# Burroughs

## **OEM Products**

## FD210 Fixed Disk Drives

## **General Description**

The Burroughs Fixed Disk Drives are random access storage devices that use non-removable disks as the storage medium. Designed for the original equipment manufacturer, the FD 210 Series provides up to 80 million bytes of on-line storage in a compact, lightweight package.

The FD 210 Fixed Disk Series currently consists of two models: the FD 211 (20MB), and the FD 214 (80 MB).

## Advanced Microprocessor Controller

Included in both models of the FD 210 Series is an Advanced Microprocessor Controller (AMC).

In addition to controlling the basic positioner and data channel functions the AMC also performs functions normally required of the host system. Among the functions provided by the AMC are the following:

CRC Generation
Error Detect, Retry and Correct
Dual Sector Buffering
Sector Relocation
File Search using Host Supplied
Parameters
Error Logging and Analysis
Confidence/Diagnostic Tests

## **Drive Module**

The drive module is a sealed unit containing one or four disks mounted on a common spindle. A rotary positioner moves two flying heads across each surface to access the data tracks. At certain locations on each surface are servo tracks that are used by the AMC to correct for alignment variations due to environmental changes.

## **Applications**

## Interface and Compatibility

The standard FD 210 interface is a simple parallel data and control bus that permits rapid integration with a host system.

The FD 210 Series is interface compatible with the Burroughs MD 122 Mini Disk Drive. The MD 122 provides up to 3 million bytes of storage on a single, removable flexible disk and up to 6 MB per drive.

The MD122 also contains the Advanced Microprocessor Controller so that FD 210 drives and MD122 drives may be mixed on the same host system controller.

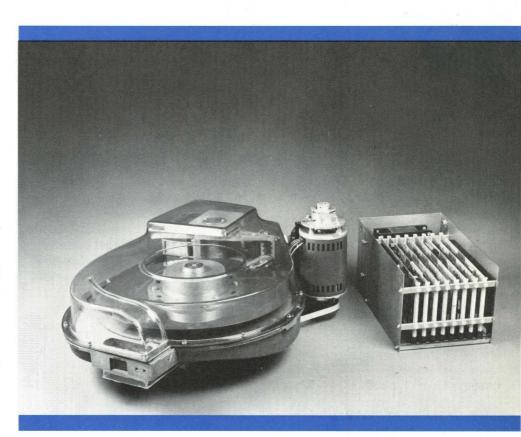
## **Standard Features**

## Software Simplicity

Due to the intelligence of the AMC, host system software to control the device is greatly simplified. Upon power-on of the FD 210; the AMC determines and reports to the host system how much storage capacity is available (20 or 80 MB, or in the case of the MD122 – 3 or 6 MB). This capability allows mixing, replacing or upgrading the disk subsystem without software change.

## **Options**

RETMA Rack Mount.
Free-Standing Cabinet and Power
Supply.

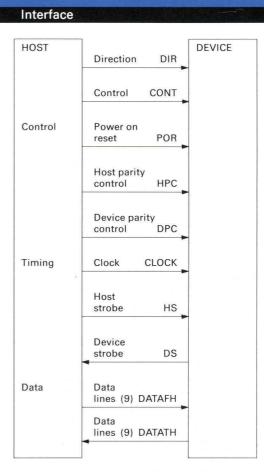


#### **Specifications Formatted** Environmental FD 211 FD 214 Data Operating temperature: 10°C to 40°C Relative humidity: 10% to 85% Maximum wet bulb temperature: 26°C Number of disks 1 4 Non-operating temperature: -40°C to 60°C Tracks per 4 16 Relative humidity, non-condensing: cylinder Sectors per track 58 58 5% to 90% Bytes per sector 256 256 **Physical Characteristics** Bytes per (without optional cabinet) cylinder 59,392 237,568 Length (in/mm) 30.0/762 19.0/483 Cylinders Width (in/mm) 336 336 per drive Height (in/mm) 10.5/266 Bytes per 19,955,712 79,822,848 Reliability drive Preventive maintenance Performance Access time (ms) **MTBF** (including settling) Sealed module (two 45 45 18,000 hrs AOT Average starts per day) 85 85 4,000 hrs AOT Maximum Other components Track-to-8 8 **MTTR** track Board replacement 0.75 hrs Latency (ms) Component replacement 1.50 hrs 10 10 Service life 7 years or Average 35,000 hrs AOT Maximum 20 20 Transfer rate Irrecoverable error one in 1012 bits (m bits/sec) 7.1 7.1 rate, maximum Recording Density Tracks per The card cage containing the controlinch 300 300 ler must receive a continuous air flow Bits per of 70 C.F.M. minimum with an air inlet inch 5,500 5,500 temperature of 40° max. Areal density (BPI2) 1.65M 1.65M **Electrical Requirements** Power consumption 310W

295W

Supply voltage: +5V, +12V, -12V. Current, idle: 6A, 0.5A, 1.4A. Current, maximum:9A, 4.5A, 4.5A.

running



## **Transfer Format**

None

All transfers are formatted similarly in both directions: 9-bit parallel, character serial. Data integrity is supported by an odd vertical parity check (VPC) with each data byte and an even longitudinal parity check (LPC) with each transfer sequence. The LPC byte terminating a sequence has an odd VPC bit.

## Logic Signals

Direction (DIR) and Control (CON): these establish the four transfer modes as follows:

DIR	CONT	MODE	Transfer	BUS
			Description	Used
0	0	Status	Status	DATATH
1	0	Command	Commands	DATAFH
0	1	Host Receive	Data	DATATH
1	1	Host send	Data	DATAFH

Host Strobe (HS) and Device Strobe (DS): depending on mode, these signal the host or device to read a data bus or acknowledge that a data bus has been read. See table below.

Host Parity Control (HPC) and Device Parity Control (DPC): used by a sending unit to indicate that the current byte is an LPC byte. Used by a receiving unit to indicate parity errors, both VPC and LPC. See table below.

## Signal Indication

Command and Host Send Modes				
HS	DeviceshouldreadDATAFH			
DS	Device has read DATAFH			
HPC	LPC byte now on DATAFH			
DPC	Parity error on DATAFH			
Host Receive and Status Modes				
DS	Host should read DATATH			
HS	Host has read DATATH			
DPC	LPC byte now on DATATH			
HPC	Parity error on DATATH			

Data bus (DATAFH): a 9-line bus consisting of 8 data line and one parity bit line. DATAFH 7 is the most significant bit. Transfer is from host.

Data bus (DATATH): same as DATAFH except transfer is to host.

CLOCK: a self-starting, free-running, 1 MHz clock generated by the host. Used by device to trigger all changes on the interface.

Power On Reset (POR): generated by the host upon power-up or programmatically after. It causes the device controller to reset itself and connected drives. POR overrides any on-going commands in the device.

## Commands

Format: a command consists of a variable number of bytes depending on the particular command. The first byte consists of two hexadecimal digits and is the "op code" for that command. Subsequent bytes express parameters (e.g., drive, sector address, number of bytes, etc.)

Command Set: these are listed in three groups below according to whether a seek and data transfer are both involved, a data transfer only, or neither.

## Group 1

Read Statistics Read Location Map Write

## Group 2

Search
Read Search Result
Read Device Attribute Record
Read Status
Host Receive Maintenance Test
Routine
Host Send Maintenance Test Routine

## Group 3

Abort Device Controller Abort Drive Reset Set Write Protect Reset Write Protect Unlock Door Lock Door Interlace

## Status Format

The device reports its status condition by the transfer of one or more bytes to the host. Set bits have the significance shown:

Bit 0 1 2	Byte 1 Drive address, bit 0 Drive address, bit 1 Drive address, bit 2
3	(most significant) Transfer delay
4	N sectors before read
5	N sectors before write
6	Operation complete
7	Interrupt
,	menupi
	Byte 2
0	Error
	Search unsuccessful
2	Corrected
1 2 3	Command not accepted
4	Command error
5	Address error/end of
	drive
6	Mandatory interrupt to
	host
7	Address not found
	Byte 3
0	Not ready - Class 2
1 2 3	Disk expiring - Class 2
2	Write protected
3	New disk
4	Danger - Class 2
5	Confidence test
	completed
6	Temporarily not avail.
	Class 2
7	Unassigned

Note: Class 2 indicates a status of a "steady state" nature.

## **Electrical Interface**

Supply voltage: +5V +/-10%

Common mode voltage: absolute value between host and device grounds must be less than 5V.

Line drivers/receivers: differential, RS422 compatible, types MC3487-Burroughs 2767 4498 and MC3486-Burroughs 2767 4506, or equivalents.

Line termination: 88.7 ohms ±2%

Cable: balanced twisted pair, characteristic impedance 87 ohms  $\pm 5\%$ , max. cable length 25 ft. (7.6m).

For further information, reference this bulletin number and write to Burroughs OEM Marketing, Burroughs Place, Detroit, MI. 48232; or call one of our special sales/application numbers (313) 972-8031 in Detroit or (714) 835-7335 in California. For overseas inquiries, write Burroughs OEM Marketing, Langwood House, High Street, Rickmansworth, Herts., England. Tel. (44) 9237-70545.

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