CTIX<sup>™</sup> OPERATING SYSTEM MANUAL

Version C Volume 2

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#### NAME

gettimeofday, settimeofday - get/set date and time

#### SYNOPSIS

```
#include <sys/time.h>
int gettimeofday(tp, tzp)
struct timeval *tp;
struct timezone *tzp;
int settimeofday(tp, tzp)
struct timeval *tp;
struct timezone *tzp;
```

#### DESCRIPTION

The current Greenwich time and the current time zone are obtained with the *gettimeofday* call, and set with the *settimeofday* call. The time is expressed in seconds and microseconds since midnight (0 hour), January 1, 1970 (GMT). The resolution of the system clock is hardware dependent, and the time may be updated continuously or in "ticks." If *tzp* is a NULL pointer, the time zone information will not be returned or set.

The structures pointed to by tp and tzp are defined in <sys/time.h> as follows:

The *timezone* structure indicates the local time zone (measured in minutes of time westward from Greenwich), and a flag that, if nonzero, indicates that Daylight Savings Time applies locally during the appropriate part of the year.

Only the superuser can set the time of day or time zone.

Note that you must link the sockets library to your program. Use **-Isocket** in the compile command line.

#### **SEE ALSO**

```
date(1), adjtime(2), ctime(3C).
```

### **RETURN VALUE**

A 0 return value indicates that the call succeeded. A -1 return value indicates an error occurred, and in this case, an error code is stored into the global variable *errno*.

#### **ERRORS**

The following error codes may be set in errno:

[EFAULT] An argument address referenced invalid memory.

[EPERM] A user other than the superuser attempted to set the time.

#### **NAME**

notify, unnotify, evwait, evnowait - manage notifications

#### **SYNOPSIS**

```
#include <notify.h>
int notify(type, arg, tag)
ushort type;
char *arg;
char *tag;
int unnotify(type, arg)
ushort type;
char *arg;
ushort evwait(tag, datum)
char **tag;
char **datum;
ushort evnowait(tag, datum)
char **tag;
char **datum;
```

#### DESCRIPTION

The *notify* system call interface allows a user process to record a number of events that it is interested in, and then waits for any one of them. Like *select* (2), it does synchronous I/O multiplexing, but *notify* waits for a wider range of events and thus has greater functionality than *select*.

The *notify* call requests a notification or set of notifications.

The unnotify call retracts an earlier request (or set of requests) for notification.

The evwait call waits for a notification to be posted to the calling process.

The *evnowait* call returns the first notification if one exists, returning immediately otherwise.

Notifications are posted FIFO (first-in, first-out) in the user process, each evwait returning the first notification or blocking until one is posted. When a notify call is given, the user must supply the type of notification, a tag, and an argument. The tag is an arbitrary number the size of a (char \*), which is returned by any evwait call triggered by that notification request. The argument is type-specific and is described below.

The return values of evwait and evnowait are the type of the notification.

It is an error for *notify* to be called with a *type* and *arg* matching a currently active notification.

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The *notify* calls support the following *types*:

### N FDREAD

Queues a notification if the file descriptor arg is readable at the time of the *notify* call, and subsequently whenever there is data to be read. A notification is also queued at the end-of-file (EOF) or when the number of writers on a pipe goes to zero. The datum returned from an *evwait* is a count of the number of bytes available to be read. At EOF, the datum is -1, and the request is deleted. This type is implemented for sockets, pipes, ttys, and streams.

### N FDWRITE

Queues a notification if the file descriptor arg is writable at the time of the *notify* call, and subsequently when the file goes from a non-writable to a writable state (that is, output is not blocked). datum is the number of characters writable. This type is implemented for sockets, pipes, and streams.

### N SIGNAL

Queues a notification on receipt of a signal. This is used in conjunction with regular signal catching [see signal(2)]. When signal notification is in effect, all caught signals queue notifications instead of causing pseudo-interrupts. If multiple instances of a caught signal occur before the process has received the notification, the returned type is **N\_LOSTSIG** rather than **N\_SIGNAL**. Ignored or defaulted signals are handled normally. Signals are not reset upon notification.

Note that only one call to *notify* 

notify(N\_SIGNAL,ignored,tag)

is required to enable notification of all signals that have a signal catching function (use a null function). *evwait* and *evnowait* return the *tag* and *datum*. *datum* is a bitwise OR of all queued signals; that is, low-numbered signals are represented as low-order bits (signal n sets  $2^{n-1}$ ).

### N UMSGREAD, N UMSGWRITE

Queues a notification if the message queue described by *arg* is or becomes readable or writable, respectively. The datum returned is the number of messages received or the number of characters that can be sent, respectively. When the message queue is removed, *datum* is -1, and the request is deleted.

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### N INDIR

If type is N\_INDIR, arg is acually a pointer to an array of the following structure (defined in /usr/include/notify.h):

```
struct n_request {
    ushort type;
    char *arg;
    char *tag;
}
```

The array should be terminated with an entry having type N\_INDIR. The entire set of notifications is either placed or removed. N\_INDIR is never returned by evwait or evnowait.

### **N\_QUERY**

Type N\_QUERY is valid only as an argument to the *notify* call. arg is a pointer to an array of **struct n\_indir**, and tag is a pointer to an **int** containing the number of elements in the array.

On return, the array contains the current active notifications in a form suitable for passing to *notify* or *unnotify* (that is, terminated by **N\_INDIR**), and the **int** pointed to by *tag* contains the number of active notifications (even if there was not enough space to copy them all back).

### N SEMOP

Queues a notification if the semaphore described by the **struct n\_semop** pointed to by *arg* would not block, is released, or is removed. *datum* is **semval** unless the semaphore has been removed, in which case it is -1.

```
struct n_semop {
    int semid;    /* semaphore ID */
    short sem_num; /* semaphore number */
    short sem_op; /* semaphore operation */
}
```

#### SEE ALSO

fcntl(2), msgop(2), pipe(2), read(2), select(2), signal(2), socket(2), wait(2), termio(7).

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NOTIFY(2) NOTIFY(2)

#### DIAGNOSTICS

All calls return -1 on error, setting errno to one of the following:

[EINVAL] Invalid type was given Caller never did a notify (unnotify, evwait, evnowait) [EINVAL] File is not of a valid type (N FDREAD, N FDWRITE) [EINVAL] [EBADF] File is not open (N FDREAD, N FDWRITE) Invalid message queue descriptor (N UMSG) [EBADF] No space available to allocate notification queue header [ENOSPC] No space available to allocate table entry for this notification [ENOSPC] Too many active notification requests for given space [ENOSPC] (N QUERY)

An address fault was generated by a user-supplied pointer [EFAULT]

#### **EXAMPLE**

```
#include "sys/types.h"
#include <sys/notify.h>
#include <stdio.h>
#include <signal.h>
int sig catch();
main()
{
      int tag, datum, i;
      char buf[BUFSIZ];
      ushort rv, evwait();
      setbuf(stdout, NULL);
      if (notify(N FDREAD, 0, 't') < 0)
            perror("notify for N FDREAD of stdin failed"), exit(1);
      if (notify(N_SIGNAL, 2, 's') < 0)
            perror("notify failed"), exit(1);
      for (i=0; i<20; i++)
            signal(i, sig catch);
```

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```
for(;;) {
            /* Wait for an event */
            rv = evwait(&tag, &datum);
            /* Tell the user about it */
            printf("0v: %d tag: %d datum: %d0, rv, tag, datum);
            switch (tag) {
            case 's':
                  break;
            case 't':
                  /* Read the input */
                  gets(buf);
                  printf("read '%s'0, buf);
                  if (*buf == 'q')
                  exit(0);
                  break;
            }
     }
}
sig_catch()
{
}
```

### WARNING

The *notify* system call interface is not portable, has little likelihood of becoming so, and may disappear in future releases of CTIX. It is therefore recommended that you use the poll(2) system call, and that existing software using *notify* be changed to use poll.

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SHMOP(2)

#### NAME

shmop - shared memory operations

#### **SYNOPSIS**

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
char *shmat (shmid, shmaddr, shmflg)
int shmid;
char *shmaddr;
int shmflg;
int shmdt (shmaddr)
char *shmaddr;
```

#### DESCRIPTION

shmat attaches the shared memory segment associated with the shared memory identifier specified by shmid to the data segment of the calling process. The segment is attached at the address specified by one of the following criteria:

- If *shmaddr* is equal to zero, the segment is attached at the first available address as selected by the system.
- If shmaddr is not equal to zero and (shmflg & SHM\_RND) is "true", the segment is attached at the address given by [shmaddr (shmaddr modulus SHMLBA)].
- If shmaddr is not equal to zero and (shmflg & SHM\_RND) is "false", the segment is attached at the address given by shmaddr.

shmdt detaches from the calling process's data segment the shared memory segment located at the address specified by shmaddr.

The segment is attached for reading if (shmflg & SHM\_RDONLY) is "true" {READ}, otherwise it is attached for reading and writing {READ/WRITE}.

shmat will fail and not attach the shared memory segment if one or more of the following are true:

[EINVAL] shmid is not a valid shared memory identifier.

[EACCES] Operation permission is denied to the calling process [see

intro(2)].

[ENOMEM] The available data space is not large enough to accommodate

the shared memory segment.

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SHMOP(2) SHMOP(2)

[EINVAL]	shmaddr is not equal to zero, and the value of [shmaddr - (shmaddr modulus SHMLBA)] is an illegal address.
[EINVAL]	shmaddr is not equal to zero, (shmflg & SHM_RND) is "false", and the value of shmaddr is an illegal address.
[EMFILE]	The number of shared memory segments attached to the calling process would exceed the system-imposed limit.
[EINVAL]	shmdt will fail and not detach the shared memory segment if shmaddr is not the data segment start address of a shared memory segment.

### SEE ALSO

exec(2), exit(2), fork(2), intro(2), shmctl(2), shmget(2).

### **DIAGNOSTICS**

Upon successful completion, the return value is as follows:

- *shmat* returns the data segment start address of the attached shared memory segment.
- shmdt returns a value of 0.

Otherwise, a value of -1 is returned and errno is set to indicate the error.

#### **NOTES**

The user must explicitly remove shared memory segments after the last reference to them has been removed.

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#### **NAME**

syslocal - special system requests

#### **SYNOPSIS**

```
#include <syslocal.h>
int syslocal (cmd [ , arg ] ... )
int cmd;
```

#### DESCRIPTION

The syslocal routine executes certain special system calls. The specific call is indicated by the first argument. See the <sys/syslocal.h> file for complete documentation of parameters.

### System Type

### int syslocal(SYSL\_SYSTEM)

Returns SYSL\_MITI for S/Series.

### Family Member

### int syslocal(SYSL\_FAMILYMEMBER)

Returns a value identifying the specific system: SYSLFMITI1 for S/120, S/221-2, or S/320; SYSLFMITI2 for S/480 or S/640; SYSLFS80 for S/80; SYSLFS280 for S/280; and SYSLFS4000 for S/4040.

### Superblock Resynchronization

int syslocal(SYSL\_RESYNC, devnum)

#### short devnum

Rereads contents of superblock from disk. *devnum* specifies the file system: The high-order byte contains the major device number of the character special device; the low-order byte contains the minor device number. Only the superuser can reread the contents of the superblock from disk.

#### Maximum Number of Users

### int syslocal(SYSL\_MAXUSERS)

Returns maximum number of users configured for this system.

### Kernel Addresses

### syslocal(SYSL\_KADDR, arg)

Returns certain addresses of kernel data structures. This allows certain programs (ps, killall) to run properly, even if /unix is not the currently running operating system.

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arg is one of the following:

**SLA V** Returns address of var structure (sys/var.h).

**SLA\_PROC** Returns address of proc structure (sys/proc.h).

**SLA\_ERR** Returns address of err structure (sys/err.h).

**SCA TIME** Returns address of int time.

SLA CDT Returns address of crash dump table (CDT) =

(sys/hardware.h).

**SLA GDUTAB** Returns address of gdutab (sys/iobuf.h).

**SLA\_USRSTK** Returns highest address of user stack.

SLA USIGN Returns signature of running UNIX (may be compared with

/unix to see if they are identical).

**SLA MEM** Returns number of bytes of physical memory.

**SLA BDEVCNT** Returns number of slots in struct bdevsw (sys/conf.h).

**SLA\_CDEVCNT** Returns number of slots in struct cdevsw (sys/conf.h).

**SLA PRELD** Returns the address of the preloaded driver table.

### Object Module Type

### syslocal(SYSL\_0413MAGIC)

Returns 1 if the kernel can support the -F option of ld().

### Read Real-Time Clock

#### sysiocal(SYSL\_RDRTC, arg)

Reads current state of real-time (battery supported) clock. arg is a pointer to struct rtc (sys/rtc.h)

### Write Real-Time Clock

### sysiocal(SYSL\_WTRTC, arg)

Writes new state of real-time clock. arg is a pointer to a struct rtc (sys/rtc.h). EIO is returned if any of the values are illegal. Only the superuser can write the real-time clock.

### Reboot System

#### syslocal(SYSL REBOOT)

Forces a software reset. Only the superuser may reset. Obsolete: retained for compatibility. Use *uadmin*(2) instead.

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#### Allocate or Bind a Loadable Driver

syslocal(SYSL\_ALLOCDRV, option, arg)

sysiocal(SYSL\_BINDDRV, option, arg)

These two functions implement the loadable driver functions of CTIX. They both require superuser privilege.

Loading drivers consists of two phases: allocation of virtual space, device numbers, and device IDs; and binding. Fully relocating a driver into memory, allocating physical space, plugging the device switch tables, calling initialization routines, and unloading require the same two phases in reverse. For information on the arguments, see /usr/include/sys/drv.h.

### **Determine Processor Type**

### syslocal(SYSL\_PROCESSOR)

Returns a value that can be used to determine what kind of processor (68010, 68020, or 68040) is running and whether floating-point hardware (68881/68040) is available.

### **Enable Fixed Priority Range**

### syslocal(SYSL\_RTNICE,flag)

Enables/disables the fixed priority range [see nice(2)]. flag is 1 for enable, 2 for disable. Only the superuser can execute this call, which affects every process.

## S/80, S/280, S/480, and S/640 Hardware Configuration

### syslocal(SYSL MITICFIG)

Returns a bit mask of the hardware that is present. Values can be found in syslocal.h. A more convenient way to get this information is by using hinv(1M).

### S/4000 Hardware Configuration

### sysiocal(SYSL\_SXCFIG, arg1, arg2)

Returns a bit mask of the hardware that is present. Values can be found in syslocal.h. A more convenient way to get this information is by using hinv(1M).

arg1 is one of the following:

SLA\_SER Returns a bit mask of the serial boards present.

SLA IEN Returns a bit mask of the Ethernet boards present.

SLA\_SCSI Returns a bit mask of the SCSI boards present.

SLA\_SERNPORT Returns number of serial ports for board denoted by

arg2.

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SLA\_IENPORT Returns number of Ethernet ports for board denoted by

arg2.

SLA\_SCSINPORT Returns number of SCSI ports for board denoted by

arg2.

SEE ALSO

fsck(1M), nice(2).

**DIAGNOSTICS** 

Note that syslocal fails if one of the following is true:

[EINVAL] cmd or any suboption is illegal.

[EFAULT] An arg points outside the process's space.

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