <sub>R</sub> = 1200V	= 1200V	V <sub>R</sub> = 1200V -	-	-	100	μА
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	1	mA					
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	65	ns					
t <sub>RR</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/μs	-	-	75	ns					
t <sub>A</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00 <b>Α</b> /μs	-	48	-	ns					
t <sub>B</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/µs	-	22	-	ns					
R <sub>NC</sub>			-	-	1.2	°C/W					

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300 µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

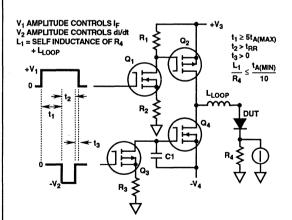
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

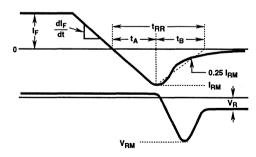
W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

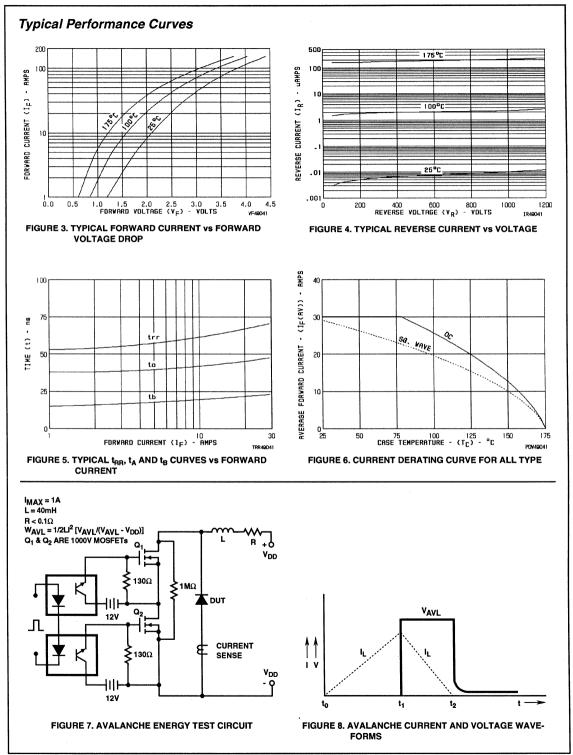
pw = pulse width.

D = duty cycle.











December 1993

### RHRG5070, RHRG5080 RHRG5090, RHRG50100

#### 50A, 700V - 1000V Hyperfast Diodes

Features Package JEDEC STYLE 2 LEAD TO-247 TOP VIEW Operating Temperature .....+175°C CATHODE (BOTTOM SIDE METAL) ANODE Avalanche Energy Rated Planar Construction CATHODE Applications Switching Power Supplies • Power Switching Circuits Symbol General Purpose Description RHRG5070, RHRG5080, RHRG5090 and RHRG50100 (TA49066) are hyperfast diodes with soft recovery characteristics (t<sub>BB</sub> < 75ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ionimplanted epitaxial planar construction. These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors. All devices supplied in the JEDEC style two lead TO-247 package. Due to space limitations, the brand on the RHRG50100 part is abbreviated to HRG50100. To order this part use the full part number, i.e. RHRG50100.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RHRG5070	RHRG5080	RHRG5090	RHRG50100
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	700V	800V	900V	1000V
Working Peak Reverse VoltageV <sub>RWM</sub>	700V	800V	900V	1000V
DC Blocking VoltageV <sub>R</sub>	700V	800V	900V	1000V
Average Rectified Forward Current $I_{F(AV)}$ (T <sub>c</sub> = +60°C)	50A	50A	50A	50A
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	100A	100A	100 <b>A</b>	100A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	500A	500A	500A	500A
Maximum Power DissipationPo	150W	150W	150W	150W
Avalanche Energy W <sub>AVL</sub> (L = 40mH)	40mj	40mj	40mj	40mj
Operating and Storage Temp T <sub>st6</sub> ,T <sub>J</sub>	-65°C to+175°C	-65°C to+175°C	-65°C to+175°C	-65°C to+175°C

HYPERFASI DIODES

#### Specifications RHRG5070, RHRG5080, RHRG5090, RHRG50100

	TEST		TECT			5070 L	IMITS	RHRC	35080 L	IMITS	RHRG5090 LIMITS			RHRG50100 LIMITS			
SYMBOL			MIN TYP	MAX	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	MAX	UNITS			
VF	l <sub>F</sub> = 50A		-	-	3.0	-	-	3.0	-	-	3.0	-	-	3.0	v		
VF	l <sub>F</sub> = 50A	T <sub>C</sub> = +150°C	-	-	2.5	-	-	2.5	-	-	2.5	-	-	2.5	۷		
I <sub>R</sub>	V <sub>R</sub> = 700V		-	-	250	-	-	-		-	-	-	-	-	μA		
	V <sub>R</sub> = 800V V <sub>R</sub> = 900V V <sub>R</sub> = 1000V		-	-	-	-	-	250	-	-	-	-	-	-	μΑ		
			•.	-	-	-	-	-	-	-	250	-	-	-	μA		
			-	-	-	-	-	-	-	-	-	-	-	250	μΑ		
I <sub>R</sub>	V <sub>R</sub> = 700V	T <sub>C</sub> = +150°C	-	-	3.0	-	-	-	-	-	-	-	-	3.0	mA		
	V <sub>R</sub> = 800V	T <sub>C</sub> = +150°C	-	-	-	-	-	3.0	-	-	-	-	-	-	mA		
	V <sub>R</sub> = 900V	T <sub>C</sub> = +150°C	-		-	-	-	-	-	-	3.0	-	-	-	mA		
	V <sub>R</sub> = 1000V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	-	-	-	3.0	mA		
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /d	t = 100A/µs	-	-	75	-	-	75	-	-	75	-	-	75	ns		
t <sub>RR</sub>	I <sub>F</sub> = 50A, dI <sub>F</sub> /	/dt = 100A/μs	-	-	95	-	-	95	-	-	95	-	-	95	ns		
t <sub>A</sub>	l <sub>F</sub> = 50A, dl <sub>F</sub> /	/dt = 100A/μs	-	54	-	-	54	-	-	54	-	-	54	-	ns		
t <sub>B</sub>	l <sub>F</sub> = 50A, dl <sub>F</sub> /	/dt = 100A/μs	-	32	-	-	32	-	-	32	-	-	32	-	ns		
R <sub>eJC</sub>			-	-	1.0		-	1.0	-	-	1.0	-	-	1.0	°C/M		

#### - - --

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300 µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

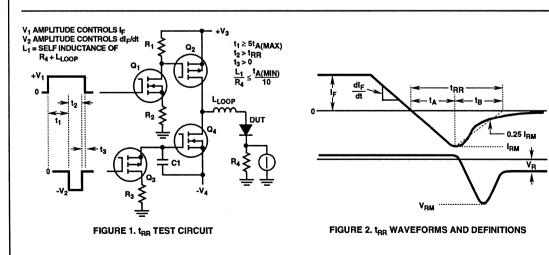
t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

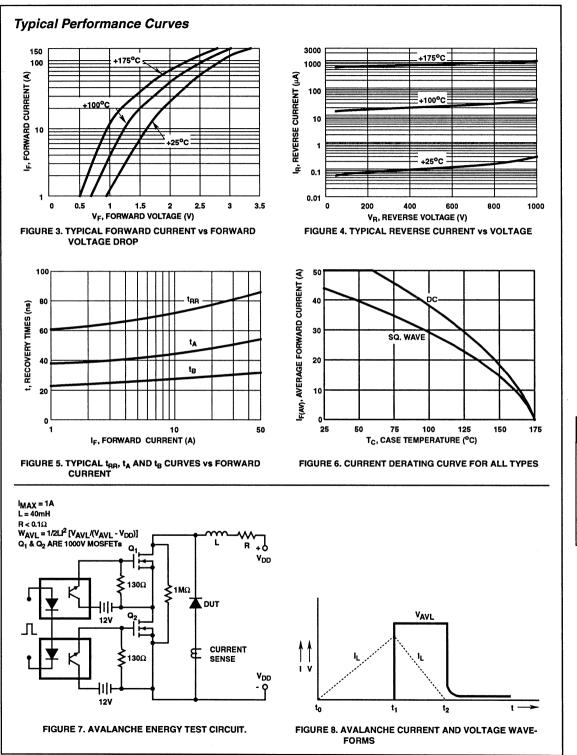
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.





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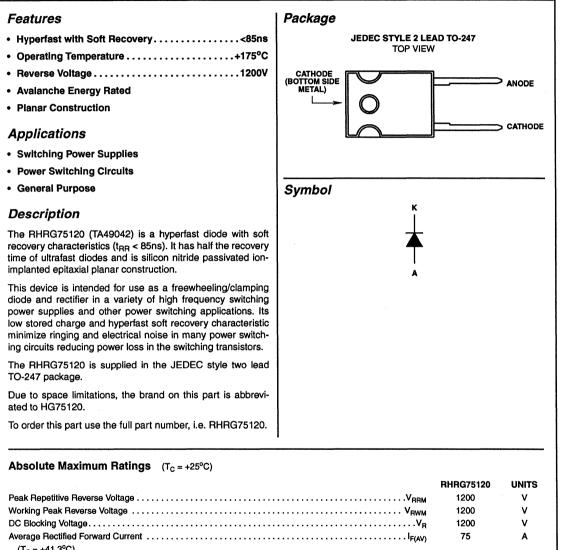
HYPERFAST DIODES



## RHRG75120

#### December 1993

#### 75A, 1200V Hyperfast Diode



$(T_{c} = +41.3^{\circ}C)$			
Repetitive Peak Surge Current I <sub>FSM</sub>	150	Α	
(Square Wave, 20kHz)			
Nonrepetitive Peak Surge Current I <sub>FSM</sub>	500	Α	
(Halfwave, 1 Phase, 60Hz)			
Maximum Power Dissipation	190	w	
Avalanche Energy	50	mj	
(L = 40mH)			
Operating and Storage Temperature	-65 to +175	°C	

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#### Specifications RHRG75120

				LIMITS						
SYMBOL	ТЕ	TEST CONDITION		ТҮР	МАХ	UNITS				
V <sub>F</sub>	/ <sub>F</sub>		-	-	3.2	v				
V <sub>F</sub>	I <sub>F</sub> = 75A	T <sub>C</sub> = +150°C	-	-	2.6	v				
I <sub>R</sub>	V <sub>R</sub> = 1200V		-	-	250	μА				
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	2	mA				
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/µs	-	-	85	ns				
t <sub>RR</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 1	00A/µs	-	-	100	ns				
t <sub>A</sub>	l <sub>F</sub> = 75A, dl <sub>F</sub> /dt = 1	00A/µs	-	60	-	ns				
t <sub>B</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 1	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 100A/μs		25	-	ns				
R <sub>NC</sub>			-	-	0.8	°C/W				

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

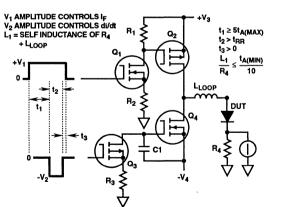
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

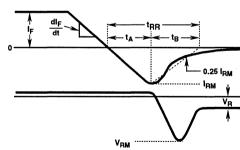
 $R_{\Theta JC}$  = Thermal resistance junction to case.

WAVL = Controlled avalanche energy (See Figures 7 and 8).

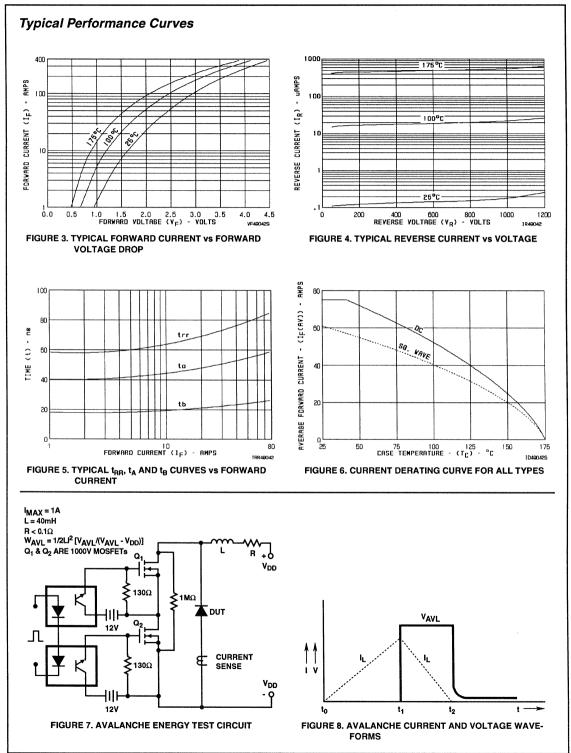
pw = pulse width.

D = duty cycle.





#### FIGURE 1. t<sub>RR</sub> TEST CIRCUIT





December 1993

## RHRU75120

#### 75A, 1200V Hyperfast Diode

Package Features JEDEC STYLE SINGLE LEAD TO-218 TOP VIEW Operating Temperature .....+175°C CATHODE (FLANGE) Avalanche Energy Rated ANODE • Planar Construction Applications Switching Power Supplies • Power Switching Circuits Symbol General Purpose Description The RHRU75120 (TA49042) is a hyperfast diode with soft recovery characteristics ( $t_{BB}$  < 85ns). It has half the recovery time of ultrafast diodes and is silicon nitride passivated ionimplanted epitaxial planar construction. This device is intended for use as a freewheeling/clamping diode and rectifier in a variety of high frequency switching power supplies and other power switching applications. Its low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors. The RHRU75120 is supplied in the JEDEC style single lead TO-218 package. Due to space limitations, the brand on this part is abbreviated to HU75120. To order this part use the full part number, i.e. RHRU75120. Absolute Maximum Ratings (T<sub>c</sub> = +25°C) 

	RHRU75120	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	1200	v
Working Peak Reverse VoltageV <sub>RWM</sub>	1200	v
DC Blocking Voltage	1200	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>C</sub> = +46°C)	75	Α
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	150	Α
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1Phase, 60Hz)	500	Α
Maximum Power Dissipation	190	w
Avalanche Energy	50	mj
Operating and Storage Temperature	-65 to +175	°C

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HYPERFAST DIODES

#### Specifications RHRU75120

SYMBOL	TEST CONDITION		MIN	ТҮР	МАХ	UNITS V
V <sub>F</sub>	l <sub>F</sub> = 75A	I <sub>F</sub> = 75A		-	3.2	
V <sub>F</sub>	I <sub>F</sub> = 75A	T <sub>C</sub> = +150°C	-	-	2.6	v
I <sub>R</sub>	V <sub>R</sub> = 1200V		-	-	250	μA
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	2	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	85	ns
t <sub>RR</sub>	l <sub>F</sub> = 75A, dl <sub>F</sub> /dt = 1	00A/µs	-	-	100	ns
t <sub>A</sub>	l <sub>F</sub> = 75A, dl <sub>F</sub> /dt = 1	00A/µs	-	60	-	ns
t <sub>B</sub>	I <sub>F</sub> = 75A, dI <sub>F</sub> /dt = 1	00A/µs	-	25	•	ns
R <sub>eJC</sub>			-	-	0.8	°C/W

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current at (See Figure 2).

 $t_B$  = Time from peak  $I_{RM}$  to projected zero crossing of  $I_{RM}$  based on a straight line from peak  $I_{RM}$  through 25% of  $I_{RM}$  (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.

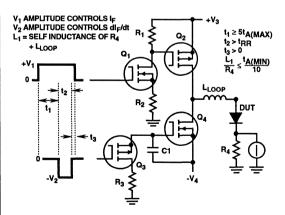
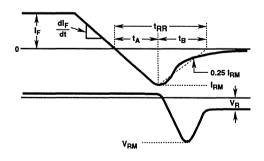
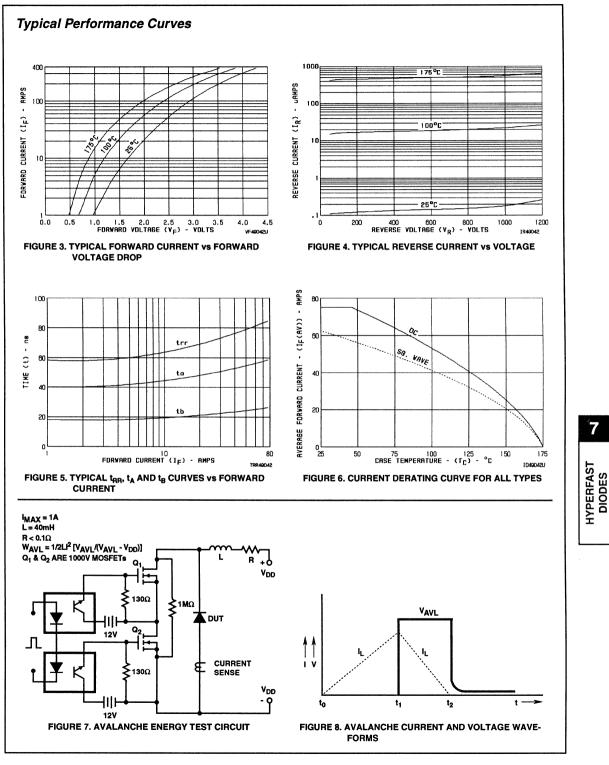


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT







### **RHRU10040** RHRU10050, RHRU10060

#### 100A, 400V - 600V Hyperfast Diodes

## Package JEDEC STYLE SINGLE LEAD TO-218 TOP VIEW CATHODE (FLANGE) ANODE Symbol

December 1993

#### Features

- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RHRU10040, RHRU10050 and RHRU10060 (TA49069) are hyperfast diodes with soft recovery characteristics (t<sub>BB</sub> < 50ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

All devices are supplied in the JEDEC style single lead TO-218 package.

Due to space limitations, the brand on this part is abbreviated to HRU10040, HRU10050 or HRU10060.

To order this part use the full part number, e.g. RHRU10040.

#### Absolute Maximum Ratings $(T_c = +25^{\circ}C)$

	RHRU10040	RHRU10050	RHRU10060	UNITS
Peak Repetitive Reverse VoltageV <sub>BRM</sub>	400	500	600	v
Working Peak Reverse Voltage V <sub>RWM</sub>	400	500	600	v
DC Blocking Voltage	400	500	600	v
Average Rectified Forward Current $\dots I_{F(AV)}$ (T <sub>c</sub> = +60.8°C)	100	100	100	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	200	200	200	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	1000	1000	1000	A
Maximum Power DissipationPp	210	210	210	w
Avalanche EnergyW <sub>AVL</sub> (L = 40mH)	50	50	50	mj
Operating and Storage Temperature $\dots \dots T_{STG}, T_J$	-65 to +175	-65 to +175	-65 to +175	°C

#### Specifications RHRU10040, RHRU10050, RHRU10060

	TEST		RHRU10040 LIMITS			RHRU10050 LIMITS			RHRU10060 LIMITS			
SYMBOL	CONDITION		MIN	ТҮР	МАХ	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 100A		-	-	2.1	-	-	2.1	-	-	2.1	v
VF	I <sub>F</sub> = 100A	T <sub>C</sub> = +150°C	-	-	1.7	•	-	1.7	-	-	1.7	v
1 <sub>R</sub>	V <sub>R</sub> = 400V		-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V		-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 600V		-	-	-	-	-	-	-	-	250	μA
IR	V <sub>R</sub> = 400V	T <sub>C</sub> = +150°C	-	-	2.0	-	-	-	-	-	-	mA
	V <sub>R</sub> = 500V	T <sub>C</sub> = +150°C	-	-	-	•	-	2.0	-	-	-	mA
	V <sub>R</sub> = 600V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	2.0	mA
t <sub>RR</sub>	l <sub>F</sub> = 1A, dl <sub>F</sub> /d	t = 100A/μs	-	-	50	-	-	50	-	-	50	ns
t <sub>RR</sub>	l <sub>F</sub> = 100A, dl	<sub>F</sub> /dt = 100A/µs	-	-	60	•	-	60	-	-	60	ns
t <sub>A</sub>	l <sub>F</sub> = 100A, dl	<sub>F</sub> /dt = 100A/µs	-	28	-	-	28	•	-	28	-	ns
t <sub>B</sub>	l <sub>F</sub> = 100A, dl	<sub>F</sub> /dt = 100A/µs	-	18	-	•	18	-	•	18		ns
R <sub>eJC</sub>			-	-	0.71	-	-	0.71		-	0.71	°C/W

#### . ... .

DEFINITIONS

 $V_{\rm F}$  = Instantaneous forward voltage (pw = 300 \mu s, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BB}$  = Reverse recovery time (See Figure 2), summation of  $t_{A} + t_{B}$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

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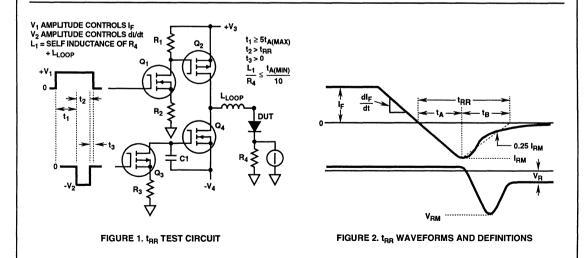
HYPERFAST DIODES

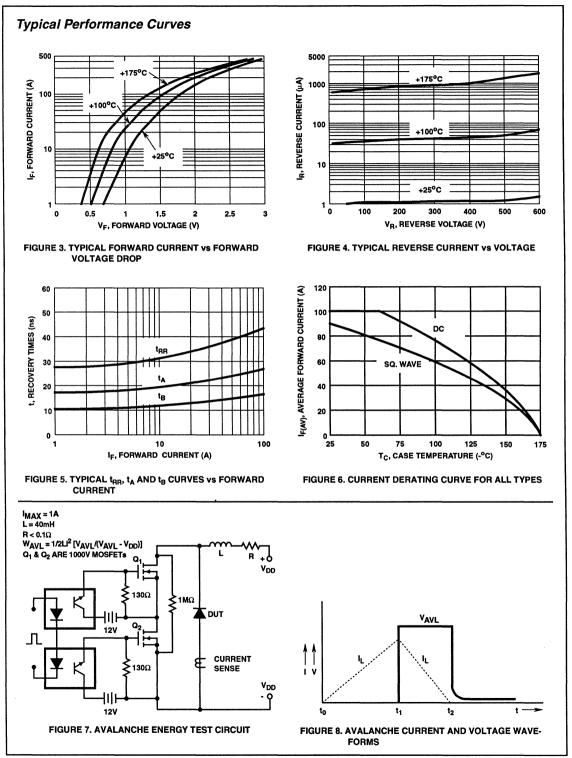
 $R_{\Theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



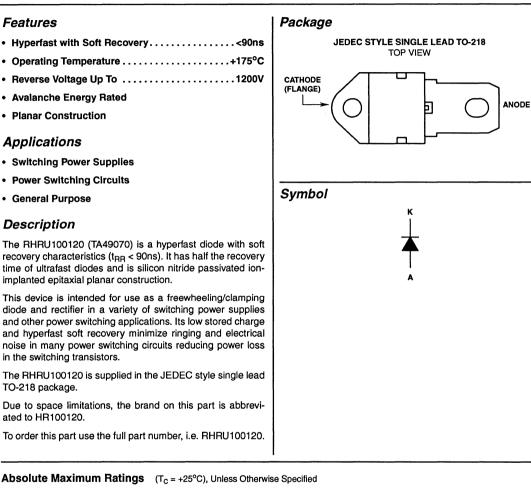




## RHRU100120

#### December 1993

#### 100A, 1200V Hyperfast Diode



	RHRU100120	UNITS
Peak Repetitive Reverse Voltage	1200	v
Working Peak Reverse VoltageV <sub>RWM</sub>	1200	ν
DC Blocking Voltage	1200	v
Average Rectified Forward Current	100	A
Repetitive Peak Surge Current I <sub>FSM</sub> (Square Wave, 20kHz)	200	A
Nonrepetitive Peak Surge Current I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	1000	A
Maximum Power Dissipation	300	W
Avalanche Energy (L = 40mH) W <sub>AVL</sub>	50	mj
Operating and Storage Temperature	-65 to +175	°C



#### Specifications RHRU100120

				LIMITS				
SYMBOL	TEST CONDITION		MIN	ТҮР	МАХ	UNITS		
V <sub>F</sub>	i <sub>F</sub> = 100A	T <sub>C</sub> = +25°C	-	-	3.2	v		
V <sub>F</sub>	I <sub>F</sub> = 100A	T <sub>C</sub> = +150°C	-	-	2.6	v		
I <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +25°C	-	-	250	μA		
l <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	2	mA		
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100	)A/µs	-	-	90	ns		
	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt = 1	100A/µs	-	-	100	ns		
t <sub>A</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt =	l <sub>F</sub> = 100A, dl <sub>F</sub> /dt = 100A/μs		60	-	ns		
t <sub>B</sub>	I <sub>F</sub> = 100A, dI <sub>F</sub> /dt = 100A/µs		-	25	-	ns		
R <sub>eJC</sub>			· ·	-	0.5	°C/W		

DEFINITIONS

 $V_F$  = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

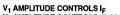
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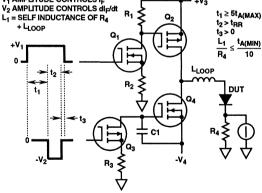
 $R_{\Theta JC}$  = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

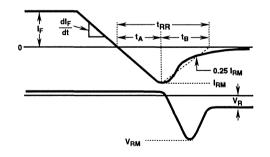
pw = pulse width.

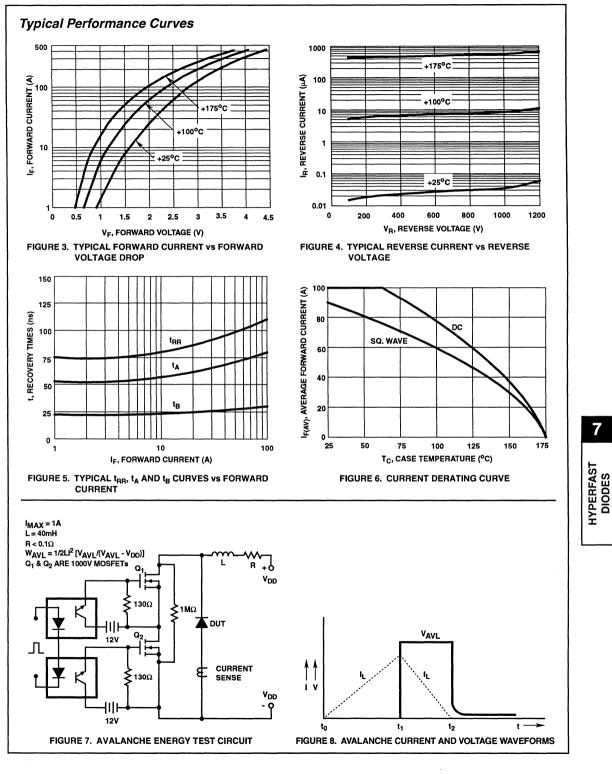
D = duty cycle.













### RHRU15040 RHRU15050, RHRU15060

#### December 1993

#### 150A, 400V - 600V Hyperfast Diodes

Features	Package
	JEDEC STYLE SINGLE LEAD TO-218
Hyperfast with Soft Recovery	TOP VIEW
Operating Temperature+175°C	
Reverse Voltage up to600V	CATHODE (FLANGE)
Avalanche Energy Rated	
Planar Construction	
Applications	
Switching Power Supplies	
Power Switching Circuits	
General Purpose	Symbol ĸ
Description	
RHRU15040, RHRU15050 and RHRU15060 (TA49071) are hyperfast diodes with soft recovery characteristics (t <sub>RR</sub> < 60ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ion-implanted epitaxial planar construction.	
These devices are intended for use as freewheeling/clamp- ing diodes and rectifiers in a variety of switching power sup- plies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reduc- ing power loss in the switching transistors.	
All devices supplied in the JEDEC style single lead TO-218 package.	
Due to space limitations, the brand on this part is abbrevi- ated to RHR15040, RHR15050, or RHR15060.	
To order this part use the full part number, e.g. RHRU15040.	
Absolute Maximum Ratings (T <sub>c</sub> = +25°C)	
	RHRU15040 RHRU15050 RHRU15060
Peak Repetitive Reverse VoltageVr	
Working Peak Reverse VoltageV <sub>F</sub>	
DC Blocking Voltage	
Average Rectified Forward CurrentI <sub>F</sub> (T <sub>C</sub> = +72°C)	<sub>AV)</sub> 150A 150A 150A
Repetitive Peak Surge Current I (Square Wave, 20kHz)	
Nonrepetitive Peak Surge Current I (Halfwave, 1 Phase, 60Hz)	<sub>ESM</sub> 1500A 1500A 1500A
Maximum Power Dissipation	P <sub>D</sub> 375W 375W 375W

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(L = 40 mH)

50mi

-65°C to +175°C

50mj

50mi

-65°C to +175°C

#### Specifications RHRU15040, RHRU15050, RHRU15060

	TEST		RHRU15040 LIMITS		RHRU15050 LIMITS			RHRU15060 LIMITS				
SYMBOL		DITION	MIN	ТҮР	MAX	MIN	ТҮР	МАХ	MIN	ТҮР	МАХ	UNITS
V <sub>F</sub>	I <sub>F</sub> = 150A		-	-	2.1	-	-	2.1	-	-	2.1	v
V <sub>F</sub>	l <sub>F</sub> = 150A	T <sub>C</sub> = +150°C	-	-	1.6		-	1.6	-	-	1.6	v
I <sub>R</sub>	V <sub>R</sub> = 400V		-	-	250	-	-	-	-	-	-	μA
	V <sub>R</sub> = 500V		-	-	-	-	-	250	-	-	-	μA
	V <sub>R</sub> = 600V		-	-	-	-	-	-	-	-	250	μA
I <sub>R</sub>	V <sub>R</sub> = 400V	T <sub>C</sub> = +150°C	-	-	2.0	-	-	-	-	-	-	mA
	V <sub>R</sub> = 500V	T <sub>C</sub> = +150°C	-	-	-		-	2.0	-	-		mA
	V <sub>R</sub> = 600V	T <sub>C</sub> = +150°C	-	-	-	-	-	-	-	-	2.0	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /d	t = 100A/µs	-	-	60	-	-	60	-	-	60	ns
t <sub>RR</sub>	l <sub>F</sub> = 150A, dl	₌/dt = 100A/μs	-	-	70	-	-	70	-	-	70	ns
t <sub>A</sub>	l <sub>F</sub> = 150A, dl	⊑/dt = 100A/μs	-	43	-	-	43	-	-	43	-	ns
t <sub>B</sub>	I <sub>F</sub> = 150A, dl	₌/dt = 100A/μs	-	20	-	-	20	-	-	20	-	ns
R <sub>eJC</sub>			-	-	0.4	-	-	0.4	-	-	0.4	°C/W

#### . ... . . . .

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_{A} + t_{B}$ .

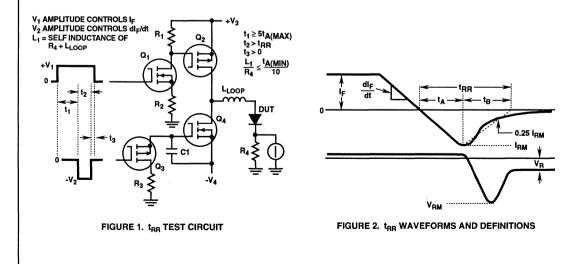
t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

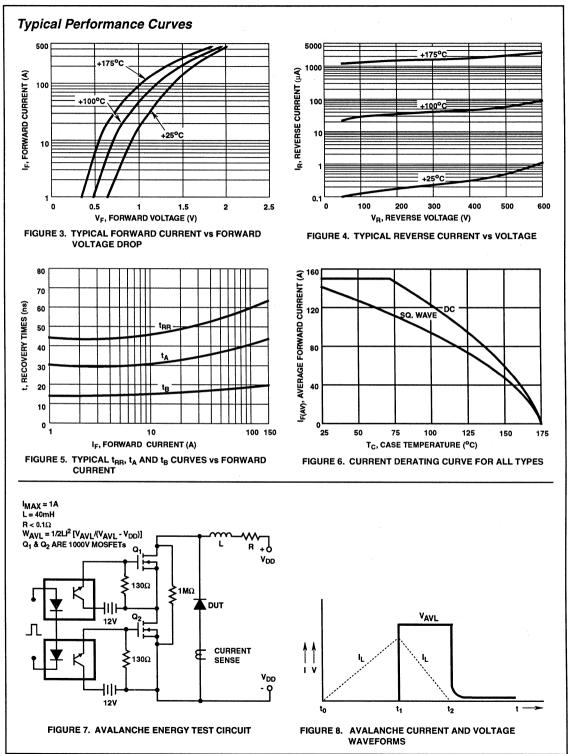
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\theta JC}$  = Thermal resistance junction to case.

pw = pulse width.

D = duty cycle.







### RHRU15090 RHRU150100

December 1993

#### Features

- Operating Temperature .....+175°C
- Reverse Voltage Up To .....1000V
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

RHRU15090 and RHRU150100 (TA49072) are hyperfast diodes with soft recovery characteristics ( $t_{\rm RR}$  < 90ns). They have half the recovery time of ultrafast diodes and are silicon nitride passivated ion-implanted epitaxial planar construction.

These devices are intended for use as freewheeling/clamping diodes and rectifiers in a variety of switching power supplies and other power switching applications. Their low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits reducing power loss in the switching transistors.

All devices supplied in the JEDEC style single lead TO-218 package.

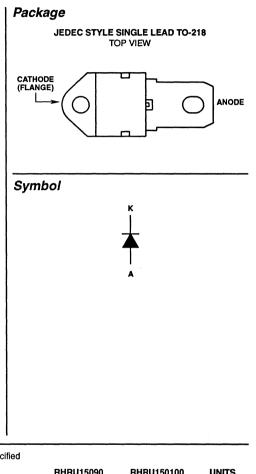
Due to space limitations, the brand on this part is abbreviated to RHR15090 or HR150100.

To order this part use the full part number, e.g. RHRU150100

Absolute Maximum Ratings (T<sub>C</sub> = +25°C), Unless Otherwise Specified

	RHRU15090	RHRU150100	UNITS
Peak Repetitive Reverse VoltageV <sub>RRM</sub>	900	1000	v
Working Peak Reverse Voltage V <sub>RWM</sub>	900	1000	v
DC Blocking VoltageV <sub>B</sub>	900	1000	v
Average Rectified Forward Current I <sub>F(AV)</sub> (T <sub>C</sub> = +42°C)	150	150	A
Repetitive Peak Surge CurrentI <sub>FSM</sub> (Square Wave, 20kHz)	300	300	A
Nonrepetitive Peak Surge CurrentI <sub>FSM</sub> (Halfwave, 1 phase, 60Hz)	1500	1500	A
Maximum Power DissipationPD	375	375	w
Avalanche Energy (L = 40mH) W <sub>AVL</sub>	50	50	mj
Operating and Storage Temperature	-65 to +175	-65 to +175	°Ċ





#### Specifications RHRU15090, RHRU150100

				LIM	ITS			[
			RHRU1509	0	F	HRU15010	0	1
SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
V <sub>F</sub>	I <sub>F</sub> = 150A, T <sub>C</sub> = +25°C	-	-	3.0	-	-	3.0	v
VF	I <sub>F</sub> = 150A, T <sub>C</sub> = +150°C	-	-	2.5	-	-	2.5	v
I <sub>R</sub>	V <sub>R</sub> = 900V, T <sub>C</sub> = +25°C	-	-	250	-	-	-	μA
	V <sub>R</sub> = 1000V, T <sub>C</sub> = +25°C	- 1	•	-	-	-	250	μΑ
I <sub>R</sub>	V <sub>R</sub> = 900V, T <sub>C</sub> = +150°C	-	•	3.0	•	•	-	mA
	$V_{\rm R} = 1000V, T_{\rm C} = +150^{\circ}{\rm C}$	-	-	-	-	-	3.0	mA
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 100A/μs	- I	•	90	-	-	90	ns
	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/μs	-	-	100	-	-	100	ns
t <sub>A</sub>	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/μs	-	65	-	-	65	-	ns
t <sub>B</sub>	I <sub>F</sub> = 150A, dI <sub>F</sub> /dt = 100A/μs	· ·	30	-	-	30	-	ns
Rejc		- 1	-	0.4	-	-	0.4	°C/W

DEFINITIONS

 $V_{\rm F}$  = Instantaneous forward voltage (pw = 300 \mu s, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{BB}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

t<sub>A</sub> = Time to reach peak reverse current (See Figure 2).

t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

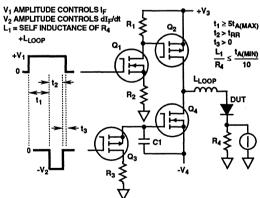
R<sub>OJC</sub> = Thermal resistance junction to case.

W<sub>AVL</sub> = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.





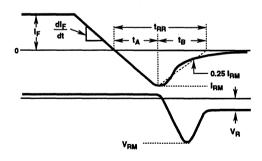
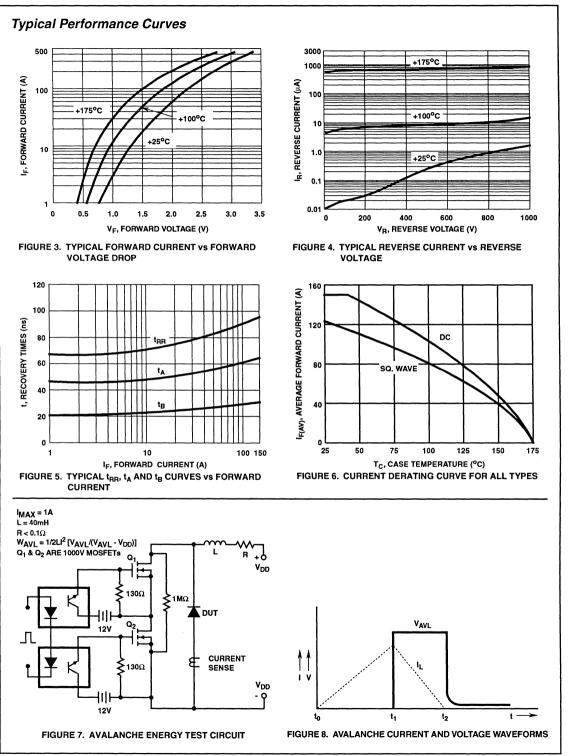


FIGURE 1. t<sub>RR</sub> TEST CIRCUIT



7

HYPERFAST

DIODES



## RHRG30120CC

#### December 1993

#### Features

- Hyperfast with Soft Recovery......<65ns
- Operating Temperature .....+175°C
- Avalanche Energy Rated
- Planar Construction

#### Applications

- Switching Power Supplies
- Power Switching Circuits
- General Purpose

#### Description

The RHRG30120CC (TA49041) is a hyperfast dual diode with soft recovery characteristics ( $t_{\rm RR}$  < 65ns). It has half the recovery time of ultrafast diodes and is silicon nitride passivated ion-implanted epitaxial planar construction.

This device is intended for use as a freewheeling/clamping diode and rectifier in a variety of high frequency switching power supplies and other power switching applications. Its low stored charge and hyperfast soft recovery minimize ringing and electrical noise in many power switching circuits, reducing power loss in the switching transistors.

The RHRG30120CC is supplied in the JEDEC style TO-247 package.

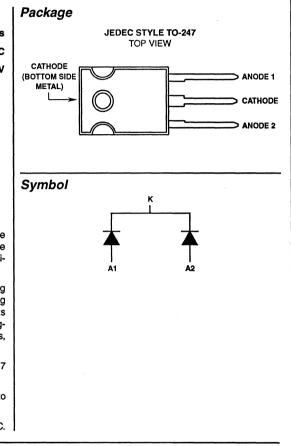
Due to space limitations, the brand on this part is abbreviated to H30120CC.

To order this part use the full part number, i.e. RHRG30120CC.

#### Absolute Maximum Ratings (T<sub>c</sub> = +25°C)

	RHRG30120CC	UNITS
Peak Repetitive Reverse Voltage	1200	v
Working Peak Reverse Voltage	1200	v
DC Blocking VoltageV <sub>R</sub>	1200	v
Average Rectified Forward Current (Per Leg)	30	v
Repetitive Peak Surge Current (Per Leg) I <sub>FSM</sub> (Square Wave, 20kHz)	60	v
Nonrepetitive Peak Surge Current (Per Leg) I <sub>FSM</sub> (Halfwave, 1 Phase, 60Hz)	300	v
Maximum Power Dissipation	125	w
Avalanche Energy	30	mj
Operating and Storage Temperature	-65 to +175	°C

### 30A, 1200V Hyperfast Dual Diode



#### Specifications RHRG30120CC

ectrical S	pecifications (P	er Leg)     T <sub>C</sub> = +25°C, Unless	Otherwise Specified	ł				
				LIMITS				
SYMBOL	TE	TEST CONDITION		ТҮР	МАХ	UNITS		
V <sub>F</sub>	I <sub>F</sub> = 30A		-	-	3.2	v		
VF	I <sub>F</sub> = 30A	T <sub>C</sub> = +150°C	-	-	2.6	v		
I <sub>R</sub>	V <sub>R</sub> = 1200V		-	-	100	μА		
1 <sub>R</sub>	V <sub>R</sub> = 1200V	T <sub>C</sub> = +150°C	-	-	1	mA		
t <sub>RR</sub>	I <sub>F</sub> = 1A, dI <sub>F</sub> /dt = 10	0A/μs	-	-	65	ns		
t <sub>RR</sub>	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 1	00A/µs	-	-	75	ns		
t <sub>A</sub>	$I_{\rm F} = 30$ A, $dI_{\rm F}/dt = 1$	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs		48	-	ns		
tø	I <sub>F</sub> = 30A, dI <sub>F</sub> /dt = 100A/μs		-	22	-	ns		
R <sub>eJC</sub>			-	-	1.2	°C/W		

DEFINITIONS

V<sub>F</sub> = Instantaneous forward voltage (pw = 300µs, D = 2%).

I<sub>R</sub> = Instantaneous reverse current.

 $t_{RR}$  = Reverse recovery time (See Figure 2), summation of  $t_A + t_B$ .

 $t_A$  = Time to reach peak reverse current (See Figure 2).

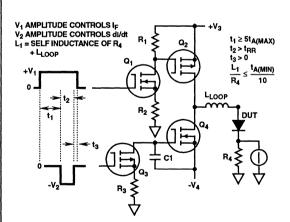
t<sub>B</sub> = Time from peak I<sub>RM</sub> to projected zero crossing of I<sub>RM</sub> based on a straight line from peak I<sub>RM</sub> through 25% of I<sub>RM</sub> (See Figure 2).

 $R_{\Theta JC}$  = Thermal resistance junction to case.

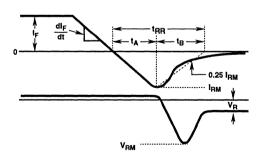
 $W_{AVL}$  = Controlled avalanche energy (See Figures 7 and 8).

pw = pulse width.

D = duty cycle.



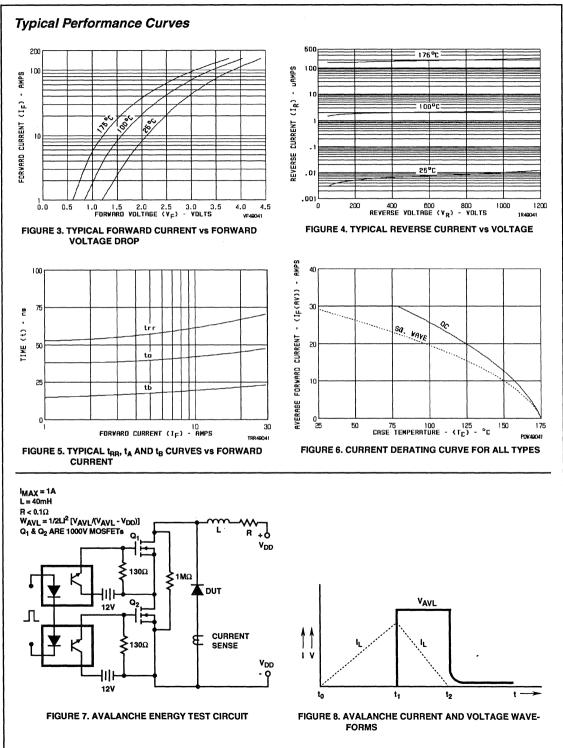




7

HYPERFAST DIODES

#### RHRG30120CC



# **MCT/IGBT/DIODES**

### **APPLICATION NOTES**

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## Introduction to the MCT User's Guide

Opportunities for continued progress in Power Delivery and Control Systems were never more evident than today. The efficient and elegant use of energy commands the attention of conservationists, political leaders, technologists, indeed, all those concerned with continued improvement in the human condition concurrent with respect for their world's environment. Power Electronics is an enabling technology that offers newly attractive solutions to many diverse applications of electric power. And progress in Power Electronics is paced by progress in the Semiconductor Components available as Power Switches.

A new Power Semiconductor Device, the MOS Controlled Thyristor, the MCT, is now available for commercial use. This is a significant benchmark in the progress of Power Electronics.

The MCT is a truly different product. It has its own set of characteristics. Some of these characteristics bear resemblance to the older thyristors, SCRs and GTOs. Yet the merger of modern MOS design and processing features with the older double injection bipolar structures results in a new device, with new characteristics and capabilities.

This manual is offered in the desire to facilitate the introduction of this new product. It will introduce the user to the new MCT technology. Our desire is to make available to the reader the experience of others; as it exists, and as it develops. It is our hope that the MCT will be properly applied and will be a rewarding experience for its users.

This introduction is an opportunity to recognize the contributions of Dr. Vic Temple and his associates at the Schenectady R&D Center, who are the developers of this new technology.

Research and Development support, first from the Electric Power Research Institute (EPRI) and NASA, followed by US Government Agency support through Wright Patterson AFB, DARPA, U.S. Navy (DTRC) and the U.S. Army Labcom, Electronics Technology and Devices Laboratory at Ft. Monmouth has been instrumental in MCT development. Some of these programs were co-funded by SDIO. The foresight and fortitude of the individuals who guide these agencies are to be acknowledged.

In closing, we at Harris Semiconductor wish you every success in your use of MCT's. We are committed to serve you, our customer.



## **MCT Description**

#### 2.0 MCT's, a New Class of Power Devices

#### 2.0.1 Background

MOS Controlled Thyristors are a new class of power semiconductor devices that combine thyristor current and voltage capability with MOS gated turn-on and turn-off. Various subclasses of MCTs can be made: P-type or N-type, symmetric or asymmetric blocking, one or two-sided Off-FET gate control, and various turn-on alternatives including direct turn-on with light. All of these sub-classes have one thing in common; turn-off is accomplished by turning on a highly interdigitated Off-FET to short out one or both of the thyristor's emitter-base junctions. This users guide focuses on the first product introduced by Harris, a P-type asymmetric blocking, MOS gated MCT.

#### 2.0.2 Description

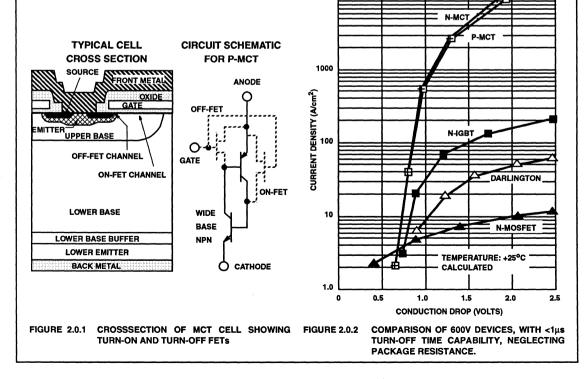
Figure 2.0.1 shows the basic elements of the MCT that Harris is now producing. On the left is a representative cross section of one cell of the device that is repeated 10's of thousands of times to make a device that can turn off 120A at  $+150^{\circ}$ C junction temperature. On the right is an equivalent circuit based on the well-known two transistor model of the thyristor. In the P-MCT a P-channel On-FET is turned on

with a negative voltage which charges up the base of the lower transistor to latch on the MCT. The MCT turns on simultaneously over the entire device area giving the MCT excellent di/dt capability. Figure 2.0.2 compares different 600V power switching devices for 2.0.3 conduction drop.

Figure 2.0.3 shows measured device comparisons which are typical of the conduction drop advantage of the MCT. Here, a 1000V P-MCT is shown with an IGBT die similarly packaged and of the same voltage rating. Note that the MCT typically has 10 to 15 times the current at the same forward drop.

#### 2.0.4 Turn Off

The MCT will remain in the on-state until current is reversed (like a normal thyristor) or until the Off-FET is activated by a positive gate voltage. Obviously, the higher the Off-FET gate voltage and the denser the Off-FET channels, the more current can be shorted across the emitter-base junction to effect turn-off. It is clear that successful turn-off requires all cells to turn off at the same time to prevent current from crowding. This imposes gate risetime constraints that are discussed later.



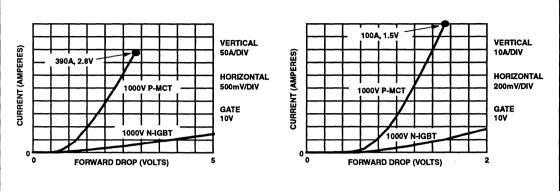


FIGURE 2.0.3 CURVE TRACER FORWARD DROP COMPARISON OF 1000V P-MCT AND N-IGBT AT +150°C

## 2.1 The MCT Advantages

#### 2.1.1 Turn-On and On-State:

MCTs, are superior devices in terms of conduction drop, surge current and di/dt capability. MCTs of similar blocking voltages, thyristors or GTOs can have lower forward drop, owing to the MCTs reduced cell size (compared to the GTO) and lack of emitter shorts (compared to the thyristor).

#### 2.1.2 Off-State:

MCTs can be made over a broad range of voltages from 100V to 8KV to 10KV. MCTs can be made symmetric or asymmetric blocking.

High dv/dt capability is provided in the MCT when the junction charging current is diverted around the Base-Emitter junction of the PNP transistor through the low impedance of the Off-FET.

Leakage current is also diverted through the Off-FET, providing excellent high temperature voltage blocking capability. For instance, under laboratory conditions, MCTs have been operated turning off 80A at  $+300^{\circ}$ C, withstanding dv/dt's of 10KV/µs at  $+250^{\circ}$ C and surviving 100 hours of blocking life testing at  $+235^{\circ}$ C junction temperatures. For these reasons it is recommended that the gate on bias be maintained continuously.

#### 2.1.3 Turn Off:

The MCT provides a turn off capability, through gate control. Conventional SCRs can not be turned off by the gate. The insulated gate structure of the MCT allows turn off of the principle current with much less drive energy than GTO -SCRs.

#### 2.1.4 Temperature Capability:

The thyristor structure and the thyristor alleviating the usual voltage and current stress of the typical MOSFET elements of the power FET or IGBT. The FET element helps the thyristor withstand self-turn-on. The Off-FET elements see little

stress, since in the MCT structure, they are not active durning blocking and conduction. The Off-FET conducts only during turn-off transitions. The FET elements neither conduct the principal current, nor are they exposed to the mode without blocking voltage.

What is the MCTs temperature limit? Obviously, in the case of Harris' first commercial offering, it is now the package and the temperature to which we have taken sufficient reliability data. Ultimately, however, it is thermal runaway associated with leakage current, perhaps as high as  $+250^{\circ}$ C in the 600 to 1000V range and  $+275^{\circ}$ C in the 100V to 300V range.

## 2.2 Why a P-MCT With Its P-Power Device Limitations?

From the above discussion it would seem that there would be few circuit niches above 100 volts or 200 volts which would not be best served with an MCT. That indeed should be the case once Harris is able to market a full line of MCTs - especially N-MCTs. However, our first MCT products are P-type, i.e., they have a blocking voltage region that is P-type with inherently higher gain and with inherently lower SOA than in an N-type device.

The reason for this choice lies in the fact that the current density that can be turned off is 2 to 3 times higher if the Off-FETs are n-channel. To have a peak turn-off capability consistent with the MCTs high RMS current rating we decided that having n-channel Off-FET's was more important than the 30% higher SOA and 2 times lower switching loss that we would get (and have measured) in an N-MCT.

We still retain the low forward drop, good di/dt and dv/dt and good voltage and temperature capability but have sacrificed some usefulness, particularly in high frequency, hard switched circuits where SOA and switching losses are critical. Even in those circuits a snubber will allow one to use the P-MCT but at increased cost.

#### 2.2.1 Where Should I Consider Using a P-MCT?

In any circuit dominated by conduction loss our first generation P-MCT can result in half the losses and use half the active silicon area - i.e., a smaller device and higher efficiency. In replacing a GTO or BJT it also offers the considerable advantage of MOS gate control. Even in hard switched circuits, at frequencies of several KHz and below, the P-MCT may be a good choice despite the possible need of a snubber circuit of some sort to keep the P-MCT within its turn-off SOA. In most instances, the MCTs high di/dt and good hard turn-on capability allows one to use a snubber consisting of a capacitor alone, somewhat reducing snubber cost and simplifying the circuit.

In Sections 5 and Section 6 P-MCTs are discussed in 1) hard switched, 2) soft switched, 3) SCR-like, 4) symmetric blocking and 5) complementary device circuits.

#### 2.2.2 Where Should I Not Use a P-MCT?

As can be seen from the device ratings section, the P-MCTs SOA is rated at half the device's breakdown voltage rather than at the 80% typical of an n-type power device. If your circuit requires hard switched inductive turn-off above the SOA level and a snubber is not cost effective then you cannot use a P-MCT. Further, if your switching losses now are equivalent to your conduction losses you may gain very little. For example, consider replacing an IGBT of 50W conduction loss and 30W switching loss with a generation 1 P-MCT. One could rightly expect to find that the P-MCT would have <25W conduction loss but nearly 60W of switching loss. Adding the appropriate snubber would put the switching loss elsewhere which would have the cost advantage of allowing the use of an MCT of half the size of the IGBT. That still might not be the right answer to your circuit.

### 2.3 Future MCT Developments

Although this material is covered later in more depth, it is appropriate to describe the kind of MCT devices that can be expected to be developed and produced by Harris and other semiconductor manufacturers.

This would first include more voltage ratings - first asymmetric MCTs down to perhaps as low as 200V and as high as 1600V. Later, high voltage MCTs will be available for what are now typically thyristor and GTO circuits. (See Reference 2.)

P-MCTs will also improve in switching capability in both SOA and turn-off time, bettering N-IGBTs in speed and turn-off loss and being at less of a disadvantage in hard switched SOA.

N-MCTs will begin to become available but with about half the peak turn-off current capability of P-MCTs. However, both P-MCTs and N-MCTs will be improving in that characteristic as improved process capability allows denser Off-FET channel structure.

As with other FET-containing devices higher current switches will be produced in the form of modules, usually including diodes, and sometimes including some degree of intelligence. Our experience is that MCTs (up to 12 have been paralleled at Harris Power R&D) can be successfully paralleled if done carefully. As with IGBTs this is best done by the manufacturer.

The timetable for these developments depends on resources.

#### 2.4 References

- V. Temple, "Power Device Evolution and the MOS-Controlled Thyristor", PCIM, November, 1987, pp 23-29.
- [2] V.A.K. Temple, S.D. Arthur et al., "Megawatt MOS Controlled Thyristor for High Voltage Power Circuits" PESC 92 Proceedings, pp 1018-1025 (Toledo, Spain, June 29 -July 3, 1992)

## **MCT Equivalent Circuit Models**

#### 3.0 Introduction

The new Harris P-MCT is a high power and high speed switching device that is useful in many applications. In our user's guide we have included several models that can be used to investigate whether the generation 1 600V P-MCT that is Harris' first commercial MCT is appropriate for your application. As other products are announced it is hoped that the data sheets will include, for example, SPICE model parameters. In addition to SPICE model parameters we have included other physically based models that may be useful and in some cases more accurate.

## 3.1 SPICE Modelling of MCTs

#### 3.1.0 Introduction

SPICE parameter extraction of the MCT device is not an easy job, because the MCT integrates the four layers of a PNPN thyristor with NMOSFET and PMOSFET elements in a single device. The SPICE program has no model for a PNPN device, so either a three-diode model or a two-transistor bipolar model must be used for the vertical PNPN structures. In general, the three-diode model is a device physics oriented approach but requires longer computation time, while the two-bipolar model is an applications oriented model and runs faster. Implementation of either of the two models requires a separation of the PNPN device somewhere in a semiconductor layer, so that minority carrier currents on both sides are not always equal. Another aspect to both models is transient analysis that is caused by current amplification of the PNPN. The bipolar model has current

QP QN ANODE BF 9.1 2.75 VAF 2000 2000 IKF 600 600 RVP+ 10 30µ IS 1.14E-10 1.14E-10 12 TF 42.9ns 207ns RLP 96.1u 9 CJE 9.47nF RVN 747µ 1.25nF VJE 1.0 0.66 OP CJC 362pF 362pF RVP 31.3m MJC 0.5 0.5 5 QN I VJC 0.64 0.64 11 8 MP RVN+, 2.5m MN L 0.5 5.0 VDROP 0.18 V w 5.63 0.715 1E18 8E13 NSUB зÓ CATHODE υ 500 200 FIGURE 3.1.1 P-MCT SUBCIRCUIT AND +150°C DEVICE

CONSTANTS

amplification, while the diode model lacks it. The two-transistor bipolar model has been chosen in this modeling.

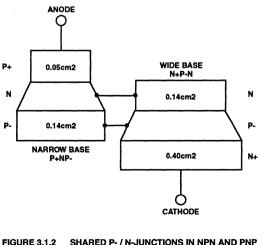
#### 3.1.1 Equivalent Circuit

As realized in Harris' first 600V P-MCT, the P-MCT can be thought of as consisting of about 11,000 parallel groups of 9 20mm x 20mm unit cells in a 0.4cm<sup>2</sup> active area. In each group of 9 cells there is one on-cell surrounded by 8 off-cells. Figure 2.0.1 showed half of a cross section, i.e., half an oncell and a complete off-cell along with the 2-transistor electrical equivalent circuit that is the basis of our SPICE model. The equivalent subcircuit model contains back-to-back connected NPN and PNP bipolar transistors, serial connected PMOSFET and NMOSFET, and parasitic passive components. The three-dimensional 600V P-MCT device has been converted to one-dimensional components with values as given in Figure 3.1.1.

#### 3.1.2 Parameter Calculation

Dimensions and physical parameters of each layer were determined assuming doping in each layer is to be uniform, and a reasonable mobility is given to each layer. Finally, resistivity and diffusion lengths are calculated.

Parameter calculation for the two bipolars requires some caution. First, the collectors of PNP and NPN bipolars share the same P-/N-junction, so the collector area of each bipolar is taken to be a half of the junction area as shown in Figure 3.1.2. Second, reverse parameters are always unnecessary



SHARED P- / N-JUNCTIONS IN NPN AND PN BIPOLAR TRANSISTORS 8

## MCT Equivalent Circuit Models

## TABLE 3.1.1 CALCULATED AND MODIFIED SPICE PARAMETERS AT T<sub>J</sub> = +150°C

TABLE A WIDE BASE N+P-N BIPOLAR		UNIT	DEVICE PHYSICS	MODIFIED SPIC
Transport Saturation Current	IS	A	1.14E-10	1.14E-10
Ideal Maximum Forward Beta	BF	-	0.536	2.75
Fwd Current Emission Coeff	NF	-	1.0	1.18
Corner for Fwd Beta Roll-Off	IKF	A	3.45E-2	6.00E2
Forward Early Voltage	VAF	v	2.05E1	2.00E3
3-E Built-In Potential	VJE	v	0.66	0.66
3-C Built-In Potential	VJC	v	0.64	0.64
Base Forward Transit Time	TF	Sec	4.72E-7	2.07E-7
3-E Zero Bias Capacitance	CJE	F	1.25E-9	1.25E-9
3-E Junction Exponent	MJE		0.5	0.5
3-C Zero Bias Capacitance	CJC	F	3.62E-10	3.62E-10
3-C Junction Exponent	MJC	-	0.5	0.5
TABLE B NARROW BASE P+NP BIPOLAR		UNIT	DEVICE PHYSICS	MODIFIED SPIC
Transport Saturation Current	IS	A	6.67E-10	1.14E-10
deal Maximum Forward Beta	BF	-	9.10	9.10
wd Current Emission Coeff	NF	-	1.0	1.18
corner for Fwd Beta Roll-Off	IKF	A	4.42E1	6.00E2
orward Early Voltage	VAF	v	2.00E2	2.00E3
B-E Built-In Potential	VJE	v	1.00	1.00
B-C Built-In Potential	VJC	v	0.64	0.64
ase Forward Transit Time	TF	Sec	4.29E-8	4.29E-8
B-E Zero Bias Capacitance	CJE	F	9.47E-9	9.47E-9
B-E Junction Exponent	MJE	·	0.5	0.5
3-C Zero Bias Capacitance	CJC	F	3.62E-10	3.62E-10
B-C Junction Exponent	MJC	· · · · · · · · · · · · · · · · · · ·	0.5	0.5
TABLE C		1	DEVICE	T
OFF MOSFET		UNIT	PHYSICS	MODIFIED SPIC
Zero Bias Threshold Voltage	VTO	V	2.0	2.0
Substrate Doping	NSUB	1/cm <sup>3</sup>	1E18	1E18
Dxide Thickness	тох	meter	7E-8	7E-8
Aobility	UO	cm <sup>2</sup> /V.sec	500	500
Channel Length	LL	meter	0.5E-6	0.5E-6
Channel Width	w	meter	5.63	5.63
TABLE D ON MOSFET		UNIT	DEVICE PHYSICS	MODIFIED SPI
Zero Bias Threshold Voltage	VTO	V	-2.0	-2.0
Substrate Doping	NSUB	1/cm <sup>3</sup>	8.0E13	8.0E13
Dxide Thickness	TOX	meter	7E-8	7E-8
Aobility	UO	cm <sup>2</sup> /V.sec	200	200
Channel Length	L	meter	5.0E-6	5.0E-6
Channel Width	w	meter	0.715	0.715
TABLE E PARASITICS		UNIT	DEVICE PHYSICS	MODIFIED SPI
PNP Emitter Resistor	RVP+	ohm	3.00E-5	3.00E-5
PMOS Series Resistor	RLP	ohm	9.61E-5	9.61E-5
MOS Series Resistor	RVN	ohm	7.47E-4	7.47E-4
P- Layer Resistor	RVP	ohm	3.17E-2	3.17E-2
NPN Emitter Resistor	RVN+	ohm	1.22E-3	2.5E-3
	1 11114		1	2.02-0

because the MCT reverse operation is inhibited. Third, the SPICE BJT model allows only choice of one of two DC models - transport saturation current (IS) only or emitter and collector saturation current (ISE and ISC). The IS only model (Gummel-Poon model) has been chosen because of its simplicity. Twelve calculated parameters for each of narrow base PNP and wide base NPN bipolars are summarized respectively in Subtables A - E of Table 3.1.1.

The PMOSFET and NMOSFET of elements of the MCT are very high speed devices compared with bipolar speed. They work as voltage controlled switches, except for several approximately 10nsec gate delays. The MOSFET uses the Shichman-Hodges model, and the gate capacitance model is a 12-section Meyer model. These choices result in 6 parameters for each MOSFET. Physical parameters are given in Subtables C and D of Table 3.1.1. Notice SPICE uses the meter as a unit of length.

Parasitics consist of one voltage source and 6 resistors. The voltage source describes an electric field in the very wide base NPN bipolar transistor. NPN and PNP emitter resistances (RVN+ and RVP+) were determined from measured data in the forward ON state. The other three parasitic resistors were calculated from Figure 2.0.1, bringing the total number of SPICE parameters to 42 as seen from Table 3.1.1.

#### 3.1.3 Parameter Calibration

The calculated SPICE parameters had to be calibrated to fit measured 600V generation 1 P-MCT data over a wide range of current, voltage, time, temperature and load.

The first step of calibration was to modify SPICE parameters to match measured forward OFF characteristics up to 700V at  $+25^{\circ}$ C/ $+100^{\circ}$ C/ $+150^{\circ}$ C. The OFF condition biases the

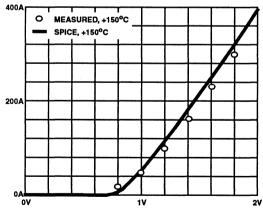


FIGURE 3.1.3. SPICE FORWARD VOLTAGE SIMULATION

center P-/N junction in reverse, and leakage current through the junction determines the MCT OFF current. Critical SPICE parameters for the forward OFF state are:

- 1. NPN bipolar: IS, BF and VAF
- 2. PNP bipolar: IS and VAF

The IS of NPN was set to be equal to the IS of PNP because the collector-base junction of both bipolars are the same P-/N junction. Fit is fairly good at high voltage and high temperature, the more critical region because of the relatively higher losses, but poor at low voltage and room temperature. Once NPN BF was set to the calculated 0.536 value, fitting was between 50% and 200% at all voltage and temperature ranges. Later BF was modified to 2.75 to accommodate transient fitting. The OFF state loss is approximately 0.23W at 700V and +150°C, and becomes negligibly small at +100°C. It is noteworthy that the most important parameter, IS for the PNP, remains unchanged at 11.4nA.

The second step of calibration is ON-state characteristics. In this condition all the emitter junctions of MCT are forward biased and the central P- and N layers are strongly modulated by two types of injected carriers from P+ and N+ emitters, so that the forward drop is very much similar to a PIN diode. Measured and simulated forward ON characteristics from 10A to 300A at +150°C are plotted in Figure 3.1.3. Fitting is approximately within 50mV except at low current. Sensitive SPICE parameters for the forward characteristics are:

- 1. NPN bipolar: IS, BF and NF
- 2. PNP bipolar: IS and NF
- 3. Parasitics: RVN+, VDROP and RVP+

As IS's and BF's were already set in the first step the NF's of two bipolars and NPN emitter series resistance (RVN+) and PNP series emitter resistance (RVP+) are available to fit the measured data. Once BF of the NPN was set to the calculated 0.536, fitting was plus/minus 100mV at all the ranges. The 2.75 NPN beta calibration comes from the transient fitting. Power loss at 100A is approximately 120W at all temperatures.

The third step is the most difficult calibration - transient turnon and turn-off which are influenced by different phenomena. An important process for the ON transient is plasma spreading carried by holes and electrons. Capacitances in the circuit delay the transient. The turn ON is fairly constant over various current, voltage and temperature. Sensitive SPICE parameters for the turn-on transient are:

- 1. NPN bipolar: BF
- 2. Parasitic: CPOLY

The minority carrier lifetimes in P- and N regions play major roles for the OFF transient. In SPICE they appear in the base transit times (TF).

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Figure 3.1.4 compares simulated and measured turn-off time and energy for  $+150^{\circ}$ C, 100A unsnubbered turn-off clamped at 300 volts. Fit to experiment is better than 10%. No doubt users will be able to refine the model for even better fits of key MCT behavior for their individual circuits. However, a perfect fit with the two-transistor model will always be difficult as it is not a true representation of the thyristor part of the MCT.

A model has been presented with fitting shown only for the  $+150^{\circ}$ C case as this is normally the limiting case. Operation at other temperature requires 2 coefficients for each of IS (for conduction drop) and NF, TF (for turn off). Later datasheets and user's guide will include these coefficients.

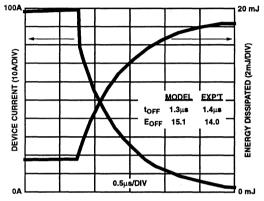


FIGURE 3.1.4. SPICE MODELLING OF 600V P-MCT TURN-OFF (300V, +150°C Inductive Turn-Off)

#### 3.1.5 Modelling Series/Parallel MCTs

One of the more important reasons SPICE modelling of MCTs was undertaken several years ago at Harris Power R&D was to design modules with parallel MCTs for a number of R&D programs focussed chiefly in aerospace systems. It was useful to introduce "weak" and "strong" MCTs in which turn-off times and forward drops were varied.

#### 3.1.6 SPICE Modelling Summary

The newly developed MCT model can simulate not only MCT devices but also MCT power circuits and systems. The MCT subcircuit is a strong tools for design and verification of MCT power circuits. However, this is a first version of the model. In the future an upgrade of the model to a more accurate version with a MOS capacitor type CPOLY. Also, more transient measurements to cover wider ranges of applications. Finally, in using SPICE models there is often a lot of "numerical noise" caused by the fact that when the MCT switches, very small time steps are needed compared to the rest of the simulation. SPICE handles those transitions poorly, sometimes leading to wild oscillations. Holding down the maximum time step can work in many cases. In others, small snubbers need to be added between nodes where voltages change too quickly. For example, while the curves

in Figure 3.1.4 had no snubber, small maximum time step was used which reduced numerical noise to acceptable levels. In using the same model as part of a half bridge circuit, a 0.5 ohm,  $0.033\mu$ F snubber across the MCT to get the SPICE simulation to work.

## 3.2 Special MCT Models

#### 3.2.0 Introduction

The big weakness of the MCT models built out of simpler devices is that they are non-physical in one important way. They do not account for the fact that the MCT is swamped with holes and electrons in the P- and N base regions. This has led to investigation of a 4-layer device model that can be implemented in SPICE or some other model useful to applications engineers. This has not yet been totally successful. However, some portions of that developing model have proved very useful, especially in calculating MCT turn-off.

Figure 3.2.1A shows a very simple MCT model for looking at turn-off. The MCT is assumed to be a current source in parallel with a capacitor. It is a very device physics oriented model which needs the current gain of the lower transistor, the recombination tail time constant and the device selfcapacitance to accurately give the device turn-off trajectory (I and V vs t) along with device losses. In fitting low and high voltage turn-off to experiment, it was found that the above parameters are a function of voltage and current. For example, depletion width depends on current density in a known fashion. Also, undepleted base width controls current gain and is thus voltage and current dependent, also in a known way. Finally, recombining excess carriers are pushed toward and into the more heavily doped buffer region where recombination lifetimes are shorter. Here, a less precise parameter variation is possible.

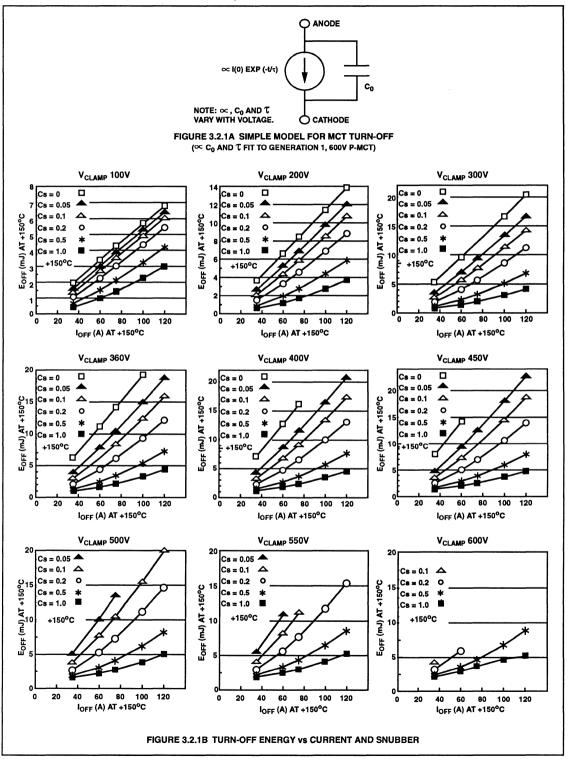
The lower part of Figure 3.2.1 shows turn-off energies calculated for inductive turn-off of different currents with various snubber capacitors for temperatures of  $+75^{\circ}$ C and  $+150^{\circ}$ C. No energies are plotted for turn-offs that would at any time exceed the device SOA. In this case the SOA used is for a typical device and not all 600V generation 1 MCTs (75P60's). Later, in section 6, measured turn-off energies are plotted for the same currents and snubbers. Fits are excellent.

The model described was implemented in "c" programming language but could also be implemented, with less accuracy, in SPICE.

## 3.3 Summary

A passable SPICE model whose parameters have been fit to the first Harris 600V MCT (75P60). This model works well in modelling more complex circuits. It does not, however, check to see if the SOA has been exceeded.

We have also shown a different type of model useful for turnoff transients which is more physical than the 2-transistor SPICE model.



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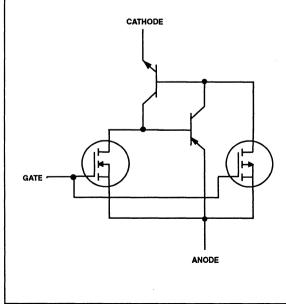
APPLICATION NOTES

## **Characteristics**

With the commercial introduction of the first MCT will come many questions concerning use and content of the data sheet. While the majority of the ratings, characteristics and curves will be familiar to most users, there are some subtle differences. This section is intended as a guide to the interpretation and significance of each of the ratings and characteristics that appear on a data sheet. The curves and figures used to illustrate these descriptions are intended to be generic and could be different than the curves included in an MCT data sheet.

## Operation Explained by Means of the Equivalent Circuit

Most of the characteristics of an MCT can be understood easily by reference to the equivalent circuit shown here. An MCT closely approximates a bipolar thyristor (The two transistor model is shown) with two opposite polarity MOSFET transistors connected between its anode and the proper layers to turn it on and off. Since an MCT is an NPNP device rather than a PNPN device the output terminal or cathode must be negatively biased. Driving the gate terminal negative with respect to the common terminal or anode turns the P channel FET on, firing the bipolar SCR. Driving the gate terminal positive with respect to the anode turns on the N channel FET on shunting the base drive to PNP bipolar transistor making up part of the SCR, causing the SCR to turn off. It is obvious from the equivalent circuit that when no gate to anode voltage is applied to the gate terminal of the device, the input terminals of the bipolar SCR are unterminated. Operation without gate bias is not recommended.



## Ratings

Most of the ratings seen on an MCT data sheet are identical to those found on PowerFET data sheets or are explained elsewhere in this document and do not need further explanation. The ratings which are differ from standard convention will be explained below.

- Peak Off-State Blocking Voltage: (V<sub>DRM</sub>)
  - Maximum allowable cathode to anode voltage. Explained in characteristic curve section.
- Peak Reverse Voltage: (V<sub>RRM</sub>)
  - The MCT is not by design a reverse blocking device, but like IGBTs it does have sufficient blocking capability to allow the use of an antiparallel diode.
- Continuous Cathode Current: (I<sub>C</sub>)
  - Explained in characteristic curve section.
- Non-repetitive Peak Cathode Current: (I<sub>TSM</sub>)
  - This is the maximum allowable current through the device in the on-state at the pulse width. Junction temperature limits the acceptable peak current and pulse width.
- Peak Controllable Current: (ITC)
  - This is the maximum amount of cathode current the device is rated to turn off when commanded by the MCT gate signal. Turn off of the device is guaranteed in the circuit listed in the particular data sheet. This capability is for both inductive and resistive circuits. The volt amp load line in Figure 4.12 must be adhered to during turn-off. Attempting to turn the device off at currents higher than the rated peak controllable current may result in destroying the device. The device may be used at currents greater than the peak controllable current if it is commutated off at a current at or below the peak controllable rating.
- Gate-Anode Voltage (Continuous): (V<sub>GA</sub>)
- Similar to other MOS gated devices.
- Gate-Anode Voltage (Peak): (V<sub>GA</sub>)
  - Allows for voltage overshoot during on and off gate voltage transitions, is explained elsewhere in the users guide.
- Rate of Change of Voltage: (dv/dt)
  - Explained in characteristic curve section.
- Rate of Change of Current: (di/dt)
  - Explained in characteristic curve section.
- Maximum Power Dissipation: (P<sub>T</sub>)
  - A function of the maximum junction to case thermal resistance (0.6°C/W) and a maximum delta temperature (junction to case) of +125°C.

- Linear Derating Factor:
  - Self explanatory.
- Operating and Storage Temperature: (T<sub>J</sub>, T<sub>STG</sub>)
  - Self explanatory.
- Maximum Lead Temperature for Soldering: (T<sub>L</sub>)
   Self explanatory.

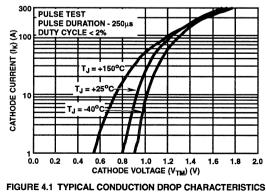
### Parameters

As with the ratings most of the parameters are similar to those found on PowerFETs or thyristor class devices, parameters which need further explanation will be clarified below.

- Peak Off-state Blocking Current: (I<sub>DRM</sub>)
- Self explanatory.
- Peak Reverse Blocking Current: (I<sub>RRM</sub>)
  - Self explanatory.
- On-state Voltage: (V<sub>TM</sub>)
  - Explained in characteristic curve section.
- Gate-anode Leakage Current: (I<sub>GAS</sub>)
  - Self explanatory.
- Input Capacitance: (C<sub>ISS</sub>)
  - The MCT does not have Miller capacitance therefore it does not have gate plateau characteristics. The gate can be viewed strictly as a capacitance.
- Switching Characteristics:
- Explained in characteristic curve section.
- Thermal Resistance: (R<sub>θJC</sub>)
  - Self explanatory.

### Static Characteristics

Low conduction drop of the MCT is what sets it apart from MOSFETs, BIPOLARs and IGBTs. As the characteristic curves show conduction drop voltage is diode like which accounts for the high DC current rating of the device. Important aspects of the conduction drop voltage characteristic are the current at which the temperature coefficient is zero and the negative temperature coefficient of the conduction drop voltage below that current.



Below the zero temperature coefficient current, conduction voltage decreases with increasing temperature; a practical ramification of this is that if mismatched devices are paralleled one device could go into thermal runaway. From a paralleling standpoint, it is advantageous to operate in an area of positive temperature coefficient which, depending on the circuit configuration, could mean operating above the peak switching capability of a single device. To operate above the zero temperature coefficient current the circuit must resonate or the current must be commutated to a safe switching level before it is switched off.

Figure 4.2 is a calculated curve which defines the DC current carrying capability of the device vs temperature, the limiting factor to the current is the rated junction temperature of +150°C. This curve was plotted using a junction to case thermal resistance of 0.6°C/W and a device with a I<sub>K</sub> vs V<sub>TM</sub> curve passing through V<sub>TM(MAX)</sub> at I<sub>C90</sub> and T<sub>J</sub> = +150°C. Using the above data and the following formula we can calculate the curve.

$$T_{C} = 150 - 0.6 * I_{DC} * V_{TM} \qquad I_{DC} = \frac{150 - T_{C}}{0.6 * V_{TM}}$$

The package limit shown on the curve is a wirebond limit and is not a function of the MCT die.

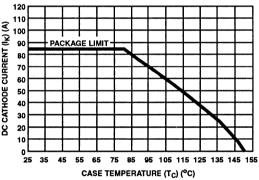


FIGURE 4.2. TYPICAL DC CURRENT CAPABILITY

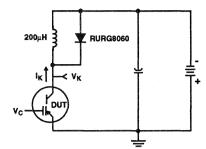
#### Switching Characteristics

Hard switched characteristics are described in Figures 4.5 through 4.10, and Figures 4.3 and 4.4 show the switching circuit and switching waveforms respectively. To obtain turn on characteristics a double pulse test must be used. The first pulse charges the load inductor to IC90. When cathode current reaches IC90 the MCT is gated off, current then transfers from the MCT to the freewheeling diode. The diode also functions as a voltage clamp which limits voltage overshoot at turn-off. After the MCT has been given time (3-5µs) to fully turn off, it is gated back on and current transfers back from the freewheeling diode to the MCT. Note that if the delay time between pulses is too long the resistance in the inductor diode loop and diode losses will cause the current to decay below IC90. Also, if the second pulse is too long the maximum switching capability of the MCT could be exceeded.

An important point must be understood for this test and any other tests which include hard switching. The peak voltage

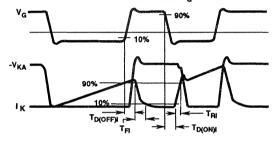
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 $V_{\text{KA}}$  is not the supply voltage but must include any voltage excursion above supply voltage while the clamp diode is turning on.



**FIGURE 4.3 INDUCTIVE SWITCHING CIRCUIT** 

MAXIMUM RISE AND FALL TIME OF VG IS 200NS



#### FIGURE 4.4 INDUCTIVE SWITCHING WAVEFORMS

Turn-off characteristics are measured at the trailing edge of the first current pulse and turn-on characteristics are measured at the beginning of the second pulse. Switching time measurements are defined as follows:

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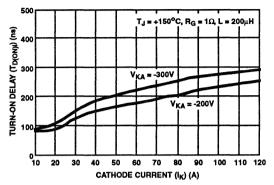
-	Measured from the 90% point of V <sub>G</sub> to the 10% point of I <sub>K</sub> .
-	Measured from the 10% point of $V_G$ to the 90% point of $I_K$ .
-	Measured from the 10% point of $I_K$ to the 90% point of $I_K$ .
•	Measured from the 90% point of $I_K$ to the 10% point of $I_K$ .
	-

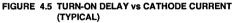
Switching loss measurements are defined as the integral of the instantaneous power loss within the following time intervals:

Turn-On Switching Loss (E <sub>ON</sub> )	-	Measured from the 90% point of $V_G$ to the $V_{KA} = V_{TM}$ point.
Turn-off switching loss (E <sub>OFF</sub> )	-	Measured from the 10% point of $V_G$ to the $I_K = 0$ point.

Maximum operating frequency curves for a typical device (Figure 4.11) are presented as a guide for estimating device performance for a specific application. Other typical frequency vs cathode current ( $I_{AK}$ ) plots are possible using the

information shown for a typical unit in Figures 4.5-4.10. The operating frequency plot of a typical device shows  $f_{max1}$  or  $f_{MAX2}$  whichever is smaller at each point. The information is based on measurements of a typical device and is bounded by the maximum rated junction temperature.





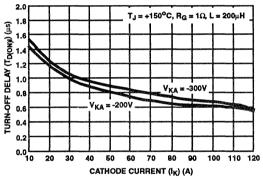
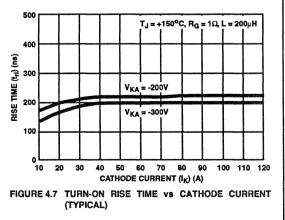
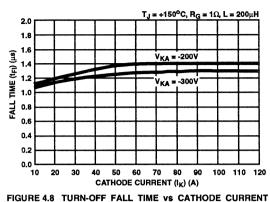


FIGURE 4.6 TURN-OFF DELAY vs CATHODE CURRENT (TYPICAL)





(TYPICAL)

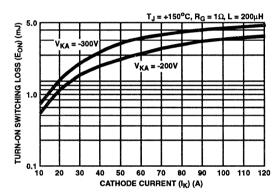
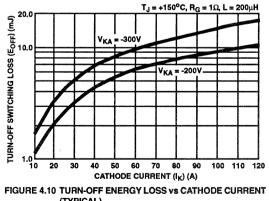
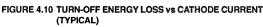


FIGURE 4.9 TURN-ON ENERGY LOSS vs CATHODE CURRENT (TYPICAL)





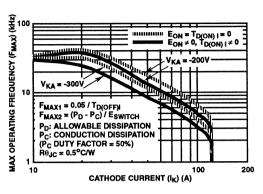


FIGURE 4.11 TYPICAL FWAY CURVES

 $F_{MAX1}$  is defined by  $F_{MAX1} = 0.05 / (T_{D(ON)I} + T_{D(OFF)I})$ .  $T_{D(ON)I} +$ TD(OFF) deadtime (the denominator) has been arbitrarily held to 10% of the on-state time for a 50% duty factor. Other definitions are possible. Device delay can establish an additional frequency limiting condition for an application other than TJMAX. TD(OFF)I is important when controlling output ripple under a lightly loaded condition.

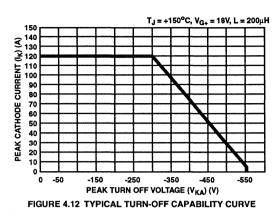
F<sub>MAX2</sub> is defined by F<sub>MAX2</sub> = (Pd - Pc) / (E<sub>ON</sub>+E<sub>OFF</sub>). The allowable dissipation (Pd) is defined by Pd =  $(T_{JMAX} - T_C) / R_{MC}$ . The sum of device switching and conduction losses must not exceed Pd. A 50% duty factor was used and the conduction losses (Pc) are approximated by Pc = (VAK IAK). EON is defined as the power loss starting at the leading edge of the input pulse and ending at the point where the anode-cathode voltage equals the conduction voltage drop, (VAK = VTM). EOFF is defined as the power loss starting at the trailing edge of the input pulse and ending at the point where the cathode current equals zero ( $I_{K} = 0$ ).

Because Turn-on switching losses can be greatly influenced by external circuit conditions and components, FMAX curves are plotted both including and neglecting turn-on losses.

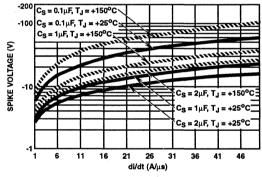
P-type MCTs have switching SOA limitations as other P-type semiconductor switches as shown in Figure 4.12. Switching capability is primarily impacted by three things:

- 1. Gate voltage rise time Gate voltage rise times longer than the times recommended in the data sheet will lower switching SOA capability below that shown in the Figure.
- 2. Gate voltage during turn-off The gate voltage must reach and maintain the recommended level until the MCT is fully turned off. Gate voltages lower than the recommended level will cause the horizontal upper switching limit to move down. Dependence of switching capability on  $V_{q}$  is described elsewhere in the users guide.
- 3. V<sub>KA</sub> peak In the high voltage region of the switching curve, switching capability is also impacted by the peak level of VKA during the switching transition. As mentioned previously, the voltage must include any overshoot above supply voltage. The overshoot will be of very short duration so an oscilloscope capabile of measuring very short pulses should be used.

### **Characteristics**



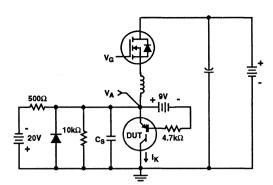
Spike voltage data is intended to aid the user in evaluating MCT performance in zero voltage resonant switching circuits. Spike voltage is defined as the peak amplitude  $V_{KA}$  will reach before the device latches on. As shown in Figure 4.13,  $V_{SPIKE}$  increases with temperature and can be reduced by adding or increasing the size of the anode-cathode capacitive snubber.



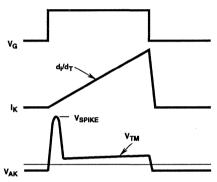


In the spike voltage test circuit (Figure 4.14) the purpose of the 20V supply, diode and 500 $\Omega$  resistor loop is to reverse bias the MCT. The reverse bias is intended to simulate the MCT bias in a resonant switching circuit as current begins flowing in the MCT. Figure 4.15 shows the timing of waveforms during the test. Load inductance and supply voltage are adjusted to provide the desired di/dt. Because V<sub>SPIKE</sub> subtracts from the inductor voltage it will cause the current ramp to be nonlinear. As V<sub>SPIKE</sub> is increased, supply voltage will also need to be increased to reduce the nonlinearity of  $I_{\rm K}$ .

Two factors that may reduce the blocking voltage capability of the MCT are temperature and dv/dt. Figure 4.16 shows the relationship of the blocking voltage of a typical MCT to dv/dt. Temperatures above the rating  $(+150^{\circ}C)$  will also reduce blocking voltage to less than rated voltage.









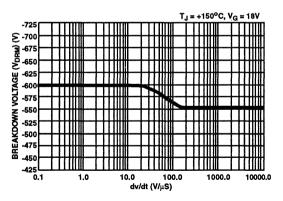


FIGURE 4.16 TYPICAL BLOCKING VOLTAGE vs dv/dt

## **Gate Circuits**

### 5.0 MCT Gate Drive Requirements and Gating Circuits

The MCT has a MOS gate, similar to FETs and IGBTs, making it relatively easy to drive. The MCT gate capacitance is typically 10nF. Unlike other MOS gate devices the MCT gate experiences essentially no Miller current during switching, simplifying gate drive requirements. However there are several differences compared with other MOS gate devices that must be considered for successful operation. These differences will be discussed in more detail in the following sections. A brief discussion of several gate drive circuits can be found in section 5.3.0.

## 5.1 Gate Waveform

#### 5.1.1 Boundary Limits

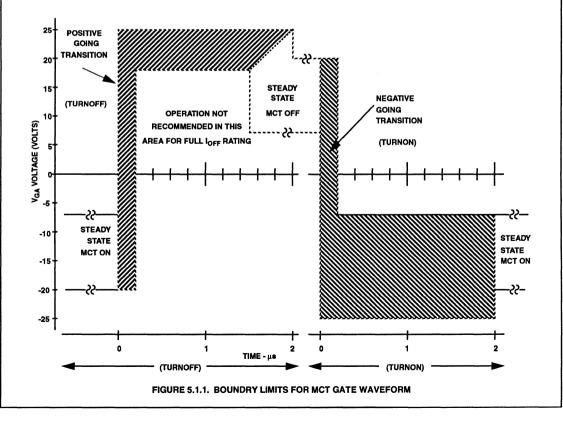
Rated performance of the MCT requires that the gate waveform meet criteria in amplitude and risetime. Figure 5.1.1 shows a graph of boundary limits for an acceptable gate waveform. The gate waveform should fall within the steady state limits during MCT ON or OFF time of the gate pulse. The gate waveform should fall within the shaded areas during the waveform transitions. These boundry limits are discussed in more detail in the following sections.

#### 5.1.2 Negative Amplitude

The MCT is gated ON with a voltage that is negative with respect to the MCT anode. Since the MCT is a thyristor, internal regeneration will insure that the device switches fully to the ON state once cathode current exceeds the device holding current (mA's). The -7V steady state ON voltage boundary insures the MCT will switch ON and switch with reasonable delay time. The -20V steady state boundary insures that the gate will not be damaged from excessive voltage.

#### 5.1.3 Negative Going Transition

One distinct difference between the MCT and other MOS gated devices is that the gate cannot be used to control the switching time of the MCT although the slope of the negative



8

going gate voltage transition does influence switching delay time. As the transition time is reduced gate displacement current will cause the MCT to initiate turn-on while the gate voltage is still positive. The boundary limits permit overshoot in negative going gate voltage.

#### 5.1.4 Positive Amplitude

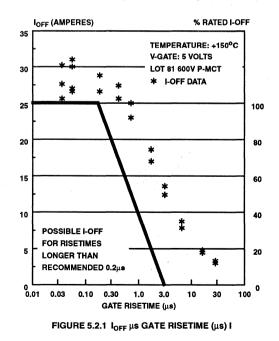
The MCT is gated OFF and held OFF with a voltage that is positive with respect to the MCT anode. The  $18V \ge 1.5\mu s$  duration OFF voltage boundary insures the MCT will switch off rated current at +150°C. The 20V steady state boundary insures the gate will not be damaged from excessive voltage. We do, however, allow the voltage to overshoot 20 volts to 25 volts but on a transient bases only

#### 5.1.5 Positive Going Transition

The MCT turns-off by internal FET transistors shorting the base-emitter junction of the internal PNP transistor. To maximize turn-off capability the shorting FETs must be turned ON uniformly and rapidly to ensure that all MCT cells turn off essentially the same current. If the gate voltage rises slowly current will redistribute among the cells reaching a value in some cells that cannot be turned off. This requirement establishes the 200ns boundary time of the positive going transition. To ease problems with inductive gate overshoot the gate voltage is allowed to transiently go as high as  $\pm 25$  volts.

#### 5.2.1 Derating

If the minimum positive steady state gate voltage is reduced or if the positive going gate voltage transition time is increased the turn-off capability of the MCT is reduced as shown by the curves in Figure 5.2.1 and Figure 5.2.2. These



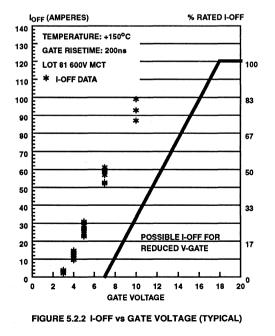
curves are not to be interpreted as device ratings. They show measured performance on a small sample of devices that are believed to be representative of the broad population of devices. The solid line curves are suggested limits that could be used to estimate reduced I<sub>OFF</sub> capability resulting from non-ideal gate voltage waveforms. The gate voltage referred to in Figure 5.2.2 occurs during the 1.5µs immediately following the positive gate transition. If increased rise time and reduced gate voltage occur simultaneously the % rating factors must be multiplied together. For example a gate pulse rise time of 0.5µs to 16V can be expected to reduce  $l_{OFF}$  capability to (0.6 x 0.83) 50% of rated.

## 5.3. Gating Circuits

#### 5.3.1 Circuits Using Commercial Parts

Circuits for gating an MCT should meet the following requirements.

- Gate Drive Voltage up to ±20V
- Rise/Fall Time <200ns
- Peak Current
- Thermal
- up to 2A
- Handle Gate Current vs Frequency Plus DC Losses
- Signal Interface
- Typically Magnetic or Optical Isolation
- Power Isolation
- Gate Drive Circuit Ohmically Connects To MCT Anode. Isolation Required For Bus Voltage And Switching dv/dt.



The circuits that follow illustrate several different approaches for gating the MCT. The fact that the required peak to peak MCT gate voltage exceeds FET drive requirements narrows the choices of commercially available ICs that can directly gate the MCT. Each of the driver circuits will typically be energized from a transformer secondary (usually high frequency) and rectifier to provide isolated DC power. The switching signal will typically be coupled through a fiber optic light pipe or optoccupler. Either of these would be energized from the isolated DC voltage through appropriate voltage divider or zener diode.

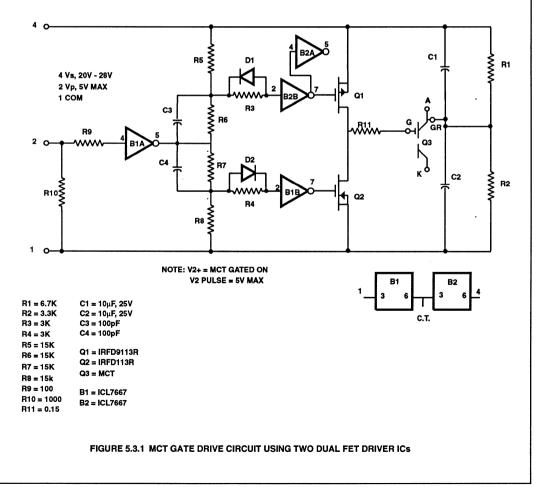
#### 5.3.2 Circuit 1 - Using Dual FET Drivers

Figure 5.3.1 shows a gate drive circuit topology which utilizes two dual 15V-18V rated FET driver ICs and discrete FETs to generate the required 20V+ MCT gate turn off signal. The secondary of power supply transformer produces  $\pm$ 13V which energizes the two dual power inverters connected between the transformer neutral and each rail. The input signal at terminal 2 is level shifted to drive upper and

lower power inverters which in turn drive FET transistors Q1 and Q2. The voltage capability of these transistors must exceed the 26V range required for the MCT. Components D1-R3 and D2-R4 provide differential delay to avoid overlap short circuit current through Q1 and Q2. Resistor R11 provides damping for gate voltage waveform. Resistors R1 and R2 establish the division of bus voltage between positive and negative voltage applied to the MCT gate. Capacitors C1 and C2 provide bus filtering and the peak current required to switch the MCT gate capacitance.

#### Assessment:

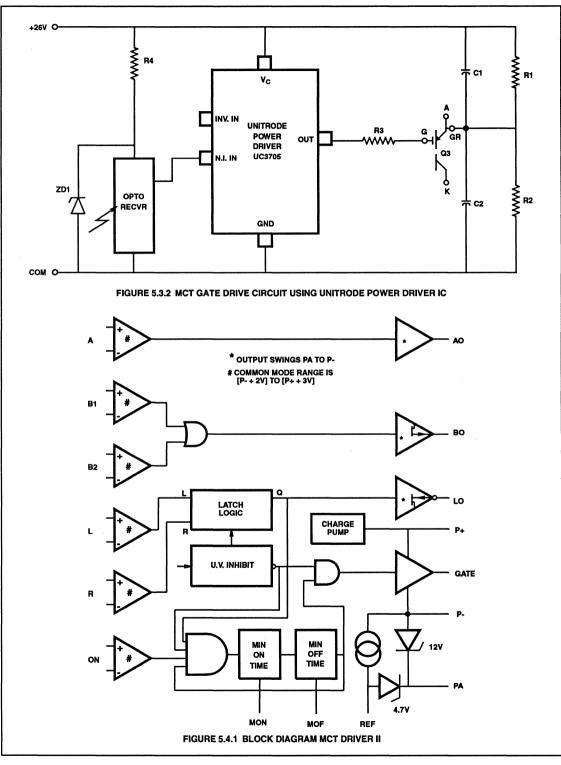
- + Circuit Operation is Tolerant of Bus Voltage Variation.
- + Circuit Can Drive MCTs in Parallel by decreasing  $R_{DS(ON)}$  of Q1 And Q2.
- + Multiple Sources for all Parts.
- Circuit is Relatively Complex for Driving a Single MCT.

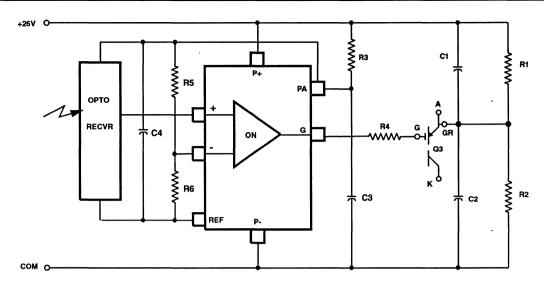


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NOTES

Gate Circuits







#### 5.3.2 Circuit 2 - Using Power Driver IC

Figure 5.3.2 shows a gate drive circuit topology which uses a 35V rated FET power driver to generate the required 20V+ MCT gate signal. The transformer and diodes produce the 26V required to directly energize the power driver. The input is compatible with a variety of opto receivers. Resistor R3 provides damping of gate voltage waveform. Resistors R1 and R2 establish the division of bus voltage between positive and negative voltage applied to the MCT gate. Capacitors C1 and C2 provide bus filtering and the peak current required to switch the MCT gate capacitance. This circuit is attractive however the user should be aware that this driver has an internal thermal shutdown feature which drives the output low if the temperature exceeds +155°C. This will gate the MCT ON, which probably will be judged undesirable.

#### Assessment:

- + Circuit Uses Few Components.
- + Higher Output Current Drivers Available.
- \_ Internal Thermal Shutdown (+155°C) Gates MCT On.

#### 5.4.0 Circuits Using Developmental Parts

#### 5.4.1 MCT Driver II

An MCT driver IC has been developed which is not yet available commercially. This IC has been designed to provide the power circuit designer with many useful functions. Figure 5.4.1 shows a simplified diagram of this integrated circuit. The circuit contains three major blocks, power circuit, main MCT ON/OFF channel and auxiliary comparators. In this discussion all voltages are referenced to the PA terminal, which is typically connected to the MCT anode.

The IC can be powered from a negative supply (7V - 12V), internally clamped at 12V, or from center tapped supply (P-to PA to P+) or from a single ended supply (P- to P+). When using a negative supply an internal charge pump energizes the P+ terminal. A -4.7V reference voltage can sink up to 30mA and can be used to directly energize opto receivers or other control circuits. Standby current is less than 5mA for the IC.

All control signals enter the IC through comparators which require only a few mV of input signal. The common mode range includes the PA terminal and -4.7V REF terminal allowing several volts of noise rejection. The main ON channel controls the gate output which is capable of driving 4 MCT gates connected in parallel. The ON channel includes Minimum-ON-Time and Minimum-OFF-Time functions which are user programmable by adding external capacitance. These functions can be used to provide adequate snubber reset time for example.

The IC contains both undervoltage inhibit and a latch which when set will force the ON channel to the MCT OFF state. The latch is set by the L comparator and is reset by the R comparator. When the latch is set the LO output will sink current (20mA max) for driving LED. With these inputs the user can implement over current or over temperature lockout functions for example.

APPLICATION NOTES

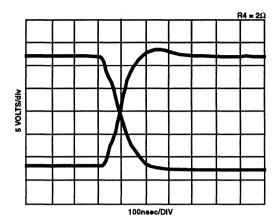
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The IC also contains two uncommitted comparator channels. The "A" channel has a totem pole output, "AO", capable of driving 20mA. The "B" channel has two comparator inputs which are OR'ed together and drive the "BO" output which will source current (20mA max) for driving an LED. These uncommitted channels can be used for detection, timing, and logic functions for example.

Figure 5.4.2 shows how this integrated circuit can be used in its simplest configuration to drive an MCT. The REF terminal can be used to power an opto receiver and provide reference voltage for the comparator input. In the arrangement shown resistors R1 and R2 establish the division of bus voltage between positive and negative voltage applied to the MCT gate. Capacitors C1 and C2 provide bus filtering and the peak current required to switch the MCT gate capacitance. Resistor R3 powers the integrated circuit. Resistor R4 provides damping the gate voltage waveform.

Figure 5.4.3 shows MCT gate voltage waveforms when driven by this IC. The + or - amplitude can be adjusted by the power supply voltage and resistors R1 and R2 to supply the desired amplitude of gate voltage.

Section 6.3 describes a DC circuit breaker which utilizes two MCTs and two of these driver ICs to implement all of the control circuits.



NOTE: + AND - AMPLITUDES CAN BE ADJUSTED TO MATCH RECOMMENDED DRIVER REQUIREMENTS.

FIGURE 5.4.3 OUTPUT VOLTAGE OF DEVELOPMENT MCT GATE DRIVER IC DRIVING ONE MCT GATE

## **Applications**

## 6.0 Using The MCT

The MOS Controlled Thyristor (MCT) is a solid state unidirectional power switch that exhibits low conduction drop (2volts - 3 volts) at high current as illustrated in Figure 6.0.1. As described in section 2, the MCT requires low power to gate, has high surge current, high di/dt and dv/dt withstand capability and is able to switch at junction temperature in excess of +150°C. The MCT should be considered for power switching applications where high current capability with relatively low conduction loss are prime requirements.

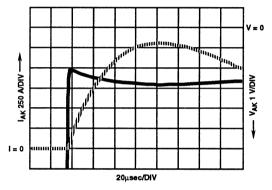


FIGURE 6.0.1. VOLTAGE ACROSS MCT DURING 1300 AMP PEAK PULSE

This section discusses key issues for successfully using the MCT in power switching circuits such as inverters, converters, motor drives, pulse circuits, etc. The discussion is divided into five categories; Hard Switching, Soft Switching, SCR circuits, AC Switch circuits and Complementary circuits.

### 6.1.0 Hard Switched Operation

#### 6.1.1 Turn-OFF Stress

Hard switching circuit applications subject the switching MCT to substantial simultaneous voltage and current during switching, resulting in high instantaneous power dissipation in the MCT. Many power conversion circuits operate in the hard switched mode. The diagram in Figure 6.1.1 shows a circuit that generates hard switched stresses on the MCT and this circuit will be used as a basis for discussing hard switched operation. The circuit is operated at very low duty factor allowing the MCT to be stressed up to rated voltage and current from a low power source. The MCT can be artificially heated (hot plate) to simulate self-heating.

The MCT in Figure 6.1.1 switches inductive current pulses from a low impedance power supply. Capacitor C1 is the DC source capacitor and must be large enough to supply the current pulse with less than 5% voltage droop. In practice it may be implemented with an electrolytic capacitor paralleled by a low impedance Multi Layer Ceramic capacitor. Inductors L1a and L1b are the stray inductances associated with the circuit loop connecting C1, D1 and MCT Q1. Inductor L2 is the principal load impedance limiting current during a pulse. Diode D1 clamps the MCT voltage to the supply bus and provides a current path for current in L2 to flow when the MCT is not conducting. Components R2, D2, C2 form a polarized snubber which, under some operating conditions, may be needed to control MCT overshoot voltage or keep the V-I switching path within the allowable SOA.

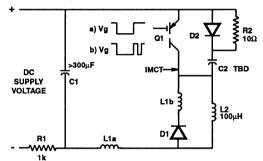


FIGURE 6.1.1 CIRCUIT THAT GENERATES HARD SWITCH-ING STRESS ON THE MCT

The  $I_{OFF}$  test uses wave form (a) to gate the MCT. When the MCT is gated ON current increases through inductance L2 to the desired peak current value. The ON time and the load inductance are selected to reach the desired current in about 50µs, for example. When the MCT is gated OFF the current through the MCT remains constant as the voltage increases until diode D1 conducts, clamping the cathode voltage to the negative bus. During this transition interval the MCT is subjected to high peak power dissipation. The increase in MCT voltage typically occurs rapidly (1000's V/µs) as the load current charges the equivalent capacitance of the MCT (~30nF). The turn-off of the MCT cannot be safely slowed down by reducing the gate drive as discussed in section 5.1.5.

While switching off, the instantaneous values of MCT voltage and current must stay within the safe switching area or "SOA" (Safe Operating Area) shown in Figure 6.1.2 The high current boundary of this curve is the maximum current that the MCT can turn off and is limited by the resistance of the internal OFF-FETs. The negative slope boundary is the SOA limit for the MCT. During the fast voltage transition, while switching off, stray inductance L1 will allow the MCT voltage to transiently exceed the supply voltage. For small values of stray inductance the overshoot voltage may be adequately limited by the capacitance of the MCT. For larger values of stray inductance it will be necessary to utilize a snubber network (C2, D2, R2 for example) to limit overshoot voltage.

The MCT power loss when switching off is a function of device current, peak voltage and junction temperature. In power circuit applications it may be necessary to add a snubber capacitor to keep the MCT I-V switching path within the safe switching area. In addition, snubber capacitance may be needed to reduce overshoot voltage, as previously discussed. The family of curves in Figure 6.1.3 shows typical MCT switching loss at +75°C and at +150°C, the maximum junction temperature for one of our 75P60 600V P-MCTs. These curves cover a range of peak voltage, snubber capacitor values and current enabling the estimation of switching loss under user conditions. Nine of these sets of curves are for +150°C junction temperature operation and therefore represent maximum typical losses in the MCT. The curves whose endpoints reach 120 amperes are limited by maximum turn-off ability of the MCT. The curves whose endpoints are less than 120 amperes are at or near the SOA limit of the MCT. In addition to the +150°C data, 3 sets of curves allow turn-off energy to be estimated at +75°C. Some of these measured switching loss curves extend beyond the Safe Switching Area limit shown in Figure 6.1.2. This does NOT imply that the Safe Switching Area limit can be exceeded safely for all devices.

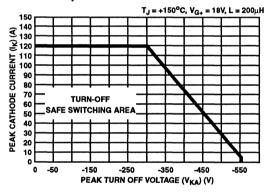


FIGURE 6.1.2. TURN-OFF CAPABILITY vs ANODE-CATHODE VOLTAGE

#### 6.1.2 Turn ON Stress

In the hard switched case, the MCT turns on from high blocking voltage with minimal inductance to limit increase in current. This condition occurs in the circuit of Figure 6.1.1 when gate waveform (b) is used. During the initial ON interval the test current is established in the inductor as previously described. After brief (5µs) off-period, which allows the MCT to fully recover blocking, the MCT is gated ON again for 5µs. During this second turn-on the MCT may experience high di/dt while the conducting diode recovers blocking voltage. The 5µs ON-time allows the MCT to turn on fully before the final OFF-transition occurs. These switching conditions are found in many types of inverter/converter circuits.

The presence of stray inductance L1 allows the MCT voltage to fall during current transfer and reduces the magnitude of peak diode recovery current. However this is in conflict with the requirement of reducing stray inductance to limit overshoot voltage and switching losses as discussed in section 6.1.1. In practice, it is typically found that overshoot voltage is the more limiting factor. Therefore, reducing stray inductance is probably the proper design objective. Typically, with fast recovery diodes, the MCT turn-ON switching loss is relatively small. Figure 6.1.4 shows typical turn-on energy loss as a function of cathode current for 200 volts and 300 volts. The MCT current that occurs during recovery of the diode can be several hundred amperes and is typically within the surge capability of the MCT. Device failures have been observed with turn-on di/dt in the range of 6000A/µs.

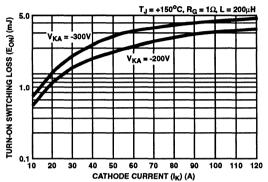


FIGURE 6.1.4. TURN-ON ENERGY LOSS vs CATHODE CUR-RENT (TYPICAL)

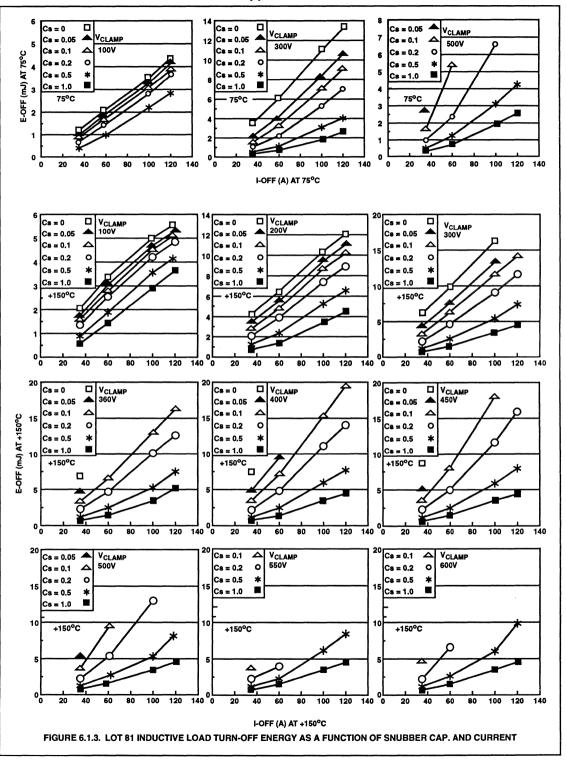
## 6.2.0 Soft Switched Operation

Soft switching and resonant power circuits are being employed,in part,as a means of reducing switching losses and stress on power switches thereby allowing higher operating frequency (references section 9 papers 16, 28, 33, 35). Soft switching occurs when the power switch is near zero current and/or zero voltage during the switching event. There are many different circuit topologies that limit switching stress on power switches. In these topologies the power switch is typically connected as part of an LC circuit and operated in one of two different modes. First, it can operate with the power switch in series with an inductor or second, with the power switch in parallel with a capacitor. The circuit in Figure 6.2.1 generates soft switching stresses on the MCTs and this circuit will be used as the basis for discussing soft switching operation.

#### 6.2.1 Circuit Operation

The circuit in Figure 6.2.1 is operated in the following sequence. Initially capacitor C1 is discharged by a large value resistor R1. The switching sequence is initiated by gating MCT Q1 ON followed by gating MCT Q2 ON. Current increases linearly through the inductor as established by Vsupply/L1. When MCT Q1 is gated OFF the voltage increases across MCT Q1 as L1 and C1 ring. The peak voltage across MCT Q1 is determined by the resonant impedance of L1C1 and the value of current in the inductor L1 at the time MCT Q1 is gated OFF. When the oscillation decays C1 will be charged to the supply voltage and the current through MCT Q2 will be small (Vsupply/R1). MCT Q2 can be gated OFF and C1 will discharge through R1 completing the sequence of operation.

Applications

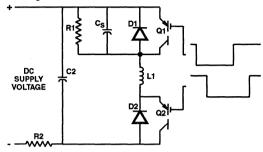


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APPLICATION NOTES

#### 6.2.2 Series Inductor Case

In the circuit in Figure 6.2.1 MCT Q2 is in series with inductor L1. Soft switching occurs if the current in the series inductor is substantially zero at the time of switching. If the inductor is larger than a few  $\mu$ H current increase during voltage collapse (<100ns) will be limited to a few amperes resulting in low turn-on loss.

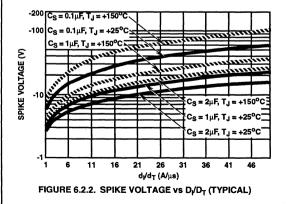


#### FIGURE 6.2.1 CIRCUIT THAT GENERATES SOFT SWITCHING STRESS ON THE MCT

During the circuit operating cycle inductor L1 and capacitor C1 ring causing current to flow through diode D2. MCT Q2 can be gated OFF during the oscillation while diode D2 is conducting, achieving soft switching. As the current tries to reverse both diode D2 and MCT Q2 block. If the conduction time of diode D2 has been longer than the recombination time of the MCT (<2 $\mu$ s) only displacement current will flow during the voltage increase across the MCT resulting in low switching loss. However, if the conduction time of diode D2 is <2 $\mu$ s, the MCT will not be fully recovered when forward voltage appears across the MCT. The remainder of the recombination tail current will flow, resulting in a small to moderate switching loss. In addition, since the MCT is not fully recovered, the turn-on voltage spike (discussed in section 6.2.3) will be reduced.

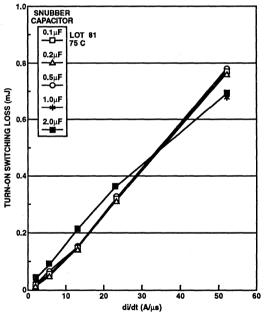
#### 6.2.3 Parallel Capacitor

In the circuit in Figure 6.2.1 capacitor C1 is in parallel with MCT Q1. Soft switching occurs in MCT Q1 when the capacitor voltage is near zero at the time of switching. The ideal



soft switched turn-on is degraded by the need for a small charge to flow into the MCT before it can switch ON. This will result in a voltage spike occuring across the MCT prior to turn-on. The curves in Figure 6.2.2 enable estimating the magnitude of this turn-on voltage spike. The curves show turn-on spike voltage as a function of current di/dt flowing into the parallel combination of capacitor and MCT. The test conditions duplicate circuit operation by having the MCT gated ON prior to becoming forward biased. These curves indicate that a turn-on voltage spike of several volts should be expected when switching 1kH resonant current increasing ing to several 10% of volts at 100kH.

When the MCT switches ON it discharges the capacitor resulting in a power loss. The curve in Figure 6.2.3 shows the value of MCT switching loss as a function of current di/dt flowing into the parallel combination of capacitor and MCT. The MCT loss results from MCT current flow prior to reaching peak voltage on the capacitor plus discharge of the capacitor.



#### FIGURE 6.2.3. SNUBBERED TURN-ON ENERGY LOSS IN MCT vs di/dt (TYPICAL)

The parallel capacitor snubbers the MCT during turn-off. This allows circuit current to transfer from the MCT into the capacitor slowing the increase in voltage across the paralleled MCT and capacitor combination. As a result switching losses in the MCT are reduced as discussed in section 6.1.1. An upper bound of MCT turn-off switching loss can be estimated using the curves in Figure 6.1.3 for the same size capacitor.

#### 6.2.4 MCT Dynamic Breakdown Voltage

Off-state DC blocking voltage of the P-type MCT is reduced by the presence of carriers within the device. When the MCT is blocking voltage, carriers can be present due to a) unrecombined carriers remaining in the turn-off recombination tail, b) displacement current from dv/dt and c) thermal generation current. Figure 6.2.4 shows the effect of a linear dv/dt ramp from zero voltage at +150°C on reducing DC blocking voltage. If your blocking voltage trajectory is less stringent, for example, sinewave or exponential, then it is appropriate to add some B.V. correction. This is discussed more fully below for dv/dt's that are essentially sinewaves.

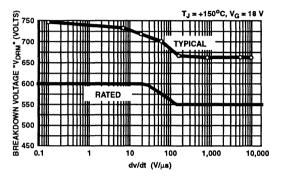
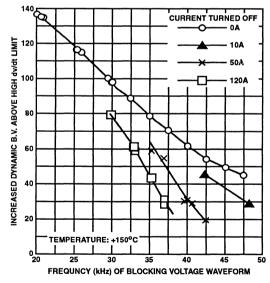


FIGURE 6.2.4. BLOCKING VOLTAGE vs dv/dt



#### FIGURE 6.2.5. TYPICAL 75P60 600V P-MCT B. V. INCREASE ABOVE HIGH dv/dt LIMIT DUE TO "EASIER" SINEWAVE VOLTAGE dv/dt

In some circuits the MCT is paralled by the resonating capacitor. When the MCT is turned-off the voltage will typically ring up across the MCT. It might be expected that the peak MCT voltage could safely approach the DC blocking voltage since dv/dt goes to zero at the voltage peak. However, since the internal carriers have a finite lifetime the voltage blocking capability becomes a function of current turned-off and sinewave pulse width. The curves in Figure 6.2.5 show how blocking voltage inceases above the high dv/dt limit of Figure 6.2.4 for decreasing resonant frequency. Because of the current that can be remaining from the turnoff recombination tail, we have chosen to show curves and data for turn-off currents from zero to 120A, the peak rated turn-off capability of the 75P60 600V P-MCT.

In Figure 6.2.5 an MCT operated at +150°C junction temperature in which no current had to be turned off, is seen to have a dynamic breakdown voltage that increases from Figure 6.5.4's 550 volts at very high frequency to about 600 volts at 45KHz and 685 volts at 20KHz. At the other extreme the same MCT, after turning off 120A, has the same 550 volt breakdown voltage at very high frequency, a 600 volt breakdown voltage at 34KHz and a projected 670 volt breakdown voltage at 20KHz.

References - Section 9 papers 16, 28, 33, 35, 39

## 6.3.0 SCR Circuits

The MCT shares high surge current capability of the SCR and therefore is the ideal power switch for many thyristor applications . In addition the MCT has other superior characteristics for thyristor applications. The MCT is fabricated with thousands of turn-on cells using LSI fine geometry. This results in a device that can switch on in less than 100ns and will withstand current rise in excess of several thousand A/us with peak current in excess of several thousand amperes. The high density of internal off-cells enables the MCT to turn off and block voltage essentially instantly. In addition the off-FETS prevent false dv/dt triggering to greater than 10,000 V/µs at +150°C operation.

Some circuit applications can effectively utilize the surge current capability of the MCT. For example, MCTs have been used to switch large capacitor banks for the purpose of generating high peak power pulses. In other applications some inverters use an auxiliary MCT to resonantly transfer load current between the main power switches of a bridge leg. Here the auxiliary MCT carries about 1.5X load current for a few microseconds during the resonant pulse. A single MCT can commutate a much higher current rated power switch.

The curve in Figure 6.3.1A shows MCT voltage drop vs current up to 2000 amperes. This data was obtained by pulsing the MCT with half sinewaves of current and measuring voltage at the current peak to avoid inductive errors. The upper current limit of the pulse test was controlled by the range of our current sensor. Note in the lower curves the good correlation with data obtained from the 400 ampere pulse curve tracer. This data was used to estimate surge current withstand capability shown in Figure 6.3.1B.

The curve in Figure 6.3.1B provides guidance in estimating allowable surge current pulses. This curve is based on a +60°C adiabatic junction temperature rise. From thyristor technology it has been established that repeated surge NOTES

pulses produce micro cracks in the device die that propagate with repeated pulses to ultimately cause failure. The table in Figure 6.3.1B provides insight in estimating the number of surge pulses which will likely produce failure.

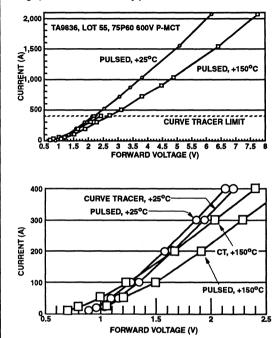


FIGURE 6.3.1A. COMPARISON OF CURVE TRACER AND PULSE VF DATA

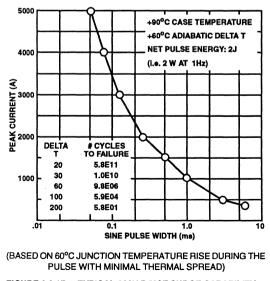


FIGURE 6.3.1B TYPICAL 600V P-MCT SURGE CAPABILITY

Our forward voltage drop pulse tester was also used to observe higher peak currents and very high di/dt's. Failures were observed after several pulses for 4 75P60 P-MCTs as shown below:

- a) Die 48 : lpk=4795A di/dt=6557A/µs
- b) Die 50 : lpk=5328A di/dt=6875A/µs
- c) Die 54 : Ipk=5650A di/dt=7377A/µs
- d) Die 55 : Ipk=5902A di/dt=8338A/µs

Although this might suggest that the allowable di/dt can be increased above the 2000A and  $2000A/\mu s$  of the 75P60 600V P-MCT this does NOT indicate that all devices will survive higher than rated di/dt and surge current.

#### 6.3.1 DC Circuit Breaker

A solid state DC circuit breaker is another application which can utilize the surge current capability and fast recovery of the MCT. In addition the control logic can be implemented using the general purpose custom MCT driver IC described in section 5.4.1. A 75 ampere instantaneous trip DC circuit breaker with 1000A interrupt capability will be described to illustrate the features and capability of the MCT driver IC and MCTs. This application utilizes developmental N-type MCTs fabricated at Harris Power R&D center (see section 8 for information on "What's ahead for MCTs"). These N-type MCTs exhibited only 10A of gated loff capability. This application could be as effectively implemented with the commercial P-type MCT. Its lower SOA capability compared to the N-type device would not negatively impact the application. It would, however, be necessary to slightly modify the circuit to accept opposite polarities of the P-type device.

Circuit breakers must be able to momentarily carry up to 10X to 20X rated current to handle inrush current from motor and lamp loads, for example. The N-type MCT used for this breaker application was similiar in conduction capability to the 75 ampere 75P60 MCT. These MCTs can easily carry surge current of 10X steady state rating. While the N-type MCT turn-off was limited to only 10 amperes, a second N-type MCT was used in an LC pulse circuit to commutate current in the first MCT. With this arrangement the breaker is able to interrupt fault current over 10X rated current. Of course the commutation circuit can be triggered to interrupt lower values of current. Many breakers have an inverse current/time trip characteristic which allows these momentary inrush currents to flow without tripping the breaker. That feature could be added to the instantaneous breaker. In the circuit to be described, the trip current level can be adjusted from 0.1X to over 10X steady state rated current.

Figure 6.3.2 shows the power circuit for the DC instant trip breaker. MCT Q1 carries the load current. MCT Q2, capacitor C1 and inductor L1 form the commutating circuit. The commutating capacitor C1 is maintained charged by the isolated power supply. When excess current is sensed in the load shunt the auxiliary MCT Q2 is gated on. The commutating current pulse flows from C1 through Q2, D1, and L1. During the time that diode D1 is conducting the main MCT Q1 is reversed biased. During this interval it is gated OFF. As the commutating current decreases voltage will increase

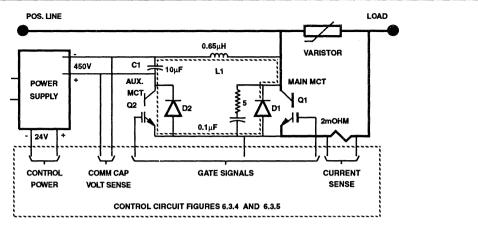


FIGURE 6.3.2. POWER CIRCUIT OF DC INSTANT TRIP BREAKER

across MCT Q1 until reactive load energy is transfered into the varistor. With this circuit arrangement the MCT can carry steady state current up to its thermal rating (~75A) and interrupt fault currents up to about 1000 amps. Because the MCT recovers within a few  $\mu$ s the commutating current pulse can be short, minimizing the size of the commutating capacitor. The auxiliary MCT Q2 switches the 1700A peak commutating current pulse. The MCTs are always gated OFF when they are reverse biased or carrying very low current.

Figure 6.3.3 shows a block diagram of the control circuit. Three signals (fault current, close command, commutation voltage) are processed to gate the main and auxiliary MCTs. Three LED indicators provide status indication.

The MCTs are arranged to share a common anode connection allowing the driver IC's to be electrically interconnected as shown in Figure 6.3.4. All of the active circuits needed for the instantaneous trip breaker are

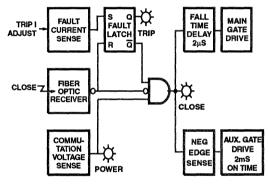
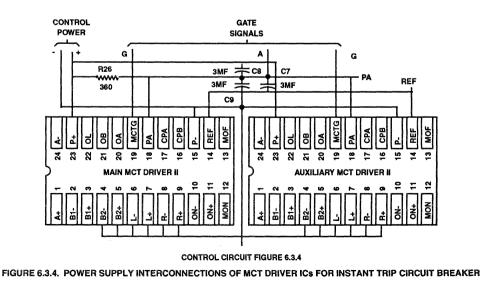


FIGURE 6.3.3. BLOCK DIAGRAM OF DC INSTANT TRIP BREAKER CONTROL





Applications

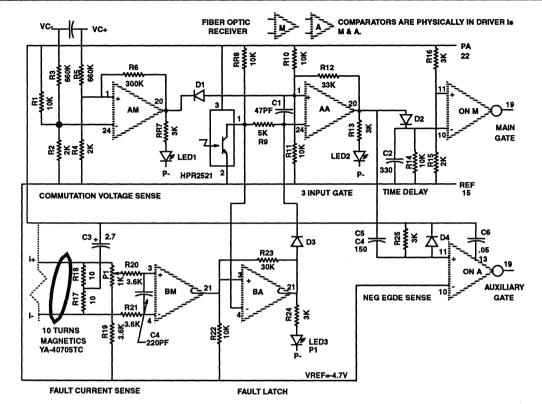
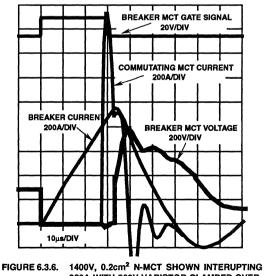


FIGURE 6.3.5. CONTROL CIRCUIT OF INSTANT TRIP BREAKER

implemented using the functions in two of the driver IC's described in section 5.4.1. Details of these control circuits are shown in Figure 6.3.5. Note that the external control circuits operate from the -4.7V reference. The Commutation Voltage Sense circuit insures that the commutation capacitor is charged to >500V before allowing the breaker to close. The Fault Current Sense circuit uses a 0.001 ohm shunt for sensing load current. The RLC filter reduces common mode noise enabling detection of the low level current signal. The OPEN/CLOSE command signal is coupled to the breaker through fiber optics. The fiber optic receiver is directly powered from the -4.7V bus. Two comparator circuits provide the latch function and the 3 input gate function. LED's are driven by the comparator outputs to show breaker status. The two ON-channels provide gate signals for the two MCTs. While this breaker provides instantaneous trip on detecting over current, additional circuits could be added to provide an inverse current-time trip response.

The waveforms in Figure 6.3.6 show operation of the breaker with an inductive load. When the breaker is closed its voltage drops to approximately 1.5V and the current increases linearly. When the load current reaches 800A, the commutating circuit is gated to produce a 1700A commutating current



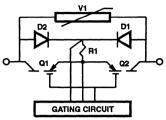
920A WITH 500V VARISTOR CLAMPED OVER-SHOOT OF 300V BUS

pulse. The main MCT is gated OFF after a 2.5µs delay which insures that the commutating current will exceed the load current thereby reverse biasing the main MCT. When the commutating current becomes less than the load current, the main MCT blocks voltage and the load current decreases as inductive energy is transfered to the varistor clamp.

The particular usefulness of this driver IC lies in simplifying the implementation of control circuits that can be combined with the gate signal which is ohmically connected to the MCT. While MCTs have turn-off capability they are nearly ideal thyristors and can be used to great advantage in thyristor circuits.

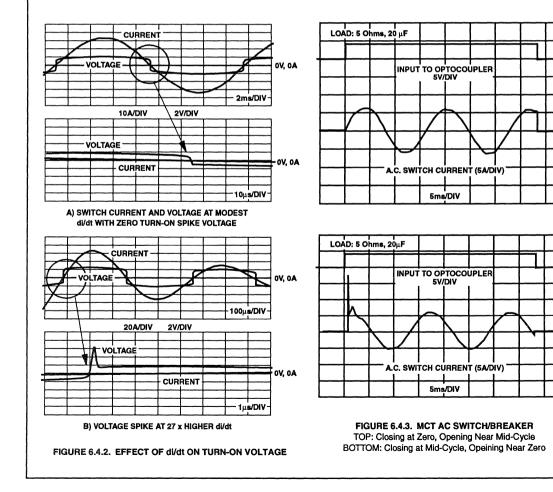
## 6.4.0 AC Switch Circuits

The reverse blocking voltage rating for the MCT is 5 volts. Thus it is necessary to utilize a series connected diode to provide reverse blocking voltage capability. The circuit in Figure 6.4.1 shows how two MCTs and two diodes can be arranged to form an AC switch function. In this arrangement a single drive circuit can be used to gate both MCTs. If it is desired to sense current through the switch, resistor R1 provides a rectified current signal that can be used for indication and/or control of the switch.





In most circuits the load being switched will be inductive. Thus some type of snubber may be necessary to control overshoot voltage which is developed when the MCTs are gated OFF. If the MCTs are gated OFF only at current zero, then the snubber may not be needed. When the switch is ON and the current goes through zero, a turn-on transient volt-



8

age develops across the switch as discussed in section 6.2.3. The waveforms in Figure 6.4.2 illustrate this turn-on transient for two different values of di/dt at current zero crossing. When the switch is used to switch low frequency current (60Hz for example), the turn-on transient voltage is small and probably not of consequence.

When the switch is used with non-unity power factor loads current surges may occur. The waveforms in Figure 6.4.3 show a leading power factor ( $20\mu$ F/5 ohm) load being switched. When closed at voltage zero crossing (top waveform) no transient occurs. However, when closed mid-cycle (lower waveform) a relatively large inrush current occurs. Thus it is possible with some sensing to close the switch at voltage zero to eliminate leading power factor current and to open the switch at current zero to eliminate lagging power factor voltage transients.

When the switch is part of a static circuit breaker it can be closed at voltage zero crossing; however, the control circuit must typically allow normal load inrush current to flow without tripping. When a fault current is detected the switch can be opened rapidly, limiting fault current, but requiring the switch to have I-off capability and inductive energy absorbtion capability (varistor). If the anticipated fault current does not exceed the surge rating (1000's of amps per MCT) of the static switch then interruption can be delayed to current zero crossing, minimizing the need for I-off capability and inductive energy absorbtion capability.

#### 6.5.0 Complementary Circuits

The 75P60 MCT is a P-type device. As such it has terminal polarities oppposite to N-type devices. Therefore, the opportunity exists to use the P-MCT in combination with N-type power devices such as N-IGBTs or N-FETs. The P-MCT provides superior current rating, speed and SOA compared to P-IGBTs, for example. While N and P devices have different characteristics their use in combination provides certain advantages.

Figure 6.5.1 illustrates an AC switch circuit using a P-MCT and an N-IGBT. Resistor R1 provides a single current signal to the gate circuit, should it be required to initiate or inhibit switch operation. The varistor V1 provides a means of limiting transient voltage across the opening switch. Figure 6.5.2 illustrates a DC bridge leg using a P-MCT and N-IGBT. This combination allows the use of a single gate circuit and power supply for each bridge leg. The gate circuit must provide appropriate gating delays to avoid short circuit current through the two power devices. Resistor R1 provides a single current signal to the gate circuit, should it be required to initiate or inhibit switch operation.

Hopefully, it will not be too long before N-MCTs are also ready for the market.

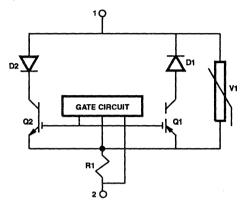


FIGURE 6.5.1. AC SWITCH USING P-MCT AND N-IGBT

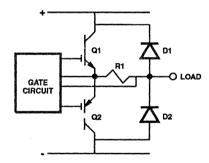


FIGURE 6.5.2. DC BRIDGE LEG USNG P-MCT AND N-IGBT

# **Comparison on MCT and IGBT**

How does the MCT compare to other Power Switches? Where is best used? This chapter provides some general comparisons. The particular requirements of a specific circuit may heavily influence the comparison in any application.

Both IGBTs and MCTs are insulated gate, field controlled switching devices with junction temperature ratings of +150°C. Comparison of the IGBT and MCT is most pertinent as both are merged bipolar/MOS structures and are applicable to power switching circuits requiring 600 Volts or higher Switch ratings. Both are useful at higher switching frequency than is generally practical with power darlingtons. By contrast, the characteristics or Power MOS transistors (majority carrier devices) sharply differentiate their preferred applications.

In high power circuits the importance of efficiency can be most critical. While efficiency is important in minimizing the cost of energy, in high power circuits the removal of heat from only a few points of efficiency loss has a significant impact on the size and nature of the system packaging. Conduction and switching losses are therefore the first point of comparison.

## **Conduction Voltage Drop**

The single most prominent feature of the MCT is that of low conduction drop, one third to one half that of the IGBT. This is illustrated in Figure 2.0.2 and Figure 2.0.3. Furthermore, the MCT conduction drop is diode like, increasing only modestly at very high peak currents. Use in circuits with high peak currents will not significantly worsen the average conduction loss. Because the MCT is a double injection device (with both N and P emitters), conduction drop does not increase as rapidly with the blocking voltage rating as with IGBTs. As MOS gated switches are developed above 1000 Volts, MCT technology will be even more advantageous.

The conduction loss (Rdson) of Power MOS transistors is an exponential function of the blocking voltage rating. At the 600 Volt level, the conduction drop per unit area of silicon is more than a factor of ten higher than the MCT. High voltage MOS transistors are competitive only in low power applications. However, Power MOS transistors can offer comparatively low conduction losses in lower voltage systems. If voltage drop is desirable at any cost, it is possible to operate Power MOS transistors at very low current density at less than the junction voltage drop of an MCT.

## Switching - Turn ON

Turn on in the MCT is initiated by the gate signal but is completed regeneratively as in an SCR. The MCT turn on is fast and handles high di/dt and peak current with low turn on loss. The recommended gate turn on drive is stiff to ensure all cells share the turn on power loss uniformly. Turn on in IGBTs is often intentionally slowed to control the reverse recovery of the free wheeling diode common to inductive switching circuits. The IGBT can be used to limit high peak recovery current in the diode, but at a sacrifice in turn on speed and loss. With the MCT, turn on voltage drop is not drive circuit adjustable. If reduction in rectifier peak recovery current is required, small saturating inductors may be used in the recovery circuit.

Turn on in the MOS transistor can be so much faster than for either the IGBT or the MCT that in comparable applications, MOS transistor switching losses would be negligible compared to conduction loss.

## Switching - Turn OFF

The best of today's IGBTs can provide faster switching and lower loss per switch cycle than the P MCT, roughly by a factor of two, in clamped inductive switch circuits. Power MOS transistor turn off loss is the lowest among the three devices by a large margin.

## **Total Losses**

From the above, it is clear that the device choice for lowest total loss is dependent on the relative proportion of conduction to turn off loss in the circuit. Some general guidelines are indicated in the section below on Applications.

## Turn Off Safe Operating Voltage (SOA)

When turning off an inductive load, a switch circuit must sustain a voltage higher than the load driving voltage. Left to itself, the switch must sustain this voltage while conducting full current. The turn off safe operating area describes a locus of maximum permissible combinations of voltage and current across the switch during turn off which will not cause improper operation of the switch. For the P MCT, the full switching current is sustainable at 50% to 60% of the breakdown voltage rating, as are lower currents at higher percentages of breakdown voltage. Capacitive snubbers can be used to shape the combination of current and voltage seen by the MCT at switching voltages above 50% BV.

The IGBT provides better turn off Safe Operating Area than the P Type MCT. IGBTs are generally rated for switching at 80% of the static blocking device rating.

## Applications

The resonant, soft switching, or zero current switching circuit configurations most often offer the lowest overall system loss. As these circuits avoid or minimize switch turn off loss, but do usually involve higher peak switch currents, the MCT will be the preferred device in such circuits, at any frequency. For instance, MCTs have been reported in the literature operating 8

at 80KHz switching rate in 10KW inverters in this class of circuit. In these circuits turn off SOA is not a significant requirement.

Active inductive switching from full current, the so called "Hard Switch" or PWM Circuits, may favor the IGBT, particularly at switching frequencies above 10KHz. In these circuits the lower switching loss of the IGBT can outweigh the lower conduction loss of the MCT.

In PWM circuits, inductive switching usually involves clamping the inductive voltage rise to some sink, such as the DC Bus. The higher Turn Off SOA voltage of the 600 Volt IGBT, 480 Volts, may make it the preferred solution for DC bus voltages above 300 Volts to 400 Volts. With P Type MCTs, & higher voltage rated device or capacitive snubbers are reguired to allow operation at a comparable bus voltage.

The IGBT can provide fault current limiting for a few microseconds in PWM circuits, allowing for the orderly shut down of the circuit from the gate drive. For the MCT, no such mechanism is available. In resonant circuits, MCT shut down can occur at the next current zero, or low current point.

Pulse discharge circuits will generally favor the MCT, due to fast turn on speed and high peak current capability at low voltage drop.

Power MOS transistors may be the only practical power switch at a switching frequency above 50KHz in hard switch circuits or 100KHz in soft switch circuits.

## **Outlook, What's Ahead for MCTs**

## 8.0 Future MCT Developments

#### 8.1 More "Generation 1" P-MCTs

The first Harris MCT products are P-MCTs of 600V and, shortly, 1000V in a die size that can be packaged in a TO-218 or TO-247 5-pin plastic package. This die size results in about a 75A RMS rating and about a 120A turn-off current capability at  $+150^{\circ}$ C. Harris plans call for an MCT of about half this size and, given enough interest, an even smaller die size that can be packaged in a TO-220 package.

Development efforts include wider ranges of voltage rating first asymmetric MCTs down to perhaps as low as 200V and as high as 1600V and, later, high voltage MCTs for what are now typically thyristor and GTO circuits. Such high voltage P-MCTs have been described in several papers including reference 8.1. Figure 8.1.1 and Figure 8.1.2 are reproduced from that paper to illustrate our initial capability (in R&D devices) of 2500V.

### 8.2 Generation 2 P-MCTs

Generation 2 P-MCTs have been made at Harris' Power R&D Center that push the present P-MCT twice as close to the diode in the physics-dominated trade-off between breakdown voltage vs forward drop vs switching speed. Details of design and process change are, of course, proprietary but the bottom line is that one can expect a generation 2 P-MCT to have an additional 100 volts in SOA and to have between 2 and 3 times lower turn-off losses. Figure 8.2.1 shows some recent turn-off energy measurements on an R&D generation 2 P-MCT.

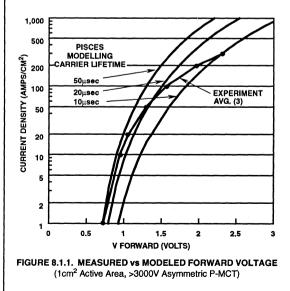
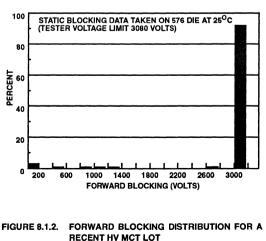


Figure 8.2.2 is a snapshot comparing switching losses at +75°C and +150°C for snubbers from 0µF to 1µF and currents to 120A for a typical generation 1 600V P-MCT compared to an early generation 2 600V P-MCT lot of the same breakdown voltage and similar die size. Unsnubbered and at very low snubber value the improvement is more than a factor of 2. At modest snubber value (0.05µF an 0.1µF) it is closer to a factor of 4. For larger snubbers and, obviously, for most resonant circuits the improvement is even greater.

### 8.3 N-MCT Development

N-MCT versions of almost all of our P-MCTs have been fabricated at Harris Power R&D to analyze the potential for a commercial product. At this time we have produced and delivered N-MCTs for various applications, all of which required little or no turn-off capability. This has included 1400V devices for 1000A, 1000V capacitor discharge circuits and 600V devices for zero current soft switched circuits with peak currents of about 800A.

As our P-MCTs have increased in turn-off capability from one or two hundred amperes per centimeter squared to more than 400A/cm<sup>2</sup> our N-MCTs have kept pace at about 1/ 2 to 1/3 of that value and now can be rated at about 150A/ cm<sup>2</sup> in peak turn-off current density at +150°C. Note that with the MCTs low forward drop that this is less than the device's RMS current rating. This lack of peak turn-off capability has kept us from as aggressively pursuing the N-MCT.



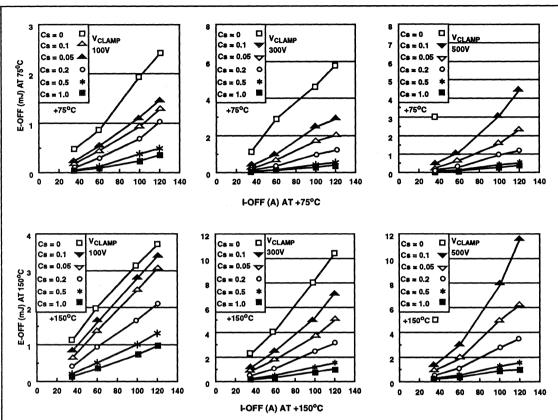


FIGURE 8.2.1. TYPICAL GENERATION 2 600V PMCT TURN-OFF ENERGY AS A FUNCTION OF SNUBBER CAP. AND CURRENT

However, as cell size and geometries become finer, turn-off capability will improve correspondingly and N-MCTs will be produced that, with their 2 times lower switching loss and 30% higher (more at high voltage) SOA, will displace P-MCTs and those N-IGBT's that our present P-MCTs cannot replace.

## 8.4 MCT Driver IC

In section 5 and section 6 an MCT driver IC was used to gate an MCT and, with some of its added functions, to implement an autonomous circuit breaker. The driver IC referred to was produced using a standard Harris process on that process' production line. From our own experience we have found that IC extremely valuable. Referring back to section 5, the driver IC has a voltage range of -12V to +35V with respect to the "A" terminal and has an output impedance in the neighborhood of 2 ohms. The inputs are all comparators with a wide dynamic range. The IC supports all types of OPTO-couplers both as receivers and senders and has a 4.7V regulated supply to power IC's if more "smarts" are necessary at the device. There is an on-board charge pump and an on-board zener that, within limits, allows one to power the IC using a dropping resistor from the MCT cath-

ode supply. Our IC also includes latched and unlatched channels as well as minimum on-time and minimum offtimes that can be set with external capacitors. Our present die is less than 200 mils on a side and for full function needs 24 pins. As just a driver, however, 6 or 7 pins are sufficient and we have looked at some MCT driver ICs in 7 pin TO-218 packages.

## 8.5 MCT Modules

MCT modules of up to 12 parallel devices, each of 4 cm2 active area, have been built and tested for various development contracts. Currently Harris is assessing 4 MCT & 2 diode and 6 MCT modules in a compact plastic module as well as industry outline modules in various current ratings. Harris will consider providing similar modules to other customers.

Although MCTs parallel reasonably well, their low forward drop and high current capability require one to be careful in selecting devices of the same forward drop and similar turnoff time and then to be very symmetric with stray impedance.

Some of our development modules include gate drive circuitry.

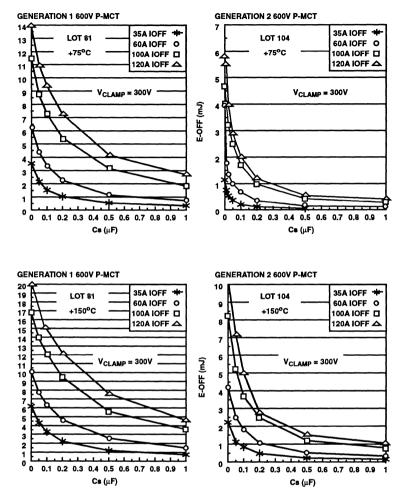


FIGURE 8.2.2. GENERATION 2 600V PMCT TURN-OFF IMPROVEMENT

## 8.6 Development Timetable

In summary, P-MCTs will also improve in switching capability in both SOA and turn-off time, bettering N-IGBTs in speed and turn-off loss and being at less of a disadvantage in hard switched SOA.

N-MCTs will begin to become available but with about half the peak turn-off current capability of P-MCTs. However, both P-MCTs and N-MCTs will be improving in that characteristic as improved process capability allows denser off-FET channel structure.

MCTs will go to high currents paralleled in modules of up to hundreds of amperes. These modules will first be dumb modules but will later contain some smarts with driver ICs such as that described in section 8.4 above. The timetable for these developments depends on resources.

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# MCT Reference List and Bibliography

The following is a list of references which is applicable to MCT technology. It is listed chronologically and a table sorting the references by topic is provided at the end. A reference may appear in more than one topic category, not all topics have references associated with them to date.

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TOPICS	REFERENCE #
Device Physics & Design	1, 2, 3, 4, 5, 6, 7, 8, 9, 11, 15, 23, 24, 25, 26, 27, 29, 30, 31, 32, 39
Hard Switching Applica- tions	12
Soft Switching Applications	16, 28, 33, 35, 39
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APPLICATION NOTES

# Harris Semiconductor



No. AN7244.2 September 1993

Harris Power MOSFETs

# **UNDERSTANDING POWER MOSFETs**

Author: Tom McNulty

Power MOSFETs (Metal Oxide Semiconductor, Field Effect Transistors) differ from bipolar transistors in operating principles, specifications, and performance. In fact, the performance characteristics of MOSFETs are generally superior to those of bipolar transistors: significantly faster switching time, simpler drive circuitry, the absence of a second-breakdown failure mechanism, the ability to be paralleled, and stable gain and response time over a wide temperature range. This note provides a basic explanation of general MOSFET characteristics, and a more thorough discussion of structure, thermal characteristics, gate parameters, operating frequency, output characteristics, and drive requirements.

### **General Characteristics**

A conventional n-p-n bipolar power transistor is a currentdriven device whose three terminals (base, emitter, and collector) are connected to the body by silicon contacts. Bipolar transistors are described as minority-carrier devices in which injected minority carriers recombine with majority carriers. A drawback of recombination is that it limits the device's operating speed. And because of its current-driven base-emitter input, a bipolar transistor present a low-impedance load to its driving circuit. In most power circuits, this low-impedance input requires somewhat complex drive circuitry.

By contrast, a power MOSFET is a voltage-driven device whose gate terminal, Figure 1(a), is electrically isolated from its silicon body by a thin layer of silicon dioxide (SiO2). As a majority-carrier semiconductor, the MOSFET operates at much higher speed than its bipolar counterpart because there is no charge-storage mechanism. A positive voltage applied to the gate of an n-type MOSFET creates an electric field in the channel region beneath the gate; that is, the electric charge on the gate causes the p-region beneath the gate to convert to an n-type region, as shown in Figure 1(b). This conversion, called the surface-inversion phenomenon, allows current to flow between the drain and source through an n-type material. In effect, the MOSFET ceases to be an n-p-n device when in this state. The region between the drain and source can be represented as a resistor, although it does not behave linearly, as a conventional resistor would. Because of this surface-inversion phenomenon, then, the operation of a MOSFET is entirely different from that of a bipolar transistor, which always retain its n-p-n characteristic.

By virtue of its electrically-isolated gate. a MOSFET is described as a high-input impedance, voltage-controlled device, whereas a bipolar transistor is a low-input-impedance, current-controlled device. As a majority-carrier semiconductor, a MOSFET stores no charge, and so can switch faster than a bipolar device. Majority-carrier semiconductors also tend to slow down as temperature increases. This effect, brought about by another phenomenon called carrier mobility (where mobility is a term that defines the average velocity of a carrier in terms of the electrical field imposed on it) makes a MOSFET more resistive at elevated temperatures, and much more immune to the thermalrunaway problem experienced by bipolar devices.

A useful by-product of the MOSFET process is the internal parasitic diode formed between source and drain, Figure 1(c). (There is no equivalent for this diode in a bipolar transistor other than in a bipolar darlington transistor.) Its characteristics make it useful as a clamp diode in inductiveload switching.

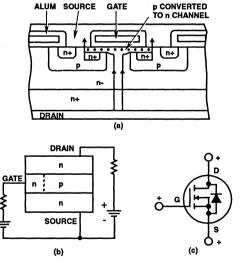


FIGURE 1. THE MOSFET, A VOLTAGE-CONTROLLED DEVICE WITH AN ELECTRICALLY ISOLATED GATE, USES MAJORITY CARRIERS TO MOVE CURRENT FROM SOURCE TO DRAIN (A). THE KEY TO MOSFET OPERATION IS THE CREATION OF THE INVER-SION CHANNEL BENEATH THE GATE WHEN AN ELECTRIC CHARGE IS APPLIED TO THE GATE (B). BECAUSE OF THE MOSFET'S CONSTRUC-TION, AN INTEGRAL DIODE IS FORMED ON THE DEVICE (C), AND THE DESIGNER CAN USE THIS DIODE FOR A NUMBER OF CIRCUIT FUNCTIONS.

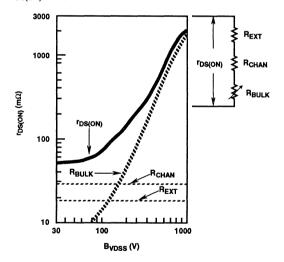
### Structure

Harris Power MOSFETs are manufactured using a vertical double-diffused process, called VDMOS or simply DMOS. A DMOS MOSFET is a single silicon chip structured with a large number of closely packed, hexagonal cells. The number of cell varies according to the dimensions of the chip. For example, a 120-mil<sup>2</sup> chip contains about 5,000 cells; a 240-mil<sup>2</sup> chip has more than 25,000 cells.

One of the aims of multiple-cells construction is to minimize the MOSFET parameter  $r_{DS(ON)}$ , or resistance from drain to source, when the device is in the on-state. When  $r_{DS(ON)}$  is minimized, the device provides superior power-switching performance because the voltage drop from drain to source is also minimized for a given value of drain-to-source current.

Since the path between drain and source is essentially resistive, because of the surface-inversion phenomenon, each cell in the device can be assumed to contribute an amount,  $R_N$ , to the total resistance. An individual cell has a fairly low resistance, but to minimize  $r_{DS(ON)}$ , it is necessary to put a large number of cells in parallel on a chip. In general, therefore, the greater the number of paralleled cells on a chip, the lower its  $r_{DS(ON)}$  value:

 $r_{DS(ON)} = R_N/N$ , where N is the number of cells.



#### FIGURE 2. THE DRAIN-TO-SOURCE RESISTANCE (r<sub>DS(ON)</sub> OF A MOSFET IS NOT ONE BUT THREE SEPARATE RESISTANCE COMPONENTS)

# TABLE 1. PERCENTAGE RESISTANCE COMPONENTS FOR A TYPICAL CHIP

B <sub>VDSS</sub>	40V	150V	500V
R <sub>CHANNEL</sub>	50%	23%	2.4%
R <sub>BULK</sub>	35%	70%	97%
REXTERNAL	15%	7%	<1%

In reality,  $r_{DS(ON)}$  is composed of three separate resistances. Figure 2 shows a curve of the three resistive components for a single cell and their contributions to the overall value of  $r_{DS(ON)}$ . The value of  $r_{DS(ON)}$  at any point of the curve is found by adding the values of the three components at that point:

# $r_{DS(ON)} = R_{BULK} + R_{CHAN} + R_{EXT}$

where R<sub>CHAN</sub> represents the resistance of the channel beneath the gate, and R<sub>EXT</sub> includes all resistances resulting from the substrate, solder connections, leads, and the package. R<sub>BULK</sub> represents the resistance resulting from the narrow neck of n material between the two players, as shown in Figure 1(a), plus the resistance of the current path below the neck and through the body of the device to the drain.

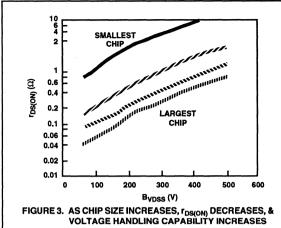
Note in Figure 2 that R<sub>CHAN</sub> and R<sub>EXT</sub> are completely independent of voltage, while R<sub>BULK</sub> is highly dependent on applied voltage. Note also that below about 150 volts,  $r_{DS(ON)}$  is dominated by the sum of R<sub>CHAN</sub> and R<sub>EXT</sub>. Above 150 volts,  $r_{DS(ON)}$  is increasingly dominated by R<sub>BULK</sub>. Table 1 gives a percentage breakdown of the contribution of each resistance for three values of voltage.

Two conclusions, inherent consequences of the laws of semiconductor physics, and valid for any DMOS device, can be drawn from the preceding discussion: First,  $r_{DS(ON)}$  obviously increases with increasing breakdown-voltage capability of a MOSFET. Second, minimum  $r_{DS(ON)}$  performance must be sacrificed if the MOSFET must withstand ever-higher breakdown voltages.

The significance of R<sub>BULK</sub> in devices with a high voltage capability is due to the fact that thick, lightly doped epi layers are required for the drain region in order to avoid producing high electric fields (and premature breakdown) within the device. And as the epi layers are made thicker and more resistive to support high voltages, the bulk component of resistance rapidly increases (see Figure 2) and begins to dominate the channel and external resistance. The r<sub>DS(ON)</sub> therefore, increases with increasing breakdown voltage capability, and low r<sub>DS(ON)</sub> must be sacrificed if the MOSFET is to withstand even higher breakdown voltages.

There is a way around these obstacles. The  $r_{DS(ON)}$  in Figure 2 holds only for a relatively small chip. Using a larger chip results in a lower value for  $r_{DS(ON)}$  because a large chip has more cells (See Figure 3). A larger chip also increases MOSFET breakdown voltage capability.

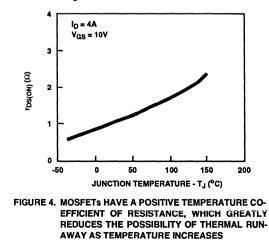
The penalty for using a larger chip, however, is an increase in cost, since chip size is a major cost factor. And because chip area increases exponentially, not linearly, with voltage, the additional cost can be substantial. For example, to obtain a given  $r_{DS(ON)}$  at a breakdown voltage twice as great as the original, the new chip requires an area four or five times larger than the original. Although the cost does not rise exponentially, it is substantially more than the original cost.



Effects of Temperature

The high operating temperatures of bipolar transistors area frequent cause of failure. The high temperatures are caused by hot-spotting, the tendency of current in a bipolar device to concentrate in areas around the emitter. Unchecked, this hot-spotting results in the mechanism of thermal runaway. and eventual destruction of the device. MOSFETs do not suffer this disadvantage because their current flow is in the form of majority carriers. The mobility of majority carriers (where, again, mobility is a term that defines the average velocity of a carrier in terms of the electrical field imposed on it) is temperature dependent in silicon: mobility decreases with increasing temperature. This inverse relationship dictates that the carriers slowdown as the chip gets hotter. In effect, the resistance of the silicon path is increased, which prevents the concentrations of current that lead to hot spots. In fact, if hot spots do attempt to form in a MOSFET, the local resistance increases and defocuses or spreads out the current, rerouting it to cooler portions of the chip.

Because of the character of its current flow, a MOSFET has a positive temperature coefficient of resistance, as shown by the curves of Figure 4.

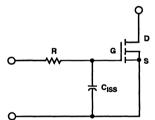


The positive temperature coefficient of resistance means that a MOSFET is inherently stable with temperature fluctuation, and provides its own protection against thermal runaway and second breakdown. Another benefit of this characteristic is that MOSFETs can be operated in parallel without fear that one device will rob current from the others. If any device begins to overheat, its resistance will increase, and its current will be directed away to cooler chips.

### **Gate Parameters**

To permit the flow of drain-to-source current in an n-type MOSFET, a positive voltage must be applied between the gate and source terminals. Since, as described above, the gate is electrically isolated from the body of the device, theoretically no current can flow from the driving source into the gate. In reality, however, a very small current, in the range of tens of nanoamperes, does flow, and is identified on data sheets as a leakage current, I<sub>GSS</sub>. Because the gate current is so small, the input impedance of a MOSFET is extremely high (in the megohm range) and, in fact, is largely capacitive rather than resistive (because of the isolation of the gate terminal).

Figure 5 illustrates the basic input circuit of a MOSFET. The elements are equivalent, rather than physical, resistance, R, and capacitance, C. The capacitance, called  $C_{ISS}$  on MOSFET data sheets, is a combination of the device's internal gate-to-source and gate-to-drain capacitance. The resistance, R, represents the resistance of the material in the gate circuit. Together, the equivalent R and C of the input circuit determine the upper frequency limit of MOSFET operation.



#### FIGURE 5. A MOSFET'S SWITCHING SPEED IS DETERMINED BY ITS INPUT RESISTANCE R AND ITS INPUT CAPACITANCE CISS

### **Operating Frequency**

Most DMOS processes develop the polysilicon gate structure rather than the older metal-gate type. If the resistance of the gate structure (R in Figure 5) is high, the switching time of the DMOS device is increased, thereby reducing its upper operating frequency. Compared to a metal gate, a polysilicon gate has a higher gate resistance. This property accounts for the frequent use of metal-gate MOSFET in high-frequency (greater than 20MHz) applications, and polysilicon-gate MOSFETs in higher-power but lower-frequency systems.

Since the frequency response of a MOSFET is controlled by the effective R and C of its gate terminal, a rough estimate can be made of the upper operating frequency from datasheet parameters. The resistive portion depends on the sheet resistance of the polysilicon-gate overlay structure, a value of approximately  $20W/\Box$ . But whereas the total R value is not found on datasheets, the C value ( $C_{ISS}$ ) is; it is recorded as both a maximum value and in graphical form as a function of drain-to-source voltage. The value of  $C_{ISS}$  is closely related to chip size; the larger the chip, the greater the value. Since the RC combination of the input circuit must be charged and discharged by the driving circuit, and since the capacitance dominates, larger chips will have slower switching times than smaller chips, and are, therefore, more useful in lower-frequency circuits. In general, the upper frequency limit of most power MOSFETs spans a fairly broad range, from 1MHz to 10MHz.

### **Output Characteristics**

Probably the most used MOSFET graphical data is the output characteristics or plot of drain-to-source voltage ( $V_{DS}$ ) as a function of drain-to-source current ( $I_D$ ). A typical characteristic, shown in Figure 6, gives the drain current that flows at various  $V_{DS}$  values as a function of the gate-to-source voltage (gs). The curve is divided into two regions: a linear region in which  $V_{DS}$  is small and drain current increases linearly with drain voltage, and a saturated region in which increasing drain voltage has no effect on drain current (the device acts as a constant-current source). The curve level at which the linear portion of the curve joins with the saturated portion is called the pinch-off region.

### **Drive Requirements**

When considering the  $V_{\rm GS}$  level required to operate a MOSFET, note, from Figure 6, that the device is not turned on (no drain current flows) unless  $V_{\rm GS}$  is greater than a certain level (called the threshold voltage). In other words, the threshold voltage must be exceeded before an appreciable increase in drain current can be expected. Generally  $V_{\rm GS}$  for many types of DMOS devices is at least 2V. This is an important consideration when selecting devices or designing circuits to drive a MOSFET gate: the gate-drive circuit must provide at least the threshold-voltage level, but preferably, a much higher one.

As Figure 6 shows, a MOSFET must be driven by a fairly high voltage, on the order of 10V, to ensure maximum saturated drain-current flow. However, integrated circuits, such as TTL types, cannot deliver the necessary voltage levels unless they are modified with external pull-up resistors. Even with a pull-up to 5V, a TTL driver cannot fully saturate most MOSFETs. Thus, TTL drivers are most suitable when the current to be switched is far less than the rated current of the MOSFET. CMOS ICs can run from supplies of IOV, and these devices are capable of driving a MOSFET into full saturation. On the other hand, a CMOS driver will not switch the MOSFET gate circuit as fast as a TTL driver. The best results, whether TTL or CMOS ICs provide the drive, are achieved when special buffering chips are inserted between the IC output and gate input to match the needs of the MOSFET gate.

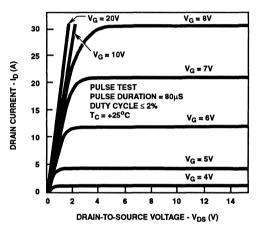


FIGURE 6. MOSFETS REQUIRE A HIGH INPUT VOLTAGE (AT LEAST 10V) IN ORDER TO DELIVER THEIR FULL RATED DRAIN CURRENT

# **Harris Semiconductor**



# No. AN7254.1 May 1992

# Harris Power MOSFETs

# SWITCHING WAVEFORMS OF THE L<sup>2</sup>FET: A 5 VOLT GATE-DRIVE POWER MOSFET

Author: C. Frank Wheatley, Jr. and Harold R. Ronan, Jr.

The switching waveforms of a newly announced series of power MOSFET devices called Logic Level FETs (L<sup>2</sup>FETs) and featuring a 5V gate drive are presented and contrasted with those of the more conventional 10V gate drive devices. A new method of characterizing MOSFET switching performance is discussed in which the MOSFET is treated as a vertical JFET driven in cascade from a low voltage lateral MOS. The 2:1 advantage in rise and fall time and the 4:1 reduction in switching "dynamic V<sub>(SAT)</sub>" dissipation with constant drive power of the L<sup>2</sup>FET over the 10V MOSFET are demonstrated and discussed

# Background

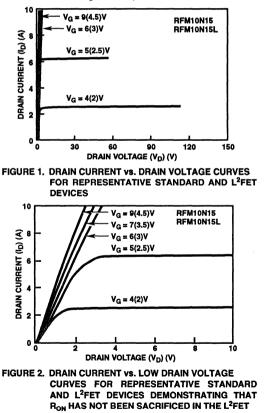
A new series of power MOSFET devices called Logic Level FETs, or L<sup>2</sup>FETs, is compatible with the 5V power supply used for logic circuitry. L<sup>2</sup>FETs retain the on resistance, drain current, and blocking voltage ratings of their 10V predecessors, but operate from a much less costly 5V supply.

The reduction in gate drive voltage is the result of halving the thickness of the gate insulator from the industry standard 100nm to 50nm (500Å). Since the surface inversion of the MOS channel is determined by the gate insulator voltage field, halving the insulator thickness halves the applied gate voltage without compromising drain characteristics.

The apparent conclusion from a study of the switching waveforms of the new device that halving the gate oxide thickness would double the gate capacitance and halve the switching speed does not prove true. Measurements demonstrate empirically a 2:1 increase in switching speed for the L<sup>2</sup>FET over its 100nm predecessor, where gate drive power is the same for both devices. The "dynamic V<sub>(SAT)</sub>" dissipation is lowered by a factor of four. The apparent anomalies are explained with the aid of a new method of switching characterization developed by treating the power MOSFET as a grounded gate, depletion mode, vertical JFET driven in cascade by a grounded source, enhancement mode, lateral MOS. The waveforms and switching characterization methods are described in detail below.

# $\mathsf{L}^2\mathsf{FET}$ Characteristics Compared to Standard Types - A Brief Review

Thirty-two different power MOSFETs of the L<sup>2</sup>FET structure have been announced. These devices were designed to be totally interchangeable with the standard power MOSFET with respect to output characteristics, while offering twice the gate sensitivity, as shown in Figures 1, 2, and 3, which are comparisons of the industry standard RFM10N15 with its Logic Level FET counterpart, the RFM10N15L. (Although the L suffix notation in the type number will ultimately be valid for the entire product matrix, the L<sup>2</sup>FET product currently available is limited to n-channel devices handling 200V or less, with 15A ratings or less.)



Figures 1 and 2 are plots of drain current versus drain voltage with gate voltage as the running parameter. The  $L^2$ FET gate voltage is in parenthesis. The low drain voltage curves of Figure 2 demonstrate that RON has not been sacrificed in the  $L^2$ FET. Figure 3 is the transfer characteristic comparison

for three different temperatures. The abscissa has two scales to reflect the different gate sensitivities; again, L values are in parenthesis. It is evident from the curve that:

- 1. The threshold voltage is scaled down by a factor of two for the L2FET.
- The threshold voltage temperature coefficient in mV/°C is scaled down.
- 3. The current level for zero temperature coefficient is unchanged.
- 4. The transconductance is scaled up by a factor of two.

All other L<sup>2</sup>FETs have similar relationships to their respective predecessors.

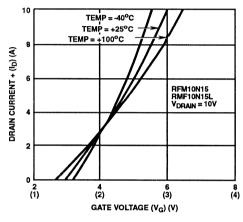


FIGURE 3. TRANSFER CHARACTERISTIC

# Switching Waveforms with Conventional Drive

The first concern when comparing devices with such a large difference of transfer sensitivity is one of "other things being equal". If the standard device is driven between zero and ten volts with an R<sub>G</sub> of 25Ω, impedance transformation dictates that the L<sup>2</sup>FET should be driven between zero and five volts with an R<sub>G</sub> of 6<sup>1</sup>/<sub>4</sub> Ω, thereby transforming open circuit voltage and short circuit current by factors of 2 (or <sup>1</sup>/<sub>2</sub>). With these parameters, either drive system will supply a peak R<sub>G</sub>, or generator dissipation, of one watt.

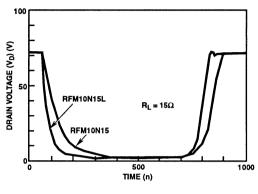
Figure 4 displays the drain voltage versus time of the RFM10N15 and the RFM10N15L when each is driven as described above with a 5A, 75V resistive load line. The time scale is 100ns per division. The table under the graph compares on delay time, rise time, off delay time, and fall time for each device. The times are measured in the normal manner, that is, involving the 10% and 90% points of the input voltage and output voltage waveforms.

Note that:

- 1. The rise and fall times are not symmetrical
- 2. The L<sup>2</sup>FET is faster

- 3. There is a "dynamic V(SAT)" type of behavior
- 4. The "dynamic  $V_{(SAT)}$  " is of a lesser amplitude for the  $L^2 \mbox{FET}$

These observations are discussed below.



ТҮРЕ	GATE DRIVE	R <sub>G</sub> (Ω)	t <sub>D(ON)</sub> (ns)	t <sub>(RISE)</sub> (ns)	t <sub>D(OFF)</sub> (ns)	t <sub>(FALL)</sub> (ns)
RFM10N15 (100nm)	0-10V	25	15	120	123	73
RFM10N15L (50nm)	0-5V	6.25	11	57	104	62

FIGURE 4. DRAIN VOLTAGE vs. TIME CURVES FOR REPRE-SENTATIVE STANDARD AND L<sup>2</sup>FET DEVICES

# Switching Waveforms with Constant Current Drive

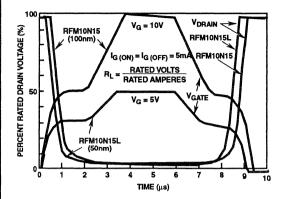
The power MOSFET is a current driven device during transitions due to the charging or discharging of capacitances. In actual applications, most drive circuits exhibit a first order approximation to a constant current where the voltage compliance is determined by ground potential or the drive circuit power supply voltage. The on current may not equal the off current; this situation is addressed below.

Figure 5 presents the curves for the RFM10N15 and RFM10N15L when each is driven from a current generator whose  $I_{G1} = I_{G2}$ , with gate voltage limits of zero and 10 or (5) volts. The drive current is kept the same for both devices in this case even though the  $L^2FET$  receives less drive power or energy. The value for  $I_{G1}$  and  $I_{G2}$  was chosen as 5mA; the time scale is 1µs/division.

### Note that:

- 1. The rise and fall times of a given device are the same with current drive.
- 2. The two devices have similar output waveforms in most regions.
- There is a persistent "dynamic V<sub>(SAT)</sub>" even at slow switching speeds.

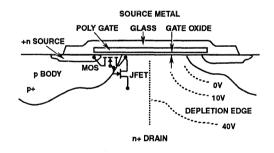
- 4. The "dynamic  $V_{\rm (SAT)}$ " curves are symmetrical during the low drain voltage portion of the turn on and turn off portion.
- 5. The "dynamic  $V_{(SAT)}$ " curves are lower in amplitude by a factor of approximately two for the L<sup>2</sup>FET.



#### FIGURE 5. CHARACTERIZATION CURVES FOR REPRESEN-TATIVE DEVICES DRIVEN FROM A CURRENT GENERATOR

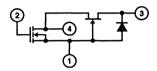
# Large Signal Equivalent Circuit of the MOSFET

If we are to understand the differences and similarities of the  $L^2FET$  relative to the conventional power MOSFET, the conventional power MOSFET must first be understood. Figure 6 shows a properly proportioned cross sectional view of the power MOSFET.



#### FIGURE 6. CROSS SECTION OF POWER MOSFET

When the drain voltage is very low and the gate is forward biased, an accumulation layer exists for the n- region beneath the gate. This layer may be thought of as serving the function of the drain for the lateral MOS. In addition, it serves as a source for a vertical depletion mode JFET. The gate of the JFET is formed by the body diffusion, particularly in the neck region. The JFET drain is the n+ region usually though of as being the MOSFET drain. This situation is shown in Figure 6, where the cross sectional view of the MOSFET is shown. The lateral MOS and the vertical JFET are schematically implied by the left half of Figure 6. The right half indicates the edge of the depletion width for several drain voltages. Note how the JFET pinches off, such that increased drain voltage is supported predominately by the JFET. This structure is schematically represented as shown in Figure 7. Note that the third quadrant diode is caused by the p-n junction associated with the gate and drain characteristic (common to all JFETs). A parasitic n-p-n transistor is not shown, nor is it discussed in this Note. Voltage node (4) is within the device, and is not precisely a single node, as represented.

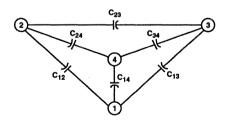


#### FIGURE 7. SCHEMATIC REPRESENTATION OF THE CROSS SECTION OF FIGURE 6

#### Interelectrode Capacitance

The equivalent circuit of Figure 7 contains four voltage nodes. Therefore, six capacitors will exist to couple these nodes. The switching waveforms are determined by these capacitors and the small signal equivalent circuit of the MOS and JFET. Of course, the MOS and JFET small signal equivalent circuits are nonlinear functions of voltage and current and invariant with frequency. Similarly, the capacitors are nonlinear with voltage and current.

Industry data sheets show three terminal characterization of this four node network at zero drain current. Under this condition, the transconductance and output resistance are zero and infinity for both the MOS and the JFET. This condition reduces the power MOSFET to the capacitor network of Figure 8, which may be replaced by three capacitors. Note that this situation is valid only when no MOSFET current flows.



# FIGURE 8. CAPACITOR NETWORK REPRESENTATION OF THE POWER MOSFET

When current does flow, node (4) of Figure 7 is a low impedance node due to the source follower characteristic of the JFET. Similarly, nodes (1) and (3) are generally low impedance nodes by virtue of the ground reference and the load resistance. Therefore, capacitive currents will usually be significant only to the input node, (2). Capacitors C<sub>12</sub>, C<sub>23</sub>, and C<sub>24</sub> are examined below over most of the switching regime when current is flowing.

# Gate to Source Capacitance, C12

When all of the die except the actual MOSFET cells are ignored, Figure 6 shows that the gate to source capacitance  $(C_{12})$  is that from the poly gate upward through the thick oxide to the source metal. In addition, there is a contribution from the poly gate to the n+ source through the thin gate oxide. Additionally a fringing capacitance exists at the edge of the polysil gate. These components of  $C_{12}$  are invariant with voltage and current. There is a fourth component from the poly gate to a region about half way along the MOS channel through the gate oxide. This component is actually distributed, and varies somewhat with current and voltage.

# Gate to Drain Capacitance, C23

Capacitor  $C_{23}$  exists only when no accumulation layer is present beneath the poly gate. Otherwise, the accumulation layer acts as an electrostatic shield. This layer exists whenever the drain voltage immediately beneath the gate oxide is essentially negative relative to the poly gate. In addition, the capacitive coupling from drain to gate diminishes greatly when the JFET is pinched off. Therefore,  $C_{23}$  exists for only a small range of drain voltage level is approached because the effective area of concern is closed off similarly to the aperture of a camera (for a hex cell).

# Gate to Internal Electrode Capacitance, C24

Capacitor C<sub>24</sub> is rather large for positive gate voltages. It is made up of that area between the poly gate and the accumulation layer, plus some of the area between the poly gate and the middle of the MOS channel. In both cases, the dielectric is the thin gate oxide. So long as the gate voltage is positive relative to the n- layer beneath the poly gate, the accumulation layer exists and C<sub>24</sub> is invariant. This accumulation layer ceases to exist when the external drain voltage minus the IR drop through the n- neck region approximately equals the gate voltage. The area associated with the accumulation layer (JFET cathode) rapidly decreases with increased drain voltage. In addition, a depletion layer may now form, leading to a further reduction of C<sub>24</sub>.

# Waveforms Expected from the Model

The following discussion relates the prior model discussion to the waveforms of Figure 5. The discussion begins with the gate voltage at +5V or +10V and the gate current equal to zero. This condition corresponds to saturated behavior, where the drain current is approximately equal to  $I_D(max)$  and the drain voltage equals  $I_D(max)$  times  $R_{DS}(ON)$ .

# Gate Voltage Slope - t<sub>OFF</sub> Delay

As time progresses,  $I_G$  = -5mA, which must flow through  $C_{12}$  +  $C_{23}$  +  $C_{24}$  of Figure 8 because the MOS and JFET are both heavily biased into conduction. Therefore,  $dV_4/dt$  =  $dV_3/dt$  = nearly 0. With large positive gate bias and drain voltage near zero,  $C_{23}$  is zero and  $C_{12}$  and  $C_{24}$  are constant. As a result, the gate voltage should be a straight line with a slope equal to:

$$dV_G/dt = I_G/(C_{12} = C_{24})$$
(1)

# Gate Voltage Plateau

As the gate voltage decreases, the drain voltage will increase imperceptibly at first until the gate voltage drops enough to bias the MOS into its constant current mode. At this point, the very high transconductance of the MOS is consistent with very little change in gate voltage to reduce the current by several percent. Several percent change in drain current corresponds to many volts in drain voltage. As a result, the gate current no longer flows from  $C_{12}$  during the constant gate voltage plateau.

### **Drain Voltage Shallow Slope**

Since  $C_{23}$  is still zero, all gate current must flow from  $C_{24}$ . Assuming that the gate voltage is plateaued and that the JFET is still heavily forward biased, node 4 of Figure 7 must ramp at linear rate. Therefore, the JFET must also ramp at this same rate.

$$dV_D/dt = I_G/C_{24}$$
(2)

Again this curve will approximate a straight line.

# Drain Transition Voltage

As mentioned above,  $C_{24}$  rapidly decreases once the drain voltage is slightly greater than the gate voltage. (Actually, this voltage is the n- voltage directly beneath the gate oxide, and differs from the drain voltage by an amount nearly equal to  $I_D r_{DS}(on)$ .)

Since the drain voltage is still fairly low and the drain current has not changed much, the gate plateau voltage still exists. Equation 2 still applies except that the value of C<sub>24</sub> has materially decreased and C<sub>23</sub> has become finite. This situation results in a substantial increase in dV<sub>D</sub>/dt.

### JFET Pinch Off Voltage - Drain Voltage Steep Slope

As the drain voltage approaches the pinch off voltage of the JFET, the JFET comes out of saturation and starts to support MOSFET drain voltage. The voltage gain of the active JFET permits large changes in the JFET drain voltage for small changes in its source-to-gate voltage. But the JFET sour-to-gate voltage is the lateral MOS drain-to-source voltage, which is dominated by equation 2 (but for low values of  $C_{24}$ ).

8

**APPLICATION** 

NOTES

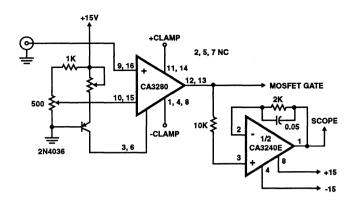
### Gate Voltage Curvature from Plateau

As the drain voltage increases, the drain current decreases. This condition requires significant decrease in gate voltage until the gate threshold is approached. A significant portion of the gate current must now flow through  $C_{12}$ . This flow produces a gradual transition in the gate voltage and some slowing of the drain voltage waveform.

### Gate Voltage Slope - t(ON) Delay

When the drain is totally off, most of the gate current flows from  $C_{12}$ . Again, this capacitance is constant, so that the waveform is a straight line with a slope equal to:

$$dV_G/dt = I_G/C_{12}$$
(3)



**FIGURE 9. TEST CIRCUIT** 

# New Switching Characterization for Power MOSFETs

The above discussion suggests that a new method of characterization may be provided for resistive switching with power MOSFETs, where constant current gate drive is employed during the transition time.<sup>1</sup> The below method bears some similarity to the gate charge concept.<sup>2</sup> The state of the gate charge is a continuous plot in this work, however, rather than a single point. This approach permits a knowledge of all waveforms with any drive circuitry, rather than just the total elapsed time. In addition, the total elapsed time is fixed (at just under 50 microseconds) by choosing the required value of constant gate current. Circuit designers are usually more comfortable with milliamperes and microseconds (although the product is charged in nanocoulombs).

### **Test Circuit - Drive**

A test circuit is shown in Figure 9. The heart of this circuit is the Harris CA3280 integrated circuit. This is an operational transconductance amplifier (OTA) operated as a comparator. An OTA is a current output circuit where the output current and output transconductance are programmed by the amplifier bias current ( $I_{ABC}$ ). Internal chip circuit feedback assures an extremely high output impedance within a compliance range established by the supply voltages. The circuit of Figure 9 is actually two OTA's in parallel. The linearizing diodes on this chip are not used.

A value of  $I_{ABC}$  is established from the collector of the 2N4036. The current into the load (the gate of the MOSFET under test) may be varied between  $+I_{ABC}$  and  $-I_{ABC}$  times a constant of proportionality (approximately 0.9). The actual value depends upon the input differential input voltage. As a comparator, the differential voltage is large resulting in saturated behavior of  $\pm I_{ABC}$ . If the gate voltage comes within a volt of the rail voltages, this current goes to zero, producing a clamping voltage. For the purposes of this Note, these supply voltages are adjusted to clamp 0 volts and +10 volts for the normal n-channel MOSFET. The behavior of this IC is excellent from submicroamperes to about 2.5mA. Higher current may be achieved by stacking many CA3280 pack-

ages one on top of another and soldering the leads parallel to the chips rather than wiring many sockets. However, this arrangement may require an increase in the bypass capacitor values.

A CA3240E MOS input op amp is used as a unity gain follower. Otherwise, the  $1m\Omega$  or  $10m\Omega$  shunting impedance of the scope would load the high impedance circuitry associated with the MOSFET gate.

### **Testing Conditions**

A pulse generator is set for  $50\mu s$  on time duration and approximately  $25\mu s$  repetition rate (about 0.2% duty cycle). The  $\pm$  clamp voltages are set to the appropriate values. The power MOSFET load resistor is chosen to equal the maximum rated voltage divided by the maximum rated current.

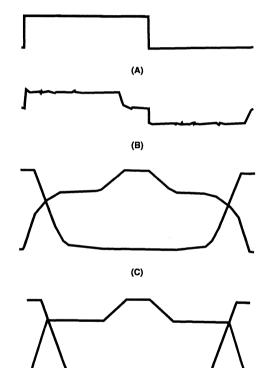
With a low value of drain supply voltage, observe the gate voltage while adjusting  $I_{ABC}$ . A convenient set of conditions occurs when a short dwell time of several  $\mu$ s exists at the +10V level. Minor adjustments may be desired for  $I_{ABC}$  as the drain supply voltage is increased to maximum rated value. The L<sup>2</sup>FETs would be tested at +5V gate clamp.

Figure 10 exhibits the pertinent waveforms for an RFM15N15. All power MOSFETs have similar waveforms. Figure 10(a) is the 3V signal to the CA3280. Figure 10(b) is the power MOSFET gate current. In this example, the amplitude is ±1mA with a third state of 0mA. Figure 10(c) displays the gate voltage and the drain voltage, 10V peak-to-peak and 150V peak-to-peak. Figure 10(d) is a piece wise linear approximation of Figure 10(c). The datum line is zero volts and applies to both waveforms. The time scale of the waveforms of Figure 10 is 100µs full scale.

There are some features of the gate and drain voltage waveforms that should be noted. These features are consistent with the equivalent model discussion.

 The waveforms during the positive gate current time are symmetrical to those during the negative gate current time. Exceptions will occur for very fast or very slow switching, and for nonsymetrical current drive. These exceptions are discussed in the following.

- The drain voltage waveform contains a rather steep slope with a fairly constant dv/dt over most of the drain voltage excursion.
- The drain voltage contains a rather shallow slope with a fairly constant dv/dt over the remainder of the drain voltage excursion.
- 4. The drain transition voltage (defined as the intercept of the above two near straight lines) typically occurs when the drain voltage equals the sum of the gate voltage (at that instant of time) plus the product of the drain current times r<sub>DS</sub>(on).
- The gate voltage waveform contains three near straight line segments during the positive gate current transition time.

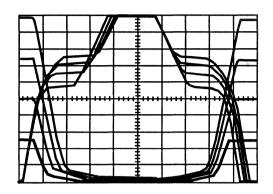


(D)

FIGURE 10. (A) 3V SIGNAL TO THE CA3280, (B) POWER MOS-FET GATE CURRENT, (C) GATE AND DRAIN VOLTAGE, (D) PIECE WISE LINEAR APPROXIMA-TION OF 10(C)

### Application of the Switching Data

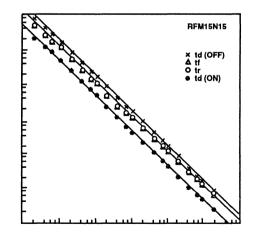
Figure 11 is a family of curves similar to Figure 10(C), where the drain supply voltage is fixed at four values. Note that the ordinate is 10V full scale for the gate voltage, while it is normalized to 100% of maximum-rated drain voltage for the drain-voltage curves. All four sets of curves are taken with a predetermined gate current,  $\pm I_T$ . The abscissa is also normalized to 100 ( $I_T/I_G$ ) microseconds full scale, where  $I_G$  is the actual gate drive current. With this characteristic curve, switching behavior may be readily predicted for almost any driving circuit, provided the load is resistive.



#### FIGURE 11. CURVES SIMILAR TO THOSE OF FIGURE 10(C) WITH DRAIN SUPPLY VOLTAGE FIXED AT FOUR VALUES

#### Symmetrical Current Drive

Waveforms of Figure 11 will scale in an inverse manner with gate current. Driving current was varied from  $\pm 200$ mA to  $\pm 2\mu$ A for the device of Figure 11. Measurements of delay time (on), rise time, delay time (off), and fall time are plotted in Figure 12 and compared to the inverse scaling suggested by Figure 11.



#### FIGURE 12. VARIOUS TIME MEASUREMENTS COMPARED TO THE INVERSE SCALING SUGGESTED BY FIGURE 11.

It is anticipated that very slow switching (in the millisecond region) will result in the chip thermally tracking the power dissipation, which would cause some deviation from the

inverse scaling. This condition was not noted on Figure 12 for gate currents as low as  $\pm 2\mu A$ .

Large gate currents result in very fast switching waveforms. The gate of each hex cell is accessed through a gate pad and gate runners, which are of a low resistivity metal followed by buried polysilicon of a moderate resistivity. As a result, the high gate currents cause a propagation delay to exist for those cells far removed from the gate runners. This effect is not seen in Figure 12, even though the gate current was increased to  $\pm 200$ mA.

#### **Asymmetrical Current Drive**

The positive and negative gate drive will often be dissimilar. Of course, the scaling must reflect this situation. At other times the gate current varies with amplitude. This condition is always true when driving from a pulse generator of fixed resistance. Piecewise linear methods will yield the gate current, which will permit the proper piecewise linear scaling. This calculation could be done in the following manner:

- 1. Mark eleven small x's along the gate waveform of Figure 11 dividing it into 10 equal voltage segments; for example,  $V_G = 0, 1, 2, \ldots 9, 10V$ .
- 2. Draw a vertical line through each x the full height of the figure, creating 10 time segments.
- 3. If the driving-pulse amplitude is 0 to 10 volts with an internal resistance of 100 ohms, calculate the piecewise linear gate current for each time segment.  $I_{G1} = (10 - 0.5)/100 =$ 95mA,  $I_{G2} = (10 - 1.5)/100 = 85mA$ , etc.
- Then scale each waveform within the pertinent time segment by the proper gate current.
- 5. Smooth the curves.
- 6. Create 10 more time segments for the right half of Figure 11 corresponding to an average gate voltage of 9.5,8.5, . . . 1.5, 0.5 volts. Call these segments 11,12,... 19,20.
- 7. In that the pulse-generator voltage is now zero volts, calculate  $I_G$  as:  $I_{G11} = (0-9.5)/100 = -95$ mA,  $I_{G12} = (0-8.5)/100 = -85$ mA, etc.
- Repeat 4 and 5. L<sup>2</sup>FETs would be treated with smaller voltage segments.

Generally, the gate-voltage plateau of Figure 11 will not be located at the middle of the pulse-generator amplitude (5 volts). As a result, rise and fall times measured this way experience differing gate currents and are "nonsymetrical". This type of measurement will also lead one to observe temperature sensitivities, load-current sensitivities, and device-to-device variability, all of which are more circuit dependent than device dependent.

#### Source-Lead Inductance

The gate-voltage waveforms may be corrected by the voltage across the source-lead inductance and external inductance, which may be mutually common to the input and

output current loops. This voltage, L di/dt, may be approximated and applied to the gate-voltage waveform after scaling Figure 12 for the actual gate currents. Generally, this effect is not appreciable for gate current small relative to ±100mA. A very loose circuit wiring arrangement with inches of mutually common source wire will exagerate this effect.

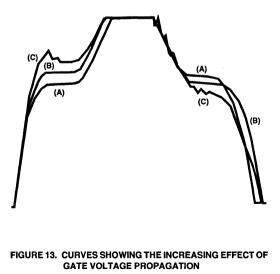
# Gate Voltage Propagation Effects

Most power MOSFET applications need switch no faster than tenths of a microsecond, but should faster switching be required, this section will become important. It must be understood that the power MOSFET appears as a distributed network of many cells when used for very fast switching.

The thousands of individual MOSFET cells are connected in parallel with highly conductive metal for the sources and drains. However, the gates are paralleled with a moderately conductive film of doped polysilicon. As a result, a very steep voltage waveform applied to the gate pad will bias those cells close by, but a delay will occur for turn on or turn off. Because of the nonlinear "input capacitance" of each cell, the delay cannot be characterized by a pure number of so many nanoseconds.

Presently, most manufacturers characterize typical switching speed for a single test condition. The test conditions are usually chosen to present the most favorable result, usually near the upper limit of usefulness.

Figures 13(A), (B), and (C) show the increasing effect of gate voltage propagation. The gate waveform is the only one shown because the drain is not affected so drastically. This is true because some cells are overdriven, offsetting the effect of the starved cells. Care must be exercised when operating with large gate effects similar to those of Figure 13(C).



Gate-propagation effects may be reduced by the following design methods:

- 1. Many gate runners.
- 2. More conductive polysilicon.
- 3. Silicide rather than polysilicon gates.
- 4. Less cells (resulting in lower transconductance and higher  $R_{\mbox{ON}}).$
- 5. Substantially different lateral and vertical structure.
- 6. High-frequency packaging.

None of the above methods will yield "breakthrough" devices unless used in combination.

Any of the previous methods require trade-offs which would not be attractive to the needs of most components users. These trade-offs are in the realm of:

- 1. Reduction of RON per unit area.
- 2. Decreased yield.
- 3. Added cost (beyond the cost of yield impact).
- 4. RFI, self-oscillation, and other problems characteristic of very fast devices.

# References

- "Power MOSFET Switching Waveforms A New Insight," H. R. Ronan, Jr., and C. F. Wheatley, Jr., Proc. Powercon 11, April 1984.
- "Correlating the Charge-Transfer Characteristics of Power MOSFETs with Switching Speed," E. Oxner, Proc. Powercon 9, April 1982.

# **Harris Semiconductor**



No. 7260.2 September 1993

# Harris Power MOSFETs

# POWER MOSFET SWITCHING WAVEFORMS: A NEW INSIGHT

Author: Harold R. Ronan, Jr. and C. Frank Wheatley, Jr.

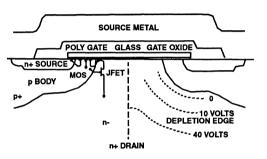
The examination of power MOSFET voltage and current waveforms during switching transitions reveals that the device characterization now practiced by industry is inadequate. In this Note, device waveforms are explained by considering the interaction of a vertical JFET driven in cascode from a lateral MOSFET in combination with the interelectrode capacitances. Particular attention is given to the drainvoltage waveform and its dual-slope nature. The three terminal capacitances now published by the industry are shown to be valid only for zero drain current. For cases where the gate drive is a voltage step generator with internal fixed resistance, the drain voltage characteristics are inferred from the gate current drive behavior and compared to observed waveforms. The nature of the "asymmetric switching times" is explained.

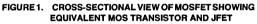
A waveform family is proposed as a more descriptive and accurate method of characterization. This new format is a plot of drain voltage and gate voltage versus normalized time. A family of curves is presented for a constant load resistance with V00 varied. Gate drive during switching transitions is a constant current with voltage compliance limits of 0 and 10 volts. Time is normalized by the value of gate driving current. The normalization shows excellent agreement with data over five orders of magnitude, and is bounded on one extreme by gate propagation effects and on the other by transition time self-heating (typically tens of nanoseconds to hundreds of microseconds).

# **Device Models**

The keystone of an understanding of power MOSFET switching performance is the realization that the active device is bimodal and must be described using a model that accounts for the dual nature. Buried in today's power MOS-FET devices is the equivalent of a depletion layer JFET that contributes significantly to switching speed. Figure 1 is a cross-sectional view of a typical power MOSFET, with MOS-FET/JFET symbols superimposed on the structure.

Figure 2 is obtained by taking the lateral MOS and vertical JFET from this conception and adding all the possible nodeto-node capacitances. Computed values of the six capacitances for a typical device structure suggest that device behavior may be adequately modeled using only three capacitors in the manner of Figure 3. This is the model to be employed for analysis and study





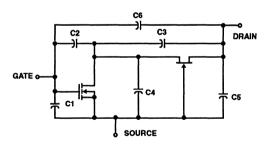


FIGURE 2. MOSTRANSISTOR WITH CASCODE-CONNECTED JFET AND ALL CAPACITORS

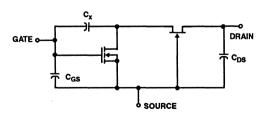


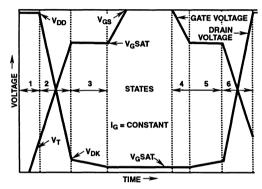
FIGURE 3. FIGURE 2 SIMPLIFIED

# Gate Drive: Constant Voltage or Constant Current

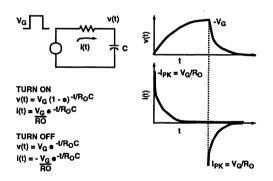
Before moving on to the study of the equivalent circuit states of the model, a gate-drive forcing function which is easy to represent, relates to reality, and best illustrates device behavior must be chosen. The choice may be immediately narrowed to two:

(1) An instantaneous step voltage with internal resistance R, Figure 5.

(2) An instantaneous step current with infinite internal resistance, Figure 6.



#### FIGURE 4. IDEALIZED POWER MOSFET WAVEFORMS



#### FIGURE 5. STEP-VOLTAGE FORCING FUNCTION

Power MOSFET devices are highly capacitive in nature; hence, simple capacitor responses to the forcing functions offer a good vehicle for comparison. The advantageous choice is immediately obvious: Figure 5. Voltage/time responses dominated by capacitance are straight lines (when constant current is used). The slope of these lines is

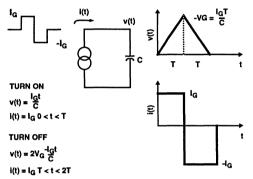
proportional to current and inversely proportional to capacitance. Analytically, then, constant current is most convenient. It is quite another matter, however, to build a bidirectional current drive that is accurate across the many decades of both current and time required to establish experimental verification.

# Six States

To completely characterize power MOSFET switching waveforms, the six states that a device assumes, Figure 6, must be addressed:

STATE	MOS	JFET
Turn-on 1	Off	Off
Turn-on 2	Active	Active
Turn-on 3	Active	Saturated*
Turn-off 4	Saturated	Saturated
Turn-off 5	Active	Saturated
Turn-off 6	Active	Active

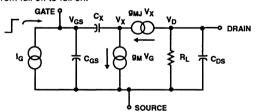
\*The term saturated is taken to mean a constant low-voltage drain-source condition.



# FIGURE 6. STEP CURRENT FORCING FUNCTION

# Equivalent Circuit

The lumped-parameter model of Figure 3, with the cascodeconnected JFET, can now be reduced to the linear equivalent circuit of Figure 7, and the six device states investigated from full off to full on.



#### LEGEND

V <sub>GS</sub>	- Gate Voltage	C <sub>DS</sub>	- Drain Source Capacitance
٧ <sub>X</sub>	- JFET Driving Voltage	gм	- MOSFET Transconductance
VD	- Drain Voltage	g <sub>мJ</sub>	- JFET Transconductance
C <sub>GS</sub>	- Gate Source Capacitance	RL	- Drain Load Resistance
с <sub>х</sub>	- MOSFET Feedback Capacitance	I <sub>G</sub>	- Constant Current Amplitude

FIGURE 7. POWER MOSFET EQUIVALENT CIRCUIT

#### State 1: MOS Off, JFET Off

In a power-MOSFET device, no drain current will flow until the device gate threshold voltage, V<sub>T</sub> is reached. During this time, the gate current drive is only charging the gate source capacitance. More accurately, I<sub>G</sub> is charging C<sub>ISS</sub> (C<sub>ISS</sub> = C<sub>GS</sub> + C<sub>GD</sub> C<sub>DS</sub> shorted), the capacitance designation published by the industry.

The current generators,  $g_M v_G$  and  $g_{MJ} V_X$  are open circuits for zero drain current, and  $R_L$  is presumed to be so low as to represent a short circuit (generally true for practical applications). This is academic however since  $C_{GS}$  is very much larger that  $C_6$ . The time to reach threshold, then, is simply:

$$T = \frac{C_{ISS} V_T}{I_G}$$

### State 2: MOS Active, JFET Active

This state graphically illustrates the dramatic influence that the JFET has on the power MOSFET drain-voltage wave- form. Instead of having to discharge  $C_x$  from  $V_{DD}$  to ground, the lateral MOSFET need only swing  $v_x$  to ground, a much smaller voltage thanks to the grounded gate JFET. Since the interaction of  $R_L$  with the device capacitances has a second-order effect on the drain voltage, the equivalent circuit of Figure 7 predicts a drain voltage change of:

$$d_{VG}/dt = g_M R_L I_G / [C_{GS} + C_X (1 + g_M / g_{MJ})]$$

In all but the smallest power-MOSFET devices,  $C_x$  is several thousand picofarads and  $g_M/g_{MJ}$  is of the order of 3:1. Power-MOSFET devices exhibit a high  $dv_D/dt$  switching rate because of the cascode-connected J FET, not because  $C_{RSS}$  ( $C_{RSS} = C_{GD}$ ) is a small value, as zero-drain-current data-sheet capacitance values might lead one to believe. If  $C_{RSS}$  were, in actuality, small, long drain voltage tails would not exist. The tail response is a direct result of JFET saturation. In order to delineate the transition from state 2 to state 3, a drain voltage at which linear extrapolations of drain-voltage slopes intersect. The time duration of state 2 is:

$$t = (V_{DD} - V_{DK})[C_{GS} + C_X(1 + g_M/g_MJ)]/g_MR_LI_G$$

#### State 3: MOS Active, JFET Saturated

When the JFET saturates, the  $g_{MJ}V_X$  current generator becomes a short circuit and the equivalent circuit predicts:

$$d_{VD}/dt = g_M R_L I_G / [C_{GS} + C_X (1 + g_M R_L)]$$

This is the Miller effect so often referred to in older texts that describe the behavior of grounded-cathode vacuum-tube amplifier circuits. Allowing for the fact that  $1 + g_M R_L$  is approximately equal to  $g_M R_L$  and  $C_X(1 + g_M R_L)$  is very much larger than  $C_{GS}$ , the expression for drain-voltage tail time is:

$$t = (V_{DK} - V_{D(SAT)})C_x \Lambda_G$$

### State 4: MOS Saturated, JFET Saturated (Turn-Off)

In this state, in addition to  $g_{MJ}V_X$  being shorted, the  $g_MV_G$  current generator is shorted, and  $I_G$  is occupied with charging  $C_X$  and  $C_{GS}$ , in parallel, from the peak value of  $V_G$  to  $V_{G(SAT)}$ . The time required for this is:

$$t = (V_G - V_{G(SAT)}(C_{GS} + C_x)/I_G$$

Since a value for CGS may be measured independently of switch-

ing time, the method described is the simplest way of determining  $C_{\boldsymbol{X}^{\ast}}$ 

On turn-off, the state time equations are equally applicable, but in reverse order (states 5 and 6); see the idealized waveform of Figure 4.

#### **Experimental Verification**

The four switching states just analyzed indicate that for a given device, all four switching state times are inversely proportional to the magnitude of the gate drive current. Figure 8 illustrates the switching performance of a typical power MOSFET across three decades of gate drive current and time. In each case the data slope is almost a perfect -1.

# A New Device Characterization

Figure 8 could not be a reasonable device data sheet presentation because it does not give the designer any information on a typical value for  $C_X$ , nor does it convey how  $V_{DK}$ ,  $g_M$ ,  $g_M/g_{MJ}$ , and  $V_G$ (sat) vary with drain current. What would be of enormous value to the designer is a plot of  $V_D(t)$ ,  $V_G(t)$  for selected values of  $V_{DD}$  and  $I_D$  within device ratings.

A reasonable characterization would be as follows:

- 1. The x axis would be normalized in terms of gate current drive.
- 2. The y axis would be normalized in terms of percent maximum rated  $V_D$  (0 to 100%).
- 3. R<sub>L</sub> = V<sub>D</sub>(max)/<sub>ID</sub>(max) would define the drain load resistance.
- 4. Four plots of  $V_D(t), V_G(t)$  at 100%, 75%, 50%, and 25%  $V_D(max)$  would be shown.

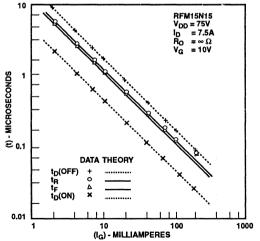
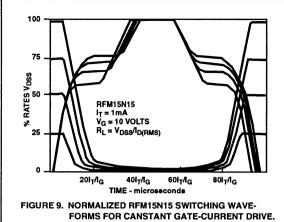


FIGURE 8. CONSTANT GATE CURRENT SWITCHING TIME

Figure 9 is such a plot for the RFM15N15 power MOSFET. With such a plot, a designer can estimate device switching performance under any resistive gate/drain conditions.



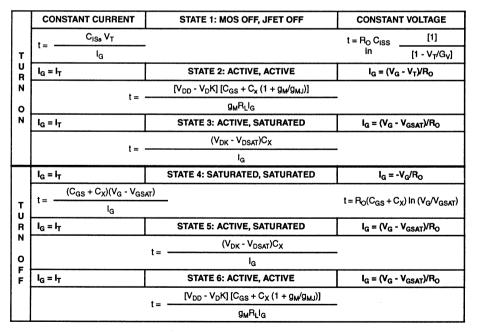
# Step-Voltage Gate Drive

The majority of power MOSFET applications employ a step gate-voltage input with a finite source resistance  $R_0$ . Often  $R_0$  for turn-on is not the same as  $R_0$  for turn-off. How can switching times for these situations be estimated using the switching characterization curves just described? The analy-

sis for resistive step voltage inputs, which is complex because the gate current is no longer constrained to be constant, but is a function of device gate-voltage response, is covered in Appendix A. (A second, shorter appendix, B, has been added to illustrate the estimation of R<sub>0</sub> for some practical gate drive circuits.) Table I summarizes the common switching equations, and indicates the appropriate 1G to be used in each state for relating step voltage drives to the characterization curves.

# **Experimental Verification**

Since the switching equations for step currents and voltages differ only by gate-current magnitudes for the same device type, one would expect a plot of switching time versus  $1/R_{\rm O}$  to be of the same form as those obtained for a step current drive. This is exactly the case, as Figure 10 is merely a variation of Figure 8. Using the relationships of Table I, the observed differences between Figs. 7 and 9 can be pinpointed. The two sets of experimental curves confirm that, on the basis of the short-circuit drive current VU/R\_O equaling the constant 1G, t6(on), t, td(off), and t1 will all be longer, as predicted by the ratios of the gate drive currents of Table 1. Notice also that t, t1 switching symmetry is disrupted by the use of a step voltage with source resistance  $R_{\rm O}$ . For states 2 and 6 the time ratio is:



### TABLE 1. COMMON SWITCHING EQUATIONS

### **Experimental Verification**

Since the switching equations for step currents and voltages differ only by gate-current magnitudes for the same device type, one would expect a plot of switching time versus  $1/R_O$  to be of the same form as those obtained for a step current drive. This is exactly the case, as Figure 10 is merely a variation of Figure 8. Using the relationships of Table I, the observed differences between Figures 7 and 9 can be pinpointed. The two sets of experimental curves confirm that, on the basis of the short-circuit drive current  $V_G/R_O$  equalling the constant  $I_G$ ,  $t_D(on)$ ,  $t_R$ ,  $t_D(off)$ , and  $t_F$  will all be longer, as predicted by the ratios of the gate drive currents of Table 1. Notice also that  $t_R$ ,  $t_F$  switching symmetry is disrupted by the use of a step voltage with source resistance  $R_O$ . For states 2 and 6 the time ratio is:

$$\frac{t_{\text{TURN-ON}}}{t_{\text{TURN-OFF}}} = \frac{V_{\text{G}(\text{SAT})}}{V_{\text{G}} \cdot V_{\text{T}}}$$

For states 3 and 5 the time ratio is:

$$\frac{t_{\text{TURN-ON}}}{t_{\text{TURN-OFF}}} = \frac{V_{G(SAT)}}{V_{G} - V_{G(SAT)}}$$

Utilization of available maximum gate drive voltage and current can be optimized for fastest power MOSFET switching speed through the use of constant-current gate drive at the expense of increased gate-drive circuit complexity.

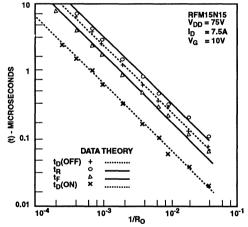


FIGURE 10. CONSTANT GATE VOLTAGE SWITCHING TIME

# Using the Characterization Curves, Figure 9

To estimate the switching times for an RFM15N15 power MOSFET under the conditions  $V_G = 10V$ ,  $V_{DD} = 75V$ ,  $R_O = 100$  ohms, and  $R_L = 10$  ohms, precedes as follows:

# State 1: MOS Off, JFET Off

This time can be estimated without recourse to the curves

- $t = 100(1200 \times 10^{-12}) in [1/(1 4/10)]$
- t= 61 ns

### State 2: MOS Active, JFET Active

$$I_{G} = (10 - 4)/100 = 60 \text{mA}$$
  
t =  $\frac{(\text{curve divisions}) \times I_{T} \mu \text{s}}{60} = \frac{9}{60} = 150 \text{ ns}$ 

#### State 3: MOS Active, JFET Saturated

$$I_{G} = (10 - 7)/100 = 30 \text{mA}$$
  
t =  $\frac{(\text{curve divisions}) \times I_{T} \mu s}{30} = \frac{14}{30} = 467 \text{ ns}$ 

#### State 4: MOS Saturated, JFET Saturated

$$C_{GS} + C_x = (gate voltage slope)(test current)$$
  
= (1.5 x 10<sup>-6</sup>s/5 volts)(10mA)

$$= (1.5 \times 10^{\circ} \text{s/}5 \text{ volts})($$

= 3000pF

- t = 100(3000 x 10<sup>-12</sup>) in [10/6.6]
- t = 125ns

#### State 5: MOS Active, JFET Saturated

$$t_{G} = \frac{6.6/100 = 66\text{mA}}{(\text{curve divisions}) \times I_{T} \,\mu\text{s}} = \frac{8}{66} = 121 \,\text{ns}$$

Figure 11 shows RFM15N15 waveforms using the conditions specified in the example.

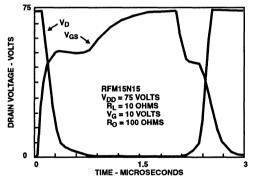


FIGURE 11. STEP GATE VOLTAGE INPUT TO AN RFM15N15

STATE	E CALCULATED MEASURED		RATIO	
	(t <sub>C</sub> , ns)	(t <sub>M</sub> , ns)	(t <sub>C</sub> /t <sub>M</sub> )	
1	61	60	1.02	
2+3	671	670	0.92	
4	125	137	0.91	
5+6	318	375	0.85	

For peak gate voltages other than 10 volts, and load resistances other than  $V_{DSS}/I_{D(RMS)}$ , the equations of Table 1 may be used in conjunction with slope estimates from the characterization curves for  $C_X$  and  $C_{GS} + C_X(1 + g_M/g_{MJ})$  at the appropriate drain-current level.

# **Characterization-Curve Limits**

The switching-time range over which the characterization can be applied is very impressive. For gate currents of the order of microamperes, device dissipation is the limiting factor. For gate currents of the order of amperes, the device response will be slowed by gate propagation delay. This delay, of course, degrades the linear switching relationship to gate current. However, as Figure 12 graphically shows, the characterization is valid across five decades of gate current and switching time, allowing all but a very few switching applications to be described by the characterization curves of Figure 9.

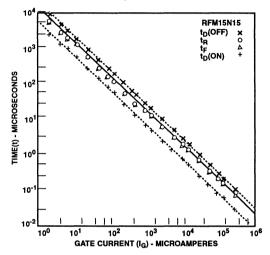


FIGURE 12. FIVE DECADES OF LINEAR RESPONSE

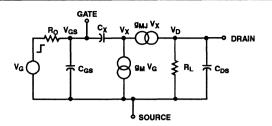
# Conclusions

The viability of the proposed characterization curves using constant current has been demonstrated and the limits of application defined. The existence of a vertical JFET in a power MOSFET makes data-sheet capacitances of little use for estimating switching times. The classical method of defining switching time by 10% and 90% is a poor representation for power MOSFETs because of the dual-slope nature of the drain waveforms. Switching influences are masked because the 10% level is controlled by one mechanism and the 90% level by another. Device comparisons based on the classical switching definition can be very misleading.

# Appendix A - Analysis for Resistive Step Voltage Inputs

# Step Voltage Gate Drive

To obtain the necessary relationships, six device switching states must be examined using the same device equivalent circuit as was used for the constant-gate-current case, but with the forcing function replaced with a step voltage with internal resistance  $R_{\Omega}$ , Figure A-1.



### LEGEND

V <sub>GS</sub>	- Gate Voltage	CDS	- Drain Source Capacitance
٧x	- JFET Driving Voltage	gм	- MOSFET Transconductance
VD	- Drain Voltage	g <sub>MJ</sub>	- JFET Transconductance
C <sub>GS</sub>	- Gate Source Capacitance	RL	- Drain Load Resistance
с <sub>х</sub>	- MOSFET Feedback Capacitance	l <sub>G</sub>	- Constant Current Amplitude

FIGURE A-1. POWER MOSFET EQUIVALENT CIRCUIT

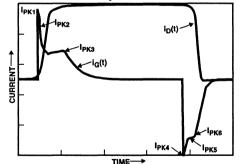
### State 1: Mos Off, JFET Off

As before, both current generators are open circuits, reducing the equivalent circuit to simply charging  $C_{ISS}$  through  $R_{O}$ .

- $t = R_0 C_{ISS} ln(1/(1 V_T/V_G)]$
- $t = V_G/R_O$

#### State 2: Mos Active, JFET Active

Before proceeding, it is wise to examine an actual device response and make use of available simplifications. Figure A-2 shows  $i_G(t)$  and  $i_D(t)$  for a typical power MOSFET driven by a step gate voltage. For truly resistive switching, realize that these waveforms are only mirror images of their voltage counterparts  $v_G(t)$  and  $v_D(t)$ . Using Figure A-2, applicable gate currents for each of the device states may be listed.





Turn-On

 $\begin{array}{l} \mbox{State 1: MOS Off, JFET Off} \\ I_{PK1} = V_G/R_O \\ \mbox{State 2: MOS Active, JFET Active} \\ I_{PK2} = (V_G \cdot V_T)/R_O \\ \mbox{State 3: MOS Active, JFET Saturated} \\ I_{PK3} = (V_G \cdot V_G(SAT))/R_O \end{array}$ 

# Turn-Off

State 4: MOS Saturated, JFET Saturated

 $I_{PK4} = V_G/R_O$ 

State 5: MOS Active, JFET Saturated

 $I_{PK5} = V_{G(SAT)}/R_O$ 

State 6: MOS Active, JFET Active

 $I_{PK6} = V_{G(SAT)}/R_O$ 

The equivalent circuit of Figure A-1 predicts that:

 $dv_D/dt = -g_M R_L (V_G - V_T) e^{-t/T_1} / T_1$ 

where T1 =  $R_0C_{GS}$  + (1 +  $g_M/g_{MJ})R_0C_X$ 

Note that  $g_M R_L (V_G - V_T)$  is usually an order of magnitude greater than  $V_{DD}$  indicating that the drain voltage is discharging toward a very large negative value. The device operation, then, is on the early, almost linear, portion of the exponential, where  $e^{i/T_1}$  approximates unity. The drain current of Figure A-2, and hence the drain voltage, does indeed exhibit a linear decrease with time.

Thus, for state 2:

$$t = \frac{[V_{DD} - V_{DK}][C_{GS} + C_X(1 + g_M/g_{MJ})]}{g_M R_L I_{PK2}}$$

where  $I_{PK2} = (V_G - V_T)/R_O$ 

### State 3: Mos Active, JFET Saturated

Because of the Miller effect, the gate voltage and, hence, the gate current, is almost constant during the tail time. The equivalent circuit then predicts:

$$\frac{dV_D}{dt} = \frac{g_M R_L I_G}{C_{GS} + (1 + g_M R_L) C_X} = \frac{I_G}{C_X}$$

$$I_G = I_{PK3} = (V_G - V_{G(SAT)})/R_O$$
and
$$t = \frac{(V_{DK} - V_{D[SAT]})C_X}{I_{PK3}}$$

### State 4: Mos Saturated, JFET Saturated (Turn-off)

Both equivalent-circuit generators are short circuits, and the gate drive is discharging  $C_X$  in parallel with  $C_{GS}$  through  $R_O$ .

$$t = R_O(C_{GS} + C_X) \ln[V_G/V_{G(SAT)}]$$
$$I_{PK4} = V_G/R_O$$

#### State 5: Mos Active, JFET Saturated

The JFET current generator  $V_x g_{m,l}$ , is operative.

$$t = \frac{[V_{DK} - V_{D[SAT]})C_X}{I_{PK5}}$$

 $I_{PK5} = V_{G(SAT)}/R_O$ 

### State 6: Mos Active, JFET Active

The Miller effect is now reduced by the activation of  $V_{G}g_{MJ}$ , and the equivalent circuit predicts:

$$t = \frac{[V_{DD} - V_{DK}][C_{GS} + C_X(1 + g_M/g_{MJ})]}{g_M R_I I_{PAK6}}$$

 $I_{PAK6} = V_{G(SAT)}/R_{O}$ 

# Appendix B - Estimating R<sub>O</sub> for Some Typical Gate-Drive Circuits

### Case 1: Typical Pulse-Generator Drive, Figure B-1

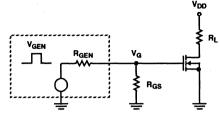


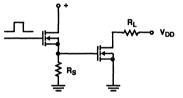
FIGURE B-1. TYPICAL PULSE-GENERATOR DRIVE CIRCUIT

Turn-On and Turn-Off

 $R_{O} = R_{GEN}R_{GS}/(R_{GEN} + R_{GS})$ 

For the typical case where  $R_{GEN}$  = 50 $\Omega$ , and a coaxial-cable termination of 50 ohms,  $R_O$  = 25 $\Omega$  and  $V_G$  =  $V_{GEN}/2$ .

### Case 2: Voltage-Follower Gate Drive, Figure B-2



#### FIGURE B-2. VOLTAGE-FOLLOWER GATE-DRIVE CIRCUIT

#### Turn-On

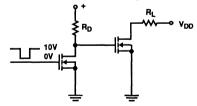
 $R_O$  is approximately equal to  $1/g_M$  for  $R_S$  very much greater than  $1/g_M.$ 

gm = transconductance of driving MOSFET transistor.

### Turn Off

 $R_0 = R_S$ 

#### Case 3: Common-Source Gate Drive, Figure B-3



#### FIGURE B-3. COMMON-SOURCE GATE-DRIVE CIRCUIT

#### Turn-On

 $R_{O} = R_{D}$  (drain-to-ground capacitance of driving device adds to  $C_{GS}$  of driven MOSFET.)

### Turn Off

 $R_{O} = R_{DS}(on)$  of driving MOSFET

R<sub>D</sub> is very much greater than R<sub>DS</sub>(on)

# Harris Semiconductor



No. AN7332.1 May 1992

# Harris Power MOSFETs

# THE APPLICATION OF CONDUCTIVITY-MODULATED FIELD-EFFECT TRANSISTORS

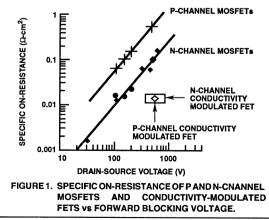
Author: Jack Wojslawowicz

# Summarv

The development of conductivity-modulated field-effect transistors, FETs, makes available to the system designer another solid-state device that can be used to implement power switching control. This paper reviews differences between the standard and the newly developed FET. It shows the significant advantages that the conductivitymodulated FET has over the standard FET. Several applications are presented to show that this new type of device works well in practical situations. The relative immaturity of the conductivity-modulated FET may limit its initial utilization. But as the family grows and product innovation and refinement takes place, this newest member of the power semiconductor family will become a viable alternative to the other members.

# General Considerations

The development of the power field-effect transistor has made available to the power-stage designer an entire new family of power semiconductors. Over the past 5 to 6 years, the breadth of product has grown to encompass the requirements of a large number of applications. A limiting factor that has slowed the utilization of power FETs in the high-current. high-voltage applications is the fact that the on-state resistance (R<sub>DS(ON)</sub>) in a standard FET is related to its breakdown voltage (B<sub>VDSS</sub>) by a nearly cubic power, i.e., R<sub>DS(ON)</sub> ≈ B<sub>VDSS</sub> 2.8. What this implies, as Figure 1 shows, is that as the breakdown voltage increases, the on-state resistance climbs even faster.



The MOSFET on-state resistance is contributed to primarily by three components of the transistor: the MOS channel, the neck region, and the extended drain region. The extended drain region contributes the most to the on-state resistance in high-voltage MOSFETs. To achieve a lower onstate resistance at a given blocking voltage, the usual technique is simply to make the die larger. However, increasing the die size has its limitations from a manufacturing point of view, since MOSFETs, with their very fine horizontal geometries, are highly defect-yield sensitive. As die size increases, the likelihood of a defect resulting in a nonfunctional part increases exponentially. This tendency, combined with a smaller number of parts per wafer, limits the availability of low-on-state-resistance, high-voltage MOS-FETs.

A change in the horizontal geometry of the MOSFET can lower the specific on-state resistance per unit area. By using more channel width with smaller source cells placed closer together, a reduction in on-state resistance can be achieved. A limitation on how close these cells can be placed arises from a possible localization of field concentrations that will limit the voltage breakdown of the structure to less than the theoretical rating due only to impurity concentrations. Therefore, for a given breakdown voltage, there exists a minimum spacing of the cell structure. Generally, the higher the required breakdown voltage, the further apart the cells must be placed.

As stated earlier, the extended drain region of the MOSFET generally contributes the most to the on-state resistance in high-voltage MOSFETs. As the required blocking voltage is increased, this region must be made thicker and more lightly doped to be able to support the desired voltage. It is this region's contribution to on-state resistance that the conductivity-modulated field-effect transistor drastically reduces. This reduction occurs as the result of the injection of minority carriers from the substrate and, in specific on-state resistance per unit area, is about 10 times less than in a standard MOSFET at the 400V BV<sub>DSS</sub> level, as shown in Figure 1.

Further analysis has shown that the specific on-state resistance may be nearly independent of blocking-voltage level. This finding implies that at a BV<sub>DSS</sub> of 1000V, the reduction in conductivity-modulated FETs over the standard MOSFETs could be perhaps 50 to 1. These reductions in on-state resistance per unit area that the conductivitymodulated FETs can achieve present the possibility that

high-voltage high-current FET-type devices can become more readily available because of the smaller die sizes associated with conductivity-modulated FETs.

# Comparison of Standard and Conductivity-Modulated FETs

Standard and conductivity-modulated FETs share some characteristics, but are substantially different in others. Shown in Table 1 is a listing of the major characteristics that make the conductivity-modulated FETs unique among power semiconductor families. Foremost, it is a voltage-gated device; its input characteristics are similar to standard power MOSFETs of comparable chip size. Very little drive power is required at low to moderate switching frequencies. The device remains under the control of the gate within its normal operating conditions. It exhibits the normal linear mode as well as the fully saturated on-state of conventional power MOSFETs. When the gate voltage is removed, the device turns off, unlike the thyristor family of power semiconductors, which must be either externally or naturally (internally) commutated.

#### TABLE 1. CONDUCTIVITY-MODULATED FET CHARACTERISTICS

Voltage Gated	Small gate power required. Similar to standard power MOSFET.
Turn Off	When gate drive is removed Unlike an SCR!
Nonlinear On-State Voltage drop	Like that of an SCR.
Turn On Speed	Fastl Comparable to a standard power MOSFET.
Turn-Off Speed	Slow! Comparable to a bipolar transistor.
Temperature Independent On-State Voltage Drop	Unlike the typical 2x variation of a power MOSFET.

The on-state voltage drop or resistance characteristic of a conductivity-modulated FET is markedly different from that of a standard power MOSFET, and is similar to that of a thyristor family member, the SCR. There is an offset voltage component (typically 0.6V) due to the p-n junction on the drain side, and a somewhat nonlinear resistive component, both of which are in series between the drain and source terminals. This series arrangement results in a highly nonlinear equivalent resistance, unlike the linear resistive characteristic of V<sub>DS(ON)</sub> of a standard FET.

The structure of the conductivity-modulated FET operates during its turn on just as a standard FET does, hence its turn-on speed is very similar to that of a standard FET. With its high input impedance and its short propagation delay, the turn-on transition of the conductivity-modulated FET, as well as the standard power FET, is easily controlled by the gate driving circuit. This characteristic allows the designer the ability to control EMI and RPI generation easily. With other power semiconductors, it may be necessary to employ elaborate circuit schemes to limit rapidly rising in-rush currents.

A significant characteristic that must be considered in power switching applications is that of turn-off speed. The internal

action that makes the conductivity-modulated FET such a silicon-efficient device also makes it an inherently slower device during turn-off. The injection of the minority carriers during the on-state conduction of current results in these carriers being present at the moment of turn-off. Without any way of removing these carriers by external means, they must recombine within the structure itself before the device can revert to its fully off-state condition. The quantity of these carriers and how fast they can deplete themselves determines the turn-off switching speed of the conductivitymodulated FET. This process of recombination is considerably slower than the simple discontinuance of majority carrier flow by which the standard power FET turns off. Hence, again, the conductivity-modulated FET is an inherently slower device. Its turn-off speed lies somewhere between the performance of a thyristor and that of a bipolar transistor.

The final characteristic that makes the conductivitymodulated FET different from a conventional FET is the variance of on-state voltage with temperature. The characteristic of the conductivity-modulated FET is similar to that of an SCR, varying about -0.6mV/°C. The conventional FET has a positive temperature coefficient such that on high-voltage devices the  $R_{DS(ON)}$  will double from its +25°C value when the junction temperature reaches +150°C. The system designer must take this characteristic into consideration when the heat sink is being designed for the system.

It is these similarities and differences that make the conductivity-modulated FET a unique member of the family of power-semiconductor switching devices. Applications of this alternative power switching device invariably make use of one or more of its unique characteristics.

# Applications

# Automotive Ignition

An application that can take advantage of the low drivepower capability of the conductivity-modulated FET is the electronic automotive ignition system. In Figure 2, the control IC takes the signal from the pickup coil located in the distributor and regulates the current through the ignition coil. At the proper time, the IC removes base drive from the bipolar transistor, which all systems currently employ as their coil driver. This removal of base drive allows the transistor to shut off which, in turn, causes a rapid decrease in the ignition-coil primary current. As the primary current decreases to zero, the energy stored in the field surrounding the primary is transferred to the secondary coil. The secondary coil, consisting of many more turns than the primary, transforms this energy into a higher voltage, resulting in a spark being generated in the cylinder. The control IC determines when this spark occurs, so as to derive usable power. With the use of a bipolar transistor, it is estimated that approximately two-thirds of the power dissipation that occurs in the control IC is the result of the need to be able to drive the required base current of the ignition output transistor. The high-impedance input of the conductivity-modulated FET virtually eliminates the basecurrent drive dissipation of the control IC.

With improved silicon usage, the conductivity-modulated FET brings to power semiconductor switching devices the die size necessary to attain the required voltage and currenthandling capabilities of the electronic ignition. This smallersized die makes possible smaller modules, whether they be hybrid or standard PC-based systems, than those currently implemented with bipolar-transistor technology.

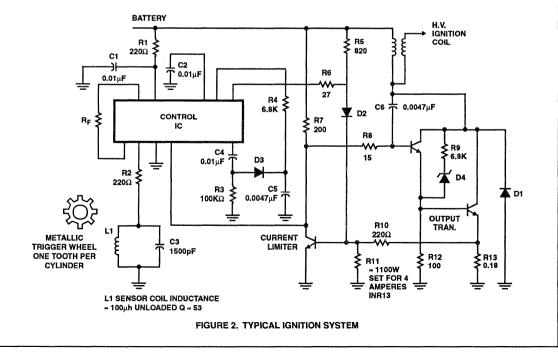
### **Brushless DC Motors**

Another emerging application that can make use of conductivity-modulated FETs is the emerging field of brushless DC motors. In this class of application, the solidstate devices are used to electronically switch the voltage to the multiplicity of windings that are employed. The motor consists of an armature that has a number of N and S poles consisting of high-strength permanent magnets. The stator is made up of the multiplicity of windings that were mentioned above; the windings are spaced incrementally about the outside frame of the housing. The voltages to these windings are all electronically switched to create a rotating magnetic field. The armature then rotates to maintain its relative position within the moving magnetic field. The switching of the voltage on the stator windings is done by means of power semiconductor devices. A basic block diagram of such a system is shown in Figure 3.

The control logic provides the proper sequence of drive signals based on the rotation direction desired, the speed desired, and the enable input. These requirements are combined with the inputs from the hall-effect sensors to determine which power devices should be activated. Since the current through the stator windings must be bidirectional, the half-bridge or totem-pole output configuration is used to steer the current. This circuit implementation is generally performed with complementary devices, although singlepolarity devices can be used with increased circuit complexity.

In a typical 120V off-line system, like the one shown in Figure 3, the switching devices must have a 300V to 400V blocking capability. For larger size motors, where larger currents are necessary, the use of power FETs generally implies the use of large die to achieve a low power dissipation to meet the heat-dissipation capability of the packaging. The conductivity-modulated FET, with its temperature-independent on-state-voltage-drop characteristic, helps this situation by keeping the dissipation lower than can be achieved with a standard power FET because of the increasing R<sub>DS(ON)</sub> characteristic of that device. The small die size of the conductivity-modulated FET, the result of better silicon utilization, again makes them the practical choice in motor control not only because of their electrical characteristics, but also because of the lower manufacturing cost of the die.

As stated above, system complexity can be reduced with complementary devices. Although p-channel conductivitymodulated FETs are not yet commerically available, laboratory samples have been fabricated which offers better silicon utilization efficiency than their conventional pchannel counterparts. This statement is based on the fact that p-channel MOSFETs require a 2.5 times larger area than an n-channel device for the same R<sub>DS(ON)</sub>. The easier drive requirements for the n-channel (directly driven from the control IC) and the simplified voltage-translation circuit for driving the p-channel devices, combined with the



smaller die size with potentially lower device cost for comparable power handling capability, makes the conductivity-modulated FET a natural for the brushless DC motor application.

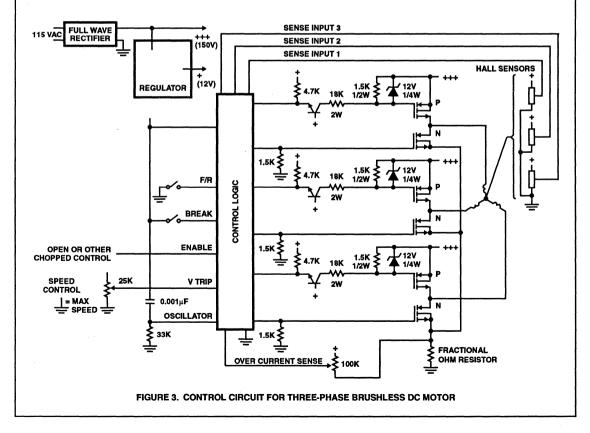
#### Switching Power Supply

One final application that has the potential for conductivitymodulated FET usage is the switching power supply. A half bridge configuration implementation is presented in Figure 4. The system shown uses a standard PWM control IC to drive the conductivity-modulated FETs through the T2 transformer. The voltage drive characteristic of these devices makes the design of transformer T2 quite simple. The control IC is more lightly loaded because it does not have to supply a continuous base drive, as would be necessary with bipolar transistors.

The operating frequency and the "dead time" are the limitations placed on this system when conductivity-modulated FETs are used. The inherent lower switching speeds of these types of devices make these limitations necessary. The system is currently limited to the 20kHz to 30kHz range, with dead times as low as 1 to 2 microseconds. This characteristic is comparable to many existing bipolar systems. Improvements in switching speeds will occur as the conductivity-modulated FET matures. It is, however, unlikely that they will ever have the same switching speeds as standard power FETs. This limitation prohibits their use in some of the newer higher-frequency power supplies being designed now with conventional FETs. However, in higher-power supplies, where conventional FETs must be paralleled to achieve a low enough  $R_{DS(ON)}$  for good efficiency, the conductivity-modulated FET may present a viable alternative with its smaller die size. Although the operating frequency of the system may have to be compromised to use them.

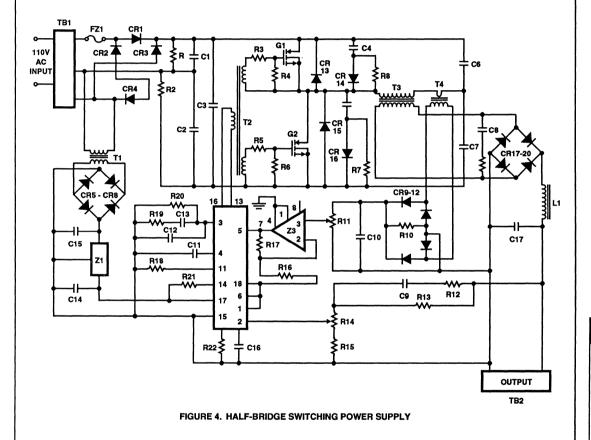
#### Conclusion

The conductivity-modulated FET represents a progression in the ever-advancing state-of-the-art development that occurs in the world of solid-state devices. The unique structure of these devices presents characteristics that make them equivalent in many ways to conventional FETs but superior in other ways. The system designer must take into account these similar and dissimilar characteristics to properly use them. The capabilities of the conductivity-modulated FETs allow them to make inroads into applications currently served by bipolar transistors, and in some cases conventional power FETs. As the devices mature through innovation and product refinement, conductivity-modulated FETs will become vital members of the family of solid-state power-semiconductor devices.



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APPLICATION NOTES

# Harris Semiconductor



# No. AN8602.1 May 1992

# Harris Power MOSFETs

# THE IGBTs - A NEW HIGH CONDUCTANCE MOS-GATED DEVICE

Author: J.P. Russell, A.M. Goodman, L.A. Goodman and J.M. Neilson

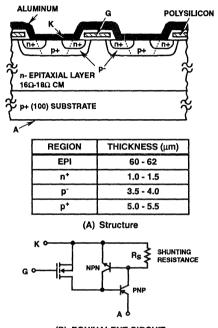
# Abstract

A new MOS gate-controlled power switch with a very low onresistance is described. The fabrication process is similar to that of an n-channel power MOSFET but employs an n-epitaxial layer grown on a p<sup>+</sup> substrate. In operation, the epitaxial region is conductivity modulated (by excess holes and electrons) thereby eliminating a major component of the on-resistance. For example, on-resistance values have been reduced by a factor of about 10 compared with those of conventional n-channel power MOSFETs of comparable size and voltage capability.

# Introduction

Vertical MOSFETs have become increasingly important in discrete power device applications due primarily to their high input impedance, rapid switching times, and low onresistance. However, the on-resistance of such devices increases with increasing drain-source voltage capability.1-3 thereby limiting the practical value of power MOSFETs to applications below a few hundred volts. In this letter, we describe the fabrication and characteristics of a new vertical power MOSFET structure that provides an on-resistance value about 10 times smaller than that of conventional power MOSFETs of the same size and voltage capability. In this device, the conductivity of the epitaxial drain region of a conventional MOSFET is dramatically increased (modulated) by injected carriers; this mechanism results in a significant reduction in the device on-resistance and leads to the acronym IGBTs (Insulated Gate Bipolar Transistor).

This device, while similar in structure to the MOS-gated thyristor,4,5 is different in a fundamental way; it maintains gate control (doesn't latch) over a wide range of anode current and voltage.<sup>6</sup> The structure and the equivalent circuit for the IGBTs are shown in Figure 1(a) and (b); they are similar to those of an MOS-gated thyristor, except for the presence of the shunting resistance Rs in each unit cell. The fabrication is like that of a standard n-channel power MOSFET except that the n-epitaxial Si layer is grown on a p<sup>+</sup> substrate instead of an n+ substrate. The heavily doped p<sup>+</sup> region in the center of each unit cell, combined with the sintered aluminum contact shorting the n<sup>+</sup> and p<sup>+</sup> regions, provides the shunting resistance shown in Figure 1(b). This has the effect of lowering the current gain of the n-p-n transistor ( $\alpha$ n-p-n) so that  $\alpha$ n-p-n +  $\alpha$ p-n-p <1. Thus latching is prevented and gate control is maintained within a large operating range of anode voltage and current.<sup>6</sup>



(B) EQUIVALENT CIRCUIT

In the remainder of this note we describe the operation and characteristics of this device.

# **Device Operation**

The IGBT is a four-layer (n-p-n-p) device with an MOS-gated channel connecting the two n-type regions. In the normal mode of operation, a positive voltage is applied to the anode (A) relative to the cathode (K). When the gate (G) is at zero potential with respect to K, no anode current (i<sub>A</sub>) flows for anode voltage V<sub>A</sub> below the breakdown level V<sub>BF</sub>. When V<sub>A</sub> < V<sub>BF</sub> and the gate voltage is larger than the threshold value V<sub>GT</sub>, electrons pass into the n<sup>-</sup>region (base of the p-n-p transistor). These electrons lower the potential of the n<sup>-</sup>region, forward biasing the p<sup>+</sup> - n<sup>-</sup> (substrate-epi-layer) junction, thereby causing holes to be injected from the p+ substrate into the n<sup>-</sup> epi-layer region. The excess electrons and holes modulate the conductivity of the high-resistivity n-region, which dramatically reduces the on-resistance of the

device. During normal operation, the shunting resistor (R<sub>S</sub>) keeps the emitter current of the n-p-n transistor very low, which keeps  $\alpha$ n-p-n very low. However, for sufficiently large i<sub>A</sub>, significant emitter injection may occur in the n-p-n transistor, causing  $\alpha$ n-p-n to increase; in this case the four-layer device may latch, accompanied by loss of control by the MOS gate. In this event, the device may be turned off by lowering i<sub>A</sub> below some "holding" value, as is typical of a thyristor.

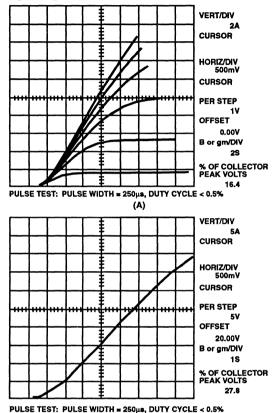
# **Device Characterization**

Two different lots of IGBT structures, consisting of about 10 wafers/lot, have been successfully prepared to date. From these wafers, 1.5mm and 3mm square devices were fabricated using a standard HEXFET geometry<sup>7</sup> with a polysilicon gate electrode over an SiO<sub>2</sub> gate dielectric. Several hundred IGBT were mounted in standard TO-3 and TO-66 packages and characterized under DC and pulsed conditions, as described below.

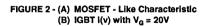
With zero gate bias, the forward characteristic of a IGBTs shows very low current (<1nA) up to about 390V, where it breaks up sharply to much larger current levels with only a slight increase in voltage. If the internal junction between the p<sup>+</sup> substrate and the n<sup>-</sup> epitaxial layer had been edge-passivated, a similar reverse breakdown characteristic would be expected. The actual reverse breakdown voltage for our devices was about 100V because edge passivation was not used.

Figure 2(a) shows the MOSFET-like transfer characteristics of an IGBT in the low gate-voltage region. A noteworthy feature of the IGBT characteristic is the ~0.7V offset, from the origin, of the steeply rising portion of the i(v) characteristics. This offset is the voltage required to forward bias the  $p^+$  - n<sup>-</sup> (substrate-epi-layer) junction, and is an integral characteristic to f the present device.

Figure 2(b) shows the i(v) characteristic of an IGBT with  $V_G = 20V$ , and demonstrates the low on-resistance of the device (~0.084 $\Omega$  at 20A). The on-resistance values of nearly all of the many IGBT fabricated to date have been less than 0.1 $\Omega$  (at 20A) for the 3mm square devices. Such values compare very favorably with those of conventional power MOS structures, as illustrated in Figure 3. Here, the open data points (and the upper curve) are from data sheet specifications of commercial power MOSFETs (Harris, IRC, and Motorola). The solid data points (and the lower curve) are those of Baliga, which he labelled "stateof-the-art",3 supplemented with some of the "best" of Harris' commercial and developmental MOSFETs. Note that the on-resistance of the IGBT is approximately IO times less than that of a 400V state-of-the-art MOSFET. Moreover, similarly low on-resistance values should be obtainable from IGBT designed for higher drain-source voltages. This is due to the fact that the resistance of the modulated region is determined by the concentrations and mobilities of the excess carriers (as in a p-i-n diode)<sup>8</sup> rather than by the background doping of the layer. In particular, the epi-layer doping and thickness of our present IGBT structures were designed for 600V, but V<sub>BF</sub> was limited to 400V by the edge design of the device. An improved edge design should provide a blocking capability closer to bulk breakdown, without altering the on-resistance of the device. This would make the IGBTs on-resistance of less than  $0.1\Omega$  even more attractive for high-voltage applications.



(B)



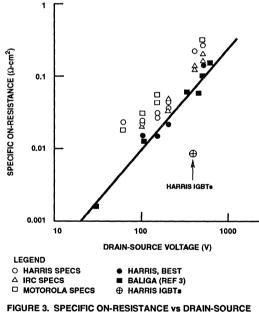
# Transient Response Measurement

Switching time measurements under pulsed gate-voltage operation were used to characterize the transient operation of the device. The response of the anode current to a square-wave gate-voltage pulse is comprised of a rapid turn-on (with a typical time less than  $1\mu$ s) and a somewhat slower turn-off. We observed that the turn-off transient consists of an initial "fast" component, followed by a "slow" tail, as shown in Figure 4.

We believe that the initial rapid decay is due to the turn-off of the MOS portion of the equivalent circuit, and the turn-off tail is due to the time required for the excess carriers in the epitaxial drain region to decay. In general, turn-off times in the range of  $5\mu$ s to  $20\mu$ s were observed, with the precise value depending on circuit conditions and the turn-off time of the gate pulse.

The n-p-n-p structure of the IGBTs is similar to that of a thyristor and can be forced to latch under sufficiently high drive conditions. We have observed latching currents in the range 10A - 30A in 3mm square chips. The magnitude of the latching current has been found to depend on both anode voltage and temperature, decreasing with increasing anode voltage or increasing temperature.

More interestingly, the latching current is also strongly influenced by the gate voltage turn-off time. Slow gate turn-off (~10µs) permits anode currents up to 30A without latching. However, rapid gate turn-off (<1µs) leads to latching at a much lower anode current level (~10A) in the same device. We believe that latching during rapid turn-off of the gate voltage is due to current being forced through the n-p-n transistor causing  $\alpha$ n-p-n to increase, and leading to the condition for latching,  $\alpha$ n-p-n +  $\alpha$ p-n-p = 1. Slow turn-off of the gate voltage prevents this, since the induced channel turns off slowly and partially shunts the n-p-n sufficiently low to avoid latching.



VOLTAGE CAPABILITY FOR STATE-OF-THE-ART POWER MOSFETS AND THE IGBTS

# Summary

A new MOS-gate-controlled power device, the IGBTs, has been described. The device has the desirable feature of a very low on-resistance similar to that of a thyristor, but is capable of maintaining gate control of the anode current over a wide range of operating conditions. The low on- resistance is due to conductivity modulation of the n epitaxial layer equivalent to the extended drain in a power MOSFET; this carries with it the penalty of slow switching compared with that of a conventional power MOSFET.

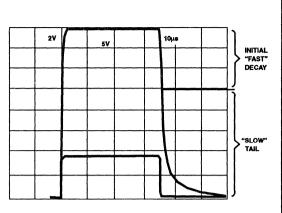


FIGURE 4. GATE VOLTAGE (LOWER TRACE) AND ANODE CURRENT (UPPER TRACE) WAVEFORMS FOR  $i_A(MAX) = 8A$ 

# Acknowledgment

The authors gratefully acknowledge the various helpful contributions of C. Nuese, D. Bergman, R. Ford, R. Jarl, G. Looney, P. Robinson, W. Romito, L. Skurkey, R. Stolzenberger, C. Wheatley, J. Wojslawowicz, and the staff of the Integrated Circuit Technology Center at RCA Laboratories. Added Note: Following submission of this Note, a similar device was described by B. J. Baliga in a presentation on December 14, 1982 at the International Electron Devices Meeting in San Francisco, CA. (B. J. Baliga et al., "The Insulated Gate Rectifier (IGR): A New Power-Switching Device", in IEDM Tech. Dig. 1982, pp 264-267.

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# **Harris Semiconductor**



# No. AN8603.2 December 1993

# Harris Power MOSFETs

# IMPROVED IGBTs WITH FAST SWITCHING SPEED AND HIGH-CURRENT CAPABILITY

Author: A.M. Goodman, J.R. Russell, L.A. Goodman, C.J. Nuese and J.M. Neilson

# Abstract

Conventional vertical power MOSFETs are limited at high voltages (>500V) by the appreciable resistance of their epitaxial drain region. In a new MOS-gate controlled device called an IGBT, this limitation is overcome by modulating the conductivity of the resistive drain region, thereby reducing the on-resistance of the device by a factor of at least 10. However, the device previously described is slow in turnoff. having a fall time in the range 8 to 40us. The purpose of our present work has been to reduce the fall time significantly and to increase the latching current level of the IGBTs, while retaining its desirable features. By modification of the epitaxial structure and addition of recombination centers, we have achieved fall times as low as 0.1µs and latching currents as high as 50A, while retaining on-resistance values <0.2Ω for a 0.09cm<sup>2</sup> chip area. The techniques used for the introduction of recombination centers include electron, gamma-ray, and neutron irradiation, as well as heavy metal doping. For a series of IGBTs (with forward-blocking voltage capabilities of 400-600V), the fall time can be reduced by more than one order of magnitude with a penalty of less than a 20% increase in on-resistance.

# Introduction

Vertical MOSFETs have become increasingly important in discrete power device applications due primarily to their high input impedance, rapid switching times and low on-resistance. However, the on-resistance of such devices increases with increasing drain-source voltage capability,<sup>1-3</sup> thereby limiting the practical value of power MOSFETs to applications below a few hundred volts. This limitation has been effectively overcome by the development of a new MOS power device in which the conductivity of the n-type epitaxial drain region is greatly increased (modulated) by the injection of minority carriers from a p-type substrate. We have called this device a COMFET-an acronym for COnductivity Modulated Field Effect Transistor;<sup>4</sup> the device has also been called an IGBT or Insulated Gate Bipolar Transistor.

The devices, as originally described, had most of the advantages of conventional power MOSFETs; in addition, they exhibited more than an order-of-magnitude reduction in high current on-resistance values, permitting improved utilization of silicon chip area. However, they also had two disadvantages:

When a IGBT is turned off, the injected minority carriers that remain in the epitaxial drain region decay by recombination with majority carriers at a rate determined by the minority-carrier lifetime,  $\tau_F$ . Large values of  $\tau$  resulted in anode-current fall time,  $t_F$  in the range 8-40ms.  $^{4,5}$ 

The maximum operating current is limited by latchup of the parasitic thyristor that is inherent in the device structure. Typical latching current levels of I<sub>L</sub>,  $\leq$  10A were observed in 0.09cm2 area devices when the gate voltage was turned off rapidly (<1ms); for slower gate voltage turnoff (~10ms), I<sub>L</sub> values as high as ~30A were observed.

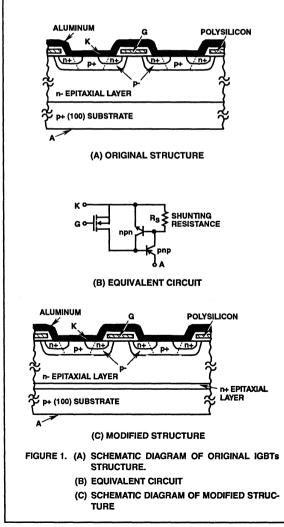
The purpose of the present work has been to reduce  $t_F$  and to increase  $I_L$  while retaining the desirable features of the device. By modifying the epitaxial structure and adding recombination centers to the epitaxial drain region, we have achieved  $t_F$  values as low as 100ns and  $I_L$  values as high as 50A with rapid gate voltage turnoff.

# **Modified Structure**

A schematic diagram of the original IGBT structure<sup>4</sup> is shown in Figure 1(a), and the equivalent circuit is shown in Figure 1(b); they are similar to those of an MOS-gated thyristor except for the presence of the shunting resistance Rs in each unit cell. The fabrication is like that of a standard n-channel power MOSFET, except that the n-epitaxial laver is grown on a p+ substrate instead of an n+ substrate. The heavily doped p+ region in the center of each unit cell, combined with the aluminum contact shorting the n+ and p+ regions, provides the shunting resistance RS. This has the effect of lowering the current gain of the n-p-n transistor in the equivalent circuit so that  $\alpha npn + \alpha pnp < 1$ , thereby preventing latching over a large operating range of anode voltage  $V_A$  and anode current  $i_A$ . However, for sufficiently large iA, emitter injection in the n-p-n transistor will increase, accompanied by an increase in onpn. When anpn + app increases to 1, the four-layer device will latch; the level of iA at which this occurs is the latching current level,  $I_L$ . Thus, it can be seen that a structure modification that lowers  $\alpha$ pnp will allow a greater range of  $i_A$  (and  $\alpha$ npn) without latching; that is, a reduction in  $\alpha$ pnp corresponds to an increase in  $I_I$ .

The modified structure shown in Figure 1(C) differs from that in Figure 1(A) by the addition of a thin (~10mm) layer of n+ silicon in the epitaxial structure between the n- region and the p+ substrate. This n+ layer lowers the emitter injection efficiency of the p-n-p transistor in the equivalent circuit, and results in an increase in I<sub>L</sub> by a factor of 2 to 3. In addition, there is also a reduction in t<sub>F</sub>.

These results are illustrated in Figure 2, in which  $t_F$ , is plotted versus  $i_A$  for each device structure. It should be noted that IGBTs with the modified structure can block high voltage only in the forward voltage direction since the emitter junction (p+ - n+) of the p-n-p transistor breaks down at a low level when the polarity of the applied voltage is reversed.



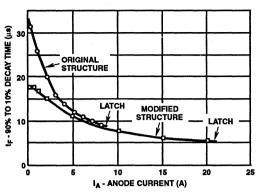
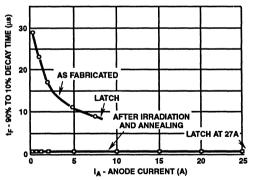


FIGURE 2. ANODE-CURRENT FALL TIME 1<sub>F</sub> VERSES ANODE CURRENT FOR ORIGINAL STRUCTURE AND MODIFIED STRUCTURE.

# Addition Of Recombination Centers

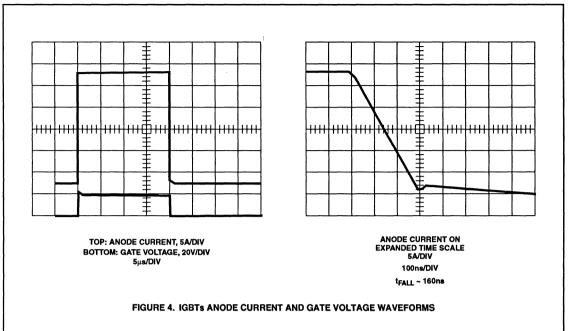
We have used a variety of techniques to add recombination centers to IGBTs; these include high energy electron, gamma ray, and fast neutron irradiation, as well as heavy metal doping. The irradiations were carried out after completion of all of the high-temperature processing steps, but in each case an additional heat treatment was necessary to stabilize the devices by annealing out gate oxide charge, as well as those radiation induced defects in the silicon (recombination centers) that would otherwise anneal out slowly at the device operating temperature.<sup>7</sup> Typical values of t<sub>F</sub> of the order of 1 $\mu$ s or less were achievable using any of the techniques.



# FIGURE 3. ANODE-CURRENT FALL TIME $t_F$ VERSUS ANODE CURRENT FOR AN AS-FABRICATED DEVICE AND AFTER 14MeV NEUTRON IRRADIATION ( $10^{13}n/cm^2$ ) FOLLOWED BY ANNEALING AT +300°C.

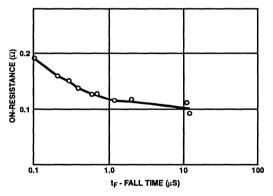
An example of the variation of t<sub>F</sub>, with i<sub>A</sub> (1) as fabricated and (2) after irradiation with 14MeV neutrons and annealing is shown in Figure 3. Here, the neutron fluence was ~10<sup>13</sup>n/ cm<sup>2</sup>; this was followed by annealing at +300°C. Note that t<sub>F</sub>, has not only been drastically reduced, but is virtually constant at ~0.6µs; i.e., almost independent of i<sub>A</sub>.

# Application Note 8603



It is possible to lower  $t_F$ , still further by appropriate irradiation and annealing or by heavy metal doping procedures, although this is not necessarily desirable for reasons that are discussed below. The smallest values of  $t_F$ , that we have obtained for fully stabilized IGBTs is in the range 100ns to 200ns. This is illustrated in Figure 4.

The reduction in minority carrier lifetime that allows faster switching also carries with it a penalty higher forward voltage drop when the device is turned on; i.e., higher on-resistance. Since, in the forward conduction of an IGBT, current and voltage are not linearly related, it is necessary to specify a current level at which to compare on-resistance values of different devices. In Figure 5 we plot the on-resistance (at i<sub>A</sub> = 20A) of a series of devices with 0.09cm<sup>2</sup> chip area against their t<sub>E</sub> values after irradiation and annealing. All t<sub>E</sub> values shown were obtained at  $i_A = 5A$ ; for the devices with short switching times, t<sub>E</sub> is virtually independent of i<sub>A</sub>. Clearly, there is a trade-off involved, and the optimum choice of a value for t<sub>E</sub> and the corresponding on-resistance value will depend, to some extent, on the intended application. However, even for the shortest switching times shown (100ns), the on-resistance value of  $0.2\Omega$  is approximately an order-of-magnitude less than that of comparably sized n-channel MOSFETs.

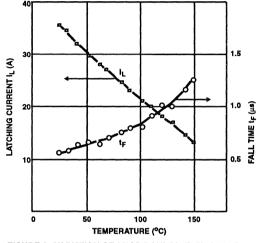


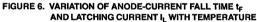
#### FIGURE 5. ON-RESISTANCE vs. ANODE-CURRENT FALL TIME t<sub>F</sub> FOR A SERIES OF IGBTs AFTER VARIOUS IRRA-DIATION AND ANNEALING TREATMENTS

APPLICATION NOTES

# Temperature Dependence of T<sub>F</sub>, And I<sub>L</sub>

All of the device performance data presented thus far have been measured at room temperature. However, power devices are often operated at elevated temperatures, and it is important to determine how their performance varies with temperature. In Figure 6 the variation of t<sub>F</sub> and I<sub>L</sub> for a device that has been irradiated and annealed is plotted versus temperature in the range +25°C to +150°C. This behavior is typical of all of the devices we have tested; i.e., t<sub>F</sub> increases and I<sub>L</sub> decreases with increasing temperature, both by a factor of between 2 and 3 in the interval +25°C to +150°C.





# Summary

By modification of the epitaxial structure of the IGBT and the addition of recombination centers, we have achieved anodecurrent fall times as low as 100ns in IGBTs with latching currents as high as 50A for a 0.09cm<sup>2</sup> chip area. We have described the trade-off between on-resistance and anodecurrent fall time that may be obtained, and have demonstrated the variation of anode-current fall time and latching current with operating temperature.

# Acknowledgment

The authors are indebted to D. Bergman, R. Ford, F. DiGeronimo, G. Looney, P. Robinson, W. Romito, L. Skurkey, M. Snowden, R. Stolzenberger, and the staff of the Integrated Circuit Technology Center at RCA Laboratories for their various contributions to the fabrication and characterization of the IGBTs. A special thank you goes to F. Taft, Z. Streletz, and H. Hendel who carried out the device irradiations.

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# Harris Semiconductor



No. AN9318 September 1993

# INSULATED-GATE TRANSISTORS SIMPLIFY AC-MOTOR SPEED CONTROL

Authors: Marvin Smith, William Sahm and Sridhar Babu

An IGT's few input requirements and low On-state resistance simplify drive circuitry and increase power efficiency in motorcontrol applications. The voltage-controlled, MOSFET-like input and transfer characteristics of the insulated-gate transistor (IGT) (see EDN, September 29, 1983, pg 153 for IGT details) simplify power-control circuitry when compared with bipolar devices. Moreover, the IGT has an input capacitance mirroring that of a MOSFET that has only one-third the powerhandling capability. These attributes allow you to design simple, low-power gate-drive circuits using isolated or level-shifting techniques. What's more, the drive circuit can control the IGT's switching times to suppress EMI, reduce oscillation and noise, and eliminate the need for snubber networks.

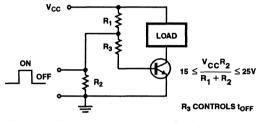
### Use Optoisolation To Avoid Ground Loops

The gate-drive techniques described in the following sections illustrate the economy and flexibility the IGT brings to power control: economy, because you can drive the device's gate directly from a preceding collector, via a resistor network, for example; flexibility, because you can choose the drive circuit's impedance to yield a desired turn-off time, or you can use a switchable impedance that causes the IGT to act as a charge-controlled device requiring less than 10 nanocoulombs of drive charge for full turn-on.

### Take Some Driving Lessons

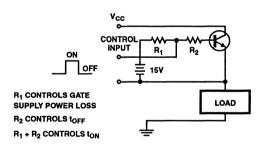
Note the IGT's straightforward drive compatibility with CMOS, NMOS and open-collector TTL/HTL logic circuits in the common-emitter configuration Figure 1A.  $R_3$  controls the turn-off time, and the sum of  $R_3$  and the parallel combination of  $R_1$  and  $R_2$  sets the turn-on time. Drive-circuit requirements, however, are more complex in the common-collector configuration Figure 1B.

In this floating-gate-supply floating-control drive scheme, R<sub>1</sub> controls the gate supply's power loss, R<sub>2</sub> governs the turn-off time, and the sum of R<sub>1</sub> and R<sub>2</sub> sets the turn-on time. Figure 1C shows another common-collector configuration employing a bootstrapped gate supply. In this configuration, R<sub>3</sub> defines the turn-off time, while the sum of R<sub>2</sub> and R<sub>3</sub> controls the turn-on time. Note that the gate's very low leakage allows the use of low-consumption bootstrap supplies using very low-value capacitors. Figure 1 shows two of an IGT's strong points. In the common-emitter Figure 1A, TTL or MOS-logic circuits can drive the device directly. In the common-collector mode, you'll need level shifting, using either a second power supply Figure 1B or a bootstrapping scheme Figure 1C.



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#### FIGURE 1B. A SECOND POWER SUPPLY

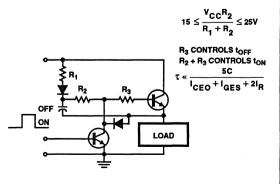


FIGURE 1C. BOOTSTRAPPING SCHEME

APPLICATION NOTES

In the common-collector circuits, power-switch current flowing through the logic circuit's ground can create problems. Optoisolation can solve this problem (Figure 2A.) Because of the high common-mode dV/dt possible in this configuration, you should use an optoisolator with very low isolation capacitance; the H11AV specs 0.5pF maximum.

For optically isolated "relay-action" switching, it makes sense to replace the phototransistor optocoupler with an H11L1 Schmitt-trigger optocoupler (Figure 2B).) For applications requiring extremely high isolation, you can use an optical fiber to provide the signal to the gate-control photodetector. These circuit examples use a gate-discharge resistor to control the IGT's turn-off time. To exploit fully the IGT's safe operating area (SOA), this resistor allows time for the device's minority carriers to recombine. Furthermore, the recombination occurs without any current crowding that could cause hot-spot formation or latch-up pnpn action. For very fast turn-off, you can use a minimal snubber network, which allows the safe use of lower value gate resistors and higher collector currents.

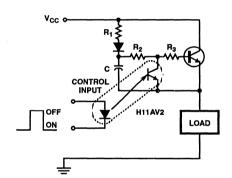


FIGURE 2A. AVOID GROUND-LOOP PROBLEMS BY USING AN OPTOISOLATOR. THE ISOLATOR IGNORES SYS-TEM GROUND CURRENTS AND ALSO PROVIDES HIGH COMMON-MODE RANGE.

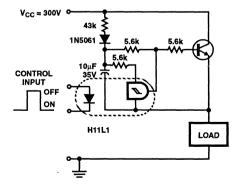


FIGURE 2B. A SCHMITT-TRIGGER OPTOISOLATOR YIELDS "SNAP-ACTION" TRIGGERING SIMILAR TO THAT OF A RELAY.

#### Pulse-Transformer Drive Is Cheap And Efficient

Photovoltaic couplers provide yet another means of driving the IGT. Typically, these devices contain an array of small silicon photovoltaic cells, illuminated by an infrared diode through a transparent dielectric. The photovoltaic coupler provides an isolated, controlled, remote dc supply without the need for oscillators, rectifiers or filters. What's more, you can drive it directly from TTL levels, thanks to its 1.2V, 20mA input parameters.

Available photovoltaic couplers have an output-current capability of approximately  $100\mu A$ . Combined with approximately  $100k\Omega$  equivalent shunt impedance and the IGT's input capacitance, this current level yields very long switching times. These transition times (typically ranging to 1 msec) vary with the photovoltaic coupler's drive current and the IGT's Miller-effect equivalent capacitance.

Figure 3 illustrates a typical photovoltaic-coupler drive along with its transient response. In some applications, the photovoltaic element can charge a storage capacitor that's subsequently switched with a phototransistor isolator. This isolator technique - similar to that used in bootstrap circuits provides rapid turn-on and turn-off while maintaining small size, good isolation and low cost.

In common-collector applications involving high-voltage, reactive-load switching, capacitive currents in the low-level logic circuits can flow through the isolation capacitance of the control element (eg, a pulse transformer, optoisolator, piezoelectric coupler or level-shift transistor). These currents can cause undesirable effects in the logic circuitry, especially in highimpedance, low-signal-level CMOS circuits.

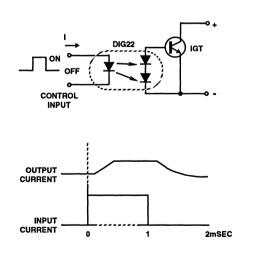


FIGURE 3. AS ANOTHER OPTICAL-DRIVE OPTION, A PHOTO-VOLTAIC COUPLER PROVIDES AN ISOLATED, REMOTE DC SUPPIY TO THE IGT'S INPUT. ITS LOW 100µA OUTPUT, HOWEVER, YIELDS LONG IGT TURN-ON AND TURN-OFF TIMES. The solution? Use fiber-optic components Figure 4 to eliminate the problems completely. As an added feature, this low-cost technique provides physical separation between the power and logic circuitry, thereby eliminating the effects of radiated EMI and high-flux magnetic fields typically found near power-switching circuits. You could use this method with a bootstrap-supply circuit, although the fiber-optic system's reduced transmission efficiency could require a gain/speed trade-off. The added bipolar signal transistor minimizes the potential for compromise.

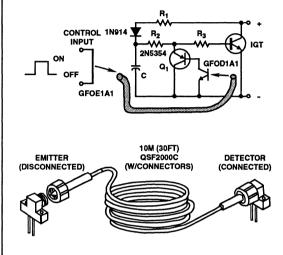


FIGURE 4. ELIMINATE EMI IN HIGH-FLUX OR NOISE ENVI-RONMENTS BY USING FIBER-OPTIC COMPO-NENTS. THESE PARTS ALSO ALLEVIATE PROBLEMS ARISING FROM CAPACITIVE COU-PLING IN ISOLATION ELEMENTS.

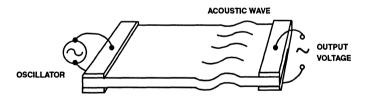
### **Piezos Pare Prices**

A piezoelectric coupler operationally similar to a pulse-train drive transformer, but potentially less costly in high volume is a small, efficient device with isolation capability ranging to 4kV. What's more, unlike optocouplers, they require no auxiliary power supply. The piezo element is a cerarnic component in which electrical energy is converted to mechanical energy, transmitted as an acoustic wave, and then reconverted to electrical energy at the output terminals Figure 5A.

The piezo element's maximum coupling efficiency occurs at its resonant frequency, so the control oscillator must operate at that frequency. For example, the PZT61343 piezo coupler in Figure 5B's driver circuit requires a 108kHz,  $\pm$ 1%-accurate astable multivibrator to maximize mechanical oscillations in the ceramic material. This piezo element has a 1W max power handling capability and a 30mA p-p max secondary current rating. The 555 timer shown provides compatible waveforms while the RC network sets the frequency.

### **Isolate With Galvanic Impunity**

Do you require tried and true isolation? Then use transformers; the IGT's low gate requirements simplify the design of independent, transformer-coupled gate-drive supplies. The supplies can directly drive the gate and its discharge resistor Figure 6, or they can simply replace the level-shifting supplies of Figure 2. It's good practice to use pulse transformers in drive circuitry, both for IGT's and MOSFETs, because these components are economical, rugged and highly reliable.





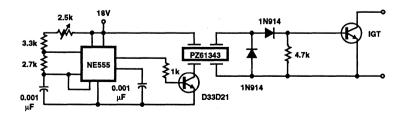


FIGURE 5B. THIS CIRCUIT PROVIDES THE DRIVE FOR THIS ARTICLE'S MOTOR-CONTROL CIRCUIT.

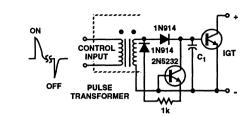
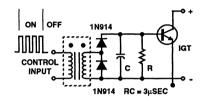


FIGURE 6A. PROVIDING HIGH ISOLATION AT LOW COST, PULSE TRANSFORMERS ARE IDEAL FOR DRIVING THE IGT. AT SUFFICIENTLY HIGH FREQUENCIES, C1 CAN BE THE IGT'S GATE-EMITTER CAPACITANCE ALONE.



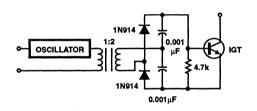
### FIGURE 6B. A HIGH-FREQUENCY OSCILLATOR IN THE TRANS-FORMER'S PRIMARY YIELDS UNLIMITED ON-TIME CAPABILITY.

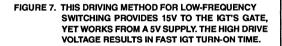
In the pulse-on, pulse-off method Figure 6A, C<sub>1</sub> stores a positive pulse, holding the IGT on. At moderate frequencies (several hundred Hertz and above), the gate-emitter capacitance alone can store enough energy to keep the IGT on; lower frequencies require an additional external capacitor. Use of the common-base n-p-n bipolar transistor to discharge the capacitance minimizes circuit loading on the capacitor. This action extends continuous on-time capability without capacitor refreshing; it also controls the gate-discharge time via the  $1k\Omega$  emitter resistor.

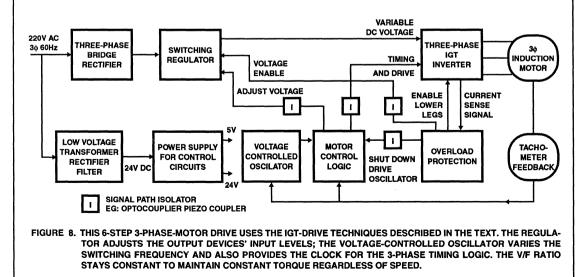
### Piezoelectric Couplers Provide 4-kV Isolation

Using a high-frequency oscillator for pulse-train drive Figure 6B yields unlimited on-time capability. However, the scheme requires an oscillator that can be turned on and off by the control logic. A diode or zener clamp across the transformer's primary will limit leakage-inductance flyback effects. To optimize transformer efficiency, make the pulses' voltage x time products equal for both the On and the Off pulses. In situations where the line voltage generates the drive power, a simple relaxation oscillator using a programmable unijunction transistor can derive its power directly from the line to provide a pulse train to the IGT gate.

The circuit shown in Figure 7 accommodates applications involving lower frequencies (a few hundred Hertz and below). The high oscillator frequency (greater than 20kHz) helps keep the pulse transformer reasonably small. The voltage-doubler circuitry improves the turn-on time and also provides long on-time capability. Although this design uses only a 5V supply on the primary side of a standard trigger transformer, it provides 15V gate-to-emitter voltage.







Polyphase motors, controlled by solid-state, adjustable-frequency ac drives, are used extensively in pumps, conveyors, mills, machine tools and robotics applications. The specific control method could be either 6-step or pulse-width modulation. This section describes a 6-step drive that uses some of the previously discussed drive techniques (see page 11, "Latch-Up: Hints, Kinks and Caveats").

Figure 8 defines the drive's block diagram. A 3-phase rectifier converts the 220V ac to dc; the switching regulator varies the output voltage to the IGT inverter. At the regulator's output, a large filter capacitor provides a stiff voltage supply to the inverter.

The motor used in this example has a low slip characteristic and is therefore very efficient. You can change the motor's speed by varying the inverter's frequency. As the frequency increases, however, the motor's air-gap flux diminishes, reducing developed-torque capability. You can maintain the flux at a constant level (as in a dc shunt motor) if you also vary the voltage so the V/F ratio remains constant.

### Fiber-Optic Drive Eliminates Interference

In the example given, the switching regulator varies the IGT inverter's output by controlling its dc input; the voltage-controlled oscillator (VCO) adjusts the inverter's switching frequency, thereby varying the output frequency. The VCO also drives the 3-phase logic that provides properly timed pulsed outputs to the piezo couplers that directly drive the IGT.

Sensing the dc current in the negative rail and inhibiting the gate signal protect the IGT from overload and shoot-through (simultaneous conduction) conditions. If a fault continues to exist for an appreciable period, inhibiting the switching regulator causes the inverter to shut off. The inverter's power-output circuit is shown in Figure 9A; the corresponding timing diagrams show resistive-load current waveforms that indicate the 3-phase power Figure 9B and waveforms of the output line voltage and current Figure 9C.

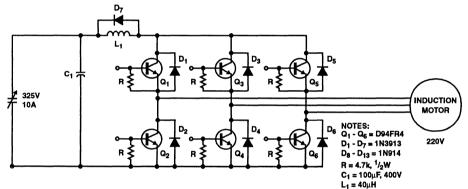


FIGURE 9A. THE POWER INVERTER'S DRIVE CIRCUIT USES SIX IGTS TO DRIVE A 2-HP MOTOR.

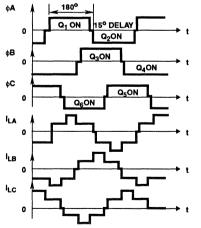


FIGURE 9B. THE TIMING DIAGRAM SHOWS THAT EACH IGT CONDUCTS FOR 165° OF EVERY 360° CYCLE; THE DELAY IS NECESSARY TO AVOID CROSS CONDUCTION.

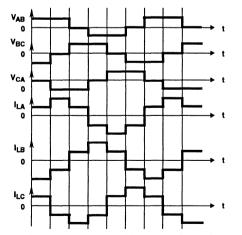


FIGURE 9C. THE THREE WINDINGS' VOLTAGES AND CUR-RENTS ARE SHOWN. NOTE THAT ALTHOUGH COSTLY SNUBBER NETWORKS ARE ELIMINATED, FREEWHEELING DIODES ARE NEEDED; THE IGTS HAVE NO INTRINSIC OUTPUT DIODE. APPLICATION NOTES

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In Figure 9's circuit, it appears that IGTs  $Q_1$  through  $Q_6$  will conduct for 180°. However, in a practical situation, it's necessary to provide some time delay (typically 10° to 15°) during the positive-to-negative transition periods in the phase current. This delay allows the complementary IGTs to turn off before their opposite members turn on, thus preventing cross conduction and eventual destruction of the IGTs.

Because of the time delay, the maximum conduction time is 165° of every 360° period. Because the IGTs don't have an integral diode, it's necessary to connect an antiparallel diode externally to allow the freewheeling current to flow. Inductor L<sub>1</sub> limits the di/dt during fault conditions; freewheeling diode D<sub>7</sub> clamps the IGT's collector supply to the dc bus.

The peak full-load line current specified by the motor manufacturer determines the maximum steady-state current that each transistor must switch. You must convert this RMSspecified current to peak values to specify the proper IGT. If the input voltage regulator had a fixed output voltage and a constant frequency, each IGT would be required to supply the starting locked-rotor current to the motor. This current could be as much as 15 times the full-load running current.

It's impractical, however, to rate an inverter based on lockedrotor current. You can avoid this necessity by adjusting the switching regulator's output voltage and by providing a fixed output-current limit slightly higher than the maximum fullload current. This way, the current requirements during startup will never exceed the current capability of an efficiently sized inverter. For example, consider a 2-hp, 3-phase induction motor specifying V<sub>L</sub> at 230V RMS and full-load current ( $I_{LFL}$ ) at 6.2A RMS. For the peak current of 8.766A, you can select IGT type D94FR4. This device has a reverse-breakdown SOA (RBSOA) of 10A, 500V for a clamped inductive load at a junction temperature of 150°C. A 400V IGT could also do the job, but the 500V choice gives an additional derating safety margin. You must set the current limit at 9A to limit the in-rush current during start-up. Note that thanks to the IGT's adequate RBSOA, you don't need turn-off snubbers.

### Use 6-Step Drive For Speed-Invariant Torque

Figure 10A shows the inverter circuit configured for this example. Diodes  $D_1$  through  $D_6$  carry the same peak current as the IGTs; consequently, they're rated to handle peak currents of at least 8.766A. However, they only conduct for a short time (15° to 20° of 180°), so their average-current requirement is relatively small.

External circuitry can control the IGT's current fall time. Resistor R controls  $t_{F1}$  Figure 10B; there's no way to control  $t_{F2}$ , an inherent characteristic of the selected IGT. In this example, a 4.7-k $\Omega$  gate-to-emitter resistor provides the appropriate fall time. The choice of current-limiting inductor  $L_1$  is based on the IGT's overload-current rating and the action time (the sum of the sensor's sensing and response time and the IGT's turn-off time) in fault conditions.

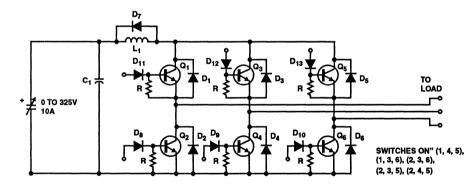


FIGURE 10A. COMPONENT SELECTION IS IMPORTANT. THE IGT SELECTED CIRCUIT HANDLES 10A, 500V AT 150°C. THE ANTH PARALLEL DIODES HAVE A SIMILAR CURRENT RATING.

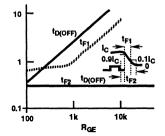


FIGURE 10B. SELECT R TO YIELD THE DESIRED TURN-OFF TIME. FINALLY, L1'S VALUE DETERMINES THE FAULT-CONDITION ACTION TIME.

You could use a set of flip flops and a multivibrator to generate the necessary drive pulses and the corresponding 120° delay between the three phases in Figure 10's circuit. A voltage-controlled oscillator serves to change the inverter's output frequency. In this circuit, IGTs Q<sub>1</sub>, Q<sub>3</sub> and Q<sub>5</sub> require isolated gate drive; the drive for Q<sub>2</sub>, Q<sub>4</sub> and Q<sub>6</sub> can be referred to common. If you use optocouplers for isolation, you'll need three isolated or bootstrap power supplies (in addition to the 5V and 24V power supplies) to drive the IGTs. Another alternative is to use transformer coupling.

### 165° Conduction Prevents Shoot-Through

Consider, however, using Figure 11A's novel, low-cost circuit. It uses a piezo coupler to drive the isolated IGT. As noted, the coupler needs a high-frequency square wave to induce mechanical oscillations in its primary side. The 555 oscillator provides the necessary 108-kHz waveform; its output is gated according to the required timing logic and then applied to the piezo coupler's primary. The coupler's rectified output drives the IGT's gate; the 4.7kW gate-to-emitter resistor provides a discharge path for  $C_{GE}$  during the IGT's turnoff. The circuit's logic-timing diagram is shown in Figure 11B.

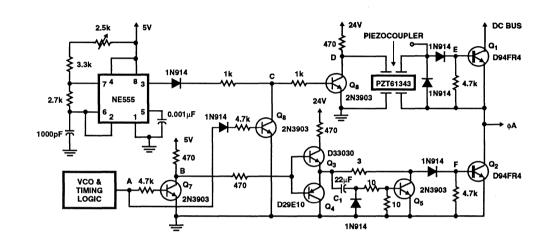


FIGURE 11A. PROVIDING PROPERLY TIMED DRIVE TO THE IGTS, THE CIRCUIT USES PIEZO COUPLING TO THE UPPER POWER DEVICE. THE 3-TRANSISTOR DELAY CIRCUIT PROVIDES THE NEEDED 15° LAG TO THE LOWER IGT TO AVOID CROSS CONDUCTION.

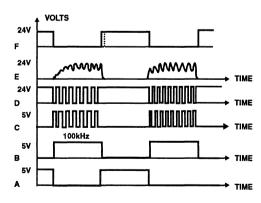


FIGURE 11B. THE TIMING DIAGRAM SHOWS THE 555'S 108-KHZ DRIVE TO THE PIEZO DEVICE AND THE LATTER'S SLOW RESPONSE.

The piezo coupler's slow response time Figure 12A contributes approximately 2° to the 15° to 20° turn-on/turn-off delay needed to avoid shoot-through in the complementary pairs. The corresponding collector current is shown in Figure 12B. C<sub>1</sub> and its associated circuitry provide the remaining delay as follows.

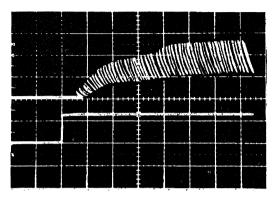


FIGURE 12A. THE PIEZO COUPLER'S SLOW RESPONSE IS NOT A DISADVANTAGE IN THIS ARTICLE'S CIRCUIT. IN FACT, IT CONTRIBUTES 2° TO THE REQUIRED 15° TURN-ONTURN-OFF DELAY.

TRACE	:	VER	<b>FICAL</b>	HORIZONTAL				
A		5V/	/DIV	200µSEC/DIV				
В		5V/	/DIV	200	µSEC/	DIV		
-				I				
	-							

FIGURE 12B. THE DRIVEN IGT'S COLLECTOR CURRENT IS SHOWN.

TRACE	VERTICAL	HORIZONTAL
A	3A/DIV	200µSEC/DIV
В	5V/DIV	200µSEC/DIV

When  $Q_3$ 's base swings negative,  $C_1$  - at this time discharged turns on  $Q_5$ . Once  $C_1$  is charged,  $Q_5$  turns off, allowing a drive pulse to turn the IGT on. When  $Q_7$ 's base goes to ground,  $Q_4$  turns on and discharges  $C_1$ , initiating the IGT's turn-off. Figure 13 shows the motor current and corresponding line voltage under light-load Figure 12A and full-load Figure 12B conditions.

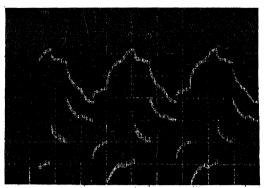


FIGURE 13A. MOTOR CURRENT AND VOLTAGE ARE SHOWN HERE, FOR LIGHT LOADS

TRACE	VERTICAL	HORIZONTAL
A	1A/DIV	1mSEC/DIV
В	50V/DIV	1mSEC/DIV

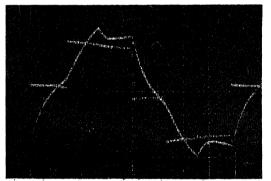


FIGURE 13B. MOTOR CURRENT AND VOLTAGE ARE SHOWN HERE, FOR HEAVY LOADS.

TRACE	VERTICAL	HORIZONTAL
A	3A/DIV	2mSEC/DIV
В	100V/DIV	2mSEC/DIV

To complete the design of the 6-step motor drive, it's necessary to consider protection circuitry for the output IGTs. The drive receives its power from a switching supply already containing provisions for protection from line over-voltage and under-voltage and transient effects. However, you still have to guard the power switches against unwanted effects on the output lines and the possibility of noise or other extraneous signals causing gate-drive timing errors.

The best protection circuit must match the characteristics of the power switch and the circuit's bias conditions. The IGT is very rugged during turn-on and conduction, but it requires time to dissipate minority carriers when turning off high currents and voltages. An analysis of the possible malfunction conditions shows that a current-sensing over current-protection circuit (combined with a di/dt-limiting inductor) provides the most complete protection.

### Tailor R<sub>GE</sub>'s Value To Avoid Latch-up

To protect against turn-on into a shorted output, you must coordinate the response time of the sensing circuit and the di/dt-limiting inductance. Moreover, the sensing must be accurate, allow tight control, and have low losses and low cost. The system in Figure 14 uses such a sensor - a  $2m\Omega$  resistor formed from 1 inch of #24 AWG copper wire with Kelvin contacts. The voltage across this resistor is chopped and ac-amplified, using the 108-kHz gate-supply oscillator as a timing source.

### Low-Cost Sensor Monitors Load Current

Amplified signals exceeding 1V p-p amplitude set a latch, removing gate drive from the IGTs and simultaneously turning off the switching regulator via the 3524 control IC. Automatic reset occurs after 10 msec, and it repeats if the line current stays below the set limit during the high-voltage supply's turnon. If the restarting line current is higher than normal, the circuit latches off during the first reset attempt and stays off until the mains voltage shuts down.

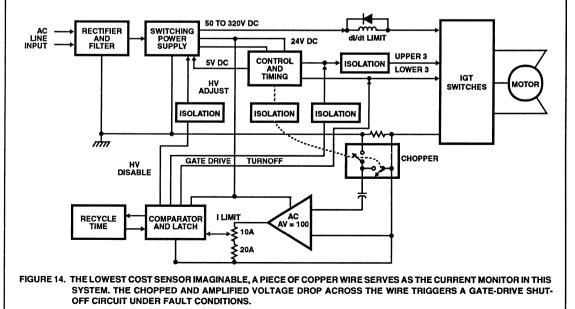
The chopped current-sensing technique proves less costly and performs better than Hall-effect sensing systems. Figure 15 gives a detailed schematic of the protection circuitry. It has sufficient bandwidth to provide a 10 $\mu$ sec system response time and features ±2% reproducibility. The circuit is cost effective, easily meets system accuracy and speed requirements, and operates from the system's frequency source and power supply (adding only 0.5W dissipation). The dominant costdetermining factors are the di/dt inductor and the associated flyback diode (required for most protection schemes anyway).

An overview of the protection circuit starts at the currentsensing resister in the high-voltage supply's ground return Figure 15A. The two H11F3 bilateral analog FET optoisolators chop the voltage across the resistor at a 50% duty cycle. The H11F3s' inputs are driven by a square wave derived from a 2-transistor bistable multivibrator that's clocked from the 108kHz 555 timer Figure 15B serving as the piezoelectric couplers drive source.

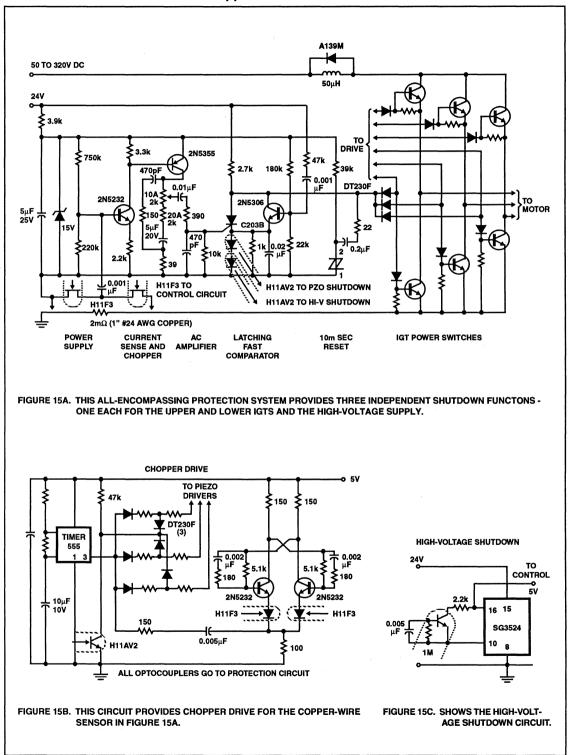
The chopped voltage waveform, a square wave of 1mV peak amplitude per ampere of summed motor current, is amplified 50 to 100 times by a 2-transistor amplifier; its peak value is then compared to a 1V reference via a Darlington-SCR comparator. The temperature coefficients of the reference and comparator compensate for the copper-wire sensing resistors TCR (approximately 400 ppm/<sup>o</sup>C). Note, however, that you can change the TC characteristics to suit a particular system's temperature requirements.

If the amplified signal exceeds the comparator's reference level, the SCR latches on, drawing the lower IGT power switches' gates Low (via the steering diodes) and turning the two H11AV2 optoisolators on. These isolators, featuring extremely low dielectric capacitance, remove the 108kHz signal from the piezo couplers' inputs, thereby halting power flow to the upper IGTs' gates. The isolators also supply 5V to the shutdown pin on the 3524 regulator Figure 15C that controls the variable high-voltage supply, thereby turning the inverters' input power off.

Providing three independent shutdown functions (lower and upper IGTs and high-voltage supply) yields foolproof protection from any foreseeable failure. An RC network times the protection circuit's reset (an action effected by firing an ST4 pnpn threshold switch) by using the timing capacitor to turn the SCR comparator off. If the load current remains above limit during the restart time, both the ST4 and the SCR remain on, preventing the reset from repeating. This action ensures permanent shutdown and prevents repeated power cycling of the power switches under shorted-load conditions.



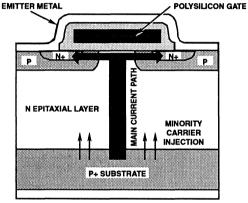
Application Note 9318



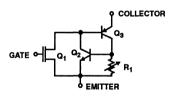
### Latch-Up: Hints, Kinks and Caveats

The IGT is a rugged device, requiring no snubber network when operating within its published safe-operating-area (SOA) ratings. Within the SOA, the gate emitter voltage controls the collector current. In fact, the IGT can conduct three to four times the published maximum current if it's in the ON state and the junction temperature is +150°C maximum.

However, if the current exceeds the rated maximum, the IGT could lose gate control and latch up during turn-off attempts. The culprit is the parasitic SCR formed by the pnpn structure shown in Figure 16. In the equivalent circuit, Q1 is a power MOSFET with a normal parasitic transistor (Q2) whose baseemitter junction is shunted by the low-value resistance R1.



METAL COLLECTOR



### FIGURE 16. THE IGT'S PARASITIC SCR IS RESPONSIBLE FOR THE DEVICE'S LATCH-UP CHARACTERISTICS.

For large current overloads, the current flowing through R1 can provoke SCR triggering. In the simplest terms, R1 represents the equivalent of a distributed resistor network, whose magnitude is a function of Q2's VCE. During normal IGT operation, a positive gate voltage (greater than the threshold) applied between Q1's gate and source turns the FET on. The FET then turns on Q<sub>3</sub> (a pnp transistor with very low gain), causing a small portion of the total collector current to flow through the R1 network.

To turn the IGT off, you must reduce the gate-to-emitter voltage to zero. This turns Q1 off, thus initiating the turn-off sequence within the device. Total fall time includes currentfall-time one (t<sub>F1</sub>) and current-fall-time two (t<sub>F2</sub>) components. The turn-off is a function of the gate-emitter resistance, Q<sub>3</sub>'s storage time and the value of VGF prior to turn-off. Device characteristics fix both the delay time and the fall time.

### Forward-Bias Latch-Up

Within the IGT's current and junction-temperature ratings, current does not flow through Q2 under forward-biased conditions. When the current far exceeds its rated value, the current flow through R1 increases and Q3's VCF also increases because of MOSFET channel saturation. Once Q3's ICR1 drop exceeds Q2's VBE(ON), Q2 turns on and more current flow bypasses the FET.

The positive feedback thus established causes the device to latch in the forward-biased mode. The value of I<sub>C</sub> at which the IGT latches on while in forward conduction is typically three to four times the device's maximum rated collector current. When the collector current drops below the value that provokes Q<sub>2</sub> turn-on, normal operation resumes if chip temperature is still within ratings.

If the gate-to-emitter resistance is too low, the Q2-Q3 parasitic SCR can cause the IGT to latch up during turn-off. During this period, RGF determines the drain-source dV/dt of power MOSFET Q1. A low R1 causes a rapid rise in voltage this increases Q2's VCE, increasing both R1's value and Q2's gain.

Because of storage time, Q3's collector current continues to flow at a level that's higher than normal for the FET bias. During rapid turn-off, a portion of this current could flow in Q<sub>2</sub>'s base-emitter junction, causing Q<sub>2</sub> to conduct. This process results in device latch-up; current distribution will probably be less uniform than in the case of forward-bias latch-up.

Because the gains of Q2 and Q3 increase with temperature and V<sub>CF</sub>, latching current - high at +25°C - decreases as a function of increasing junction temperature for a given gateto-emitter resistance.

How do you test an IGT's turn-off latching characteristic? Consider the circuit in Figure 17. Q<sub>1</sub>'s base-current pulse width is set approximately 2µsec greater than the IGT's gatevoltage pulse width. This way, the device under test (DUT) can be switched through Q1 when reverse-bias latch-up occurs. This circuit allows you to test an IGT's latching current nondestructively.

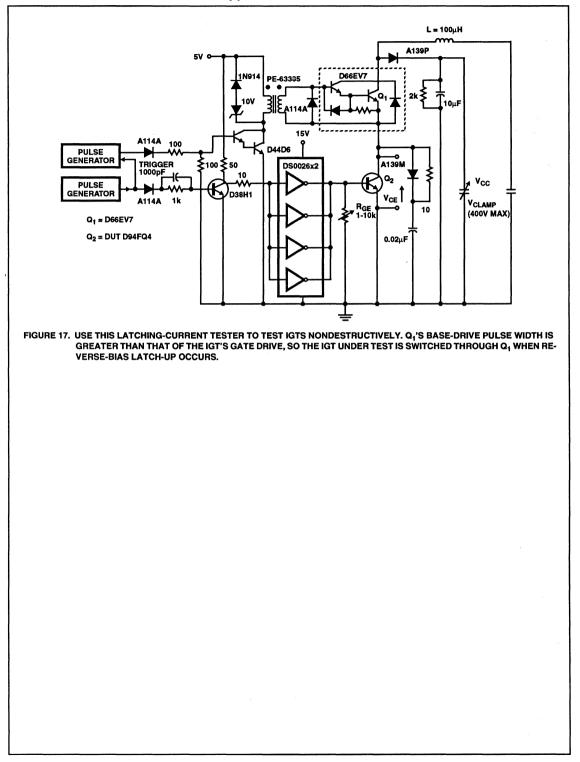
The results? Clamped-inductive-load testing with and without snubbers reveals that snubbering increases current handling dramatically: With RGE =1k $\Omega$ , a 0.02 $\mu$ F snubber capacitor increases current capability from 6A to 10A; with RGE =  $5k\Omega$ , a 0.09µF snubber practically doubles capacity (25A vs 13A).

Conclusions? You can double the IGT's latching current by increasing RGE from  $1k\Omega$  to  $5k\Omega$ , and double it again with a polarized snubber using CS < 0.1µF. The IGT is therefore useful in situations where the device must conduct currents of five to six times normal levels for short periods.

Finally, you can also use the latching behavior to your advantage under fault conditions. In other words, if the device latches up during turn-off under normal operation, you could arrange it so that a suitable snubber is switched electronically across the IGT.

NOTES

Application Note 9318



# **Harris Semiconductor**



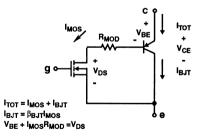
# No. AN9319 September 1993

# Harris Power

# PARALLEL OPERATION OF INSULATED GATE TRANSISTORS

Author: Sebald R. Korn, Consulting Applications Engineer

In the November issue of Powertechnics, the general considerations of paralleling semiconductor switches were presented. Some of the important factors include the characteristics of different types of load reactances and the action of the switching device during its turn-on delay, rise time and turn-off delay times. Different types of switching devices must be handled differently when operated in parallel. Power bipolar transistors, SCRs, MOSFETs and IGTs all have different characteristics which must be taken into consideration. The IGT transistor combines the high input impedance, voltage controlled turn on/turn off capabilities of power MOSFETs and the low on-state conduction losses of bipolar transistors. Like MOSFETs, the output characteristics of IGTs are generated by plotting collector-emitter current, collector-emitter voltage and gate voltage. Unlike the MOSFET, there is an offset voltage generated by the collector-emitter junction of the npn transistor. However, once this offset is overcome, the effective on-resistance in the saturation region is much lower for the IGT than for the MOSFET. A steady state equivalent circuit is shown in Figure 1. Total device current equals MOSFET current (IMOS) plus bipolar current (IBIT) and since the MOSFET current is the base current of the pnp, these current components are related by the gain of the pnp.



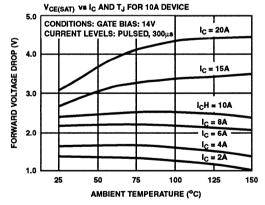
### FIGURE 1. N-CHANNEL IGT<sup>™</sup> TRANSISTOR STEADY STATE EQUIVALENT CIRCUIT

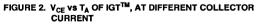
To understand the unusual behavior of its temperature coefficient, negative at low current, almost zero at normal current, and positive at high current, we analyzed the IGT by treating the two branch currents comprising the conduction path as two separated devices. The IGT's on-state voltage drop is composed of the MOSFET voltage drop plus the bipolar V<sub>BE</sub> drop apparently parallel by a pnp-transistor. Note

that the only part of the bipolar in parallel to the MOSFET and modulation resistance is the base-collector junction, but the base-emitter junction is common to both branches.

We also know from measurements, the MOSFET's temperature coefficient in the epi-resistance is positive. We know further that as the device temperature increases, the bipolar transistor's gain increases, the V<sub>BE</sub> drop decreases, which both tend to reduce on-voltage drop. On the other hand, the MOSFET and epi-resistance voltage drop will increase with temperature, tending to increase on-voltage voltage.

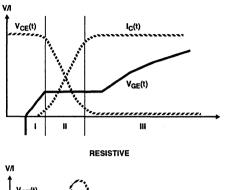
These effects cancel and the net result is that the IGT exhibits much less variation of on-voltage voltage with temperature than either bipolars or MOSFETs. The temperature coefficient goes from a bipolar like negative (at low currents) to zero (at rated current) and to a MOSFET-like positive coefficient as current density increases (Figure 2).

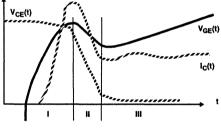




### **Turn-On Switching Performance**

Like the MOSFET, the IGT gate presents a capacitive load to the drive circuit. The IGT capacitive elements and their typical variation with voltage is analogous to the MOSFET, hence the IGT turn-on interval can be divided into three distinct regions (refer to Figure 3). In region I, the input capacitance is charged until the gate voltage reaches the value needed to initiate collector current conduction. In region I, turn-on is essentially completed as the collector voltage falls rapidly to the 10% level. The effective capacitance increases dramatically in this region due to the Miller effect. In region III, the collector voltage slowly settles to its saturation level. At the start of Section III, the effective input capacitance remains high because as the collector voltage is driven below the gate voltage, the polarity of the collector gate voltage reverses and  $C_{\rm GC}$  increases dramatically. When the collector reaches the saturation voltage level, the gate rises to the gate-emitter supply level (typically 15 volts).





INDUCTIVE WITH DIODE RECOVERY

### FIGURE 3. IGT<sup>TM</sup> TRANSISTOR TURN ON WAVEFORM

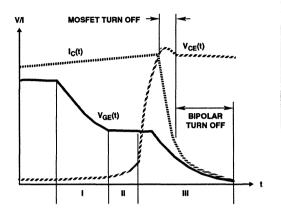
### **Turn-Off Switching Performance**

The turn off interval is also composed of three regions as shown in Figure 4 for the case of an inductive load. Region I represents the discharge of the gate to the point where the gate voltage just sustains the collector current.

Region II corresponds to reversing the voltage on  $C_{GC}$  whose value is very high at this point. The gate voltage changes very little during this period and the collector-emitter voltage begins to rise slightly. Taken together, regions I and II represent a turn-off delay. Referring back to the equivalent circuit of Figure 1 when the device is fully on, the MOS-FET voltage prevents the base-collector junction of the pnp from becoming forward biased. Thus the pnp contributes no significant storage time delay during turn off. In region III, the collector voltage rises rapidly at a rate controlled by the amount of current supplied by the gate drive to reverse charge  $C_{GC}$ .

The turn off current fall exhibits two distinct phases: an initial fast drop followed by a slow exponential fall. The initial fast drop is due to the fast cutoff of the MOSFET current. After

the MOSFET channel cuts off, the pnp transistor undergoes an open base turn off. The gate drive circuit only controls the initial turn off delay and the slope of the MOSFET current fall by how fast it withdraws gate charge. The pnp exponential turn off tail is a characteristic of the device design.



### FIGURE 4. IGT<sup>™</sup> TRANSISTOR TURN OFF WAVEFORMS

### Device Design To Optimize Turn Off

The bipolar current tail was the cause of the excessive switching times of the first-generation IGT. Turn off of the pnp transistor is a function of the stored base charge and the lifetime of carriers in the base region.

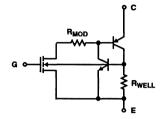
Shortening the pnp turn-off time involves decreasing the bipolar current component and/or reducing the carrier lifetime. The carrier recombination rate can be reduced by localized techniques such as electron or proton irradiation. In addition to a faster decay rate, an irradiated device will have a power pnp gain. By decreasing the bipolar current component, the MOSFET current and the amount of initial drop in the turn-off waveform both increase, resulting in a substantially lower current level for the bipolar decay.

### **Turn-Off SOA Optimization**

The dynamic equivalent circuit of the IGT includes a parasitic pnp thyristor (Figure 5). When the sum of the current gains of the npn and pnp exceeds one, the four layer pnp structure latches on and gate control is lost. The npn is effectively shorted by the emitter metal but there is a finite well resistance,  $P_{WELL}$ , below the surface. The npn gain is very low until sufficient current flows through  $P_{WELL}$  to exceed its  $V_{BE}$  threshold. Thus,  $V_{BE(ON)} = (I_{WELL})$  ( $P_{WELL}$ ) provides a latching criteria.

The R<sub>WELL</sub> resistance increases with temperature due to falling carrier mobility in the P<sub>WELL</sub> region. The I<sub>WELL</sub> current is the pnp collector current and hence depends upon the pnp gain. I<sub>WELL</sub> can be increased dramatically by displacement currents from high dv/dt. Increased temperature causes increased pnp gain and hence increased I<sub>WELL</sub>. The V<sub>BE(ON)</sub> threshold will decrease with increasing temperature.

Clearly, high-temperature, fast turn-off of an inductive load represents a worse case test. Second generation IGT are SOA limited and not latching-current limited. They will fail due to operation outside the power related current at  $150^{\circ}C$  under the fast ( $R_{GE} = 100\Omega$ ), inductive turn off conditions. This performance has been achieved by minimizing  $P_{WELL}$  through cell design and the addition of a deep p+ diffusion and by utilizing the buffer layer structure to lower pnp gain.



### FIGURE 5. DYNAMIC EQUIVALENT CIRCUIT OF THE IGT™ TRANSISTOR

### **Results Of Paralleling IGT**

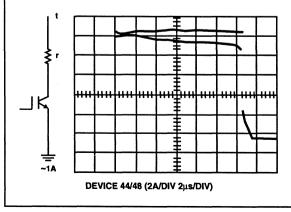
From our experience with paralleling devices like bipolars and MOSFETs, there seemed to be no reason why IGTs should not perform reasonably well.

To perform the measurement, we used the IGT-4E10 and the IGT-4E11 both rated at  $I_C = 10A$  at  $T_C = 100^{\circ}C$  and a  $V_{CE} = 500V$ . We also used a 20A device the IGT-6E21.

The parameters we considered important for parallel operation, the saturation voltage  $V_{CE(SAT)}$  which we measured at different current levels and a gate voltage  $V_{GE} = 14V$ . Gate threshold voltage ( $V_{G(TH)}$ ) which we measured at 250µA and 1A (at that level, we can call it an input voltage versus output current) and transconductance (G<sub>FS</sub>).

NO.	V <sub>CE(SAT)</sub> 10A	V <sub>G(TH)</sub> 1A	G <sub>FS</sub>	I	T <sub>DELAY</sub> ON	TR	T <sub>DELAY</sub> OFF	T <sub>F</sub>
44	2.35	5.38		10.5		225	250	402
48	2.55	5.50	3.8	9.5	51	236	230	381
۵%	85%	22%	13%	10%	0%	4.8%	8.6%	5.5%

TABLE 1



The circuit we used consisted of HP pulse generators 222 and 214A driving a logic gate (7402N) and the memory driver D50026 connected to the gate through resistors R<sub>1</sub> and R<sub>2</sub> to the gate of the IGT, a Tektronix scope 7854 and current probes 6021 and 6302.

Device 44 and 48 were selected as an average combination and deltas of the different parameters can be seen in Table 1. Parallel operation is good, delta I = 1A at 9.5A and 10.5A in each device. We see clearly the FET and bipolar turn off.

The same devices were used to increase the current to about 40A, checking for latching problems, which did not occur.

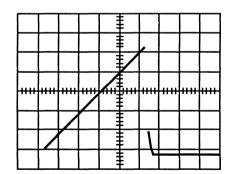
We then changed the gate resistor from  $50\Omega$  to  $4.7\Omega$  and increased case temperature to the rated  $150^{\circ}$ C. Still no problems became apparent. Note that the peak current was over four times the rated continuous current.

The same pair was also used to switch on an inductive load (L =  $182\mu$ H). Excellent parallel operation is achieved with this combination. Even 500ns resolution did not reveal any problems.

The first interesting combination 14 specified  $T_{FMAX} = 1\mu s$ and 15 specified  $t_{FMAX} = 605\mu s$ . The trade-off in switching speed versus  $V_{CE(SAT)}$  can be seen in Table 2.

TABLE 2	A
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NO.	V <sub>CE(SAT)</sub> 10A	V <sub>G(TH)</sub> 1А	G <sub>FS</sub>	ı	T <sub>DELAY</sub> ON	т <sub>я</sub>	T <sub>DELAY</sub> OFF	T <sub>F</sub>
19 20	2.15 2.15	5.55 4.95	4.7 4.3	10.2 9.8	58 46	244 252	277 269	835 871
Δ%	0%	12%	9%	4%			2.9%	4.3%



### DEVICE 14/15 60% DIFFERENCE ~ V<sub>CE(SAT)</sub> AND LARGE DIFFERENCE IN SWITCHING TIME

Excellent parallel operation is achieved with this combination, even the 500ns resolution does not reveal any problems.

Device 20 having the lower  $V_{CE(SAT)}$  and lower  $V_{G(TH)}$  is taking the higher share of current. Both parameters  $V_{CE(SAT)}$  and  $V_{G(TH)}$  are important in the overall performance. Turn off

showing is excellent, but the 500ns time scale shows the result of the difference in the  $t_{DELAY}$  off, of 23ns and the difference in device 15 and 16, are the devices having low  $V_{CE(SAT)}$  and long turn off times. If paralleled with the proper device (same type), excellent parallel operation is achieved.

N	э.	V <sub>CE(SAT)</sub> 10A	V <sub>G(TH)</sub> 1A	G <sub>FS</sub>	I	T <sub>DELAY</sub> ON	T <sub>R</sub>	T <sub>DELAY</sub> OFF	T <sub>F</sub>
1. 1!		2.25 1.40	5.75 5.35	4.3 5.7	6.0 14.8	53 54	264 228	246 436	750 4317
Δ	%	60%	7%	32%	47%	1.8%	16%	102%	575%

TABLE 2B

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			FT		
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		Ē			

CURRENT SHARING OF DEVICE 19/20 (2A/DIV, 5µs/DIV)

Note that 15 paralleled before with the much faster 14 showing extremely poor current sharing.

The 38 and 48 were paralleled to show an inductive load and the recovery current of diode. This is a realistic waveform found in many applications.

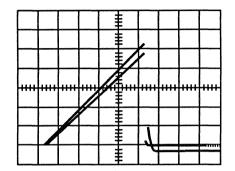
Here we paralleled two 20A IGT transistors. Also excellent current showing which is confirmed at the  $500\mu\text{s}/\text{div}$  time scale in.

We paralleled the device 50 and 14 which have a relatively large delta 78% in fall time.

They can be operated in parallel and share much better than we might expect. The large deltas in fall time are the result of the relatively large delta at the current tail in comparison to the rest of the fall time.

NO.	V <sub>CE(SAT)</sub> 10A	V <sub>G(TH)</sub> 1A	G <sub>FS</sub>	I	T <sub>DELAY</sub> ON	TR	T <sub>DELAY</sub> OFF	T <sub>F</sub>		
14 15	2.25 2.15	5.75 4.95	4.3 4.3	9.2 10.4	53 46	264 252	246 269	750 871		
۵%	5%	16%	0%	13%			9.3%	16%		

TABLE 3



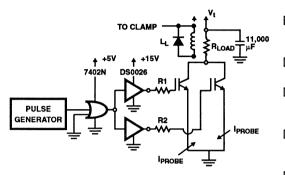


### Conclusion

All the conventional wisdom applied in the past to parallel bipolar type devices and MOSFET type devices can be applied to parallel operation of IGT Transistors.

- V<sub>CE(SAT)</sub> voltage should be compared at rated current and should not exceed approximately 20% difference.
- Gate threshold voltage which we measured and compared is important, but could be replaced by V<sub>GATE</sub> vs I<sub>C</sub> at rated current. Maximum differences should not exceed 10-20%.
- Transconductance g<sub>FS</sub> differences are not as critical as assumed and may be ignored.
- 4. t<sub>D(ON)</sub> and rise time are important for current sharing when switching resistive or inductive loads with reverse recovery currents at turn on, but tolerances are small, seldom posing a problem. Check FBSOA. Note that the fastest device takes most of the current. Emitter inductors can be inserted.
- t<sub>D(OFF)</sub> and fall time show also small tolerances, but don't seem to pose a problem. Different device types and different manufacturers should never be paralleled. Note that the slowest device takes most of the current. Removal rate of gate voltage may become a factor. Emitter inductors less than 100μH show excellent results [3].
- Circuit layout should be mechanically and electrically symmetrical. All lead length and differences in lead length become a factor (12-15nH/inch). Separate the gate circuit from the collector circuit (to avoid magnetic coupling).

- Always use separate gate resistor to avoid oscillation. We did not see a problem of rated current but we have not made sufficient measurements to insure no problems.
- 8. Close thermal coupling is recommended (common heat-sink) resulting in only small differences in junction temperature.



### FIGURE 6. TEST CIRCUIT TO EVALUATE PARALLEL OPERATION OF IGT<sup>™</sup> TRANSISTOR

The IGT's key parameters show relatively close distribution making it difficult to establish exact limits for parallel operation but following the above recommendations will give very good results. Additional measurements were made and in no instances did I exceed 2.5A.

IGT Transistors can be paralleled with a relatively small amount of difficulty. Some current derating may be advisable, which tends to improve current sharing. (We can see on the inductive switching waveform up to 6A sharing is almost perfect.)

In the future, switching modules rated at 100A and 200A or higher having blocking voltages of 500V or 1200V are realistic possibilities.

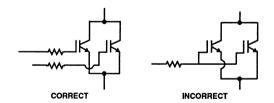


FIGURE 7. PROBLEM GATE CONNECTION

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- [6] Paralleling Power MOSFET's in Switching Applications, by Kim Gauen, Motorola, Application Note AN-918, 1984.
- [7] Parallel Operation of MOSFET's in DC-DC Converters, Rudy Severns, Siliconix, Powertechnics Magazine, June 1985.
- [8] A Chopper for Motor Speed Control Using Parallel Connected Power HEXFET's<sup>TM</sup>, by S. Clemente, B. Pelly, IR.
- [9] MOS Power Applications Handbook, Siliconix, Inc., Chapter 5.3, Parallel Operation of Power MOSFET's (TA84-5).
- [10] Motor Control Applications of Second Generation IGT Power Transistors, by Donald J. MacIntyre, Jr., Application Note 200.95.
- [11] Non-destructive Forward Biased Second Breakdown Testing, No. 78-3, by Sebald Korn, Internal General Electric Report.

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8-87

# Application Note 9319

				1					r	
	V <sub>CE(</sub>	<sub>BAT)</sub> AT V <sub>GE</sub> =	: 14V	GATE TH	RESHOLD	TRANS- CONDUC-	RESIS	TIVE	INDU	CTIVE
DEVICE NUMBER	2A	5A	10A	250μΑ	1A	TANCE G <sub>FS</sub>	T <sub>DELAY</sub> ON	TR	T <sub>DELAY</sub> OFF	Τ <sub>F</sub>
TO-3 LOT 1	4353									
37	1.42V	1.82V	2.30	3.60V	5.50	4.3	51ns	230ns	23ns	390
38	1.54	2.05	2.70	3.70	5.75	4.2	53	253	230	427
42	1.4	1.78	2.25	3.75	5.60	5.4	45	223	226	421
44	1.42	1.82	2.35	3.50	5.38	4.3	51	225	250	402
47	1.50	1.98	2.60	3.75	5.75	4.2	58	238	226	422
48	1.49	1.94	2.55	3.50	5.50	3.8	51	236	230	381
50	1.45	1.87	2.40	3.62	5.60	4.4	58	232	240	389
∆ MAX			0.45		0.25	1.6				
	V <sub>CE(</sub>	<sub>SAT)</sub> AT V <sub>GE</sub> =	= 14V	GATE TH	RESHOLD	TRANS-	RESIS	STIVE	INDU	CTIVE
DEVICE NUMBER	2A	6A	10A	250µA	1A	CONDUC- TANCE G <sub>FS</sub>	T <sub>DELAY</sub> ON	T <sub>R</sub>	T <sub>DELAY</sub> OFF	T <sub>F</sub>
TO-3 LOT 1	4933.1 — I	GT 6E11			•					
13	1.34	1.79	2.13	3.70	5.90	4.7	55	261	277	808
		1							1	

### TABLE 4. RESULTS OF PARALLELING IGT<sup>™</sup> TRANSISTORS

DEVICE NUMBER	2A	6A	10A	250µA	1A	TANCE G <sub>FS</sub>	T <sub>DELAY</sub> ON	T <sub>R</sub>	T <sub>DELAY</sub> OFF	T <sub>F</sub>
TO-3 LOT	14933.1 — I	GT 6E11								
13	1.34	1.79	2.13	3.70	5.90	4.7	55	261	277	808
14	1.37	1.85	2.25	3.94	5.75	4.4	53	264	246	750
19	1.32	1.78	2.15	3.75	5.55	4.7	58	244	277	835
20	1.30	1.78	2.15	3.10	4.95	4.3	46	252	269	871
Δ	,		0.18		0.8	0.4				
TO-3 LOT	(X) — IGT 6	E10	•							
15	0.95	1.20	1.40	4.00	5.35	5.7	54	228	496	4317
16	0.96	1.21	1.42	3.95	5.30	5.7	58	227	515	4190

# Harris Semiconductor

No. AN9320 June 1993



# Harris Power

8

APPLICATION NOTES

# PARALLEL OPERATION OF SEMICONDUCTOR SWITCHES

Sebald R. Korn, Consulting Applications Engineer

In uninterruptable power supplies demands for current handling capability to meet load current requirements plus margins for overload and reliability purposes often exceed the capability of the largest semiconductor device type considered and paralleling may become an attractive alternative. All switching power semiconductors starting with SCR's [1], bipolar transistors [2-4] darlingtons [5] and field effect transistors [6-10], have been successfully paralleled, but proper precaution had to be taken. We will review some of these methods, describe the characteristics of the insulated gate transistors, and show the proper methods to operate this relatively new family of devices in parallel.

All semiconductor circuits using parallel connected devices to switch a higher load current can easily be analyzed by using Kirchoff's law. As long as all voltage drops in the parallel branches are equal, the currents through the branches are equal.

This sounds sensible and logical, but as soon as we consider the different stages every switching device has to assume and we consider the parameters of each switching device which guarantees equal voltage drops in the branches over the required temperature range and over the duration of the switching cycle, complications begin to appear. At first glance, each switching device has only two functional states, an "off- state" and an "on-state". But by closer examination, we have to consider how we get from "off" to "on" and back to "off", the "dynamic" area of the switching waveform (Figure 1). The dynamic area is only a fraction of the total waveform, but it is by far the most important when it comes to parallel operation.

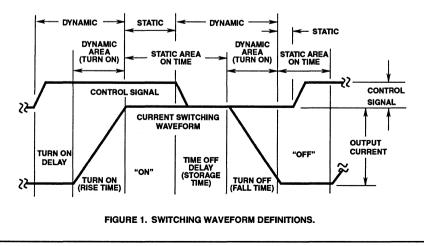
In power electronics, there are three different load types; resistive, capacitive, and inductive. The resulting waveforms are sufficiently different to require either different switching devices or the circuit designer may have to change the switching circuit to meet the different requirements, especially when devices are operated in parallel.

### **Off-State**

The off-state is probably the least demanding state in parallel operation of semiconductor devices. As long as leakage current is low, even differences of more than 100% would not create any difficulties.

### **On-State**

The on-state is again a relatively uncritical and uneventful period (Figure 2). Most devices in switching applications are overdriven and differences in gain or transconductance do not translate into proportional output current.

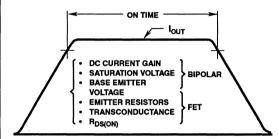




Even if a bipolar device takes a larger share of the total current, the rapid fall-off in gain and the increase in  $V_{SAT}$  as it takes the higher share will prevent disaster. Thermal runaway in bipolar applications is not as frequent as we may believe [2-4].

For bipolar devices, the parameter having a clear negative temperature coefficient is  $V_{BE}$ .  $V_{CE(SAT)}$ , on the other hand, can have positive or negative temperature coefficient depending on the device type (npn or pnp) and operating point.

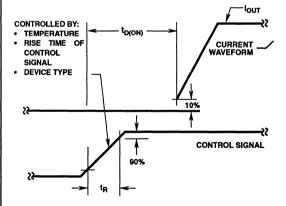
The ease of paralleling of power FETs has been pointed out by many authors [6-9], and has been demonstrated in many applications, although each application requires analysis of both dynamic and static sharing.



# FIGURE 2. ON TIME OF SWITCHING WAVEFORM AND CONTROLLING PARAMETERS.

### **Turn-On Delay Time**

Turn-on delay time is the time from where the control signal is applied, reaches 10% amplitude, to the point where the switched current rises to the 10% amplitude (Figure 3).

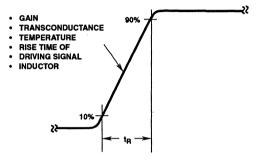


### FIGURE 3. DEFINITION OF TURN-ON, DELAY TIME, T<sub>D(ON)</sub> AND CONTROLLING PARAMETERS.

Fortunately, differences is turn-on delay are relatively small. Although this delay is significant in large-area SCR's, but it is much less a problem with bipolars or power FET's. It is less important when switching inductive loads, but should be monitored when devices to be paralleled switch resistive load, discharge capacitor or have to carry the recovery current of a diode. Needless to say, it is desirable to have small turn-on delays for parallel operation. To reduce deltas in  $t_{D(ON)}$ , it is advisable to drive devices with fast rising control signals and use devices from the same mask design. The same device type number does not guarantee that they are made from the same mask design. Therefore, devices from different manufacturers should not be intermixed.

### **Rise Time**

Rise time is an interesting part of the switching waveform (Figure 4). The device operates in an analog domain, although for a very short time, but nevertheless, analog.



# FIGURE 4. RISE TIME OF L<sub>OUT</sub> WAVEFORMS AND PARAMETERS INFLUENCING IT.

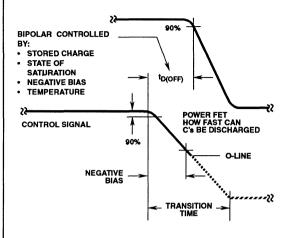
Again, transconductance and junction temperature become important considerations, but junction temperature differences as a result of rise time differences are relatively small. Inductors inserted into the emitter lead on bipolars, source lead on FET's or cathode lead on diodes, can be extremely effective [3]. All differences in turn-on delay and rise time become visible at thin part of the waveform. Differences which may exist, although small, require the evaluation of the forward biased safe operating area (FBSOA).

In most cases, transistors have almost rectangular FBSOA for the short durations they remain in the analog domain of the turn-on period. Problems seldom exist, but precautions should not be ignored either.

Note that the device with the shortest turn-on delay and the shortest rise-time will take most of the current. Most transistors have a negative temperature coefficient of input voltage and Miller effect feedback which can cause current begging if power dissipation is high during turn on.

### Turn-Off Delay Time (Storage Time)

Turn-off delay time is the prelude to the most important part of the switching waveform, especially on bipolar devices (Figure 5). On bipolar devices, it is important to remove the stored charge as fast as possible, which may require more expensive drive circuitry. Especially on large power darlingtons, negative bias or baker clamps result in significant reduction of storage time and improve parallel operations. The transition time of the base current signal from positive to negative (npn device) is important in the removal rate of the stored charge.

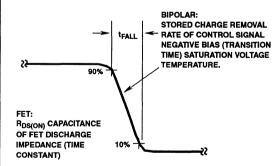


# FIGURE 5. TURN-OFF WAVEFORM AND PARAMETERS INFLUENCING IT.

### Fall Time

Parameters which reduce storage time will also reduce fall time (Figure 6). For paralleled devices, differences in turn-off delay or storage time will have a noticeable effect on fall time.

When inductive loads are turned off, the reverse biased safe operating area (RBSOA) must be considered on bipolar devices. Hot spot formation [11] which results in sudden reduction of the  $V_{BE}$  and further increase in  $I_B$  could result in permanent damage.



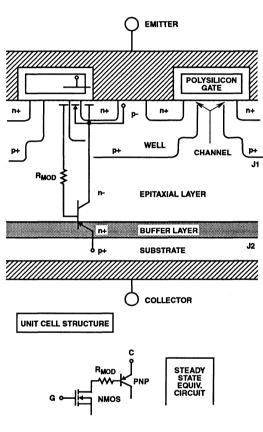
### FIGURE 6. FALL TIME AND INFLUENCING PARAMETERS.

### The Insulated Gate Transistor

The insulated gate transistor (IGT<sup>TM</sup>) combines the high input impedance, voltage controlled turn on/turn off capabilities of power MOSFETs and the low on-state conduction losses of bipolar transistors, making it an ideal device for many power electronics switching control applications.

### IGT Structure and Operation

The basic device structure is illustrated by the unit cell cross section of Figure 7. Like the MOSFET, the IGT consists of many individual cells connected in parallel. Processing of the IGT is similar to the vertical D-MOS technology used in MOSFETs. In the steady state, the n-channel IGT may be modeled as a bipolar pnp driven by an n-channel MOSFET. The MOSFET supplies base current to the pnp thus the MOSFETs gate voltage controls the total current.



### FIGURE 7. UNIT CELL CROSS SECTION AND STEADY STATE EQUIVALENT CIRCUIT OF IGT TRANSISTOR.

In normal operation, the emitter is grounded, the collector biased positive and with no gate-emitter voltage applied; J1 is reverse biased. The device is in the forward blocking mode. When a positive voltage is applied to the gate with respect to the emitter, an inversion channel is formed under the gate and MOSFET current flows from the n+ source region into the n-epi-layer to become the base current for the pnp. Junction J2 becomes forward biased and the device enters the conduction state. Holes are injected from the bot-

tom percent region into the n-epi-layer. The injected minority carrier density is 100 to 1000 times higher that the doping level of the n-type epi-region. This conductivity modulation allows the IGT to operate at a forward conduction current density 20 times that of an equivalent MOSFET. It is primarily in the thick epi, high-voltage devices where conductivity modulation has its major impact to reduce on-resistance.

The typical output characteristics and the symbol of the IGT are shown in Figure 8. Like on MOSFETs, the output characteristics curves are generated by plotting collector emitter currents, collector emitter voltage. Unlike the MOSFET, there is an offset voltage generated by the collector emitter junction of the npn-transistor. However, once this offset is overcome, the effective on-resistance in the saturation region is much lower for the IGT than for the MOSEET.

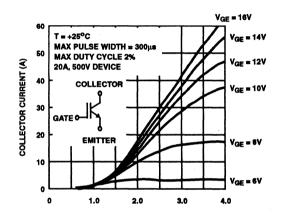


FIGURE 8. OUTPUT CHARACTERISTICS AND CIRCUIT SYMBOL FOR N-CHANNEL IGT TRANSISTOR.

### References

- SCR Manual, 6th Edition, General Electric Semiconductor Department, Auburn, New York, Chapter 6.2, Parallel Operation of SCR's.
- [2] Use Equations to Parallel Transistors. Otto R. Buhler, IBM, Boulder, Colorado, Electronics Design 4, February 15,1977.
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- [6] Paralleling Power MOSFET's in Switching Applications, by Kim Gauen, Motorola, Application Note AN-918, 1984.
- [7] Parallel Operation of MOSFET's in DC-DC Converters, Rudy Severns, Siliconix, Powertechnics Magazine, June 1985.
- [8] A Chopper for Motor Speed Control Using Parallel Connected Power HEXFET's<sup>TM</sup>, by S. Clemente, B. Pelly, IR.
- [9] MOS Power Applications Handbook, Siliconix, Inc., Chapter 5.3, Parallel Operation of Power MOSFET's (TA84-5).
- [10] Motor Control Applications of Second Generation IGT<sup>TM</sup> Power Transistors, by Donald J MacIntyre, Jr., Application Note 200.95.
- [11] Non-destructive Forward Biased Second Breakdown Testing, No. 78-3, by Sebald Korn, Internal General Electric Report.

# **MCT/IGBT/DIODES**

# HARRIS QUALITY AND RELIABILITY

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# **Quality and Reliability Assurance**

The ability to build and maintain the high levels of quality and reliability today, depends on inherent design and process capability, and not the degree of test and inspection. Both the design and production facilities for Power MOS-FETs are totally new, with state-of-the-art equipment and process techniques which deliver this needed capability.

# In-Process Quality Control

All critical phases of the highly automated power MOSFET manufacturing cycle have been characterized with respect to their intrinsic variability. Statistical limits have been established to give warning of abnormal process trends and fluctuations, based on this intrinsic capability. These limits are constantly tightened as the process improves and are well within the engineering specifications. The emphasis at Harris is to employ statistical methods at the point of control, rather than an inspection point at the end of a process.

# **Control of Outgoing Product**

The quality control lot acceptance sampling of finished product is performed after manufacturing has performed 100% inspection of all specified electrical characteristics. The current sampling level is 0.1% AQL for electrical parameters, and is constantly being improved. However, due to tight parameter distributions gained through process control and inherent design capability, the average outgoing quality level (AOQ) to the customer has been in the order of 100 PPM (0.01%).

### **Reliability Assurance**

Harris Semiconductor has a world-wide reliability program that helps to shape the direction of new product development, assures that the reliability level is maintained throughout the production cycle, and develops specific models to predict the reliability in the end-use application. In order to meet these objectives, a reliability facility is maintained at each manufacturing location for real-time feedback. A centralized reliability engineering organization develops all new test methods and supports new product/process development. Each group is fully trained in the reliability and applied statistics disciplines, as well as failure analysis, and are responsible for using these techniques to monitor and improve product capability.

# The Reliability Program

The reliability-assurance program operates at all stages of production, using the following four-pronged approach:

### **Product Design and Development**

During early development, initial product lots are characterized through accelerated reliability tests which establish the product capability. Once the design had been fine-tuned, multiple production runs are initiated and samples are subjected to a full range of standardized accelerated tests. All lots must meet pre-established reliability standards before any new design or process can be released for production.

### Wafer HTRB

Harris Semiconductor has developed a totally unique in-line reliability test performed at the wafer level. Samples from each wafer lot receive a 24-hour +150°C bias life test to measure passivation integrity and surface cleanliness.

### **Real Time Indicators (RTI)**

RTI's are short-duration accelerated-stress tests used to control the occurrence of specific failure mechanisms that can significantly affect product reliability. The stress levels are designed to induce failures, so that product-capability shifts can be detected and corrected. They are performed weekly at each manufacturing location. In this real-time method of determining reliability, a continuous flow of data is provided to indicate how well the manufacturing process is performing product.

TEST	CONDITIONS	PACKAGE	TYPICAL DURATION
Power Cycling	PD = 4.75W T <sub>J</sub> = +35°C - 175°C (approx.)	Plastic	10 - 15K Cycles
Power Cycling	PD = 4.75W T <sub>J</sub> = +35°C - 175°C (approx.)	TO-3	20 - 50K Cycles
D-S Bias Life	T <sub>A</sub> = +150°C 80% of Drain Source	All	168 Hours
G-S Bias Life	G - S = 16V T <sub>A</sub> = +150°C	All	168 Hours

### TABLE 1. TYPICAL MOSFET RTI TESTS

### **Requalification Program (RQP)**

Each product is requalified every six to twelve months to the same matrix of tests required for the initial production release. This operation measures the changes in the total capability of each MOSFET family to meet the original reliability design objectives. Table 2 is typical of the data generated for RQP.

PACKAGE	TEST AND CONDITIONS	DURATION	CUM. HOURS OR CYCLES	% NON- FUNCTIONAL
All	Bias Life Drain-Source = 80% of rated T <sub>A</sub> = +150°C	500 Hours	300,000	0.33
All	Bias Life Gate-Source = 16V, T <sub>A</sub> = +150⁰C	500 Hours	270,000	0.00
All	Operating Life T <sub>A</sub> = +150°C, Free Air	500 Hours	230,000	0.00
TO-31 TO-39	Thermal Cycling -65°C to +150°C	400 Cycles	133,600	0.30
TO-220	Thermal Shock -65°C to +150°C	400 Cycles	100,000	0.00
TO-31 TO-39	Power Cycling Delta T <sub>J</sub> = +78°C PD = 56W (TO-3) or 2W (TO-39)	20,000 Cycles	5,480K	0.73
TO-220	Power Cycling Delta T <sub>J</sub> = +135°C, PD = 4.75W	10,000 Cycles	1,850K	0.00
TO-220	Pressure Cooker	24 Hours	3,072	0.00

### TABLE 2. ACCELERATED POWER MOSFET TEST RELIABILITY SUMMARY

FAILURE RATE IN %/1000 HOURS AT 60% UCL							
TEST $T_A = +125^{\circ}C$ $T_A = +90^{\circ}C$ $T_A = +75^{\circ}C$							
Bias Life	0.09	0.005	0.001				
Operating Life 0.07 0.004 0.001							

NOTE: Failure rate based on Nonfunctional performance in an operating mode, extrapolated from +150°C data using 1.0eV activation energy.

# MCT/IGBT/DIODES 10

# PACKAGING AND ORDERING INFORMATION

### PAGE

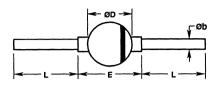
HERMETIC GLASS PACKAGES	10-3
HERMETIC STEEL PACKAGES	10-4
PLASTIC PACKAGES	10-5

### **ORDERING INFORMATION**

To order any part in this databook use full part number on the datasheet.

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# **Hermetic Glass Packages**

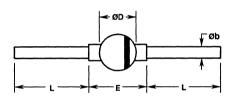


### NOTES:

- 1. No current JEDEC outline for this package.
- 2. Case is one piece glass, hermetically sealed.
- 3. Leads are solderable per MIL-STD-202, Method 208.
- 4. Color band (polarity symbol) indicates cathode connection.
- 5. Weight 0.04 ounces, 1.1 grams.
- 6. Controlling dimension: Inch.
- 7. Revision 1 dated 3-93.

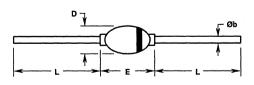
### AL-3 AXIAL LEAD DIODE PACKAGE

	INC	HES	MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Øb	0.048	0.052	1.22	1.32	-
ØD	0.170	0.250	4.32	6.35	-
E	-	0.300	-	7.62	-
L	1.000	-	25.40	-	-



### NOTES:

- 1. No current JEDEC outline for this package.
- 2. Case is one piece glass, hermetically sealed.
- 3. Leads are solderable per MIL-STD-202, Method 208.
- 4. Color band (polarity symbol) indicates cathode connection.
- 5. Weight 0.037 ounces, 1.04 grams.
- 6. Controlling dimension: Inch.
- 7. Revision 1 dated 3-93.



### NOTES:

- 1. Case is one piece glass, hermetically sealed.
- 2. Leads are solderable per MIL-STD-202, Method 208.
- 3. Color band (polarity symbol) indicates cathode connection.
- 4. Weight 0.02 ounces, 0.56 grams.
- 5. Controlling dimension: Inch.
- 6. Revision 1 dated 3-93.

### AL-4 AXIAL LEAD DIODE PACKAGE

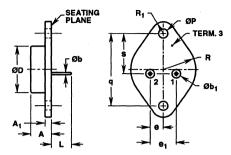
	INC	HES	MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Øb	0.037	0.042	0.94	1.07	-
ØD	0.115	0.180	2.93	4.57	-
E	•	0.300	•	7.62	•
L	1.000	-	25.40	-	-

# DO-204

### JEDEC STYLE DO-204 AXIAL LEAD DIODE PACKAGE

	INC	HES	MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Øb	0.028	0.034	0.72	0.86	-
ØD	0.100	0.150	2.54	3.81	-
E	-	0.240	-	6.09	-
L	1.000	-	25.40	-	-

# Hermetic Steel Packages



### NOTES:

- 1. These dimensions are within allowable dimensions of Rev. C of JEDEC TO-204AA outline dated 11-82.
- 2. Lead dimension (without solder).
- 3. Add typically 0.002 inches (0.05mm) for solder coating.
- 4. Position of lead to be measured 0.250 inches (6.35mm) from bottom of seating plane.
- 5. Controlling dimension: Inch.
- 6. Revision 2 dated 6-93.

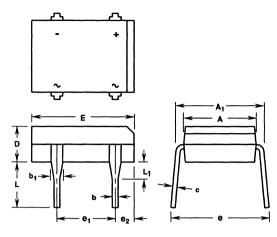
### TO-204AA

### JEDEC TO-204AA HERMETIC STEEL PACKAGE

	INC	INCHES MILLIMETERS			
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	0.310	0.330	7.88	8.38	-
A <sub>1</sub>	0.060	0.065	1.53	1.65	-
Øb	0.038	0.042	0.97	1.06	2, 3
Øb <sub>1</sub>	0.138	0.145	3.51	3.68	-
ØD	-	0.800	-	20.32	-
е	0.21	5 TYP	5.46 TYP		4
θ1	0.430	) BSC	10.92	BSC	4
L	0.430	-	10.93	-	-
ØP	0.155	0.160	3.94	4.06	-
q	1.187	7 BSC	30.15	BSC	-
R	0.495	0.525	12.58	13.33	-
R <sub>1</sub>	0.131	0.185	3.33	4.69	-
S	0.655	0.675	16.64	17.14	-

**BR-4** 

# **Plastic Packages**



1. No current JEDEC outline for this package.

2. Leads are solderable per MIL-STD-750, Method 2026. 3. Polarity and input symbols marked on body.

### NOTES SYMBOL MIN MAX MIN MAX A 0.245 0.255 6.23 6.47 -A<sub>1</sub> 0.285 0.315 7.24 8.00 b 0.018 0.022 0 46 0.55 -0.035 0.045 0.89 1.14 b, -0.23 0.27 0.009 0.011 с -D 0.120 0.130 3.05 3.30 -Ε 0.320 0.335 8.13 8.50 -0.300 0.350 7.62 8.89 -A 0.195 0.205 4.96 5.20 e, . 0.055 0.075 1.40 1.90 e, .

0.185

0.080

3.81

1.27

4.69

2.03

-

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MILLIMETERS

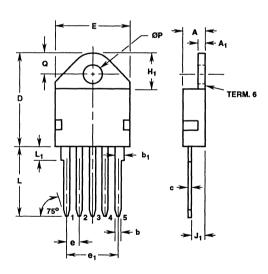
**4 PIN BRIDGE RECTIFIER PLASTIC PACKAGE** INCHES

0.050 4. Weight 0.04 ounces, 1.1 grams.

5. Controlling dimension: Inch.

0.150

6. Revision 1 dated 3-93.



### NOTES:

NOTES:

- 1. These dimensions are within allowable dimensions of Rev. A of JEDEC MO-093AA outline dated 2-90.
- 2. Tab outline optional within boundaries of dimensions E and Q.
- 3. Lead dimension and finish uncontrolled in L1.
- 4. Lead dimension (without solder).
- 5. Add typically 0.002 inches (0.05mm) for solder coating.
- 6. Maximum radius of 0.050 inches (1.27mm) on all body edges and corners.

### **MO-093AA**

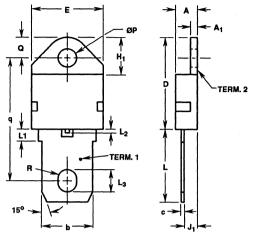
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Ľ,

**5 LEAD JEDEC MO-093AA PLASTIC PACKAGE** 

	INC	INCHES MILLIMETERS			
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	0.185	0.195	4.70	4.95	-
A <sub>1</sub>	0.058	0.062	1.48	1.57	-
b	0.049	0.053	1.25	1.34	3, 4, 5
b <sub>1</sub>	0.070	0.080	1.78	2.03	3, 4
с	0.018	0.022	0.46	0.55	3, 4, 5
D	0.800	0.820	20.32	20.82	-
E	0.615	0.625	15.63	15.87	2
е	0.110	) ΤΥΡ	2.80 TYP		7
e <sub>1</sub>	0.438 BSC		11.12	BSC	7
H <sub>1</sub>	-	0.330	-	8.38	-
J <sub>1</sub>	0.115	0.125	2.93	3.17	8
L	0.575	0.600	14.61	15.24	-
L <sub>1</sub>	-	0.130	-	3.30	3
ØP	0.159	0.163	4.04	4.14	-
Q	0.176	0.186	4.48	4.72	2

- 7. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 8. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 9. Controlling dimension: Inch.
- 10. Revision 1 dated 1-93.



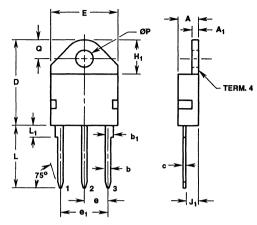
### NOTES:

- 1. No current JEDEC outline for this package.
- 2. Tab outline optional within boundaries of dimensions  ${\sf E}$  and  ${\sf Q}.$
- 3. Maximum radius of 0.050 inches (1.27mm) on all body edges and corners.
- 4. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 5. Controlling dimension: Inch.
- 6. Revision 1 dated 1-93.

TO-21	8
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SINGLE LEAD JEDEC STYLE TO-218 PLASTIC PACKAGE

	INC	HES	MILLIM	ETERS	
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.185	0.195	4.70	4.95	-
A <sub>1</sub>	0.058	0.062	1.48	1.57	-
b	0.433	0.443	11.00	11.25	-
c	0.018	0.022	0.46	0.55	-
D	0.800	0.820	20.32	20.82	-
E	0.615	0.625	15.63	15.87	2
H <sub>1</sub>	-	0.330	-	8.38	-
J <sub>1</sub>	0.115	0.125	2.93	3.17	4
L	0.635	0.655	16.13	16.63	-
L1	-	0.130	-	3.30	-
L <sub>2</sub>	-	0.034	-	0.86	-
L <sub>3</sub>	0.195	0.205	4.96	5.20	-
ØP	0.159	0.163	4.04	4.14	-
Q	0.176	0.186	4.48	4.72	2
q	1.080	1.088	27.44	27.63	-
R	0.078	0.082	1.99	2.08	-



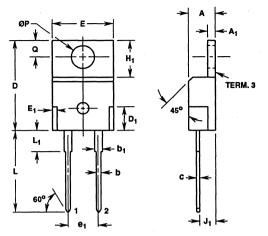
NOTES:

- 1. These dimensions are within allowable dimensions of Rev. E of JEDEC TO-218AC outline dated 6-86.
- 2. Tab outline optional within boundaries of dimensions E and Q.
- 3. Lead dimension and finish uncontrolled in  $\mathsf{L}_1.$
- 4. Lead dimension (without solder).
- 5. Add typically 0.002 inches (0.05mm) for solder coating.
- 6. Maximum radius of 0.050 inches (1.27mm) on all body edges and corners.
- 7. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 8. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 9. Controlling dimension: Inch.
- 10. Revision 1 dated 1-93.

TO	-21	8AC			
		IFOFO	 	-	0

3 LEAD JEDEC TO-218AC PLASTIC PACKAGE

	INC	HES	MILLIM		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.185	0.195	4.70	4.95	-
A <sub>1</sub>	0.058	0.062	1.48	1.57	-
b	0.049	0.053	1.25	1.34	3, 4, 5
b <sub>1</sub>	0.070	0.080	1.78	2.03	3, 4
c	0.018	0.022	0.46	0.55	3, 4, 5
D	0.800	0.820	20.32	20.82	-
E	0.615	0.625	15.63	15.87	2
e	0.219	TYP	5.56 TYP		7
e <sub>1</sub>	0.438	BSC	11.12 BSC		7
H <sub>1</sub>	-	0.330	-	8.38	-
J <sub>1</sub>	0.115	0.125	2.93	3.17	8
L	0.575	0.600	14.61	15.24	-
L <sub>1</sub>	-	0.130	-	3.30	3
ØP	0.159	0.163	4.04	4.14	-
Q	0.176	0.186	4.48	4.72	2



### NOTES:

- 1. These dimensions are within allowable dimensions of Rev. J of JEDEC TO-220AC outline dated 3-24-87.
- 2. Lead dimension and finish uncontrolled in L1.
- 3. Lead dimension (without solder).
- 4. Add typically 0.002 inches (0.05mm) for solder coating.
- 5. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 7. Controlling dimension: Inch.
- 8. Revision 2 dated 12-93.

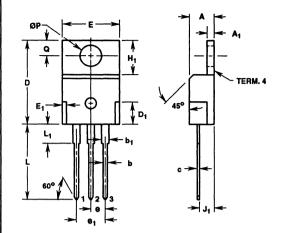
### TO-220AC

### 2 LEAD JEDEC TO-220AC PLASTIC PACKAGE (FOR RECTIFIERS ONLY)

	INCHES		INCHES MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.170	0.180	4.32	4.57	-
A <sub>1</sub>	0.048	0.052	1.22	1.32	-
b	0.030	0.034	0.77	0.86	3, 4
b <sub>1</sub>	0.045	0.055	1.15	1.39	2, 3
C	0.014	0.019	0.36	0.48	2, 3, 4
D	0.590	0.610	14.99	15.49	-
D <sub>1</sub>	-	0.160	-	4.06	-
E	0.395	0.410	10.04	10.41	-
E1	-	0.030	-	0.76	-
e <sub>1</sub>	0.200	BSC	5.08 BSC		5
H <sub>1</sub>	0.235	0.255	5.97	6.47	•
J <sub>1</sub>	0.100	0.110	2.54	2.79	6
L	0.530	0.550	13.47	13.97	-
L1	0.130	0.150	3.31	3.81	2
ØP	0.149	0.153	3.79	3.88	•
Q	0.102	0.112	2.60	2.84	-

**TO-220AB** 

# Plastic Packages (Continued)



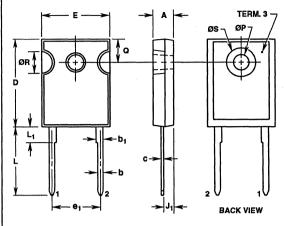
	INCHES		MILLIM	ETERS	
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.170	0.180	4.32	4.57	-
Α <sub>1</sub>	0.048	0.052	1.22	1.32	-
b	0.030	0.034	0.77	0.86	3, 4
b <sub>1</sub>	0.045	0.055	1.15	1.39	2, 3
с	0.014	0.019	0.36	0.48	2, 3, 4
D	0.590	0.610	14.99	15.49	-
D <sub>1</sub>	-	0.160	-	4.06	-
E	0.395	0.410	10.04	10.41	-
E <sub>1</sub>	-	0.030	-	0.76	-
е	0.100	) ΤΥΡ	2.54 TYP		5
e <sub>1</sub>	0.200 BSC		5.08	BSC	5
H <sub>1</sub>	0.235	0.255	5.97	6.47	-
J <sub>1</sub>	0.100	0.110	2.54	2.79	6
L	0.530	0.550	13.47	13.97	-
L <sub>1</sub>	0.130	0.150	3.31	3.81	2
ØP	0.149	0.153	3.79	3.88	•
Q	0.102	0.112	2.60	2.84	-

NOTES:

1. These dimensions are within allowable dimensions of Rev. J of JEDEC TO-220AB outline dated 3-24-87.

- 2. Lead dimension and finish uncontrolled in L1.
- 3. Lead dimension (without solder).
- 4. Add typically 0.002 inches (0.05mm) for solder coating.
- 5. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 6. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 7. Controlling dimension: Inch.
- 8. Revision 1 dated 1-93.

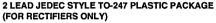
PACKAGING AND ORDERING INFO



NOTES:

- 1. Lead dimension and finish uncontrolled in L1.
- 2. Lead dimension (without solder).
- 3. Add typically 0.002 inches (0.05mm) for solder coating.
- 4. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 5. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.

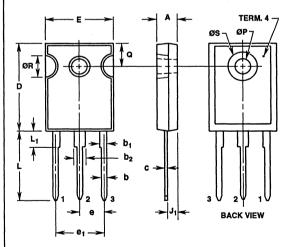
### TO-247



	INCHES MILLIMETERS			ETERS	
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.180	0.190	4.58	4.82	-
b	0.046	0.051	1.17	1.29	2, 3
b <sub>1</sub>	0.060	0.070	1.53	1.77	1, 2
С	0.020	0.026	0.51	0.66	1, 2, 3
D	0.800	0.820	20.32	20.82	-
E	0.605	0.625	15.37	15.87	-
θ <sub>1</sub>	0.438	BSC	11.12 BSC		4
J <sub>1</sub>	0.090	0.105	2.29	2.66	5
L	0.620	0.640	15.75	16.25	-
ել	0.145	0.155	3.69	3.93	1
ØP	0.138	0.144	3.51	3.65	-
Q	0.210	0.220	5.34	5.58	
ØR	0.195	0.205	4.96	5.20	-
ØS	0.260	0.270	6.61	6.85	-

6. Controlling dimension: Inch.

7. Revision 2 dated 12-93.



### NOTES:

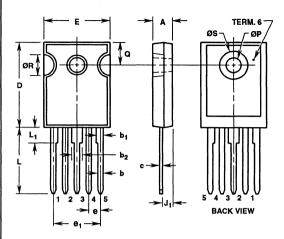
- 1. Lead dimension and finish uncontrolled in L1.
- 2. Lead dimension (without solder).
- 3. Add typically 0.002 inches (0.05mm) for solder coating.
- 4. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 5. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.

TO-247		
3 LEAD JEDEC STYLE	TO-247 PLASTIC	PACKAGE

	INCHES		MILLIM		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.180	0.190	4.58	4.82	-
b	0.046	0.051	1.17	1.29	2, 3
b <sub>1</sub>	0.060	0.070	1.53	1.77	1, 2
b <sub>2</sub>	0.095	0.105	2.42	2.66	1, 2
C	0.020	0.026	0.51	0.66	1, 2, 3
D	0.800	0.820	20.32	20.82	•
E	0.605	0.625	15.37	15.87	
9	0.219	TYP	5.56 TYP		4
θ1	0.438	BSC	11.12 BSC		4
J <sub>1</sub>	0.090	0.105	2.29	2.66	5
L	0.620	0.640	15.75	16.25	-
L <sub>1</sub>	0.145	0.155	3.69	3.93	1
ØP	0.138	0.144	3.51	3.65	-
Q	0.210	0.220	5.34	5.58	-
ØR	0.195	0.205	4.96	5.20	-
ØS	0.260	0.270	6.61	6.85	-

6. Controlling dimension: Inch.

7. Revision 1 dated 1-93.



### NOTES:

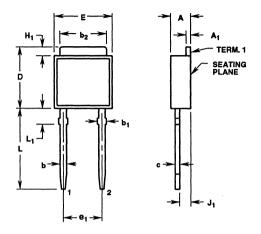
- 1. Lead dimension and finish uncontrolled in L1.
- 2. Lead dimension (without solder).
- 3. Add typically 0.002 inches (0.05mm) for solder coating.
- 4. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 5. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.

### TO-247 5 LEAD JEDEC STYLE TO-247 PLASTIC PACKAGE

	INC	HES	MILLIM		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.180	0.190	4.58	4.82	-
b	0.046	0.051	1.17	1.29	2, 3
b <sub>1</sub>	0.060	0.070	1.53	1.77	1, 2
b <sub>2</sub>	0.095	0.105	2.42	2.66	1, 2
с	0.020	0.026	0.51	0.66	1, 2, 3
D	0.800	0.820	20.32	20.82	-
E	0.605	0.625	15.37	15.87	-
е	0.110	) TYP	2.79 TYP		4
ө <sub>1</sub>	0.438	BSC	11.12 BSC		4
J <sub>1</sub>	0.090	0.105	2.29	2.66	5
L	0.620	0.640	15.75	16.25	-
L <sub>1</sub>	0.145	0.155	3.69	3.93	1
ØP	0.138	0.144	3.51	3.65	-
Q	0.210	0.220	5.34	5.58	-
ØR	0.195	0.205	4.96	5.20	-
ØS	0.260	0.270	6.61	6.85	-

6. Controlling dimension: Inch.

7. Revision 1 dated 1-93.



### NOTES:

- 1. No current JEDEC outline for this package.
- 2. Solder finish uncontrolled.
- 3. Dimension (without solder).
- 4. Add typically 0.0006 inches (0.015mm) for solder coating.
- 5. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.

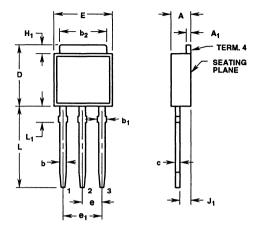
### TO-251

### 2 LEAD JEDEC STYLE TO-251 PLASTIC PACKAGE (FOR RECTIFIERS ONLY)

	INC	HES	MILLIM	ETERS	
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	0.086	0.094	2.19	2.38	-
A <sub>1</sub>	0.018	0.022	0.46	0.55	3, 4
b	0.028	0.032	0.72	0.81	3, 4
b <sub>1</sub>	0.033	0.040	0.84	1.01	3
b <sub>2</sub>	0.205	0.215	5.21	5.46	3, 4
c	0.018	0.022	0.46	0.55	3, 4
D	0.270	0.290	6.86	7.36	-
E	0.250	0.265	6.35	6.73	-
θ1	0.180	BSC	4.57	BSC	5
H <sub>1</sub>	0.035	0.045	0.89	1.14	-
J <sub>1</sub>	0.040	0.045	1.02	1.14	6
L	0.355	0.375	9.02	9.52	-
L <sub>1</sub>	0.075	0.090	1.91	2.28	2

6. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.

- 7. Controlling dimension: Inch.
- 8. Revision 1 dated 6-93.



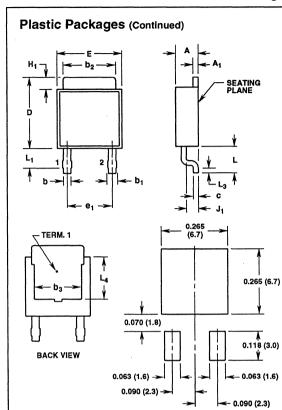
### SYMBOL MIN MAX MIN MAX NOTES 0.086 0.094 2.19 2.38 А 0.018 0.022 0.46 0.55 3, 4 A<sub>1</sub> 0.028 0.032 0.72 0.81 3, 4 b 0.033 0.040 0.84 1.01 з b<sub>1</sub> b<sub>2</sub> 0.205 0.215 5.21 5.46 3,4 0.018 0.022 0.46 0.55 3,4 с 0.270 0.290 7.36 D 6.86 . Ε 0.250 0.265 6.35 6.73 -0.090 TYP 2.28 TYP ө 5 0.180 BSC 4.57 BSC 5 e1 H<sub>1</sub> 0.035 0.045 0.89 1.14 -0.040 0.045 1.02 1.14 J 6 L 0.355 0.375 9.02 9.52 -0.075 0.090 1.91 2.28 2 L,

MILLIMETERS

### NOTES:

- 1. These dimensions are within allowable dimensions of Rev. C of JEDEC TO-251AA outline dated 9-88.
- 2. Solder finish uncontrolled.
- 3. Dimension (without solder).
- 4. Add typically 0.0006 inches (0.015mm) for solder coating.
- 5. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 6. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 7. Controlling dimension: Inch.
- 8. Revision 1 dated 1-93.

### **TO-251AA 3 LEAD JEDEC TO-251AA PLASTIC PACKAGE** INCHES



MINIMUM PAD SIZE RECOMMENDED FOR SURFACE-MOUNTED APPLICATIONS TO-252

# 2 LEAD JEDEC STYLE TO-252 PLASTIC PACKAGE (FOR RECTIFIERS ONLY)

	INCHES		INCHES MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
A	0.086	0.094	2.19	2.38	-
A <sub>1</sub>	0.018	0.022	0.46	0.55	4, 5
b	0.028	0.032	0.72	0.81	4, 5
b <sub>1</sub>	0.033	0.040	0.84	1.01	4
b <sub>2</sub>	0.205	0.215	5.21	5.46	4, 5
b <sub>3</sub>	0.190	-	4.83	-	2
С	0.018	0.022	0.46	0.55	4, 5
D	0.270	0.290	6.86	7.36	-
E	0.250	0.265	6.35	6.73	-
e <sub>1</sub>	0.180	BSC	4.57	BSC	7
H <sub>1</sub>	0.035	0.045	0.89	1.14	-
J <sub>1</sub>	0.040	0.045	1.02	1.14	-
L	0.100	0.115	2.54	2.92	-
L <sub>1</sub>	0.075	0.090	1.91	2.28	3
L <sub>3</sub>	0.020	-	0.51	-	4, 6
L <sub>4</sub>	0.170	-	4.32	-	2

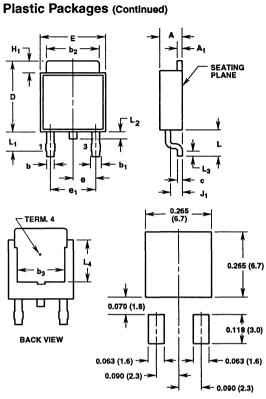
NOTES:

1. No current JEDEC outline for this package.

- 2. L4 and b3 dimensions establish a minimum mounting surface for terminal 1.
- 3. Solder finish uncontrolled.
- 4. Dimension (without solder).
- 5. Add typically 0.0006 inches (0.015mm) for solder coating.
- 6. L<sub>3</sub> is the terminal length for soldering.
- 7. Position of lead to be measured 0.090 inches (2.28mm) from bottom of dimension D.
- 8. Controlling dimension: Inch.
- 9. Revision 1 dated 6-93.

**TO-252AA** 

2 LEAD JEDEC TO-252AA PLASTIC PACKAGE



MINIMUM PAD SIZE RECOMMENDED FOR SURFACE-MOUNTED APPLICATIONS

	INCHES		INCHES MILLIMETER		ETERS	
SYMBOL	MIN	MAX	MIN	MAX	NOTES	
A	0.086	0.094	2.19	2.38	-	
A <sub>1</sub>	0.018	0.022	0.46	0.55	4, 5	
b	0.028	0.032	0.72	0.81	4, 5	
b <sub>1</sub>	0.033	0.040	0.84	1.01	4	
b <sub>2</sub>	0.205	0.215	5.21	5.46	4, 5	
b <sub>3</sub>	0.190	-	4.83	-	2	
c	0.018	0.022	0.46	0.55	4, 5	
D	0.270	0.290	6.86	7.36	-	
E	0.250	0.265	6.35	6.73	-	
θ	0.090	) ΤΥΡ	2.28	ТҮР	7	
θ1	0.180	BSC	4.57	BSC	7	
H <sub>1</sub>	0.035	0.045	0.89	1.14	-	
J <sub>1</sub>	0.040	0.045	1.02	1.14	-	
L	0.100	0.115	2.54	2.92	-	
Lı	0.075	0.090	1.91	2.28	3	
L2	0.025	0.040	0.64	1.01	-	
L <sub>3</sub>	0.020	-	0.51	-	4,6	
L <sub>4</sub>	0.170	-	4.32	-	2	

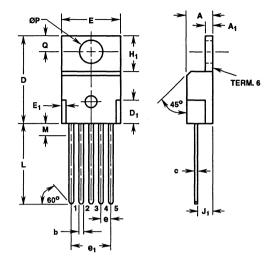
NOTES:

1. These dimensions are within allowable dimensions of Rev. B of JEDEC TO-252AA outline dated 9-88.

- L<sub>4</sub> and b<sub>3</sub> dimensions establish a minimum mounting surface for terminal 1.
- 3. Solder finish uncontrolled.
- 4. Dimension (without solder).
- 5. Add typically 0.0006 inches (0.015mm) for solder coating.
- 6. L<sub>3</sub> is the terminal length for soldering.
- 7. Position of lead to be measured 0.090 inches (2.28mm) from bottom of dimension D.
- 8. Controlling dimension: Inch.
- 9. Revision 2 dated 6-93.



# Plastic Packages (Continued)



# NOTES:

- 1. These dimensions are within allowable dimensions of Rev. A of JEDEC TS-001AA outline dated 8-89.
- 2. Lead finish uncontrolled in zone M.
- 3. Lead dimension (without solder).
- 4. Add typically 0.002 inches (0.05mm) for solder coating.
- 5. Position of lead to be measured 0.250 inches (6.35mm) from bottom of dimension D.
- 6. Position of lead to be measured 0.100 inches (2.54mm) from bottom of dimension D.
- 7. Controlling dimension: Inch
- 8. Revision 3 dated 12-93.

TS-001AA	
<b>5 LEAD JEDEC TS-001AA PLAS</b>	TIC PACKAGE

	INCHES		MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	0.170	0.180	4.32	4.57	-
A <sub>1</sub>	0.048	0.052	1.22	1.32	-
b	0.030	0.034	0.77	0.86	3, 4
с	0.014	0.019	0.36	0.48	2, 3, 4
D	0.590	0.610	14.99	15.49	-
D <sub>1</sub>	-	0.160	-	4.06	-
E	0.395	0.410	10.04	10.41	-
E1	-	0.030	-	0.76	-
e	0.067	' TYP	1.70 TYP		5
e <sub>1</sub>	0.268	BSC	6.80 BSC		5
H <sub>1</sub>	0.235	0.255	5.97	6.47	-
J <sub>1</sub>	0.100	0.110	2.54	2.79	6
L	0.530	0.550	13.47	13.97	-
м	0.130	0.150	3.31	3.81	2
ØP	0.149	0.153	3.79	3.88	-
Q	0.102	0.112	2.60	2.84	-

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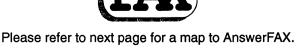
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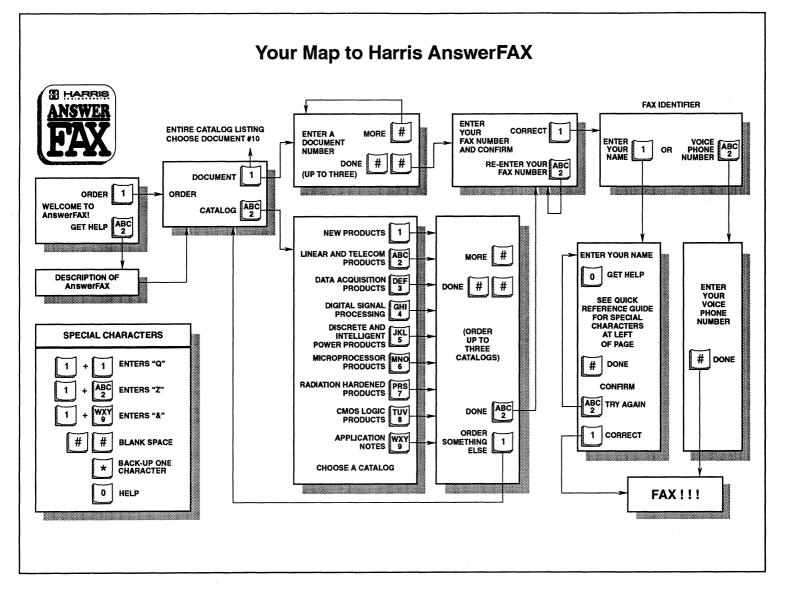
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	PSG201.21	PRODUCT SELECTION GUIDE (NEW 1994: 616pp) Key product information on all Harris Semiconductor devices. Sectioned (Linear, Data Acquisition, Digital Signal Processing, Telecom, Intelligent Power, Discrete Power, Digital Microprocessors and Hi-Rel/Military and Rad Hard) for easy use and includes cross references and alphanumeric part number index.			
	DB500B	LINEAR AND TELECOM ICs (1993: 1,312pp) Product specifications for: op amps, comparators, S/H amps, differential amps, arrays, special analog circuits, telecom ICs, and power processing circuits.			
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#### Harris Semiconductor 3031 Tisch Way 1 Plaza South San Jose, CA 95128 TEL: (408) 985-7322 FAX: 408 985 7455

**CK Associates** 8333 Clairemont Mesa Blvd. Suite 102 San Diego, CA 92111 TEL: (619) 279-0420 FAX: 619 279 7650

## Ewing Foley, Inc. 185 Linden Avenue Auburn, CA 95603 TEL: (916) 885-6591 FAX: 916 885 6594

Ewing Foley, Inc. 895 Sherwood Lane Los Altos, CA 94022 TEL: (415) 941-4525 FAX: 415 941 5109

Vision Technical Sales, Inc. 26010 Mureau Road Suite 140 Calabasas, CA 91302 TEL: (818) 878-7955 FAX: 818 878 7965

## CANADA

Blakewood Electronic Systems, Inc. #201 - 7382 Winston Street Burnaby, BC Canada V5A 2G9 TEL: (604) 444-3344 FAX: 604 444 3303

## **Clark Hurman Associates**

Unit 14 20 Regan Road Brampton, Ontario Canada L7A IC3 TEL: (905) 840-6066 FAX: 905 840-6091 308 Palladium Drive Suite 200 Kanata, Ontario Canada K2B 1A1 TEL: (613) 599-5626 FAX: 613 599 5707 78 Donegani, Suite 200 Pointe Claire, Quebec Canada H9R 2V4 TEL: (514) 426-0453

# COLORADO

FAX: 514 426 0455

Compass Mktg. & Sales, Inc. 5600 So. Quebec St. Suite 350D Greenwood Village, CO 80111 TEL: (303) 721-9663 FAX: 303 721 0195

CONNECTICUT Advanced Tech. Sales, Inc. Westview Office Park Bldg. 2, Suite 1C 850 N. Main Street Extension Wallingford, CT 06492 TEL: (508) 664-0888 FAX: 203 284 8232

#### FLORIDA

Harris Semiconductor 2401 Palm Bay Rd. Palm Bay, FL 32905 TEL: (407) 729-4984 FAX: 407 729 5321

#### Sun Marketing Group 1956 Dairy Rd. West Melbourne, FL 32904 TEL: (407) 723-0501 FAX: 407 723 3845

Sun Marketing Group 4175 East Bay Drive, Suite 128 Clearwater, FL 34624 TEL: (813) 536-5771 FAX: 813 536 6933

Sun Marketing Group 600 S. Federal Hwy., Suite 218 Deerfield Beach, FL 33441 TEL: (305) 429-1077 FAX: 305 429 0019

# GEORGIA

**Giesting & Associates** 2434 Hwy. 120, Suite 108 Duluth, GA 30136 TEL: (404) 476-0025 FAX: 404 476 2405

# ILLINOIS

Harris Semiconductor 1101 Perimeter Dr., Suite 600 Schaumburg, IL 60173 TEL: (708) 240-3480 FAX: 708 619 1511

# **Oasis Sales**

1101 Tonne Road Elk Grove Village, IL 60007 TEL: (708) 640-1850 FAX: 708 640 9432

#### INDIANA

Harris Semiconductor 11590 N. Meridian St. Suite 100 Carmel, IN 46032 TEL: (317) 843-5180 FAX: 317 843 5191

**Giesting & Associates** 370 Ridgepoint Dr. Carmel, IN 46032 TEL: (317) 844-5222 FAX: 317 844 5861

#### IOWA

**Oasis Sales** 4905 Lakeside Dr., NE Suite 203 Cedar Rapids, IA 52402 TEL: (319) 377-8738 FAX: 319 377 8803

# KANSAS

Advanced Tech. Sales. Inc. 601 North Mur-Len, Suite 8 Olathe, KS 66062 TEL: (913) 782-8702 FAX: 913 782 8641

#### KENTUCKY

**Giesting & Associates** 204 Pintail Court Versailles, KY 40383 TEL: (606) 873-2330 FAX: 606 873 6233

#### MARYLAND

New Era Sales, Inc. 890 Airport Pk, Rd, Suite 103 Glen Burnie, MD 21061 TEI: (410) 761-4100 FAX: 410 761-2981

# MASSACHUSETTS

**Harris Semiconductor** Six New England Executive Pk. Burlington, MA 01803 TEL: (617) 221-1850 FAX: 617 221 1866

Advanced Tech Sales, Inc. 348 Park Street, Suite 102 Park Place West N. Reading, MA 01864 TEL: (508) 664-0888 FAX: 508 664 5503

# MICHIGAN

Harris Semiconductor 27777 Franklin Rd., Suite 460 Southfield, MI 48034 TEL: (810) 746-0800 FAX: 810 746 0516

#### **Giesting & Associates** 34441 Eight Mile Rd., Suite 113 Livonia, MI 48152 TEL: (810) 478-8106 FAX: 810 477 6908

# February 24, 1995

# **Giesting & Associates** 1279 Skyhills N.E.

Comstock Park, MI 49321 TEL: (616) 784-9437 FAX: 616 784 9438

# MINNESOTA

**Oasis Sales** 7805 Telegraph Road Suite 210 Bloomington, MN 55438 TEL: (612) 941-1917 FAX: 612 941 5701

## MISSOURI

Advanced Tech. Sales 13755 St. Charles Rock Rd. Bridgeton, MO 63044 TEL: (314) 291-5003 FAX: 314 291 7958

# NEBRASKA

Advanced Tech. Sales, Inc. 601 North Mur-Len. Suite 8 Olathe, KS 66062 TEL: (913) 782-8702 FAX: 913 782 8641

#### NEW JERSEY

Harris Semiconductor Plaza 1000 at Main Street Suite 104 Voorhees, NJ 08043 TEL: (609) 751-3425 FAX: 609 751 5911

#### Harris Semiconductor 724 Route 202

P.O. Box 591 Somerville, NJ 08876 TEL: (908) 685-6150 FAX: 908 685-6140

Tritek Sales, Inc. One Mall Dr., Suite 410 Cherry Hill, NJ 08002 TEL: (609) 667-0200 FAX: 609 667 8741

# NEW MEXICO

Compass Mktg. & Sales, Inc. 4100 Osuna Rd., NE, Suite 109 Albuquerque, NM 87109 TEL: (505) 344-9990 FAX: 505 345 4848

# NEW YORK

Harris Semiconductor Hampton Business Center 1611 Rt. 9, Suite U3 Wappingers Falls, NY 12590 TEL: (914) 298-0413 FAX: 914 298 0425

Harris Semiconductor 490 Wheeler Rd, Suite 165B Hauppauge, NY 11788-4365 TEL: (516) 342-0219 FAX: 516 342 0295

Foster & Wager, Inc. 300 Main Street Vestal, NY 13850 TEL: (607) 748-5963 FAX: 607 748 5965

# North American Sales Offices and Representatives (Continued)

Foster & Wager, Inc. 2511 Browncroft Blvd. Rochester, NY 14625 TEL: (716) 385-7744 FAX: 716 586 1359

Foster & Wager, Inc. 7696 Mountain Ash Liverpool, NY 13090 TEL: (315) 457-7954 FAX: 315 457 7076

Trionic Associates, Inc. 320 Northern Blvd. Great Neck, NY 11021 TEL: (516) 466-2300 FAX: 516 466 2319

# NORTH CAROLINA

Harris Semiconductor 4020 Stirrup Creek Dr. Building 2A, MS/2T08 Durham, NC 27703 TEL: (919) 405-3600 FAX: 919 405 3660

# New Era Sales

1215 Jones Franklin Road Suite 201 Raleigh, NC 27606 TEL: (919) 859-4400 FAX: 919 859 6167 OHIO Glesting & Associates P.O. Box 39398 2854 Blue Rock Rd. Cincinnati, OH 45239 TEL: (513) 385-1105 FAX: 513 385 5069 6324 Tamworth Ct. Columbus, OH 43017 TEL: (614) 752-5900 6200 SOM Center Rd. Suite D-20 Solon, OH 44139 TEL: (216) 498-4644 FAX: 216 498 4554

#### OKLAHOMA

Nova Marketing 8421 East 61st Street, Suite P Tulsa, OK 74133-1928 TEL: (800) 826-8557 TEL: (918) 660-5105 FAX: 918 357 1091

# OREGON

Northwest Marketing Assoc. 6975 SW Sandburg Rd. Suite 330 Portland, OR 97223 TEL: (503) 620-0441 FAX: 503 684 2541

# PENNSYLVANIA

Giesting & Associates 471 Walnut Street Pittsburgh, PA 15238 TEL: (412) 828-3553 FAX: 412 828 6160

# TEXAS

Harris Semiconductor 17000 Dallas Parkway, Suite 205 Dallas, TX 75248 TEL: (214) 733-0800 FAX: 214 733 0819

Nova Marketing 8310 Capitol of Texas Hwy. Suite 180 Austin, TX 78731 TEL: (512) 343-2321 FAX: 512 343-2487

# February 24, 1995

8350 Meadow Rd., Suite 174 Dallas, TX 75231 TEL: (214) 265-4600 FAX: 214 265 4668

Corporate Atrium II, Suite 140 10701 Corporate Dr. Stafford, TX 77477 TEL: (713) 240-6082 FAX: 713 240 6094

#### UTAH

Compass Mktg. & Sales, Inc. 5 Triad Center, Suite 320 Salt Lake City, UT 84180 TEL: (801) 322-0391 FAX: 801 322-0392

#### WASHINGTON

Northwest Marketing Assoc. 12835 Bel-Red Road Suite 330N Bellevue, WA 98005 TEL: (206) 455-5846 FAX: 206 451 1130

#### WISCONSIN

Oasis Sales 1305 N. Barker Rd. Brookfield, WI 53005 TEL: (414) 782-6660 FAX: 414 782 7921

# North American Authorized Distributors and Corporate Offices

Hamilton Hallmark and Zeus are the only authorized North American distributors for stocking and sale of Harris Rad Hard Space products.

Alliance Electronics 7550 E. Redfield Rd. Scottsdale, AZ 85260 TEL: (602) 483-9400 FAX: (602) 443 3898

Arrow/Schweber Electronics Group 25 Hub Dr. Melville, NY 11747 TEL: (516) 391-1300 FAX: 516 391 1644

Electronics Marketing Corporation (EMC) 1150 West Third Avenue Columbus, OH 43212 TEL: (614) 299-4161 FAX: 614 299 4121 Farnell Electronic Services 300 North Rivermede Rd. Concord, Ontario Canada L4K 3N6 TEL: (416) 798-4884 FAX: 416 798 4889

Gerber Electronics 128 Carnegie Row Norwood, MA 02062 TEL: (617) 769-6000, x156 FAX: 617 762 8931 Hamilton Hallmark 10950 W. Washington Blvd. Culver City, CA 90230

TEL: (310) 558-2000 FAX: 310 558 2809 (Mil) FAX: 214 343 5988(Com) Newark Electronics

4801 N. Ravenswood Chicago, IL 60640 TEL: (312) 784-5100 FAX: 312 275-9596

# Wyle Electronics

(Commercial Products) 3000 Bowers Avenue Santa Clara, CA 95051 TEL: (408) 727-2500 FAX: 408 988-2747

#### Zeus Electronics, An Arrow Company

100 Midland Avenue Pt. Chester, NY 10573 TEL: (914) 937-7400 TEL: (800) 52-HI-REL FAX: 914 937-2553

## **Obsolete Products:**

Rochester Electronic 10 Malcom Hoyt Drive Newburyport, MA 01950 TEL: (508) 462-9332 FAX: 508 462 9512

# North American Authorized Distributors

# ALABAMA

Arrow/Schweber Huntsville TEL: (205) 837-6955

Hamilton Hallmark Huntsville TEL: (205) 837-8700

Wyle Electronics Huntsville TEL: 205) 830-1119

Zeus, An Arrow Company Huntsville TEL: (407) 333-3055 TEL: (800) 52-HI-REL ARIZONA Alliance Electronics, Inc. Gilbert TEL: (602) 813-0233 Scottsdale TEL: (602) 483-9400 Arrow/Schweber Tempe TEL: (602) 431-0030 Hamilton Hallmark Phoenix TEL: (602) 437-1200 Wyle Electronics Phoenix TEL: (602) 437-2088 Zeus, An Arrow Company Tempe

TEL: (408) 629-4789 TEL: (800) 52-HI-REL

CALIFORNIA Alliance Electronics, Inc. Santa Clarita TEL: (805) 297-6204 Arrow/Schweber Calabasas TEL: (818) 880-9686 Fremont TEL: (408) 432-7171 Irvine TEL: (714) 587-0404 San Diego TEL: (619) 565-4800 San Jose TEL: (408) 441-9700 Hamilton Hallmark Costa Mesa TEL: (714) 641-4100 Los Angeles TEL: (818) 594-0404 Sacramento TEL: (916) 624-9781 San Diego TEL: (619) 571-7540 San Jose TEL: (408) 435-3500

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#### CANADA

Arrow/Schweber Burnaby, British Columbia TEL: (604) 421-2333 Dorval, Quebec

TEL: (514) 421-7411

Nepan, Ontario TEL: (613) 226-6903

Mississagua, Ontario TEL: (905) 670-7769

Farnell Electronic Services Burnaby, British Columbia TEL: (604) 291-8866

Calgary, Alberta TEL: (403) 273-2780

Concord, Ontario TEL: (416) 798-4884

V. St. Laurent, Quebec TEL: (514) 335-7697

Nepean, Ontario TEL: (613) 596-6980

Winnipeg, Manitoba TEL: (204) 786-2589

Hamilton Hallmark Mississagua, Ontario TEL: (905) 564-6060

Montreal TEL: (514) 335-1000

Ottawa TEL: (613) 226-1700

Vancouver, B.C. TEL: (604) 420-4101 Toronto

TEL: (905) 564-6060

COLORADO Arrow/Schweber Englewood TEL: (303) 799-0258 Hamilton Hallmark Denver

TEL: (303) 790-1662 Colorado Springs

TEL: (719) 637-0055 Wyle Electronics Thornton TEL: (303) 457-9953

Zeus, An Arrow Company TEL: (408) 629-4789 TEL: (800) 52-HI-REL CONNECTICUT Alliance Electronics, Inc. Shelton TEL: (203) 926-0087 Arrow/Schweber Wallingford TEL: (203) 265-7741 Hamilton Hallmark Danbury TEL: (203) 271-2844 Zeus, An Arrow Company TEL: (914) 937-7400 TEL: (800) 52-HI-REL **FLORIDA** Arrow/Schweber **Deerfield Beach** TEL: (305) 429-8200 Lake Marv TEL: (407) 333-9300 Hamilton Hallmark Miami TEL: (305) 484-5482 Orlando TEL: (407) 657-3300 Largo

TEL: (813) 541-7440 Wyle Electronics Fort Lauderdale TEL: (305) 420-0500 St. Petersburg TEL: (813) 576-3004 Zeus, An Arrow Company Lake Mary TEL: (407) 333-3055

GEORGIA

Arrow/Schweber Duluth TEL: (404) 497-1300 Hamilton Halimark Atlanta TEL: (404) 623-5475 Wyle Electronics Duluth TEL: (404) 441-9045 Zeus. An Arrow Company

TEL: (800) 52-HI-REL

TEL: (407) 333-3055 TEL: (800) 52-HI-REL

#### ILLINOIS

Alliance Electronics, Inc. Vernon Hills TEL: (708) 949-9890 Arrow/Schweber Itasca TEL: (708) 250-0500 Hamilton Hallmark Chicago TEL: (708) 860-7780 Newark Electronics, Inc. Chicago TEL: (312) 907-5436

# Wyle Electronics

Addison TEL: (708) 620-0969 **Zeus, An Arrow Company** Itasca TEL: (708) 250-0500 TEL: (800) 52-HI-REL

INDIANA Arrow/Schweber

Arrow/Schweber Indianapolis TEL: (317) 299-2071 Hamilton Hallmark Indianapolis

TEL: (317) 872-8875 Zeus, An Arrow Company

TEL: (708) 250-0500 TEL: (800) 52-HI-REL

# IOWA

Arrow/Schweber Cedar Rapids TEL: (319) 395-7230 Hamilton Hallmark

Cedar Rapids TEL: (319) 362-4757

Zeus, An Arrow Company TEL: (214) 380-4330 TEL: (800) 52-HI-REL

# KANSAS

Arrow/Schweber Lenexa TEL: (913) 541-9542 Hamilton Hallmark Kansas City

TEL: (913) 888-4747

Zeus, An Arrow Company TEL: (214) 380-4330 TEL: (800) 52-HI-REL

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Columbia TEL: (301) 596-7800 Hamilton Hallmark Baltimore TEL: (410) 988-9800 Wyle Electronics Columbia TEL: (410) 312-4844

Zeus, An Arrow Company TEL: (914) 937-7400 TEL: (800) 52-HI-REL

MASSACHUSETTS

Alliance Electronics, Inc. Winchester TEL: (617) 756-1910 Arrow/Schweber Wilmington TEL: (508) 658-0900 Gerber Norwood TEL: (617) 769-6000 Hamilton Hallmark Peabody

TEL: (508) 532-9893 Wyle Electronics Burlington

(617) 272-7300

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Zeus, An Arrow Company Wilmington, MA TEL: (508) 658-4776 TEL: (800) HI-REL

MICHIGAN Arrow/Schweber

Livonia TEL: (313) 462-2290 Hamilton Hallmark

Detroit TEL: (313) 347-4271

Zeus, An Arrow Company TEL: (708) 250-0500 TEL: (800) 52-HI-REL

#### MINNESOTA

Arrow/Schweber Eden Prarie TEL: (612) 941-5280

Hamilton Hallmark Minneapolis TEL: (612) 881-2600

Wyle Electronics Minneapolis

TEL: (612) 853-2280 Zeus, An Arrow Company TEL: (214) 380-4330 TEL: (800) 52-HI-REL

# MISSOURI

Arrow/Schweber St. Louis

TEL: (314) 567-6888

Hamilton Hallmark St. Louis TEL: (314) 291-5350

Zeus, An Arrow Company TEL: (214) 380-4330 TEL: (800) 52-HI-REL

# NEW JERSEY

Arrow/Schweber Mariton TEL: (609) 596-8000 Pinebrook TEL: (201) 227-7880

Hamilton Hallmark Cherry Hill

TEL: (609) 424-0110 Parsippany

TEL: (201) 515-1641 Wyle Electronics

Mt. Laurel TEL: (609) 439-9110 Pine Brook

TEL: (201) 882-8358 Zeus, An Arrow Company TEL: (914) 937-7400

TEL: (800) 52-HI-REL

Hamilton Hallmark Albuquerque TEL: (505) 828-1058 Zeus, An Arrow Company TEL: (408) 629-4789 TEL: (800) 52-HI-REL

\* Field Application Assistance Available

# North American Authorized Distributors (Continued)

NEW YORK Alliance Electronics, Inc. Binghamton TEL: (607) 648-8833

Huntington TEL: (516) 673-1930

Arrow/Schweber Farmingdale TEL: (516) 293-6363

Hauppauge

TEL: (516) 231-1000 Melville

TEL: (516) 391-1276 TEL: (516) 391-1300 TEL: (516) 391-1633

Rochester TEL: (716) 427-0300

Hamilton Hallmark Long Island TEL: (516) 434-7400

Rochester

TEL: (716) 475-9130 Ronkonkoma

TEL: (516) 737-0600 Zeus, An Arrow Company Pt. Chester TEL: (914) 937-7400 TEL: (800) 52-HI-REL

# NORTH CAROLINA

Arrow/Schweber Raleigh TEL: (919) 876-3132

EMC Charlotte TEL: (704) 394-6195

Hamilton Hallmark Raleigh TEL: (919) 872-0712

Zeus, An Arrow Company TEL: (407) 333-3055 TEL: (800) 52-HI-REL

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Alliance Electronics, Inc. Dayton TEL: (513) 433-7700 Arrow/Schweber Solon TEL: (216) 248-3990

Centerville TEL: (513) 435-5563

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TEL: (216) 498-1100 Columbus TEL: (614) 888-3313 Dayton TEL: (513) 439-6735 Toledo TEL: (419) 242-6610 Zeus, An Arrow Company TEL: (708) 595-9730 TEL: (800) 52-HI-REL OKLAHOMA Arrow/Schweber Tuisa TEL: (918) 252-7537 Hamilton Hallmark Tulsa TEL: (918) 254-6110 Zeus, An Arrow Company TEL: (214) 380-4330 TEL: (800) 52-HI-REL

Hamilton Hallmark

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# TEXAS

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TEL: (512) 835-4180 Dallas TEL: (214) 380-6464 Houston TEL: (713) 647-6868 Hamilton Hallmark Austin TEL: (512) 258-8848 Dallas TEL: (214) 553-4300 Houston TEL: (713) 781-6100 Wyle Electronics Austin TEL: (512) 345-8853 Houston TEL: (713) 879-9953 Richardson TEL: (214) 235-9953 Zeus, An Arrow Company Carrollton TEL: (214) 380-4330 TEL: (800) 52-HI-REL

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Wyle Electronics West Valley City TEL: (801) 974-9953

Zeus, An Arrow Company TEL: (408) 629-4789 TEL: (800) 52-HI-REL

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Seattle TEL: (206) 881-6697

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Milwaukee TEL: (414) 780-7200

Wyle Electronics Waukesha

TEL: (414) 521-9333 Zeus, An Arrow Company TEL: (708) 250-0500

TEL: (800) 52-HI-REL

# Harris Semiconductor Chip Distributors

Chip Supply, Inc. 7725 N. Orange Blossom Trail Orlando, FL 32810-2696 TEL: (407) 298-7100 FAX: (407) 290-0164

Eimo Semiconductor Corp. 7590 North Glenoaks Blvd. Burbank, CA 91504-1052 TEL: (818) 768-7400 FAX: (818) 767-7038

Minco Technology Labs, inc. 1805 Rutherford Lane Austin, TX 78754 TEL: (512) 834-2022 FAX: (512) 837-6285

# Puerto Rican

Authorized Distributor Hamilton Hallmark TEL: (809) 731-1110

# South American Authorized Distributor

Graftec Electronic Sales Inc. One Boca Place, Suite 305 East 2255 Glades Road Boca Raton, Florida 33431 TEL: (407) 994-5933 FAX: 407 994-5518

# BRASIL

Graftec Brasil Ltda. Rua baroneza De ITU 336 - 5 01231-000 - Sao Paulo - SP Brasil TEL: 55-11-826-5407 FAX: 55-11-826-6526

# European Sales Offices and Representatives

#### European Sales Headquarters Harris S.A. Mercure Center Rue de la Fusee 100 B-1130 Brussels, Belgium TEL: 32 2 724 221 11 FAX: 32 2 724 2205/...09

AUSTRIA Eurodis Electronics GmbH Lamezanstrasse 10 A - 1232 Vienna TEL: 43 1 61062-0 FAX: 43 1 610625

#### DENMARK Delco AS Titangade 15 DK - 2200 Copenhagen N TEL: 45 35 82 12 00

FAX: 45 35 82 12 05

# FINLAND

J. Havulinna & Son Reinikkalan Kartano SF - 51200 Kangasniemi TEL: 358 59 432031 FAX: 358 59 432367

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SALES OFFICES

# European Sales Offices and Representatives (Continued)

# February 24, 1995

FRANCE         Harris Semiconducteurs SARL           * 2-4, Avenue de l'Europe         F - 78941 Velizy Cedex           TEL: 33 1 34 65 40 80 (Dist)         TEL: 33 1 34 65 40 27 (Sales)           FAX: 33 1 39 46 40 54         FAX	Erwin W. Hildebrandt Nieresch 32 D - 48301 Nottuln-Darup TEL: 49 2502 60 65 FAX: 49 2502 18 89 FINK Handelsvertretung Laurinweg, 1 D - 85521 Ottobrunn	ITALY         Harris SRL           * Viale Fulvio Testi, 126         I-20092 Cinisello Balsamo, (Milan)           TEL: 39 2 262 07 61         (Disti & OEM ROSE)           TEL: 39 2 240 95 01         TEL: 39 2 240 95 01	UNITED KINGDOM Harris Semiconductor Ltd * Riverside Way Camberley Surrey GU15 3YQ TEL: 44 276 686 886 FAX: 44 276 682 323
GERMANY Harris Semiconductor GmbH * Putzbrunnerstrasse 69	TEL: 49 89 6 09 70 04 FAX: 49 89 6 09 81 70 Hartmut Welte	(Disti & OEM Italy) FAX: 39 2 262 22 158 (ROSE)	Laser Electronics Ballynamoney Greenore Co. Louth, Ireland TEL: 353 4273165 FAX: 353 4273518 Complementary Technologies Ltd Redgate Road South Lancashire, Ind. Estate Ashton-In-Makerfield Wigan, Lancs WN4 8DT TEL: 44 942 274 731 FAX: 44 942 274 732
D-81739 München TEL: 49 89 63813-0 FAX: 49 89 6377891	Hepbacher Strasse 11A D - 88677 Markdorf TEL: 49 7544 7 25 55	NETHERLANDS Harris Semiconductor SA Benelux OEM Sales Office Kouterstraat 6 NL - 5345 LX Oss TEL: 31 4120 38561 FAX: 31 4120 34419	
Harris Semiconductor GmbH Kieler Strasse 55-59	FAX: 49 7544 7 25 55		
D-25451 Quickborn TEL: 49 4106 50 02-04 FAX: 49 4106 6 88 50	ISRAEL Aviv Electronics Ltd Hayetzira Street, 4 Ind. Zone IS - 43651 Ra'anana PO Box 2433 IS - 43100 Ra'anana		
Harris Semiconductor GmbH Wegener Strasse, 5/1		SPAIN Elcos S. L. C/Avda. Europa, 30 1 B-A Spain 28224 Pozuelo de Alarcon Madrid TEL: 34 1 352 3052 FAX: 34 1 352 1147	
D - 71063 Sindelfingen TEL: 49 7031 8 69 40 FAX: 49 7031 87 38 49	TEL: 972 9 983232 FAX: 972 9 916510		Stuart Electronics Ltd. Phoenix House Bothwell Road
Ecker Michelstadt GmbH In den Dorfwiesen 2A			Castlehill, Carluke Lanarkshire ML8 5UF TEL: 44 555 751566 FAX: 44 555 751562
Postfach 33 44 D - 64720 Michelstadt TEL: 49 6061 22 33			
FAX: 40 COC1 E0 00		Besyol Londra Asfalti	

# European Authorized Distributors

AUSTRIA Avnet E2000 GmbH Waidhausenstrasse 19 A - 1140 Wien TEL: 43 1 9112847

FAX: 43 1 9113853

FAX: 49 6061 50 39

EBV Elektronik Diefenbachgasse 35/6 A - 1150 Wien TEL: 43-222-8941774 FAX: 43-22-8941775

**Eurodis Electronics GmbH** Lamezanstrasse 10 A - 1232 Wien TEL: 43 1 610620 FAX: 43 1 610625

**Spoerle Electronic** Heiligenstädter Str. 52 A - 1190 Wien TEL: 43 1 31872700 FAX: 43 1 3692273

# BELGIUM

- **Diode Spoerle** Keiberg II Minervastraat, 14/B2 B-1930 Zaventem TEL: 32 2 725 46 60 FAX: 32 2 725 45 11
- **EBV Elektronik** \* Excelsiorlaan 35 B - 1930 Zaventem TEL: 32 2 716 00 10 FAX: 32 2 720 81 52

**Eurodis Texim Electronics** Avenue des Croix de Guerre 116 B - 1120 Brussels TEL: 32 2 247 49 69 FAX: 32 2 215 81 02

# DENMARK

Avnet Nortec Transformervej, 17 DK - 2730 Herley TEL: 45 42 84 2000 FAX: 45 44 92 1552

Ditz Schweitzer Vallensbaekvej 41 Postboks 5 DK - 2605 Brondby TEL: 45 42 45 30 44 FAX: 45 42 45 92 06

# FINLAND

Avnet Nortec Italahdenkatu, 18 SF - 00210 Helsinki TEL: 358 061 318250 FAX: 358 069 22326

Bexab Sinimaentie 10C P.O. Box 51 SF - 02630 ESPOO TEL: 358.0.50 23 200 FAX: 358.0.50 23 294

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# TAIWAN

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#### TAIWAN

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# Applied Component

Technology Corp. 8F No. 233-1 Pao-Chial Road Hsin Tien City, Taipei Hsein, Taiwan, R.O.C. TEL: (02) 9170858 FAX: (02) 9171895

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